



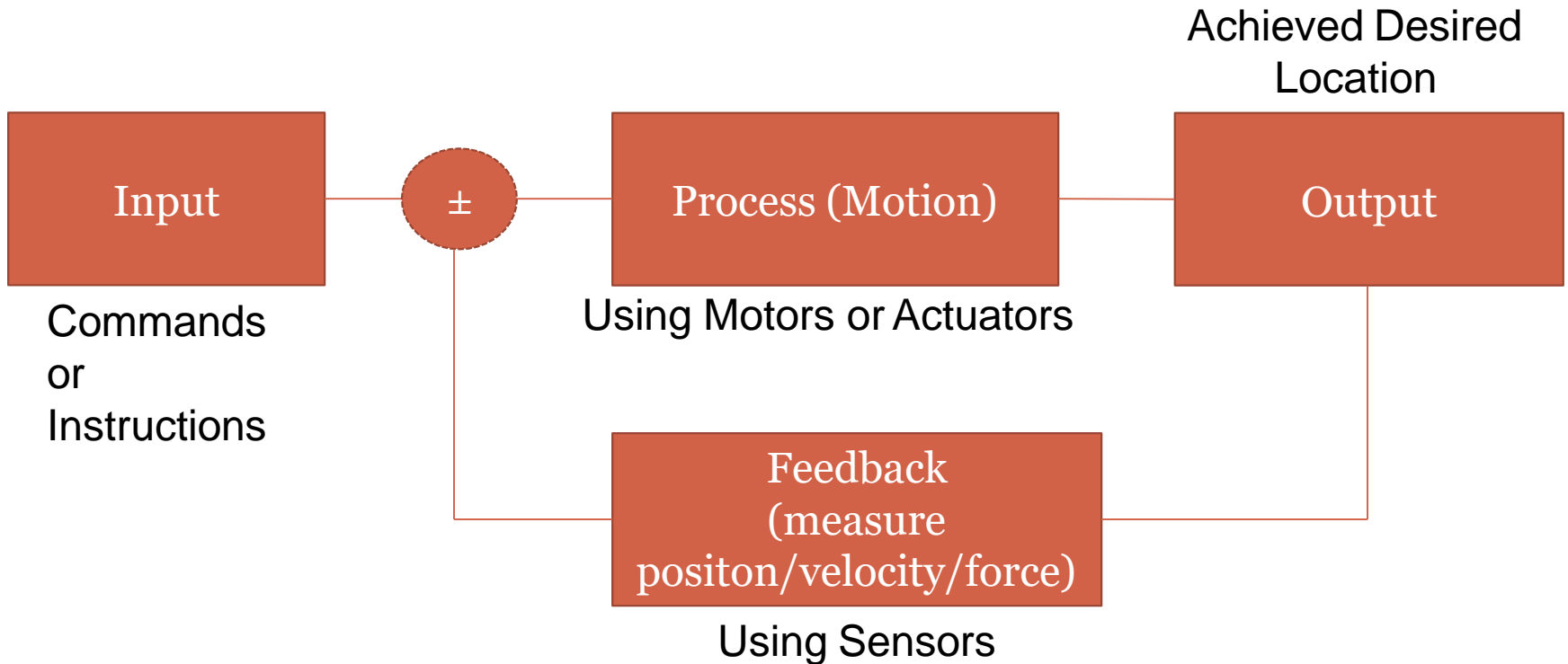
# ROBOTICS II

Robotic Sensors  
Incremental & Absolute Encoders

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# Robotic Control System



# Importance of Sensors and Actuators

## What is Robotic Sensor

Robotic sensors are used to detect the environment and measure the parameters for controlling the robotic manipulator such as distance, velocity, pressure, and force etc.

