



PROGRAMMABLE LOGIC CONTROLLERS MENG 3500







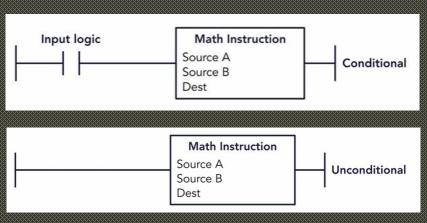
The PLC's mathematical processing capability enables it to execute arithmetic operations on values stored in memory words or registers.

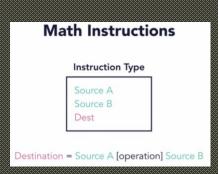
The specific math instructions available depend on the PLC model and its processor.

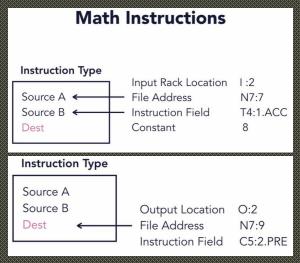
These math instructions typically require two input values, conduct the designated arithmetic operation, and then store the result in a designated memory location.

Among the fundamental mathematical functions carried out by CompactLogix PLCs are, but not limited to:

- Addition (ADD)
- Subtraction (SUB)
- Multiplication (MUL)
- Division (DIV)
- Square Root (SQR)
- Clear (CLR)

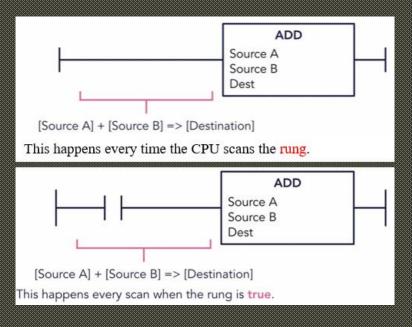


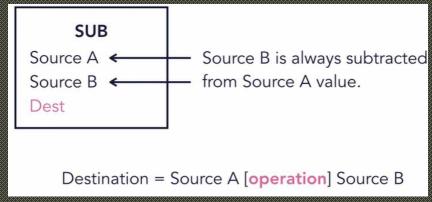


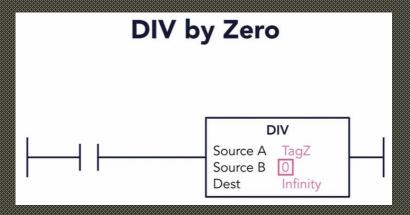


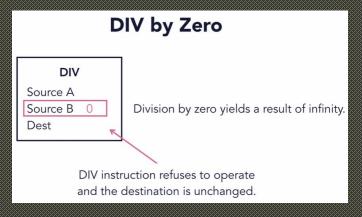
All these operations are executed as output instructions.



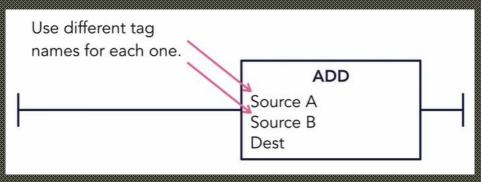


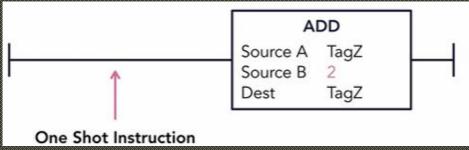


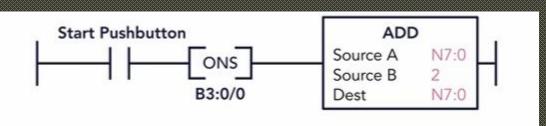


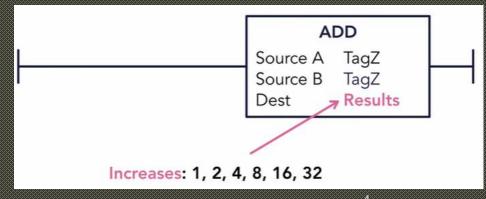








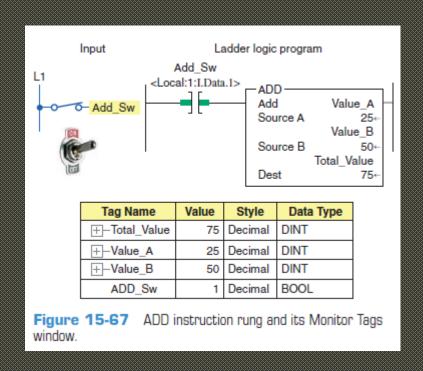


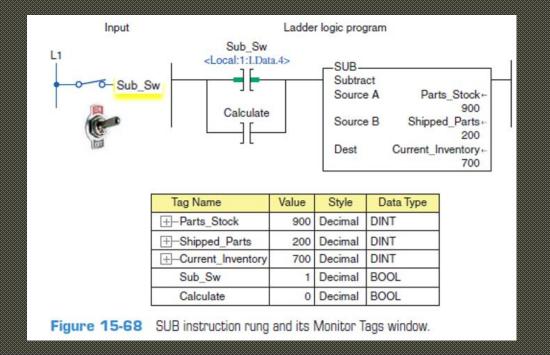




Addition and Subtraction Instructions

The Source can be a constant value or a tag. The result of the ADD or SUB instructions is put in the destination (Dest) tag.

