ENGI-1500 Physics -2

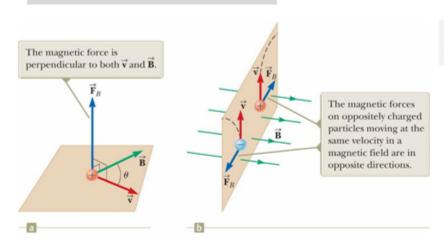
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Winter 2023



Reminder of the previous week

Particle in a magnetic field



$$\vec{\mathbf{F}}_{B} = q\vec{\mathbf{v}} \times \vec{\mathbf{B}}$$

$$1 T = 1 \frac{N}{C \cdot m/s}$$

$$1 T = 1 \frac{N}{A \cdot m}$$

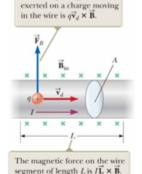
$$1 T = 10^4 G$$

Magnetic force on current

$$\vec{\mathbf{F}}_{_{\mathcal{B}}} = I\vec{\mathbf{L}} \times \vec{\mathbf{B}}$$

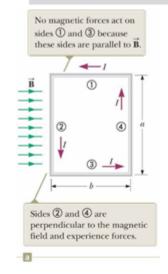
$$d\vec{\mathbf{F}}_B = Id\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$

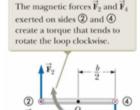
$$\vec{\mathbf{F}}_{B} = I \int_{a}^{b} d\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$

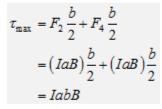


The average magnetic force

Torque on a current loop







Right Hand Rule

(2) Your upright thumb shows the direction of the magnetic force on a positive particle.

(1) Point your fingers in the direction of \vec{v} and then curl them toward the direction of \vec{B} .

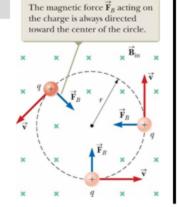
Motion of a charged particle

$$\sum F = F_B = m\alpha$$

$$F_B = qvB = \frac{mv^2}{r}$$

$$r = \frac{mv}{qB}$$
 $\omega = \frac{v}{r} = \frac{qB}{m}$

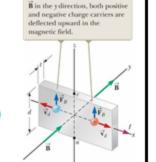
$$T = \frac{2\pi r}{v} = \frac{2\pi}{\omega} = \frac{2\pi n}{qB}$$



The Hall Effect

$$\Delta V_{\rm H} = \frac{IB}{nqt}$$
$$= \frac{R_{\rm H}IB}{t}$$

$$R_H = \frac{1}{nq}$$
 (Hall coefficient)



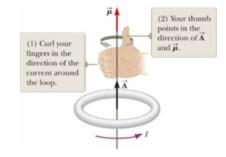
When I is in the x direction and



$$\vec{\mu}\equiv I\vec{\mathbf{A}}$$

$$\vec{\mu}_{\text{coil}} = NI\vec{\mathbf{A}}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$



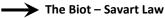
Week 6 / Class 6

Sources of Magnetic Fields (Ch. 29) Review

Outline of Week 6 / Class 6

- Reminder of the previous week
- Sources of Magnetic Fields (Ch. 29)
 - The Biot Savart Law
 - The Magnetic Force Between Two Parallel Conductors
 - Ampère's Law
 - The Magnetic Field of a Solenoid
 - Gauss's Law in Magnetism
 - Magnetism in Matter [Reading from Textbook]
- Review
- Examples
- Next week's topic

Sources of Magnetic Fields (Ch. 29)



The Magnetic Force Between Two Parallel Conductors
Ampère's Law
The Magnetic Field of a Solenoid
Gauss's Law in Magnetism
Magnetism in Matter [reading from textbook]

Faraday's Law (Ch. 30)
Faraday's Law of Induction

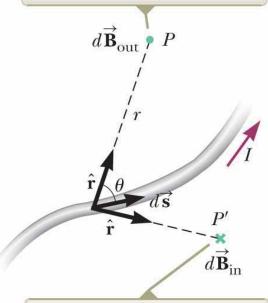
Sources of Magnetic Fields (Ch. 29)

The Biot – Savart Law

The Biot – Savart Law

- Hans Christian Ørsted discovered that electric currents create magnetic fields (1819 1820).
 - Oersted found that electric current in a wire changed the orientation of a nearby compass needle.
- **Jean-Baptiste Biot** and **Félix Savart** performed quantitative experiments on the force exerted by an electric current on a nearby magnet.
- Biot and Savart arrived at a mathematical expression that gives the magnetic field in terms of the current that produces the field.
- Findings of their experiments were as follows (for magnetic field dB at point P associated with a length element of ds on a wire carrying steady current I):
 - dB is perpendicular to both ds (points in the direction of the current) and the unit vector
 r (directed from ds toward P).
 - The magnitude of $d\mathbf{B}$ is inversely proportional to \mathbf{r}^2 ($\mathbf{r} = \mathbf{distance}$ from $d\mathbf{s}$ to \mathbf{P}).
 - The magnitude of dB is proportional to the current I and the magnitude ds of length element ds.
 - The magnitude of $d\mathbf{B}$ is proportional to $sin\mathbf{\Theta}$ (Θ = angle between vectors $d\mathbf{s}$ and \mathbf{r})

The direction of the field is out of the page at *P*.



The direction of the field is into the page at P'.

The Biot – Savart Law

The experimental observations are summarized in the mathematical expression known today
as the Biot-Savart law (for a small derivative element of ds):

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

μ₀ is a constant called the permeability of free space;

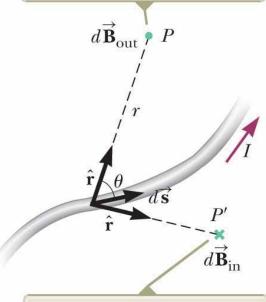
$$\mu_0 = 4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}$$

 To find the total magnetic field B created at some point by a current of finite size, we must sum up the contributions from all current elements Ids that make up the current. That is, we must take the integral of the expression over the entire current distribution;

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

The integrand is a cross product and therefore a vector quantity.

The direction of the field is out of the page at *P*.



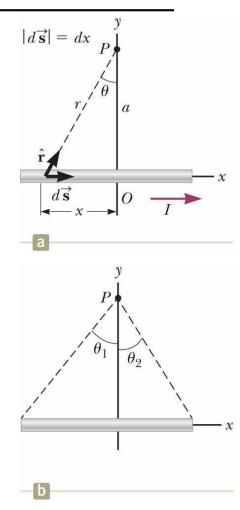
The direction of the field is into the page at P'.

Example 29.1

Consider a thin, straight wire of finite length carrying a constant current *I* and placed along the *x axis* as shown in the figures. Determine the *magnitude and direction of the magnetic field* at point *P* due to this current.

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{i}}}{r^2}$$

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$



Example 29.1

Consider a thin, straight wire of finite length carrying a constant current *I* and placed along the *x axis* as shown in the figures. Determine the *magnitude and direction of the magnetic field* at point *P* due to this current.

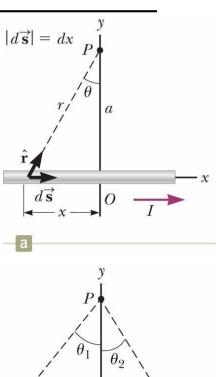
Solution

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{i}}}{r^2}$$

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Conceptualize

Using the Biot – Savart law, we can find the magnetic field contribution from a small element of current and then integrate over the current distribution.



Example 29.1

Consider a thin, straight wire of finite length carrying a constant current I and placed along the x axis as shown in the figures. Determine the *magnitude and direction of the magnetic field* at point *P* due to this current.

Solution

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{i}}}{r^2}$$

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2} \qquad \vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Analyze

Let's use the length element ds in the figure. The direction of the magnetic field at point P is out of the page.

Let's evaluate the cross product in the Biot –

Savart law:

Substituting into d**B** equation:

r in terms of **\theta**:

x in terms of $\boldsymbol{\theta}$:

$$d\vec{s} \times \hat{\mathbf{r}} = |d\vec{s} \times \hat{\mathbf{r}}| \hat{\mathbf{k}} = \left[dx \sin\left(\frac{\pi}{2} - \theta\right) \right] \hat{\mathbf{k}} = (dx \cos\theta) \hat{\mathbf{k}}$$

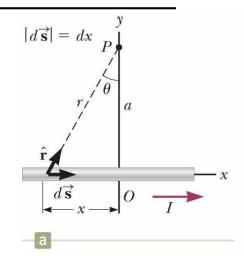
(1)
$$d\vec{\mathbf{B}} = (dB)\hat{\mathbf{k}} = \frac{\mu_0 I}{4\pi} \frac{dx \cos \theta}{r^2} \hat{\mathbf{k}}$$

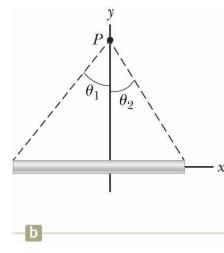
We need to express dx and r in terms of θ

$$(2) \quad r = \frac{a}{\cos \theta}$$

$$x = -a \tan \theta$$

Negative sign is necessary because ds is located at a negative value of x.





Source: Serway, Raymond A., and John W. Jewett. scientists and engineers. 10th Edition. Cengage learning, 2018.