Focusing only position and velocity sensors

# Applications of Sensors in Robotics

- To detect the object in work envelop
- Position and velocity of robotic joint and links
- Pressure and Force measurement in gripper to hold an object

# Angular Position and Velocity Sensors

- Encoders

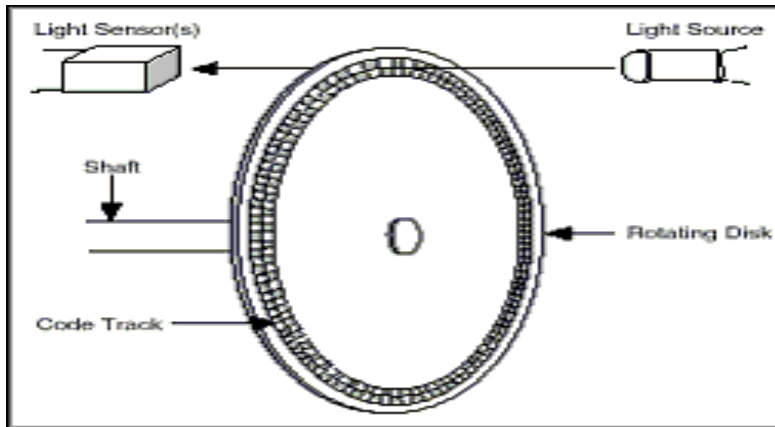
Incremental Encoders

Robotics I

Absolute Encoders

Robotics II

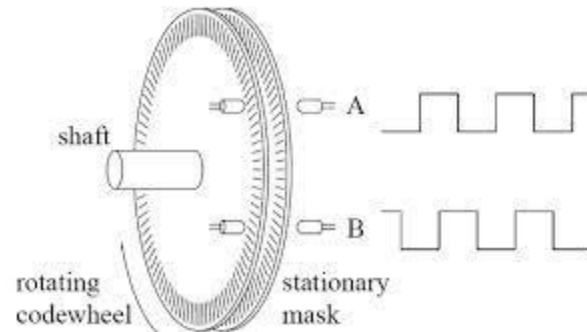
# Incremental Encoders



Opaque disk  
with slits

$$S = \frac{\text{Total no's of pulses in one min}}{\text{number of slits}} \text{ rpm}$$

Resolution = 360 / number of slits



# Quiz

## Question 1

If an optical encoder has 12 slits and it gives 8 output pulse signals then determine the angular displacement of the joint where the encoder is attached. If you get 100 pulses in one minute then tell the speed of the joint (rpm: rev. per minute)

Number of slits = 12

Number of output pulses = 8

Angular Displacement = ?

Resolution= minimum value of detection=  $360/360 = 1$  degree

One pulse = 30 deg.

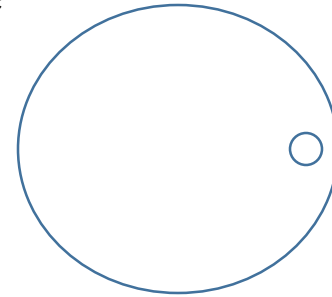
8 pulses =  $8 \times 30 = 240$  deg.

Speed=?

12 pulses = 1 rev

1 pulse =  $1/12$  rev

100 pulses =  $(1/12) \times 100 \text{ rev/min} = 100/12 = 8.33 \text{ rpm}$



# Absolute Encoder

Consists of an optical disk ( Glass disk) in which the number of tracks are produced Chemically

Resolution of encoder

$$R e s = \frac{360^{\circ}}{2^n}$$

$$\begin{aligned} Res &= 360 / 2^8 \\ Res &= 360 / 256 = \\ &= 1.4 \text{ deg.} \end{aligned}$$