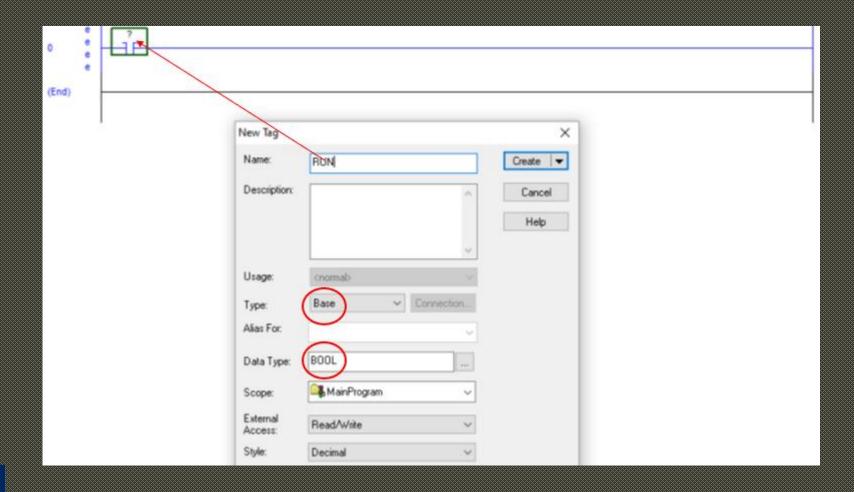






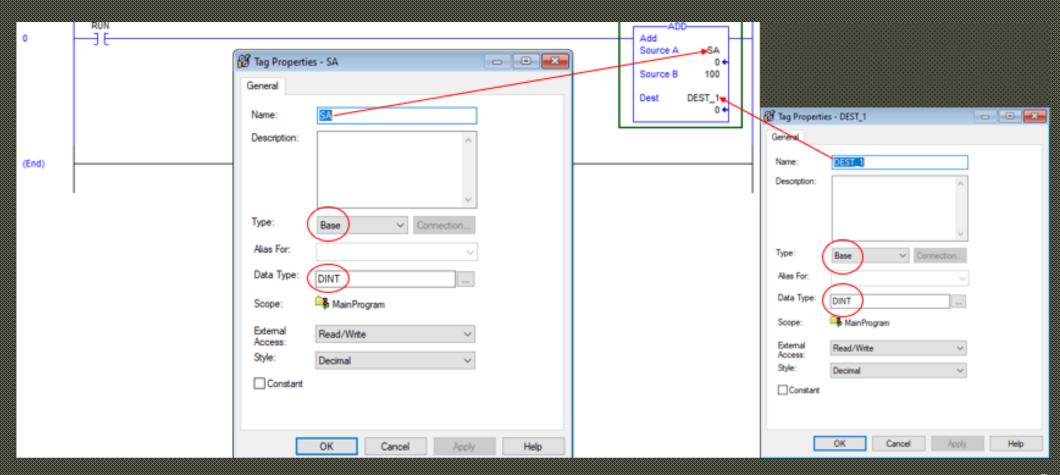
Addition Instruction

When the RUN (Type: Base; Data Type: BOOLEAN) bit becomes TRUE, the output ADD instruction will be executed every scan.





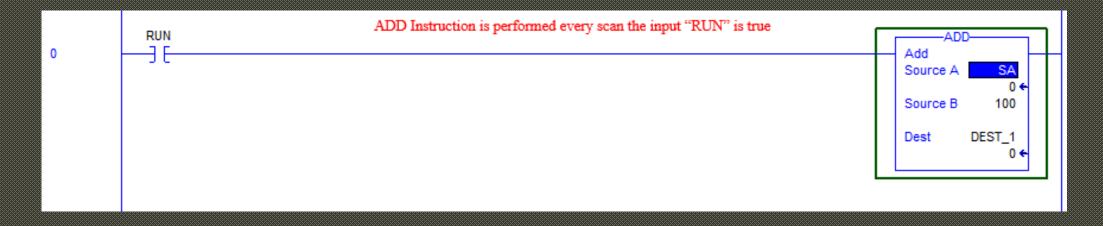
Addition Instruction





Addition Instruction

Destination tag different form the Source A and Source B tags





Addition Instruction

Destination tag, same as the Source A tag, causes continuous accumulation in the Destination.

```
ACCUMULATION OF THE VLUE IN DESTINATION

RUN

ADD

Add

Source A SA

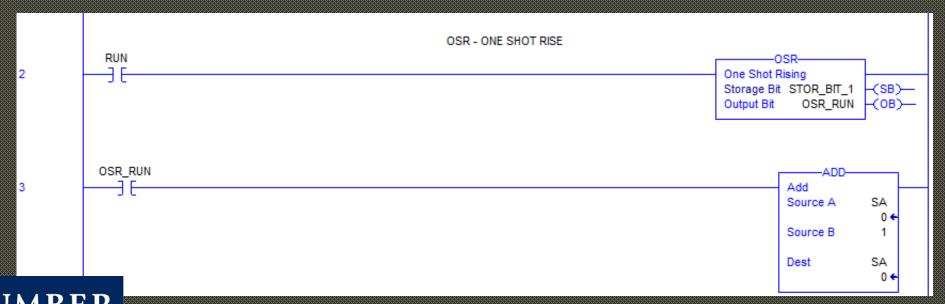
0 ←

Source B 1

Dest SA

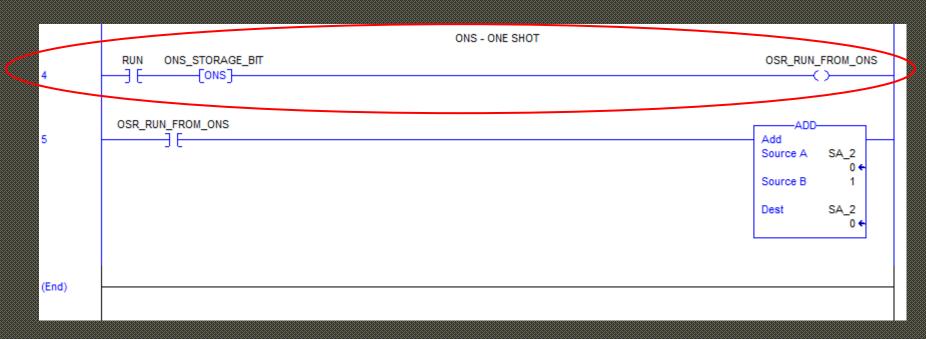
0 ←
```

To avoid accumulation, use output bit of the OSR instruction.