Example 29.1

Consider a thin, straight wire of finite length carrying a constant current I and placed along the x axis as shown in the figures. Determine the *magnitude and direction of the magnetic field* at point *P* due to this current.

Solution

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \vec{\mathbf{n}}}{r^2}$$

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2} \qquad \vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Analyze

Let's use the length element $d\mathbf{s}$ in the figure. The direction of the magnetic fi $d\mathbf{B} = (dB)\hat{\mathbf{k}} = \frac{\mu_0 I}{4\pi} \frac{dx \cos \theta}{r^2} \hat{\mathbf{k}}$

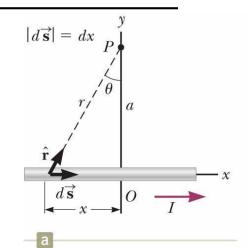
Now we can write
$$d\mathbf{x}$$
 in terms of $\boldsymbol{\theta}$:

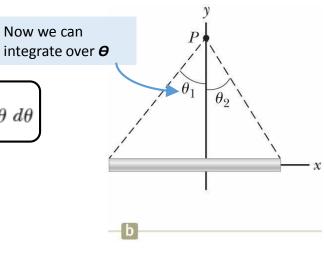
Integrating over
$$\boldsymbol{\Theta}$$
 (from Θ_1 to Θ_2):

$$x = -a \tan \theta$$
(3) $dx = -a \sec^2 \theta \ d\theta = -\frac{a \ d\theta}{\cos^2 \theta}$

(4)
$$dB = -\frac{\mu_0 I}{4\pi} \left(\frac{a d\theta}{\cos^2 \theta}\right) \left(\frac{\cos^2 \theta}{a^2}\right) \cos \theta = \boxed{-\frac{\mu_0 I}{4\pi a} \cos \theta d\theta}$$

$$B = -\frac{\mu_0 I}{4\pi a} \int_{\theta_1}^{\theta_2} \cos \theta \ d\theta = \frac{\mu_0 I}{4\pi a} (\sin \theta_1 - \sin \theta_2)$$





Example 29.1

Consider a thin, straight wire of finite length carrying a constant current I and placed along the x axis as shown in the figures. Determine the *magnitude and direction of the magnetic field* at point *P* due to this current.

Solution

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \vec{\mathbf{n}}}{r^2}$$

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2} \qquad \vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

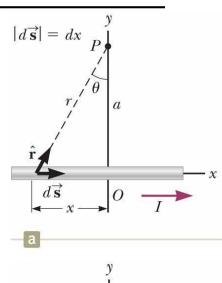
Finalize

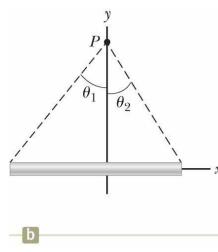
We can use the final result to find the magnetic field of an infinitely long, straight wire by taking the angle Θ to the limits: $\Theta_1 = \pi/2$ (for x=-\infty) and $\Theta_1 = -\pi/2$ (for x=+\infty).

$$\frac{\mu_0 I}{4\pi a} \left(\sin \theta_1 - \sin \theta_2 \right)$$

$$(\sin\Theta_1 - \sin\Theta_2) = [\sin(\pi/2) - \sin(-\pi/2)] = 2$$

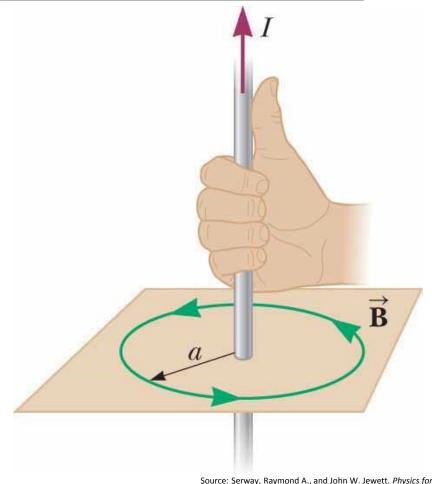
$$B = \frac{\mu_0 I}{2\pi a}$$





Right Hand Rule

- The magnetic field surrounding a long ,straight, current-carrying wire can be found with the *right hand rule*:
 - As shown in the figure, circle the wire with the right hand by making sure the thumb is positioned along the direction of the current.
 - The fingers wrap in the direction of the magnetic field.
- The Magnetic field line circles are concentric with the wire and they lie in planes perpendicular to the wire
- The magnitude of B is constant on any circle of radius a
- The magnetic field lines form a closed loop.



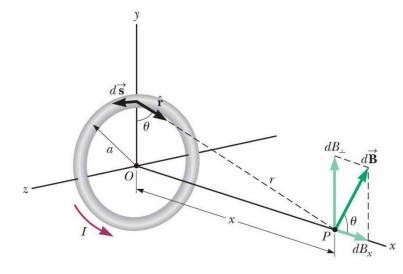
<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Example 29.3

Consider a circular wire loop of radius **a** located in the **yz plane** and carrying a steady current **I** as in the figure. Calculate the magnetic field at an axial point **P** a distance **x** from the center of the loop.

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$



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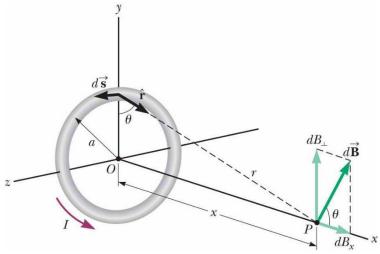
$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Solution

Every ds element is perpendicular to the vector $\hat{\mathbf{r}}$ at the location of the element. Therefore, $ds \times \hat{\mathbf{r}} = (ds)(1)(\sin 90^\circ) = ds$

All length elements around the loop are at the same distance r from P: $r^2 = a^2 + x^2$



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$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Solution

Use Equation 30.1 to find the magnitude of $d\vec{B}$ due to the current in any length element $d\vec{s}$:

Find the *x* component of the field element:

Integrate over the entire loop:

From the geometry, evaluate $\cos \theta$:

Substitute this expression for $\cos \theta$ into the integral and note that *x* and *a* are both constant:

Integrate around the loop:

$$dB = \frac{\mu_0 I}{4\pi} \frac{|d\vec{s} \times \hat{\mathbf{r}}|}{r^2} = \frac{\mu_0 I}{4\pi} \frac{ds}{(a^2 + x^2)}$$

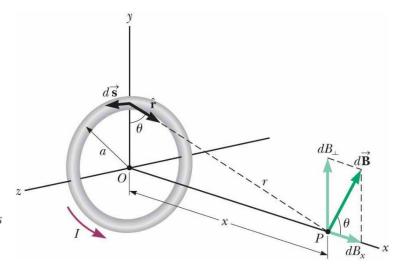
$$dB_x = \frac{\mu_0 I}{4\pi} \frac{ds}{(a^2 + x^2)} \cos \theta$$

$$B_x = \oint dB_x = \frac{\mu_0 I}{4\pi} \oint \frac{ds \cos \theta}{a^2 + x^2}$$

$$\cos \theta = \frac{a}{(a^2 + x^2)^{1/2}}$$

$$B_x = \frac{\mu_0 I}{4\pi} \oint \frac{ds}{a^2 + x^2} \left[\frac{a}{(a^2 + x^2)^{1/2}} \right] = \frac{\mu_0 I}{4\pi} \frac{a}{(a^2 + x^2)^{3/2}} \oint ds$$

$$B_{x} = \frac{\mu_{0}I}{4\pi} \frac{a}{(a^{2} + x^{2})^{3/2}} (2\pi a) = \frac{\mu_{0}Ia^{2}}{2(a^{2} + x^{2})^{3/2}}$$



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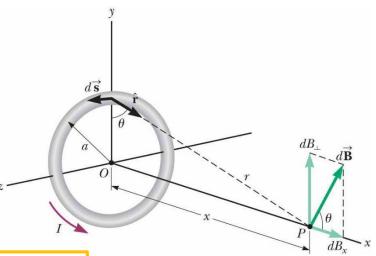
$$dB_x = \frac{\mu_0 I}{4\pi} \frac{ds}{(a^2 + x^2)} \cos \theta$$

$$B_{x} = \oint dB_{x} = \frac{\mu_{0}I}{4\pi} \oint \frac{ds \cos \theta}{a^{2} + x^{2}}$$

$$\cos \theta = \frac{a}{(a^2 + x^2)^{1/2}}$$

$$B_{x} = \frac{\mu_{0}I}{4\pi} \oint \frac{ds}{a^{2} + x^{2}} \left[\frac{a}{(a^{2} + x^{2})^{1/2}} \right] = \frac{\mu_{0}I}{4\pi} \frac{a}{(a^{2} + x^{2})^{3/2}} \oint ds$$

$$B_{x} = \frac{\mu_{0}I}{4\pi} \frac{a}{(a^{2} + x^{2})^{3/2}} (2\pi a) = \frac{\mu_{0}Ia^{2}}{2(a^{2} + x^{2})^{3/2}} \longrightarrow B = \frac{\mu_{0}I}{2a} \text{ (at } x = 0)$$



Sources of Magnetic Fields (Ch. 29)

The Biot – Savart Law



The Magnetic Force Between Two Parallel Conductors

Ampère's Law

The Magnetic Field of a Solenoid
Gauss's Law in Magnetism
Magnetism in Matter [reading from textbook]

Faraday's Law (Ch. 30)
Faraday's Law of Induction

Sources of Magnetic Fields (Ch. 29)