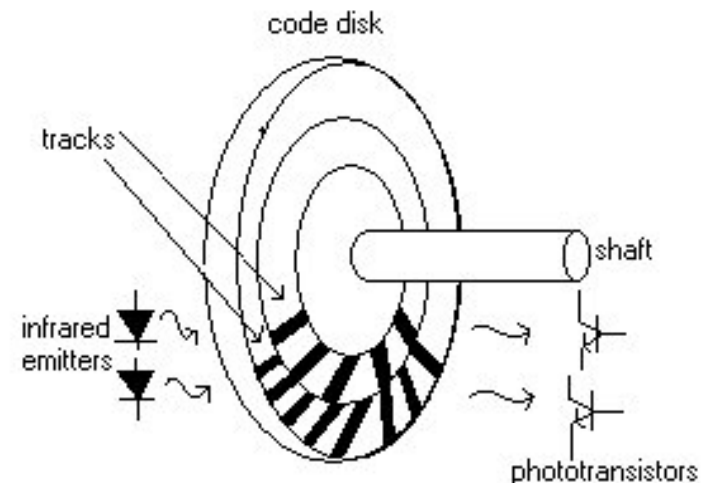


Fig 1. A rotary optical encoder

Where n is number of tracks in the optical disk

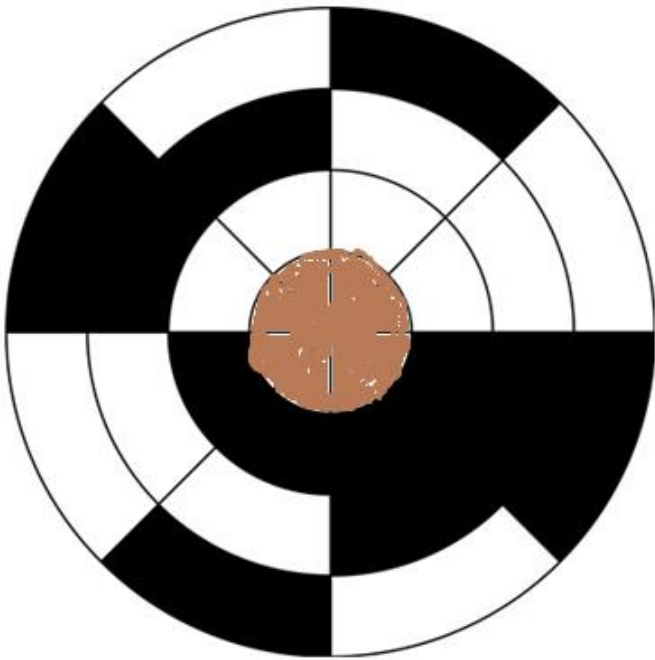
*2<sup>n</sup> the unique position on you disk*



# Absolute Encoder

- The optical disk of the absolute encoder is designed to produce  $N$  distinct positions of the shaft.
- If there are 8 tracks, the encoder is capable of producing 256 distinct positions or an angular resolution of  $1.406$  ( $360/256$ ) degrees.
- The most common types of numerical encoding used in the absolute encoder are gray and binary codes

# 3-bit binary Code



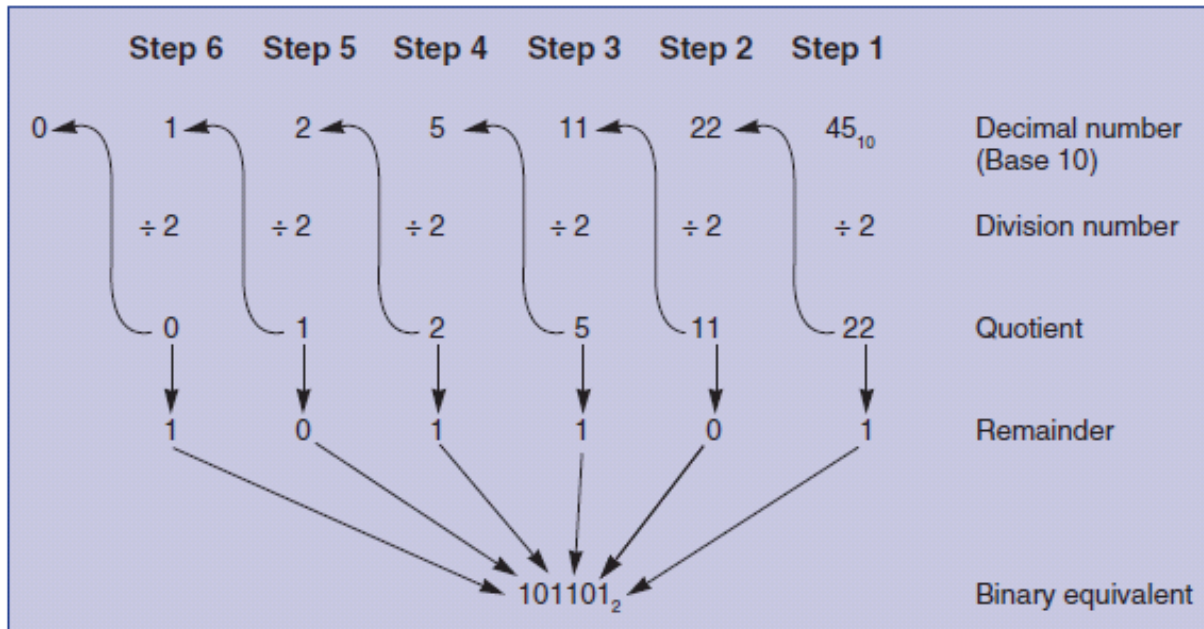
Dec	Binary
0	000
1	001
2	010
3	011
4	100
5	101
6	110
7	111