Addition Instruction

You may use ONS instruction instead of OSR or OSF



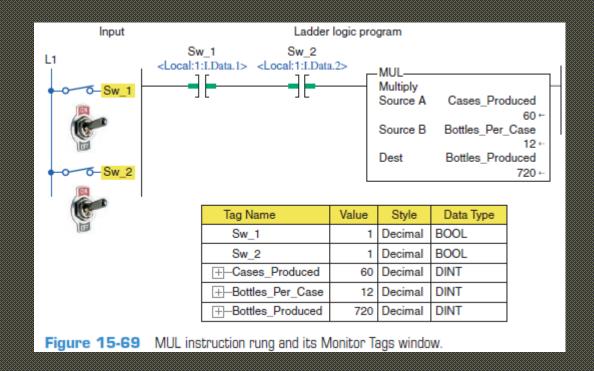
Operates akin to OSR

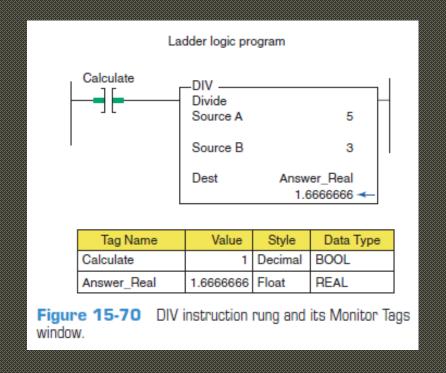
Other mathematical instructions are also encountering the same issue with the Destination as the one observed.



Multiplication and Division Instructions

The Source can be a constant value or a tag. The result of the MUL or DIV instructions is put in the destination (Dest) tag.





(Frank D. Petruzella Programmable Logic Controllers 4th edition)



Compute Instruction

- > CPT instruction is used to calculate the formula in the Expression and store the result in the Destination
- > CPT is an output instruction

```
COMPUTE INSTRUCTION

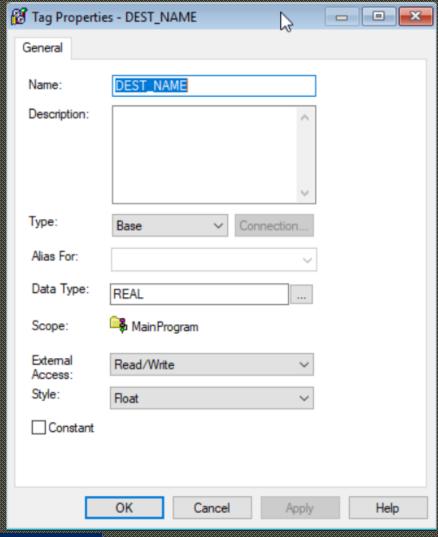
SWITCH

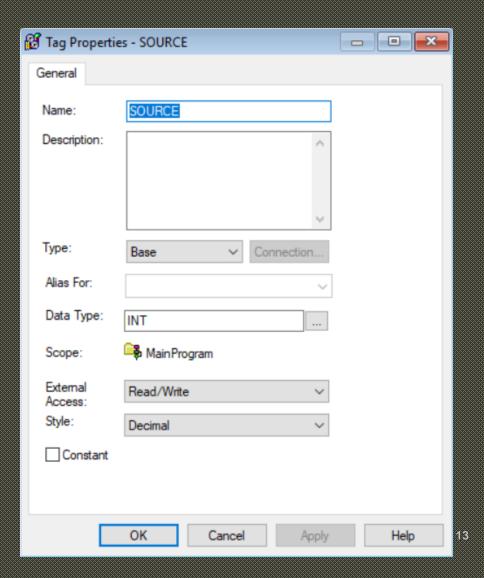
Compute
Dest
DEST_NAME
0.0 ←
Expression 0.05*SOURCE+5.6

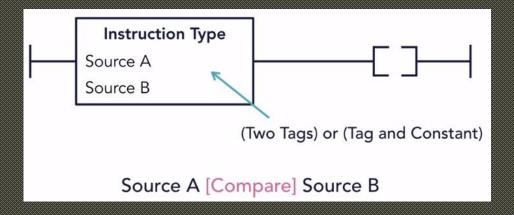
(End)
```

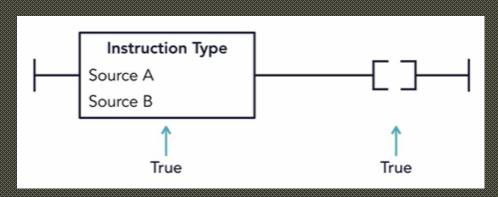


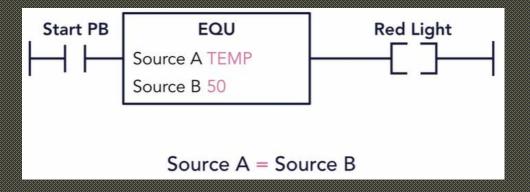
Compute Instruction





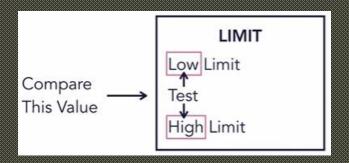


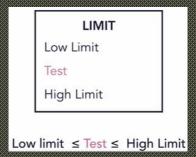


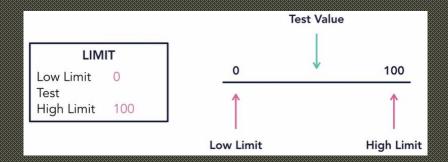


Instruction			
EQU	Equal		
NEQ	Not Equal		
GRT	Greater than		
GEQ	Greater than or Equal		
LES	Less than		
LEQ	Less than or Equal		