The Magnetic Force Between Two Parallel Conductors

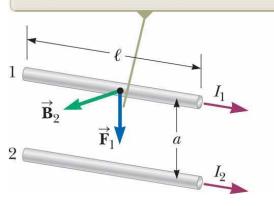
The Magnetic Force Between Two Parallel Conductors

- Consider two long, straight, parallel wires separated by a distance a and carrying currents l_1 and l_2 in the same direction.
- Let's determine the force exerted on one wire due to the magnetic field set up by the other wire.
- Wire 2, which carries a current I₂ and is identified arbitrarily as the source wire, creates a magnetic field B₂ at the location of wire 1, the test wire.
 - The magnitude of this magnetic field is the same at all points on wire 1.
 - The direction of B₂ is perpendicular to wire 1 as shown in the figure.
- The magnetic force on a length *I*, of wire 1 is:

$$\vec{\mathbf{F}}_1 = I_1 \vec{\boldsymbol{\ell}} \times \vec{\mathbf{B}}_2$$
 — Is perpendicular to B_2 — $F_1 = I_1 \ell B_2$

$$F_1 = I_1 \ell B_2 = I_1 \ell \left(\frac{\mu_0 I_2}{2\pi a} \right) = \frac{\mu_0 I_1 I_2}{2\pi a} \ell$$

The field $\vec{\mathbf{B}}_2$ due to the current in wire 2 exerts a magnetic force of magnitude $F_1 = I_1 \ell B_2$ on wire 1.

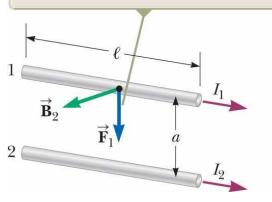


The Magnetic Force Between Two Parallel Conductors

- When the field set up at wire 2 by wire 1 is calculated, the force F_2 acting on wire 2 is found to be equal in magnitude and opposite in direction to F_1 .
- When the currents are in opposite directions (that is, when one of the currents is reversed in the figure), the forces are reversed and the wires repel each other.
- Hence, parallel conductors carrying currents in the same direction attract each other, and parallel conductors carrying currents in opposite directions repel each other.
- Because the magnitudes of the forces are the same on both wires, we denote the magnitude of the magnetic force between the wires as simply F_B .
- This force can be expressed in terms of per unit length as follows:

$$F_1 = I_1 \ell B_2 = I_1 \ell \left(\frac{\mu_0 I_2}{2\pi a} \right) = \frac{\mu_0 I_1 I_2}{2\pi a} \ell \longrightarrow \frac{F_B}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi a}$$

The field $\vec{\mathbf{B}}_2$ due to the current in wire 2 exerts a magnetic force of magnitude $F_1 = I_1 \ell B_2$ on wire 1.



The Magnetic Force Between Two Parallel Conductors

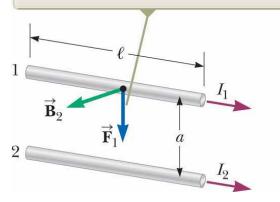
Definition of the unit Ampere

- When the magnitude of the force per unit length between two long, parallel wires that carry identical currents and are separated by 1m is $2x10^{-7}$ N/m, the current in each wire is defined to be 1A.
- The value $2x10^{-7}$ N/m is obtained from the magnetic force equation with $I_1 = I_2 = 1A$ and a = 1m.

$$\frac{F_{\rm B}}{\ell} = \frac{\mu_{\rm 0}I_{\rm 1}I_{\rm 2}}{2\pi a}$$

- Because this definition is based on a force, a mechanical measurement can be used to standardize the *ampere*.
- The National Institute of Standards and Technology uses an instrument called a *current balance* for primary current measurements. The results are then used to standardize other, more conventional instruments such as ammeters.

The field $\vec{\mathbf{B}}_2$ due to the current in wire 2 exerts a magnetic force of magnitude $F_1 = I_1 \ell B_2$ on wire 1.



Sources of Magnetic Fields (Ch. 29)

The Biot – Savart Law

The Magnetic Force Between Two Parallel Conductors



The Magnetic Field of a Solenoid
Gauss's Law in Magnetism
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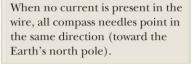
Faraday's Law (Ch. 30)
Faraday's Law of Induction

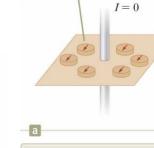
Sources of Magnetic Fields (Ch. 29)

Ampere's Law

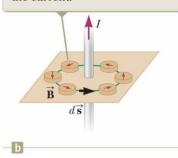
- Earlier we discussed that the direction of the magnetic field produced by the current in the wire is consistent with the right-hand rule.
 - The magnetic field line has no beginning and no end. Rather, it forms a closed loop around the current carrying wire.
- Now let's evaluate the product $\overrightarrow{B} \cdot d\overrightarrow{s}$ for a small length element $d\overrightarrow{s}$ on the circular path defined by the compass needles and sum the products for all elements over the closed circular path.
 - Along this path, the vectors $d\vec{s}$ and \vec{B} are parallel at each point, so $\vec{B} \cdot d\vec{S} = Bds$
 - The magnitude of \overrightarrow{B} is constant on this circle

$$\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \iint ds = \frac{\mu_0 I}{2\pi r} (2\pi r) = \mu_0 I$$





When the wire carries a strong current, the compass needles deflect in a direction tangent to the circle, which is the direction of the magnetic field created by the current.



- Earlier we discussed that the direction of the magnetic field produced by the current in the wire is consistent with the right-hand rule.
 - The magnetic field line has no beginning and no end. Rather, it forms a closed loop around the current carrying wire.
- Now let's evaluate the product $\overrightarrow{B} \cdot d\overrightarrow{s}$ for a small length element $d\overrightarrow{s}$ on the circular path defined by the compass needles and sum the products for all elements over the closed circular path.
 - Along this path, the vectors \overrightarrow{ds} and \overrightarrow{B} are parallel at each point, so $\overrightarrow{B} \cdot \overrightarrow{dS} = Bds$
 - The magnitude of \overrightarrow{B} is constant on this circle

$$\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \iint ds = \frac{\mu_0 I}{2\pi r} (2\pi r) = \mu_0 I$$

The line integral of $\vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$ around any closed path equals $\mu_0 I$, where I is the total steady current passing through any surface bounded by the closed path:

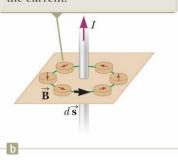
$$\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = \mu_0 I$$





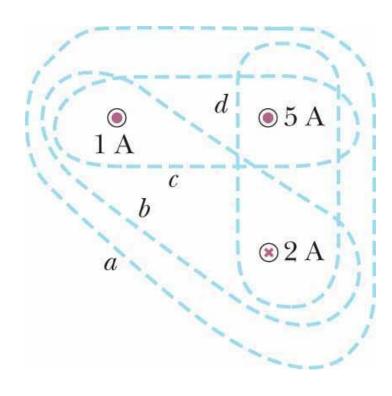
When the wire carries a strong current, the compass needles deflect in a direction tangent to the circle, which is the direction of the magnetic field created by the current.

When no current is present in the



Quick Quiz 29.3

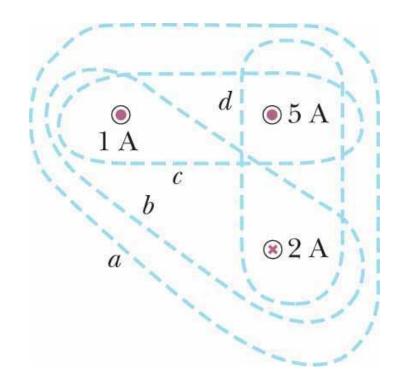
Rank the magnitudes of $\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$ for the closed paths a through d in the figure from greatest to least.



Quick Quiz 29.3

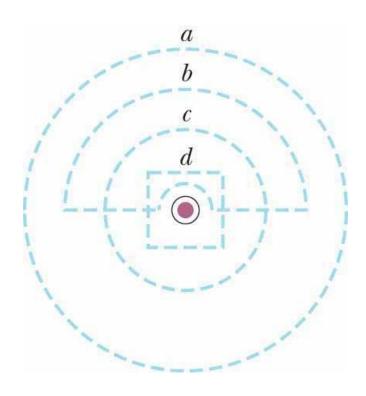
Rank the magnitudes of $\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$ for the closed paths a through d in the figure from greatest to least.

Solution



Quick Quiz 29.4

Rank the magnitudes of $\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$ for the closed paths a through d in the figure from greatest to least.

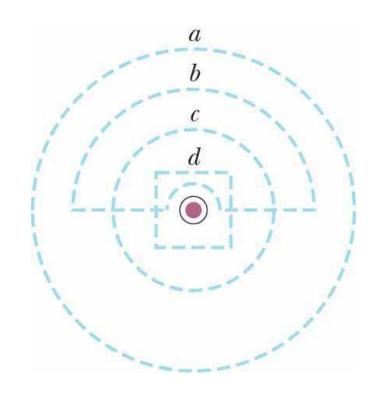


Quick Quiz 29.4

Rank the magnitudes of $\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}}$ for the closed paths a through d in the figure from greatest to least.