Binary numbers 0, 1

Number of tracks = 03

Distinct position =  $2^3 = 8$  000,01,10,11

# Decimal to Binary



**Decimal-to-Binary Conversion**

# 3-bit binary Code

$$4/2 = 2 \text{ ; } 20 = 100$$

## Convert from Decimal to Binary

Divide the number with 2

Example 1: Decimal number = 2

$2/2 = \textit{Quotient} = 1 ; \textit{Remainder} = 0$

Combined them = 10

In 03 bits = 010

Example 2: Decimal number 3

$3/2 = \textit{Quotient} = 1 ; \textit{Remainder} = 1$

Combined them = 11

In 03 bits = 011

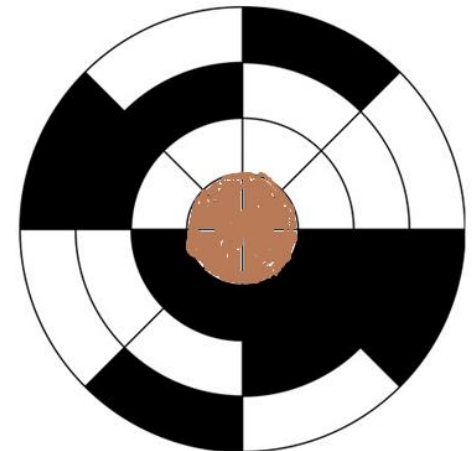
Example 3: Decimal number 4

$4/2 = \textit{Quotient} = 2 ; \textit{Remainder} = 0$

$\textit{Quotient} (2) / 2 = \textit{Quotient} = 1 ; \textit{Remainder} = 0$

Combined all them = 100

Dec	Binary
0	000
1	001
2	010
3	011
4	100
5	101
6	110
7	111

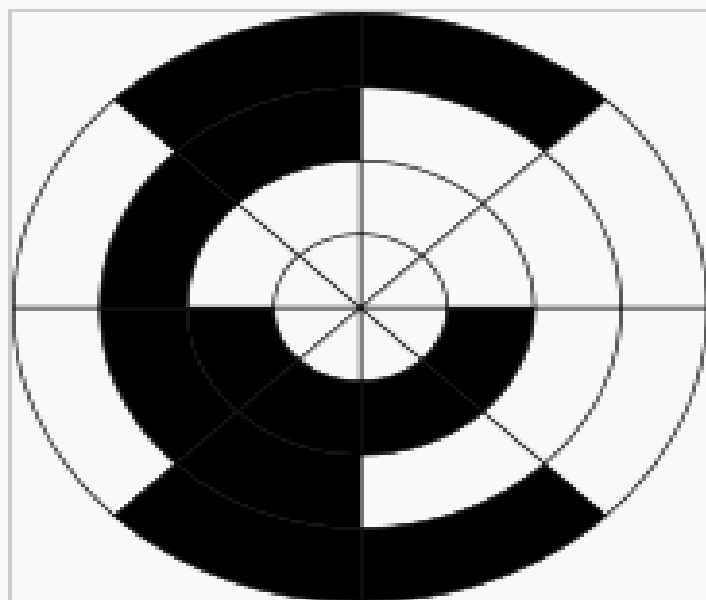


# Binary to Gray Code

- Start with a word that contains all zeros.
- Go to the least significant bit and toggle it (i.e., change it from 0 to 1 or from 1 to 0).
- If the resulting code has not been used before (i.e., is unique), then keep the resulting code and proceed to the next.
- Otherwise, if the code is not unique, then undo the change and move to the next significant bit and toggle it.
- Repeat the steps above until all codes have been generated.