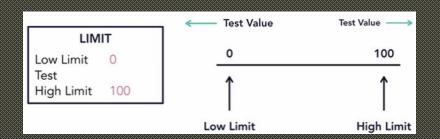


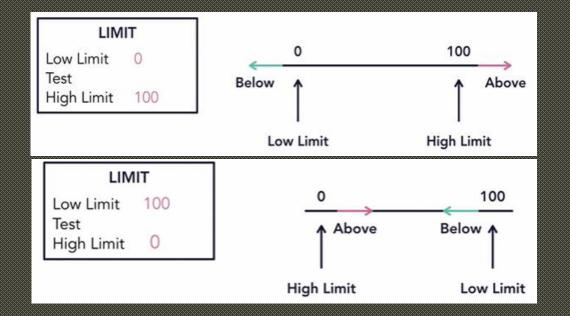




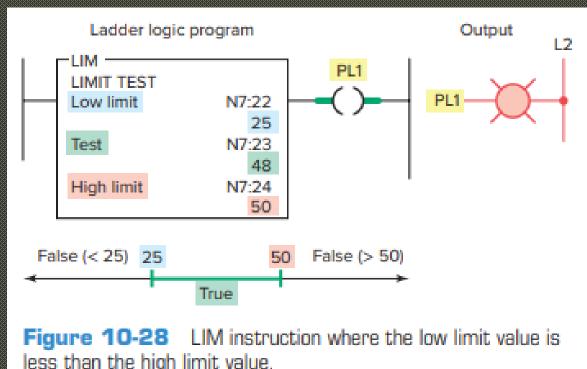


What if we want to test outside the limits?

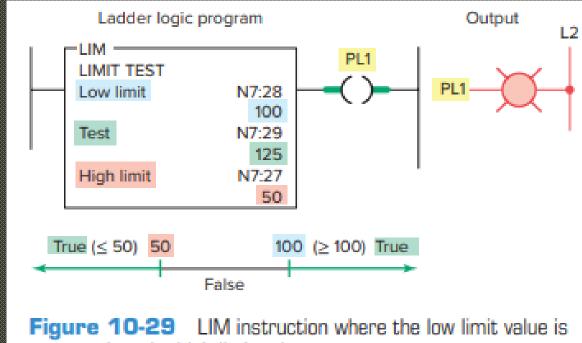








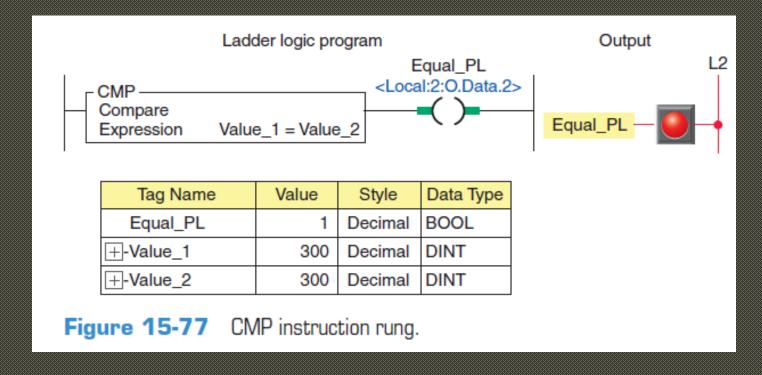
less than the high limit value.



greater than the high limit value.

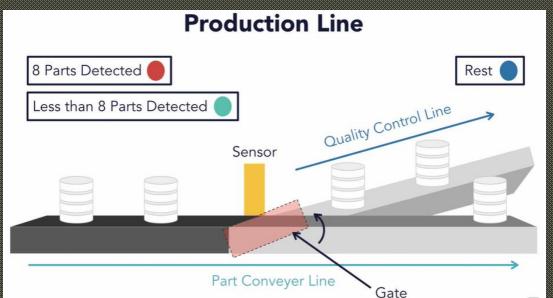


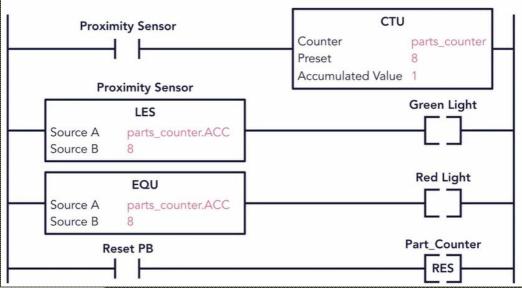
- ➤ The <u>compare (CMP)</u> instruction performs a comparison on the arithmetic operations specified by the expression. The expression may contain arithmetic operators, comparison operators, and tags.
- ➤ The execution of a CMP instruction is slightly slower and uses more memory than the execution of the other comparison instructions.
- > The advantage of the CMP instruction is that it allows you to enter complex expressions in one instruction.

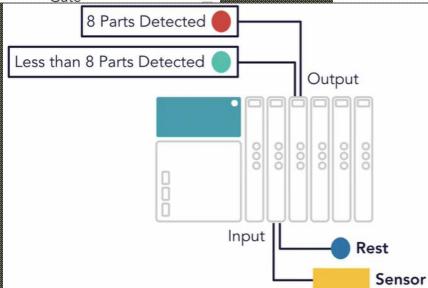




COMPARISON INSTRUCTIONS - Example





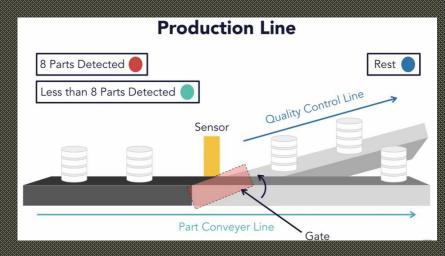


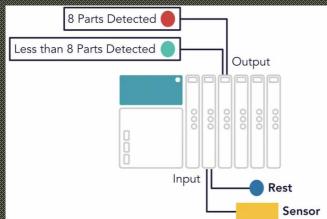
- Proximity sensor is used to count the number of damaged parts
- The Gate, used to separate the damaged parts is not part of the program