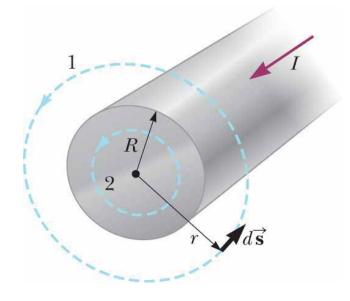
Solution

$$a = c = d > b = 0$$



Example 29.5

A long, straight wire of radius R carries a steady current I that is uniformly distributed through the cross section of the wire. Calculate the magnetic field a distance r from the center of the wire in the regions $r \ge R$ and r < R.



Example 29.5

A long, straight wire of radius R carries a steady current I that is uniformly distributed through the cross section of the wire. Calculate the magnetic field a distance r from the center of the wire in the regions $r \ge R$ and r < R.

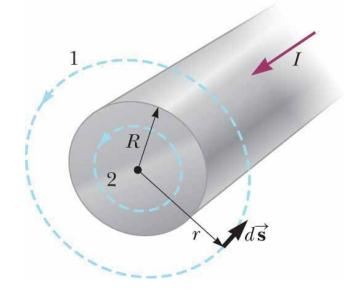
Solution

Conceptualize

Study the figure to understand the structure of the wire and the current in the wire. The current creates magnetic fields everywhere, both inside and outside the wire. Based on our discussions about long, straight wires, we expect the magnetic field lines to be circles centered on the central axis of the wire.

Categorize

Because the wire has a high degree of symmetry, we categorize this example as an Ampère's law problem. For the $r \ge R$ case, we should arrive at the same result as was obtained in the previous example, where we applied the Biot–Savart law to the same situation.



Example 29.5

A long, straight wire of radius R carries a steady current I that is uniformly distributed through the cross section of the wire. Calculate the magnetic field a distance r from the center of the wire in the regions $r \ge R$ and r < R.

Solution

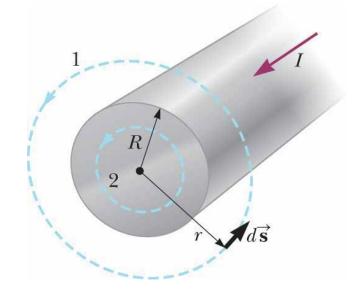
For the exterior of the wire

For the magnetic field exterior to the wire, let us choose for our path of integration *circle 1* in the figure. From symmetry, **B** must be constant in magnitude and parallel to **ds** at every point on this circle.

The total current passing through the plane of the circle is *I* and we can apply the Ampère's law:

$$\mathbf{\vec{D}} \mathbf{\vec{B}} \cdot d\mathbf{\vec{s}} = B \mathbf{\vec{D}} ds = B(2\pi r) = \mu_0 I$$

$$B = \boxed{\frac{\mu_0 I}{2\pi r}} \quad \text{(for } r \ge R\text{)}$$



Example 29.5

A long, straight wire of radius R carries a steady current I that is uniformly distributed through the cross section of the wire. Calculate the magnetic field a distance r from the center of the wire in the regions $r \ge R$ and r < R.

Solution

For the interior of the wire

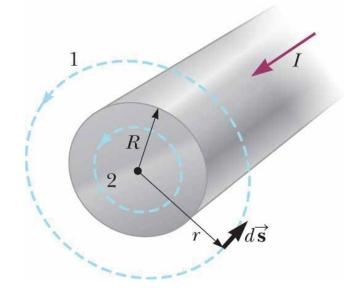
Now for the interior of the wire (r<R), the current I' passing through the plane of circle 2 is less than the total current I. Because the current is uniformly distributed across the cross section of the wire, the current density J is constant in the interior of the wire. Therefore, for any area A of the interior perpendicular to the length of the wire, the current passing through that area is I' = JA

$$\frac{I'}{I} = \frac{JA'}{JA} = \frac{\pi r^2}{\pi R^2}$$

$$\Rightarrow I' = \frac{r^2}{R^2}I$$

Now we can apply Ampere's law to circle 2:

$$\mathbf{\vec{J}} \mathbf{\vec{B}} \cdot d\mathbf{\vec{s}} = B(2\pi r) = \mu_0 I' = \mu_0 \left(\frac{r^2}{R^2} I \right) \longrightarrow B = \boxed{\left(\frac{\mu_0 I}{2\pi R^2} \right) r} \quad \text{(for } r < R)$$



Example 29.5

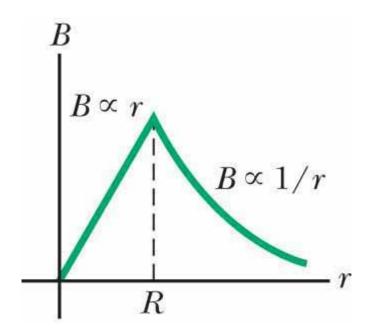
A long, straight wire of radius R carries a steady current I that is uniformly distributed through the cross section of the wire. Calculate the magnetic field a distance r from the center of the wire in the regions $r \ge R$ and r < R.

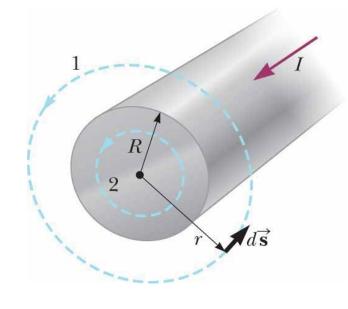
Solution

$$B = \frac{\mu_0 I}{2\pi r} \quad (\text{for } r \ge R)$$

$$B = \left(\frac{\mu_0 I}{2\pi R^2}\right) r \quad (\text{for } r < R)$$

$$B = \frac{\mu_0 I}{2\pi R}$$





Sources of Magnetic Fields (Ch. 29)

The Biot - Savart Law

The Magnetic Force Between Two Parallel Conductors Ampère's Law

The Magnetic Field of a Solenoid

Gauss's Law in Magnetism

Magnetism in Matter [reading from textbook]

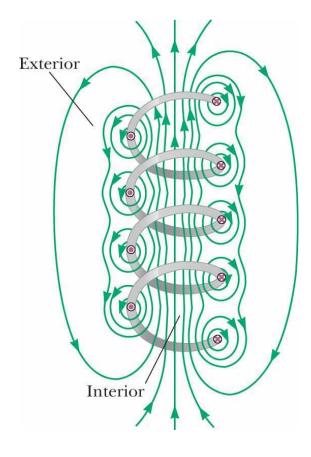
Faraday's Law (Ch. 30)
Faraday's Law of Induction

Sources of Magnetic Fields (Ch. 29)

The Magnetic Field of a Solenoid

The Magnetic Field of a Solenoid

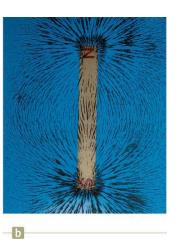
- A solenoid is a long wire wound in the form of a helix.
- With this configuration, a *reasonably uniform magnetic field* can be produced in the space surrounded by the turns of wire—which we shall call the interior of the solenoid—when the solenoid carries a current.
- When the turns are closely spaced →
 - Each loop can be approximated as circular loop
 - Net magnetic field = vector sum of fields resulting from all turns
- Figure shows the magnetic field lines surrounding a loosely wound solenoid

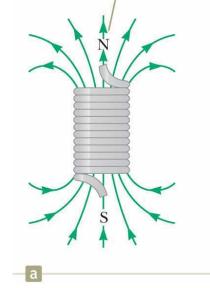


The Magnetic Field of a Solenoid

- If turns are closely spaced and the solenoid is of finite length → the external magnetic field is similar to that of a bar magnet
- As length of the solenoid increases →
 - Interior field becomes more uniform
 - Exterior field becomes weaker
- Ideal solenoid:
 - · when the turns are closely spaced and
 - The length is much greater than the radius of turns

The magnetic field lines resemble those of a bar magnet, meaning that the solenoid effectively has north and south poles.





The Magnetic Field of a Solenoid

- Let's try to find the magnetic field of a solenoid.
- Let's focus on the external first.
- Consider the cross section of a solenoid in the figure. Let's take the amperian loop (loop 1) perpendicular to the page, surrounding the ideal solenoid.
 - This loop encloses a small current as the charges in the wire move coil by coil along the length of the solenoid.
 - Therefore, there is a nonzero magnetic field outside the solenoid but it's weak.
 - For an ideal solenoid, this weak field is the only field external to the solenoid.

Ampère's law applied to the rectangular dashed path can be used to calculate the magnitude of the interior field. Loop 2 Loop 1 Ampère's law applied to the circular path whose plane is perpendicular to the page can be used to show that there is a weak field outside the solenoid.

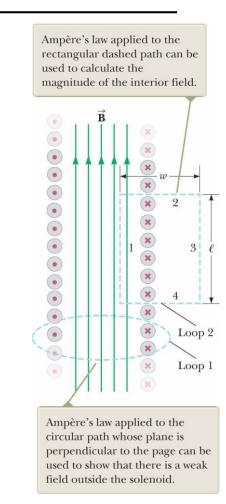
Source: Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

The Magnetic Field of a Solenoid

- Now let's focus on the interior magnetic field.
- We can use Ampère's law to obtain a quantitative expression for the interior magnetic field in an ideal solenoid. Because the solenoid is ideal, B in the interior space is uniform and parallel to the axis and the magnetic field lines in the exterior space form circles around the solenoid.
- Consider the rectangular path (loop 2) of length \(\ell\) and width \(\omega\) shown in the figure.
- Let's apply Ampère's law to this path by evaluating the integral of $\overrightarrow{B} \cdot d\overrightarrow{s}$ over each side of the rectangle:

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = \int \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \int ds = B\ell$$
path 1

Can we see that the contributions from path 2, 3 and 4 are all zero?