Dec	Binary	Gray
0	000	000
1	001	001
2	010	011
3	011	010
4	100	110
5	101	111
6	110	101
7	111	100

# 3 bit Gray Code



Rotary encoder for angle-measuring devices marked in 3-bit binary-reflected Gray code (BRGC)

Dec	Binary	Gray
0	000	000
1	001	001
2	010	011
3	011	010
4	100	110
5	101	111
6	110	101
7	111	100

# 4-Bit Binary and Gray Codes

<b>Decimal code</b>	<b>Rotation range (deg.)</b>	<b>Binary code</b>	<b>Gray code</b>
0	0-22.5	0000	0000
1	22.5-45	0001	0001
2	45-67.5	0010	0011
3	67.5-90	0011	0010
4	90-112.5	0100	0110
5	112.5-135	0101	0111
6	135-157.5	0110	0101
7	157.5-180	0111	0100
8	180-202.5	1000	1100
9	202.5-225	1001	1101
10	225-247.5	1010	1111
11	247.5-270	1011	1110
12	270-292.5	1100	1010
13	292.5-315	1101	1011
14	315-337.5	1110	1001
15	337.5-360	1111	1000

## 4-Bit Binary Code Absolute Encoder disk track pattern

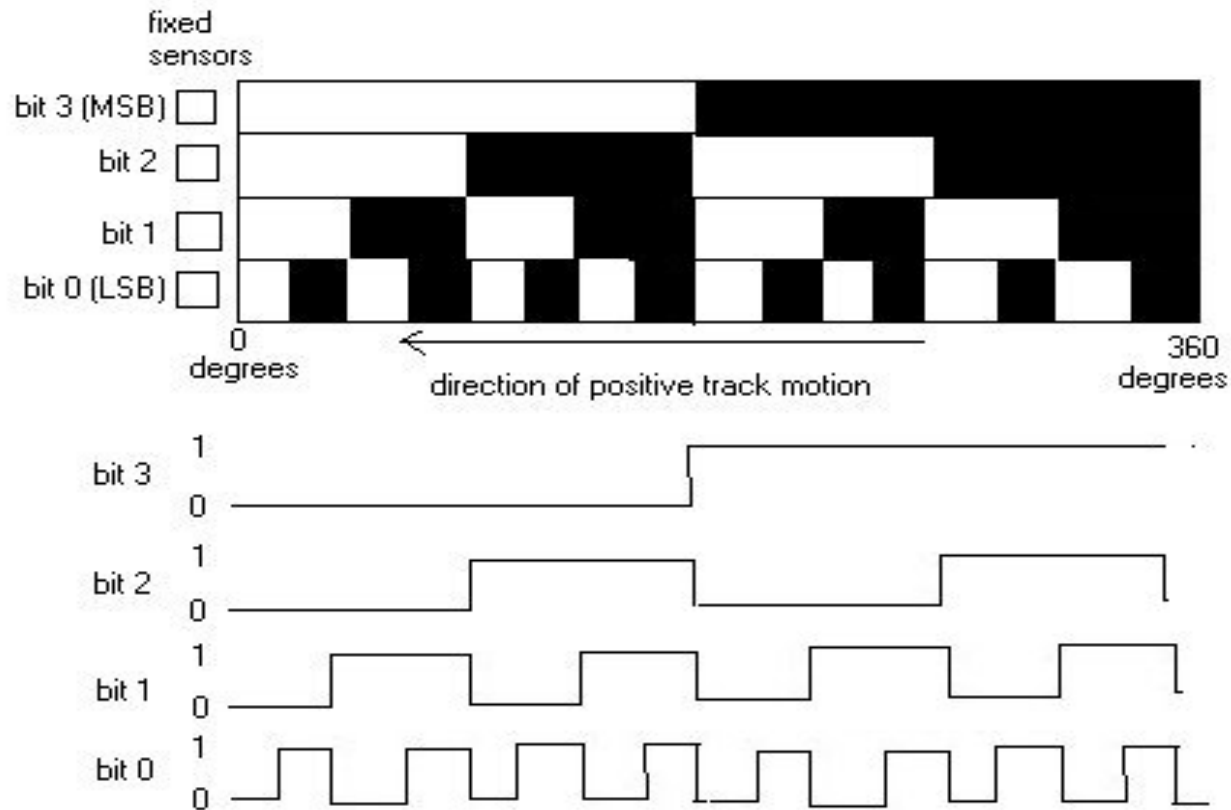


Fig 3 4-Bit binary code absolute encoder disk track patterns



## 4-Bit Grey Code Absolute Encoder disk track pattern

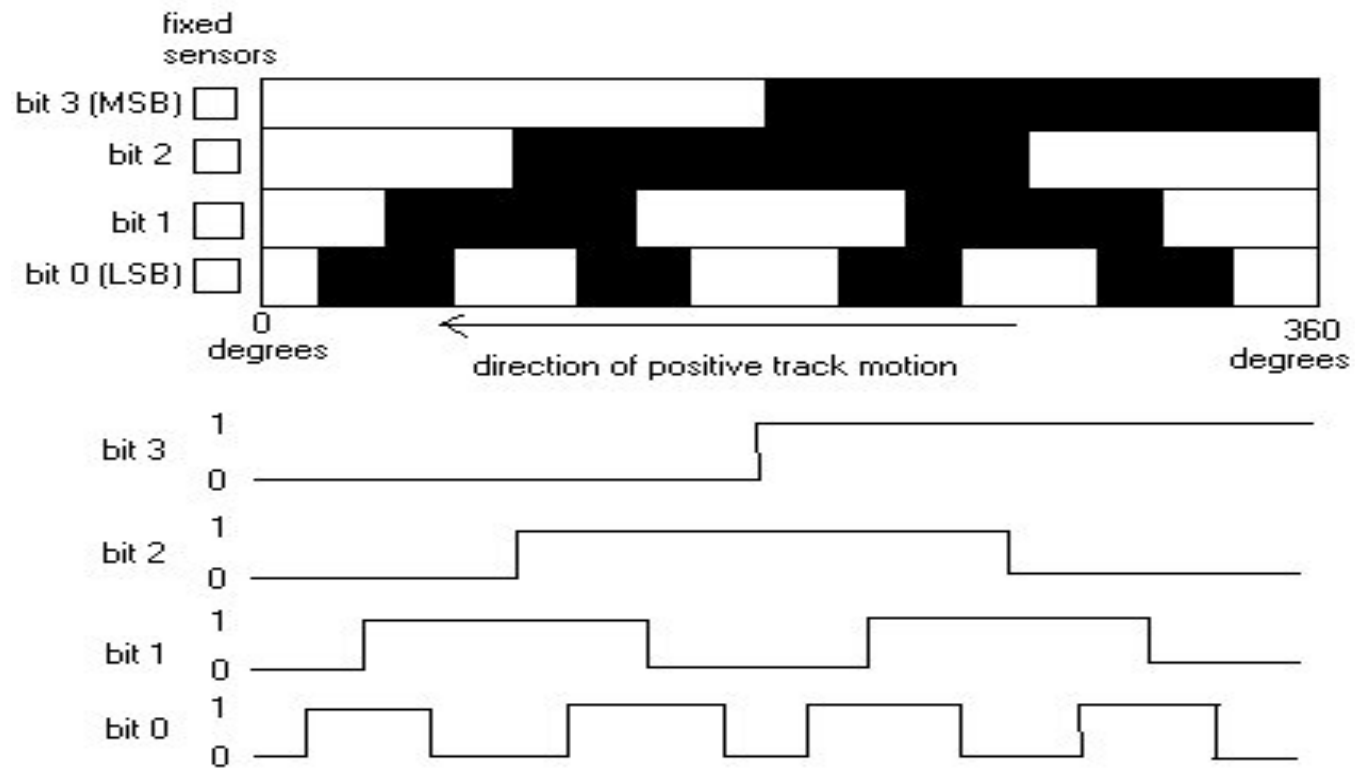


Fig 2. 4-Bit gray code absolute encoder disk track patterns

# Quiz

- For an absolute encoder write down the gray code for the disk of three tracks. Calculate the resolution of the encoder and also draw the gray region on disk. Binary code for three bits data are given below.

Binary  
000  
001  
010  
011  
100  
101  
110  
111