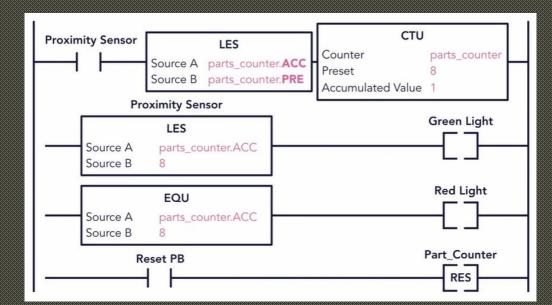


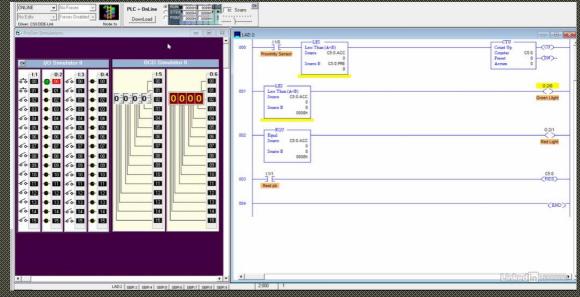
COMPARISON INSTRUCTIONS - Example

To prevent the Counter from exceeding the Preset Value



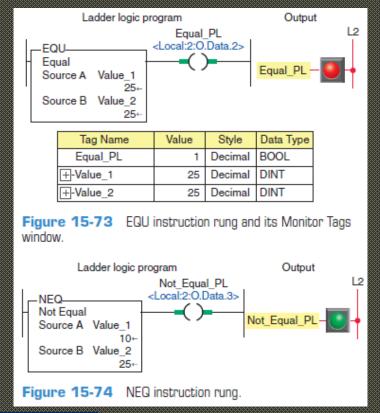


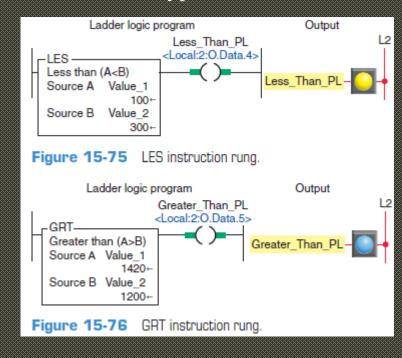


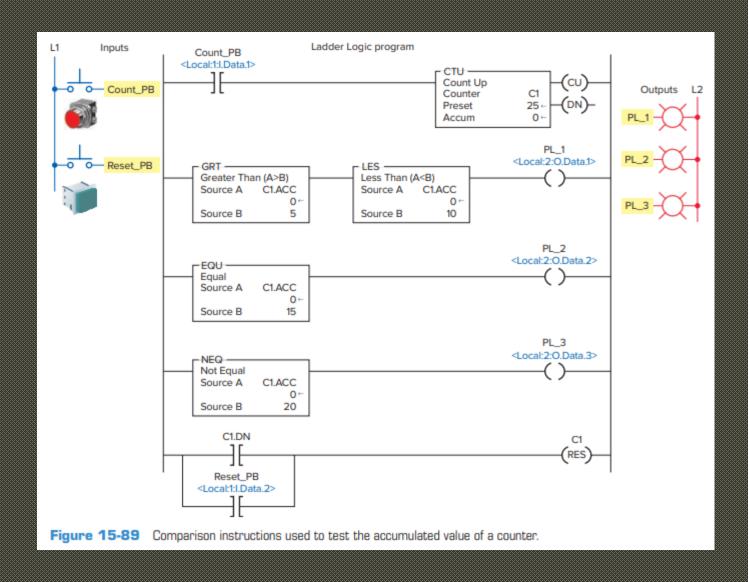




- ➤ Comparison instructions are used to compare two values. They can be used to see if two values are equal, if one value is greater or less than the other, and so on;
- > All of them are input instructions;
- ➤ The value stored at Source A is compared to the value stored at Source B;
- > Source A and Source B may be **SINT**, **INT**, **DINT**, **or REAL** data types;