<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

The Magnetic Field of a Solenoid

$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = \int \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \int ds = B\ell$$
path 1

 The right side of Ampère's law involves the total current I through the area bounded by the path of integration. In this case, the total current through the rectangular path equals the current through each turn multiplied by the number of turns. If N is the number of turns in the length, the total current through the rectangle is NI:

$$\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B\ell = \mu_0 NI$$

$$B = \mu_0 \frac{N}{\ell} I = \mu_0 nI$$

where $n = N/\ell$, is the number of turns per unit length.

Ampère's law applied to the rectangular dashed path can be used to calculate the magnitude of the interior field. Loop 2 Ampère's law applied to the circular path whose plane is perpendicular to the page can be used to show that there is a weak field outside the solenoid.

<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Sources of Magnetic Fields (Ch. 29)

The Biot – Savart Law

The Magnetic Force Between Two Parallel Conductors Ampère's Law

The Magnetic Field of a Solenoid



Magnetism in Matter [reading from textbook]

Faraday's Law (Ch. 30)
Faraday's Law of Induction

Sources of Magnetic Fields (Ch. 29)

Gauss's Law in Magnetism

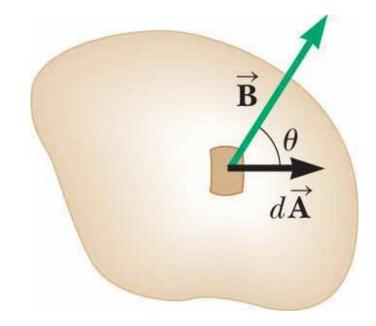
Gauss's Law in Magnetism

- We can define the magnetic flux similar to the definition of electric flux earlier.
- Consider an element of area dA on an arbitrarily shaped surface (figure)
- If the magnetic field at this element is **B**:
 - Magnetic flux through this element is B-dA
 - dA = vector perpendicular to the surface
- Total magnetic flux **\$\phi B\$** through the surface is:

$$\Phi_{B} \equiv \int \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}}$$

- Special case: plane of area A in a uniform field B that makes an angle O with dA
 - Magnetic flux through plane is:

$$\Phi_{\scriptscriptstyle B} = BA\cos\theta$$

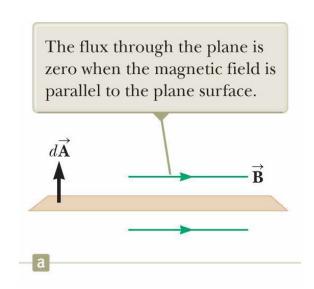


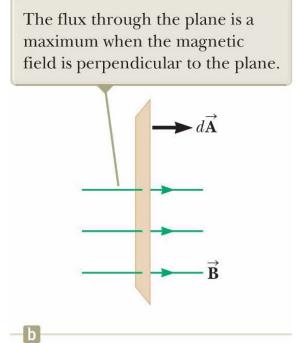
Source: Serway, Raymond A., and John W. Jewett. Physics for scientists and engineers. 10th Edition. Cengage learning, 2018.

Gauss's Law in Magnetism

- If the magnetic field is parallel to the plane (figure (a)):
 - Θ = 90°
 - Dot product is zero → the flux through the plane = 0
- If the field is perpendicular to the plane (figure (b)):
 - $\Theta = 0^{\circ}$
 - Dot product is max → the flux through the plane = BA (the maximum value)
- Unit of magnetic flux is T·m² → defined as weber (Wb)

$$1 \text{ Wb} = 1 \text{ T} \cdot \text{m}^2$$



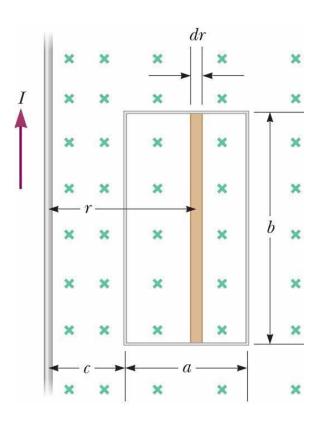


Source: Serway, Raymond A., and John W. Jewett. Physics for scientists and engineers. 10th Edition. Cengage learning, 2018.

Magnetic Flux Through a Rectangular Loop

Example 29.7

A rectangular loop of width a and length b is located near a long wire carrying a current I. The distance between the wire and the closest side of the loop is c. The wire is parallel to the long side of the loop. Find the **total magnetic flux** through the loop due to the current in the wire.



Source: Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Magnetic Flux Through a Rectangular Loop

Example 29.7

A rectangular loop of width **a** and length **b** is located near a long wire carrying a current **I**. The distance between the wire and the closest side of the loop is **c**. The wire is parallel to the long side of the loop. Find the **total magnetic flux** through the loop due to the current in the wire.

Solution

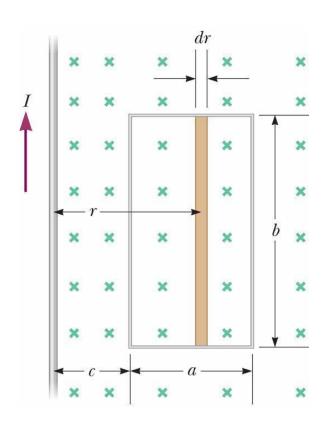
$B = \boxed{\frac{\mu_0 I}{2\pi r}}$

Conceptualize

The magnetic field lines due to the wire will be circles, many of which will pass through the rectangular loop. We know that the magnitude of the magnetic field is a function of distance r from a long wire. Therefore, the magnetic field varies over the area of the rectangular loop.

Categorize

Because the magnetic field varies over the area of the loop, we must *integrate* over this area to find the total flux. That identifies this as an analysis problem.



Source: Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Magnetic Flux Through a Rectangular Loop

Example 29.7

A rectangular loop of width **a** and length **b** is located near a long wire carrying a current **I**. The distance between the wire and the closest side of the loop is **c**. The wire is parallel to the long side of the loop. Find the **total magnetic flux** through the loop due to the current in the wire.

Solution

Noting that **B** is parallel to **dA** at any point within the loop, we can find the magnetic flux through the rectangular area:

We can now express the area element (the rectangular strip in the figure) as a $d\mathbf{A} = b d\mathbf{r}$:

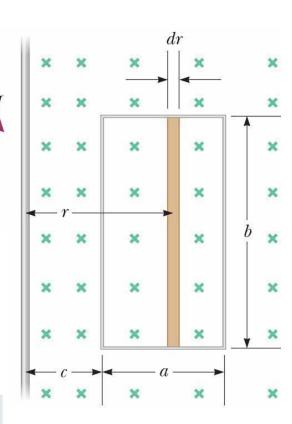
Integrating from r=c to r=a+c:

$$\Phi_B = \int \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} = \int B dA = \int \frac{\mu_0 I}{2\pi r} dA$$

$$\Phi_B = \int \frac{\mu_0 I}{2\pi r} b \, dr = \frac{\mu_0 I b}{2\pi} \int \frac{dr}{r}$$

$$\Phi_B = \frac{\mu_0 Ib}{2\pi} \int_c^{a+c} \frac{dr}{r} = \frac{\mu_0 Ib}{2\pi} \ln r \bigg|_c^{a+c}$$

$$= \frac{\mu_0 Ib}{2\pi} \ln \left(\frac{a+c}{c} \right) = \frac{\mu_0 Ib}{2\pi} \ln \left(1 + \frac{a}{c} \right)$$



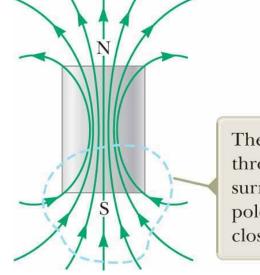
<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Gauss's Law in Magnetism

The net magnetic flux through any closed surface is always zero:

$$\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} = 0$$

- We learned that the magnetic fields are continuous and form closed loops
- Figure: magnetic field lines do not begin or end at any point
- For any closed surface :
 - Number of lines entering surface = number leaving surface
 - Net magnetic flux = 0



The net magnetic flux through a closed surface surrounding one of the poles or any other closed surface is zero.

<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Sources of Magnetic Fields (Ch. 29)

The Biot – Savart Law

The Magnetic Force Between Two Parallel Conductors

Ampère's Law

The Magnetic Field of a Solenoid

Gauss's Law in Magnetism



→ Magnetism in Matter [reading from textbook]

Faraday's Law (Ch. 30)

Faraday's Law of Induction

Sources of Magnetic Fields (Ch. 29)

Magnetism in Matter [Reading from Textbook]

The electron has an angular momentum \vec{L} in one direction and a magnetic moment $\vec{\mu}$ in the opposite direction.

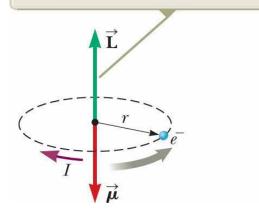


TABLE 29.1 Magnetic Moments of Some Atoms and lons

Atom or Ion	Magnetic Moment (10 ⁻²⁴ J/T)	
H	9.27	
He	0	
Ne	0	
Ce ³⁺	19.8	
Yb^{3+}	37.1	

$$\mu_{\rm B} = \frac{e\hbar}{2m_e} = 9.27 \times 10^{-24} \text{ J/T}$$

<u>Source:</u> Serway, Raymond A., and John W. Jewett. *Physics for scientists and engineers*. 10th Edition. Cengage learning, 2018.