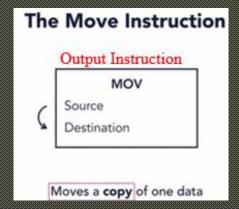


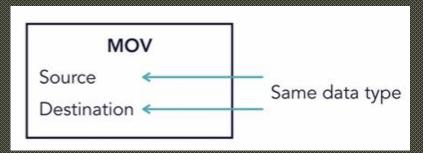


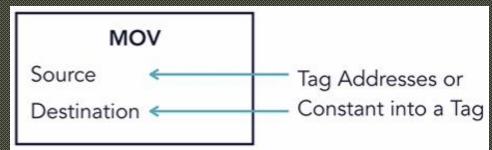


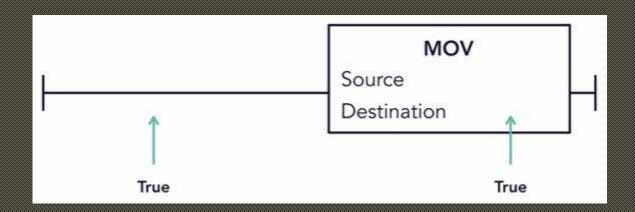


Move Instruction



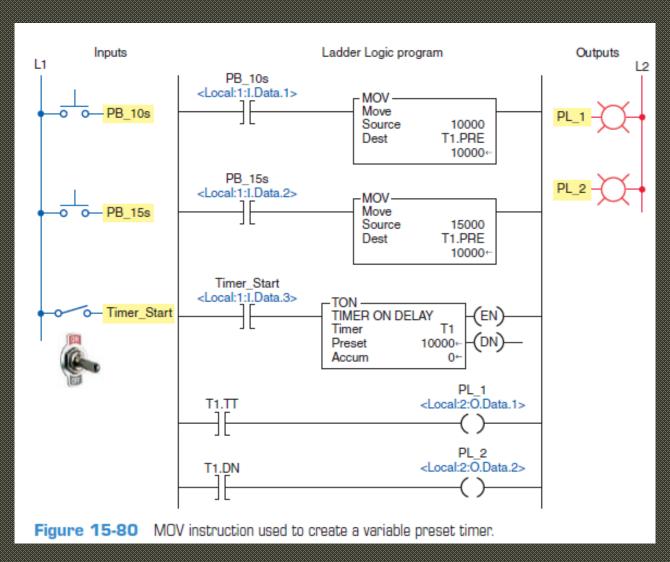






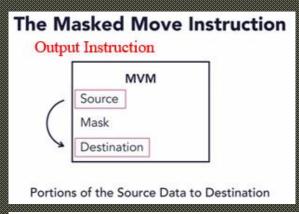


Move Instruction Example

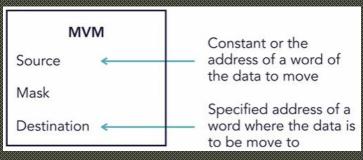


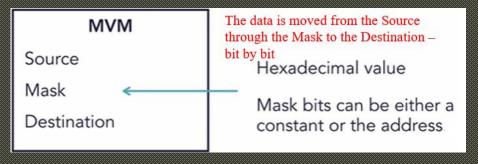


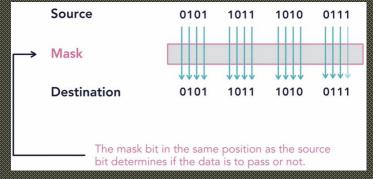
Move with Mask Instruction







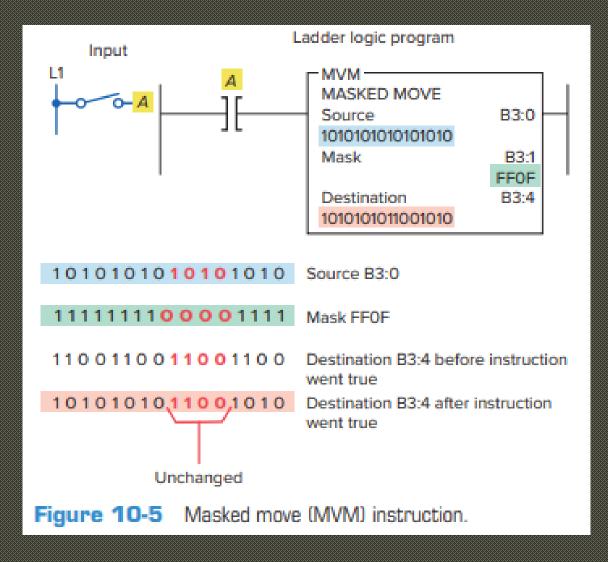




Source	0101	1011	1010	0111
Mask ^{00FF}	0000	0000	1111	1111
Destination	0000	0000	1010	0111



Move with Mask Instruction

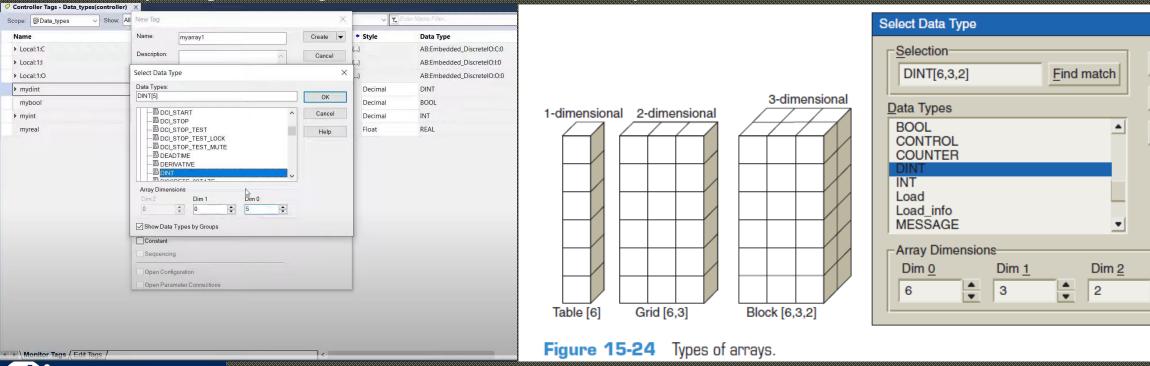




Arrays

- ➤ Many control programs require the ability to store blocks of information in memory in the form of tables that can be accessed at runtime.
- An Array is a tag type that contains a block of multiple pieces of data. Each element of an array must be of the same data type (e.g., BOOL, SINT, or INT).

> An array occupies a contiguous block of controller memory.





Х

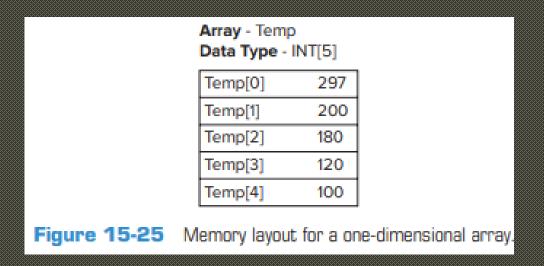
OK

Cancel

Help

Arrays

- > Arrays are like tables of values
- ➤ A single tag within the array is one element
- > The elements start with 0 and extend to the number of elements minus 1
- > The use of arrayed data types offers the fastest data throughput (output) from a ControlLogix/CompactLogix processor

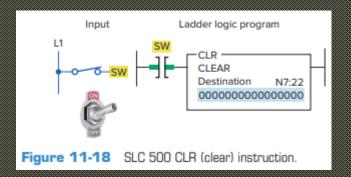




Clear Instruction

- > The Clear (CLR) instruction is an output instruction that can move 0s to the Destination memory tag.
- > This is an output instruction.

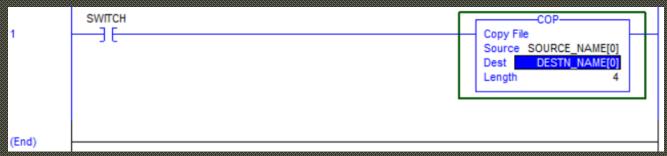
```
SWITCH
Clear
Dest CLR_DEST
0 ←
```

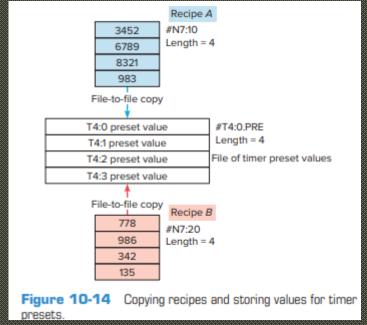


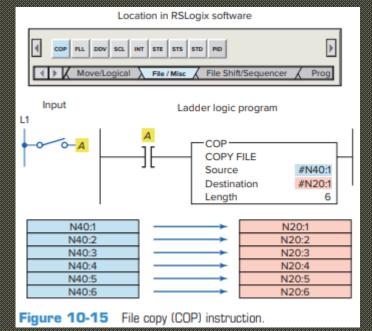


Copy Instruction

The **Copy** (**COP**) instruction is an output instruction that copies the group of Source elements to another group of Destination elements.