Faraday's Law (Ch. 30)

Faraday's Law of Induction [Covered Previous Week]

Motional EMF

Lenz's Law

The General Form of Faraday's Law

Generators and Motors

Eddy Currents

Review

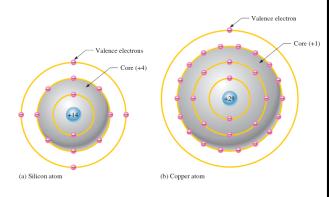
Wk-1 (Ch. 22)

- Electrical charges
 - **Positive** and **Negative** charges
 - Same signs repel each other
 - Opposite signs attract each other



Source: Serway, Raymond A., and John W. Jewett. Physics for scientists and engineers. 10th Edition. Cengage learning, 2018.

• The atom - Bohr model and valence electrons



 Coulomb's Law Electric force between charges

$$F_e = k_e \frac{|q_1||q_2|}{r^2}$$
= 8.9876×10⁹ N·m²

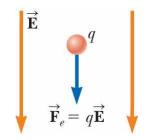
$$k_e = 8.9876 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2$$

$$k_e = \frac{1}{4\pi\varepsilon_0}$$

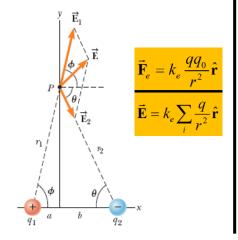
$$\varepsilon_0 = 8.8542 \times 10^{-12} \text{ C}^2/\text{N} \cdot \text{m}^2$$

 $e = 1.60218 \times 10^{-19} \text{ C}$

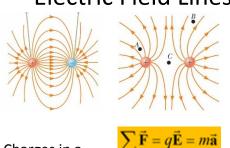
Electric Fields



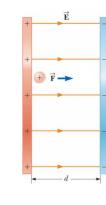
Electric field due to charges



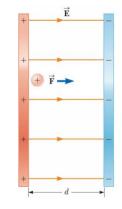
Electric Field Lines



Charges in a **Uniform Field**



Motion of a charged particle in uniform E field



Source: Serway, Raymond A., and John W. Jewett. Physics for scientists and engineers, 10th Edition, Cengage learning, 2018.

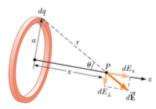
Source: Floyd, Thomas L. Electronic devices:

conventional current version, Pearson, 2012.

Wk-2 (Ch. 23 & Ch. 24)

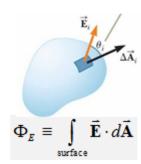
Continuous Charge Distributions

E field of cont. charge dist.



$$\vec{\mathbf{E}} = k_{e} \lim_{\Delta q_{i} \to 0} \sum_{i} \frac{\Delta q_{i}}{r_{i}^{2}} \hat{\mathbf{r}}_{i} = k_{e} \int \frac{dq}{r^{2}} \hat{\mathbf{r}}$$

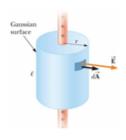
Electric flux



Gauss's Law

$$\Phi_{E} = \mathbf{\vec{E}} \cdot d\mathbf{\vec{A}} = \frac{q_{\text{in}}}{\varepsilon_{0}}$$

- Net flux through any closed surface surrounding a point charge \mathbf{q} is given by q/ϵ_0 .
- Net electric flux through closed surface that surrounds no charge = 0



$$E = \frac{\lambda}{2\pi\epsilon_0 r} = 2k_\epsilon \frac{\lambda}{r}$$

Electric Potential

Electric Potential Diff.

$$\Delta V = -\int_{A}^{B} \vec{\mathbf{E}} \cdot d\vec{\mathbf{s}}$$

$$V_{\rm B} - V_{\rm A} = -\int_{\rm A}^{\rm B} \vec{\mathbf{E}} \cdot d\vec{\mathbf{s}}$$

Electric potential due to a point charge

$$V = k_e \frac{q}{r}$$

E field from E potential

$$E_{x} = -\frac{\partial V}{\partial x}$$

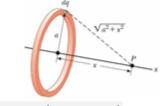
$$E_{y} = -\frac{\partial V}{\partial y}$$

$$E_{z} = -\frac{\partial V}{\partial z}$$

· E potential of cont. charge dist.

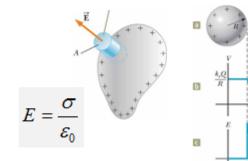
$$V = k_s \int \frac{dq}{r}$$

Prof. Faruk Erkmen, PhD PEng MBA PMP



$$V = \frac{k_{\varepsilon}}{\sqrt{a^2 + x^2}} \int dq = \frac{k_{\varepsilon} Q}{\sqrt{a^2 + x^2}}$$

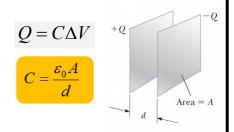
E field of charged conductors



Wk-3 (Ch. 25 & Ch. 26)

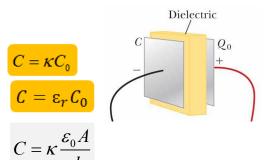
Capacitance and Dielectrics

Definition

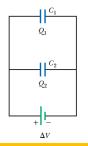


$$U_E = \frac{Q^2}{2C} = \frac{1}{2}Q\Delta V = \frac{1}{2}C(\Delta V)^2$$

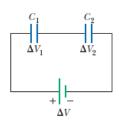
With Dielectric Slab



• Combination of Capacitors



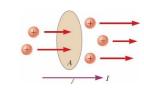
$$C_{\text{eq}} = C_1 + C_2 + C_3 + \cdots$$
 (parallel combination)



$$\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \cdots$$
 (series combination)

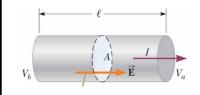
Current and Resistance

Electric current



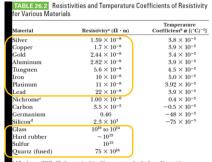
$$I = \frac{dQ}{dt} \qquad 1 \text{ A} = 1 \text{ C/s}$$

Resistance



$$R = \rho \frac{\ell}{A} \quad R \equiv \frac{\Delta V}{I}$$

Resistivities



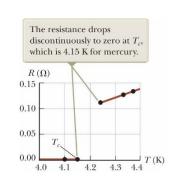
* All values at 20 °C. All elements in this table are assumed to be free of impurities.

* See Section 26.4.

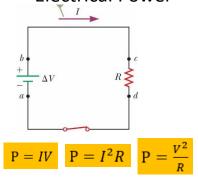
* A nickel-chromium alloy commonly used in heating elements. The resistivity of Ni

A nixel-enromanm alloy commonly used in neating elements. The resistivity of Nichrom ricis with composition and ranges between 1.00×10^{-6} and 1.50×10^{-6} $\Omega \cdot$ m. The resistivity of silicon is very sensitive to purity. The value can be changed by severa ders of magnitude when it is doped with other atoms.

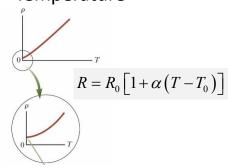
Superconductors



Electrical Power

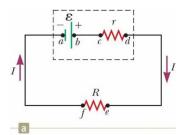


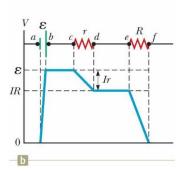
 Resistance and Temperature



Wk-4 (Ch. 27)

Electromotive Force (EMF)





$$\Delta V = \varepsilon - Ir$$

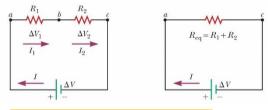
$$\varepsilon = IR + Ir$$

$$I = \frac{\varepsilon}{R + r}$$

$$I\varepsilon = I^{2}R + I^{2}r$$

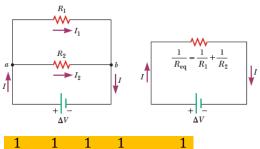
Resistor Combinations

Series Combination



$$R_{eq} = R_1 + R_2 + R_3 + \dots + R_n$$

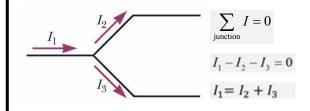
Parallel Combination



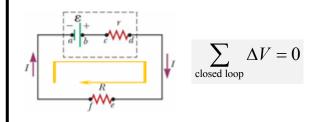
$$\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_n}$$

Kirchhoff's Rules

Kirchhoff's Current (Junction) Rule



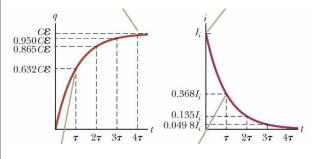
Kirchhoff's Voltage (Loop) Rule



RC Circuits

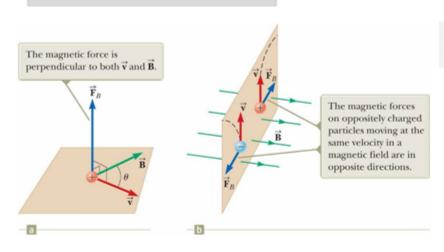
$$q(t) = C\varepsilon (1 - e^{-t/RC})$$
$$= Q_{\max} (1 - e^{-t/RC})$$

$$i(t) = \frac{\varepsilon}{R} e^{-t/RC} \qquad \tau = RC$$



Wk-5 (Ch. 28)

Particle in a magnetic field



$$\vec{\mathbf{F}}_{B} = q\vec{\mathbf{v}} \times \vec{\mathbf{B}}$$

$$1 T = 1 \frac{N}{C \cdot m/s}$$

$$1 T = 1 \frac{N}{A \cdot m}$$

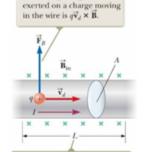
$$1 T = 10^4 G$$

Magnetic force on current

$$\vec{\mathbf{F}}_{\scriptscriptstyle R} = I\vec{\mathbf{L}} \times \vec{\mathbf{B}}$$

$$d\vec{\mathbf{F}}_B = Id\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$

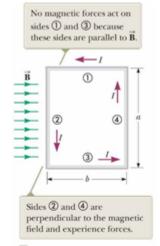
$$\vec{\mathbf{F}}_B = I \int_a^b d\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$



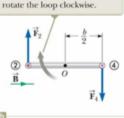
The average magnetic force

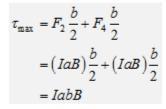
The magnetic force on the wire segment of length L is $I\vec{L} \times \vec{B}$.