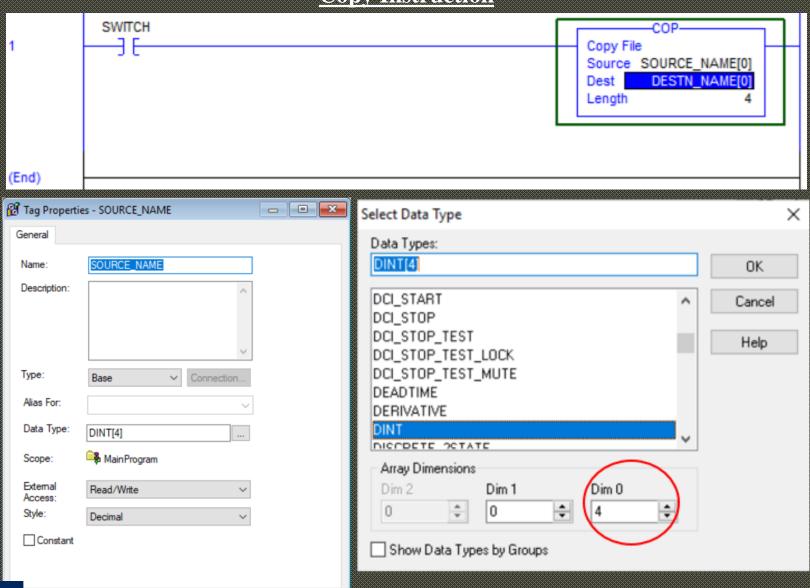






29

Copy Instruction



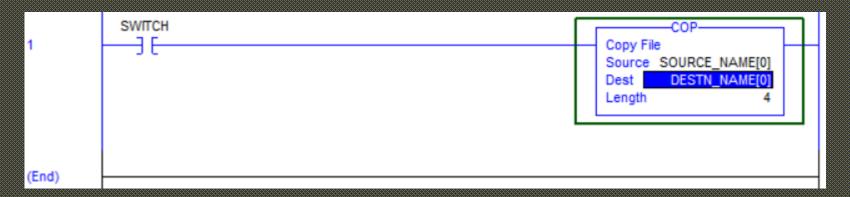
HUMBER

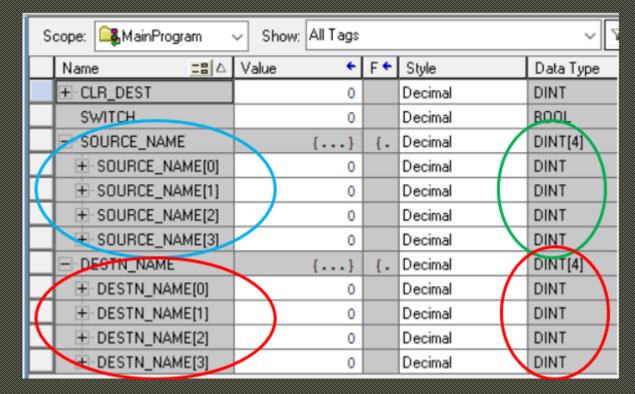
OK

Cancel

Apply

Copy Instruction



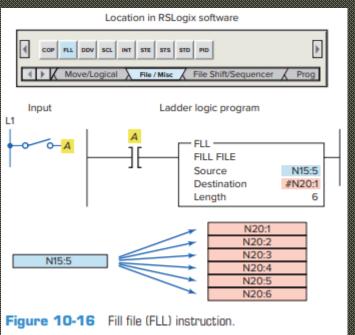


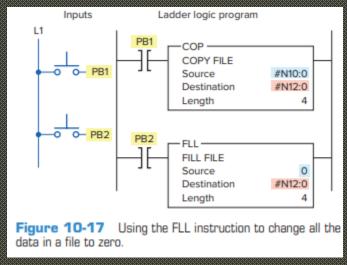


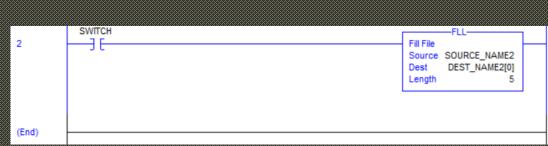
Fill File Instruction

The Fill File (FLL) instruction is an output instruction that performs the word-to-file copy in the first scan the rung is true.

- When input A goes true, the value in N15:5 is copied into N20:1 through N20:6
- Because the instruction transfers to the end of the file, the file will be filled with the same data value in each word
- The FLL instruction is frequently used to zero all the data in a file