Torque on a current loop



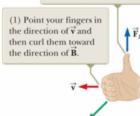
The magnetic forces \vec{F}_9 and \vec{F}_4 exerted on sides 2 and 4 create a torque that tends to rotate the loop clockwise.





Right Hand Rule

(2) Your upright thumb shows the direction of the magnetic force on a positive particle.



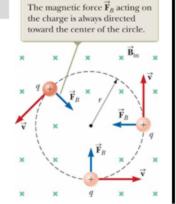
Motion of a charged particle

$$\sum F = F_B = m\alpha$$

$$F_B = qvB = \frac{mv^2}{r}$$

$$r = \frac{mv}{qB}$$
 $\omega = \frac{v}{r} = \frac{qB}{m}$

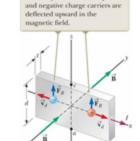
$$T = \frac{2\pi r}{v} = \frac{2\pi}{\omega} = \frac{2\pi m}{qB}$$



The Hall Effect

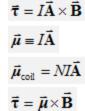
$$\begin{split} \Delta V_{\rm H} &= \frac{IB}{nqt} \\ &= \frac{R_{\rm H}IB}{t} \end{split}$$

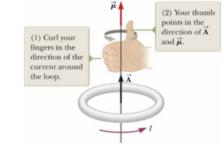
$$R_H = \frac{1}{nq}$$
 (Hall coefficient)



When I is in the x direction and

B in the y direction, both positive



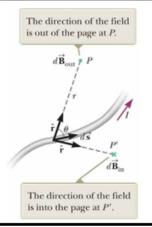


Wk-6 (Ch. 29)

The Biot - Savart Law

$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{Id\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

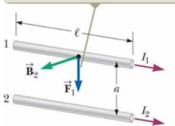


The Magnetic Field of a Solenoid

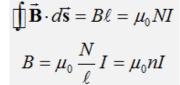
The field $\vec{\mathbf{B}}_2$ due to the current in wire 2 exerts a magnetic force of magnitude $F_1 = I_1 \ell B_2$ on wire 1.

The Magnetic Force Between

Two Parallel Conductors



$$F_1 = I_1 \ell B_2 = I_1 \ell \left(\frac{\mu_0 I_2}{2\pi a} \right) = \frac{\mu_0 I_1 I_2}{2\pi a} \ell$$



Ampère's law applied to the circular path whose plane is perpendicular to the page can be used to show that there is a weak field outside the solenoid.

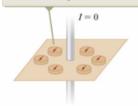
Ampère's law applied to the rectangular dashed path can be

magnitude of the interior field.

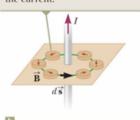
used to calculate the

Ampère's Law

When no current is present in the wire, all compass needles point in the same direction (toward the Earth's north pole).

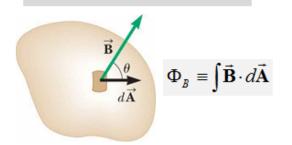


When the wire carries a strong current, the compass needles deflect in a direction tangent to the circle, which is the direction of the magnetic field created by the current.



 $\iint \vec{\mathbf{B}} \cdot d\vec{\mathbf{s}} = B \iint ds = \frac{\mu_0 I}{2\pi r} (2\pi r) = \mu_0 I$

Gauss's Law in Magnetism



Midterm Exam Overview

Physics-2, ENGI-1500, W23 Midterm Exam

■ Date: Tuesday, February 21, 2022 | regular class time [8:55am - 11:35am]

8:55 - 9:00 Seating and exam distribution

9:00 - 11:30 Exam time (150 minutes)

11:30 - 11:35 Collection of papers

■ Place: BCTI-310

- Exam will be <u>in-person</u>. Please be present on time.
- Exam will consist of classical questions and multiple-choice questions.
- Formula page will be provided. Calculators are allowed.
- Office hour before midterm exam (optional): on Thursday, February 16, 2023:
 - 1pm to 2pm
 - NX building, 3rd floor [please email so I can let you in]
 - If you have questions but can't join the office hour, please feel free to email me.
- If you have questions, comments, concerns about the exam please let me know.

Midterm Exam First Page

Midterm Exam ENGI-1500, Winter 2023 Group A February 21, 2023

ENGI-1500 Physics-2 Midterm Exam - Group A

Student Name: _	
Student ID:	

 Place:
 BCTI-310
 [in-person, synchronous exam]

 Date:
 Tuesday, February 21, 2023 – 8:55am – 11:35am

 8:55 - 9:00
 Seating and exam distribution

 9:00 - 11:30
 Exam time (150 minutes)

 11:30 - 11:35
 Collection of all papers

Your Marks			Version
			Δ
			$\overline{}$

Instructions:

Please do not start the exam until you read the following instructions carefully and sign at the bottom.

- Ensure your full name and student number is entered correctly at the top of the first page.
- Exam time is 2 hours and 30 minutes (150 minutes).
- No group work, or any form of collaboration between students is permitted in the exam room.
- This is a closed book exam. Formula sheet will be provided as appendix.
- No extra blank papers or workbooks are allowed. If necessary, you may write on the back of the pages or ask for additional pages from your instructor.
- All personal electronic devices (phones, computers, tablets, smart watches, earphones, etc.) must be put away. No digital aids are permitted, except for a calculator. Please note; cell phones are not permitted as calculators.
- · This exam consists of classical questions and multiple-choice questions.
- . All multiple-choice questions are to be answered on the exam sheet, please mark your choice clearly.
- Each multiple choice question has only one correct answer.
- Please show your work and solution steps clearly on the question sheets. You are encouraged to show your solution steps for the classical questions to be considered for partial credits.

The exam policy explained above is in immediate effect at the start of the exam.

Student Signature		Date	
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Please do not turn this page until instructed to do so.

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Midterm Exam Appendix

Midterm Exam Appendix ENGI-1500, Winter 2023

Group A February 21, 2023

Appendix-A: Formulas

Coulomb's law (electric force):

$$\overrightarrow{\mathbf{F}}_{12} = k_{\epsilon} \frac{q_1 q_2}{r^2} \, \hat{\mathbf{r}}_{12}$$

$$\overrightarrow{\mathbf{E}} \; = \; k_e \, \frac{q}{r^2} \; \widehat{\mathbf{r}} \quad \overrightarrow{\mathbf{E}} \; = \; k_e \sum_i \frac{q_i}{r_i^2} \; \widehat{\mathbf{r}}_i \quad \overrightarrow{\mathbf{E}} \; = \; k_e \int \frac{dq}{r^2} \; \widehat{\mathbf{r}}$$

Continuous Charge Distributions:

 $p=Q/V \rightarrow dq=pdV$; $\sigma=Q/A \rightarrow dq=\sigma dA$; $\lambda=Q/I \rightarrow dq=\lambda dI$

Electric force and field relationship:

$$\vec{\mathbf{F}}_{r} = q \vec{\mathbf{E}}$$

Electric flux through a surface:

$$\Phi_E = EA \cos \theta$$

$$\Phi_E = \int_{\text{surface}} \vec{E} \cdot d\vec{A}$$

$$\Phi_E = \oint \vec{\mathbf{E}} \cdot d\vec{\mathbf{A}} = \frac{q_{in}}{\epsilon_0}$$

Electric potential difference:

$$\Delta V = \frac{\Delta U}{q} = -\int_{0}^{0} \vec{\mathbf{E}} \cdot d\vec{s} \qquad \Delta V = -Ed$$

$$V = k_e \frac{q}{r}$$
 $V = k_e \int \frac{dq}{r}$

Electric potential energy:

$$U=k_{\epsilon}\,\frac{q_1q_2}{r_{12}}$$

Electric field in terms of electric potential:

$$E_x = -\frac{dV}{dx}$$

Capacitance, charge and potential difference:

$$C = \frac{Q}{\Delta V}$$

Equivalent capacitance (parallel comb.):

$$C_{\mathrm{eq}} = C_1 + C_2 + C_3 + \cdots$$
 Equivalent capacitance (series comb.):

$$\frac{1}{C_{\text{eq}}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \cdots$$

Capacitor with a dielectric constant:

$$C = \kappa C_0$$

Energy stored in a capacitor:

$$U_E = \frac{Q^2}{2C} = \frac{1}{2}Q \Delta V = \frac{1}{2}C (\Delta V)^2$$

$$I \equiv \frac{dQ}{dt} \qquad I_{\text{avg}} = nqv_d A$$

Electric current density:

$$J = \frac{I}{A}$$
 $J = \sigma E$

Ohm's law, resistance and resistivity:

$$R \equiv \frac{\Delta V}{I} \quad R = \rho \frac{\ell}{A} \quad \rho = \rho_0 [1 + \alpha (T - T_0)]$$

Drift velocity:

$$\vec{\mathbf{v}}_d = \frac{q \vec{\mathbf{E}}}{m_e} \tau$$

$$P = I \Delta V \quad P = I^2 R = \frac{(\Delta V)^2}{R}$$

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Midterm Exam Appendix ENGI-1500, Winter 2023

Group A February 21, 2023

Equivalent resistance (series comb.):

$$R_{\rm eq} = R_1 + R_2 + R_3 + \cdots$$

Equivalent resistance (parallel comb.):

$$\frac{1}{R_{\rm eq}} = \frac{1}{R_{\rm I}} + \frac{1}{R_{\rm 2}} + \frac{1}{R_{\rm 3}} + \cdots$$

RC circuits as a function of time (charging):

$$q(t) = Q_{\rm max} (1 - e^{-t/RC}) \ i(t) = \frac{\mathcal{E}}{R} \, e^{-t/RC} \label{eq:qt}$$

RC circuits as a function of time (discharging):

$$q(t) = Q_i e^{-t/RC} \quad i(t) = -\frac{Q_i}{RC} e^{-t/RC}$$

$$\tau = RC$$

Circuit analysis - Kirchhoff's rules:

$$\sum_{\text{junction}} I = 0$$
 $\sum_{\text{closed loop}} \Delta V = 0$

Magnetic force on a moving charged particle:

$$\vec{\mathbf{F}}_{\scriptscriptstyle B} = q \vec{\mathbf{v}} \times \vec{\mathbf{B}} \quad F_{\scriptscriptstyle B} = |q| v B \sin \theta$$

Magnetic dipole moment:

$$\vec{\mu} = I \vec{A}$$

Charged particle moving in a uniform magnetic field (circular path):

$$r = \frac{mv}{qB}$$
 $\omega = \frac{qB}{m}$

Magnetic force on a current carrying conductor:

$$\vec{\mathbf{F}}_B = I \vec{\mathbf{L}} \times \vec{\mathbf{B}} \quad d\vec{\mathbf{F}}_B = I d\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$

Torque on a current loop in a uniform magnetic field:

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

Newton's 2nd law:

$$\sum \vec{\mathbf{F}} = m\vec{\mathbf{a}}$$

Appendix-B: Constants

Description	Symbol	Value	Unit
Avogadro's number	NA	6.022 141 79 x 10 ²³	particles / mol
Coulomb constant	$k_e = 1/(4\pi E_0)$	8.987 551 788 x 10 ⁹	N·m²/C²
Electron mass	m _e	9.109 382 15 x 10 ⁻³¹	kg
Proton mass	m _p	1.672 621 637 x 10 ⁻²⁷	kg
Neutron mass	mn	1.674 927 211 x 10 ⁻²⁷	kg
Elementary (electron) charge	e	-1.602 176 487 x 10 ⁻¹⁹	с
Elementary (proton) charge	р	+1.602 176 487 x 10 ⁻¹⁹	c
Gravitational constant	G	6.674 28 x 10 ⁻¹¹	N·m²/kg²
Permittivity of free space	ε ₀	8.854 187 817 x 10 ⁻¹²	C ² /N·m ²
Permeability of free space	μο	4π x 10 ⁻⁷	T·m/A
Speed of light in vacuum	С	2.997 924 58 x 108	m/s

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Midterm Exam Appendix

Midterm Exam Appendix NGI-1500, Winter 2023			Group A February 21, 2023
ppendix-C: Derivatives &	Integrals		
$\frac{d}{dx}k = 0$	(1)	$\int dx = x + C$	(1)
$\frac{1}{c}[f(x) \pm g(x)] = f'(x) \pm g'(x)$	(2)	$\int x^{n} dx = \frac{x^{n+1}}{n+1} + C$	(2)
$\frac{1}{e} [k \cdot f(x)] = k \cdot f'(x)$	(3)	$\int \frac{dx}{x} = \ln x + C$	(3)
[f(x)g(x)] = f(x)g'(x) + g(x)f		$\int e^{x} dx = e^{x} + C$	(4)
$\left(\frac{f(x)}{g(x)}\right) = \frac{g(x)f'(x) - f(x)g'(x)}{[g(x)]^2}$	(x) (5)	J	
$f(g(x)) = f'(g(x)) \cdot g'(x)$	(6)	$\int a^x dx = \frac{1}{\ln a}a^x + C$	(5)
$x^n = nx^{n-1}$	(7)	$\int \ln x dx = x \ln x - x + C$	(6)
$\sin x = \cos x$	(8)	$\int \sin x dx = -\cos x + C$	(7)
$\cos x = -\sin x$	(9)	$\int \cos x dx = \sin x + C$	(8)
$\tan x = \sec^2 x$	(10)	$\int \tan x dx = -\ln \cos x + C$	(9)
$\cot x = -\csc^2 x$	(11)	$\int \cot x dx = \ln \sin x + C$	(10)
$\sec x = \sec x \tan x$	(12)	$\int \sec x dx = \ln \sec x + \tan x + C$	(11)
$\csc x = -\csc x \cot x$	(13)	4	()
$e^x = e^x$	(14)	$\int \csc x dx = -\ln \csc x + \cot x + C$	(12)
$a^x = a^x \ln a$	(15)	$\int \sec^2 x dx = \tan x + C$	(13)
$\ln x = \frac{1}{x}$	(16)	$\int \csc^2 x dx = -\cot x + C$	(14)
$\sin^{-1} x = \frac{1}{\sqrt{1 - x^2}}$	(17)	$\int \sec x \tan x dx = \sec x + C$	(15)
$\cos^{-1} x = \frac{-1}{\sqrt{1-x^2}}$	(18)	$\int \csc x \cot x dx = -\csc x + C$	(16)
$\tan^{-1} x = \frac{1}{x^2 + 1}$	(19)	$\int \frac{dx}{\sqrt{\alpha^2 - x^2}} = \sin^{-1} \frac{x}{a} + C$	(17)
$\cot^{-1} x = \frac{-1}{x^2 + 1}$	(20)	$\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \tan^{-1} \frac{x}{a} + C$	(18)
$sec^{-1}x = \frac{1}{ x \sqrt{x^2 - 1}}$	(21)	<i>y</i>	
$\frac{1}{x} \csc^{-1} x = \frac{-1}{ x \sqrt{x^2 - 1}}$	(22)	$\int \frac{dx}{x\sqrt{x^2 - a^2}} = \frac{1}{a} \sec^{-1} \frac{ x }{a} + C$	(19)

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Review Questions & Solutions

Midterm Review Questions with Solutions ENGI-1500 Physics-2, Winter 2023



Review Questions

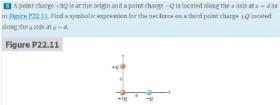
- 1 Electric Fields [Ch. 22]
- 1.1 [Textbook 22.5]

A 7.50-nC point charge is located 1.80 m from a 4.20-nC point charge.

- (a) Find the magnitude of the electric force that one particle exerts on the other.
- (b) Is the force attractive or repulsive?
- 1.2 [Textbook 22.10]

Three point charges lie along a straight line as shown in Figure P22.10, where $q_1=6.00~\mu\text{C},$ $q_2=1.50~\mu\text{C},$ and $q_3=-2.00~\mu\text{C}.$ The separation distances are $d_1=3.00~\text{cm}$ and $d_2=2.00~\text{cm}$. Calculate the magnitude and direction of the net electric force on (a) q_1 , (b) q_2 , and (c) q_3 .

1.3 [Textbook 22.11]



Humber College Institute of Technology and Advanced Learning

Textbook: Serway, Raymond A., and John W. Jewett. Physics for scientists and engineers. 10th Edition. Cengage learning, 2018.

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Midterm Review Questions with Solutions ENGI-1500 Physics-2, Winter 2023

Solutions

Review Questions

- 1 Electric Fields [Ch. 22]
- 1.1 [Textbook 22.5]

A 7.50-nC point charge is located 1.80 m from a 4.20-nC point charge.

- (a) Find the magnitude of the electric force that one particle exerts on the other.
- (b) Is the force attractive or repulsive?

Solution:

(a)
$$|F| = \frac{k_r |q_1| |q_2|}{r^2}$$

$$F = \frac{k_r e^2}{r^2} = \frac{(8.99 \times 10^9 \text{ N} \cdot \text{m}^2 / \text{C}^2)(7.50 \times 10^{-9} \text{ C})(4.20 \times 10^{-9} \text{ C})}{(1.80 \text{ m})^2}$$

$$= |8.74 \times 10^{-8} \text{ N}|$$

(b) The charges are like charges. The force is repulsive.

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Reading / Preparation for Next Week

Next week:

Midterm exam on Tuesday, February 21, 2023