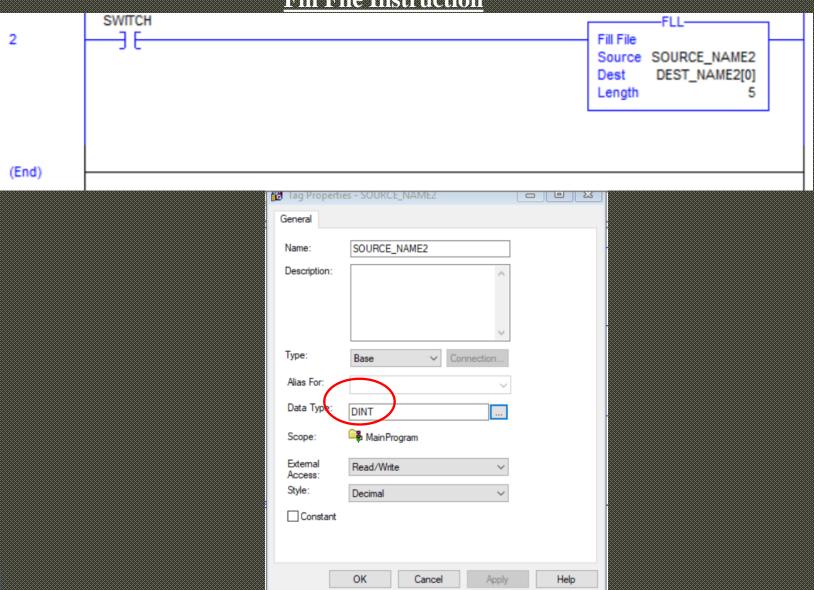




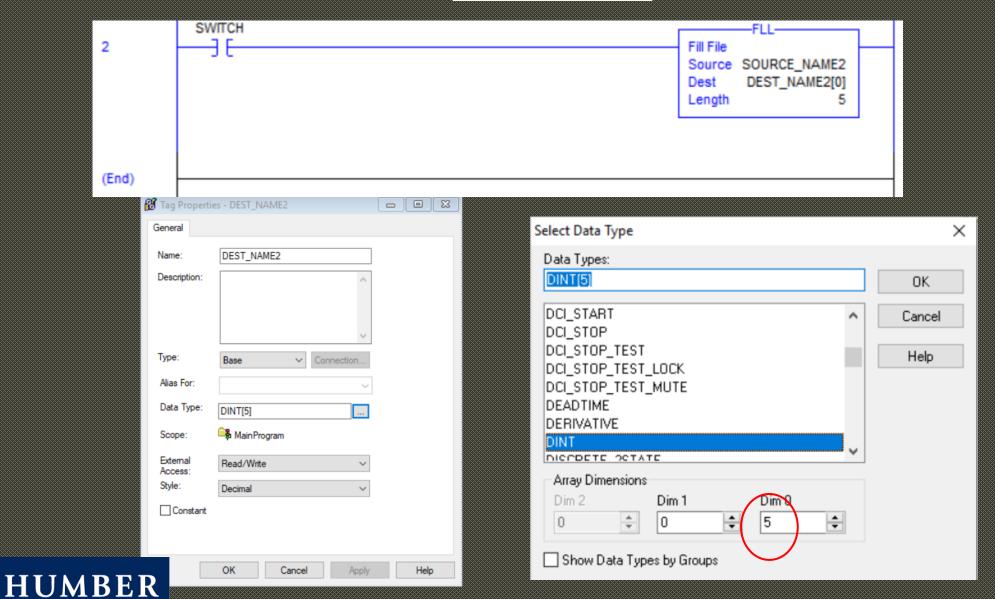




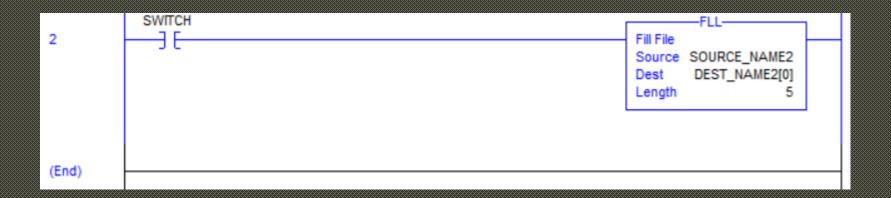
Fill File Instruction

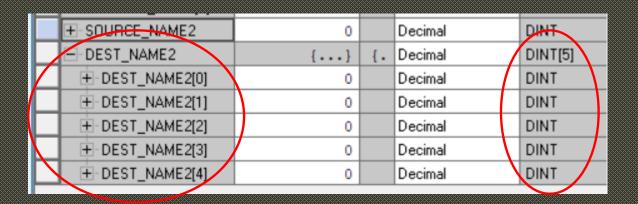


Fill File Instruction



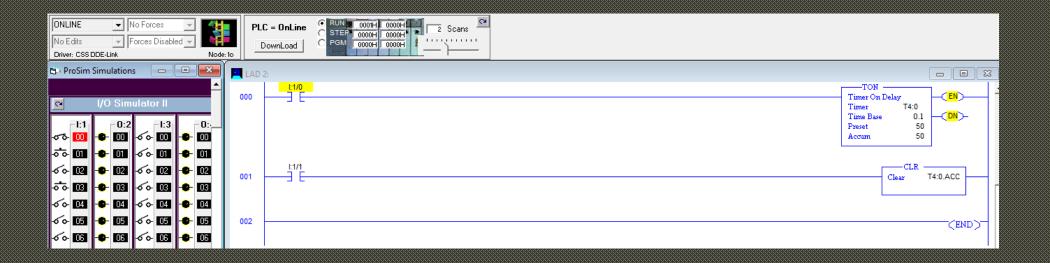
Fill File Instruction





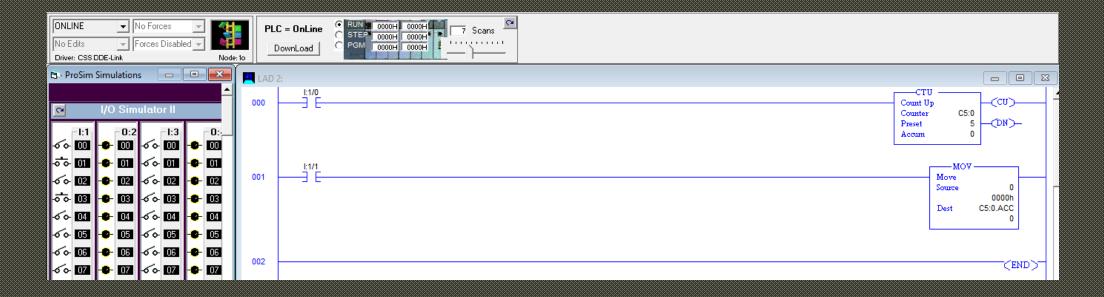


Problem 1. Reset a timer using the CLR instruction.



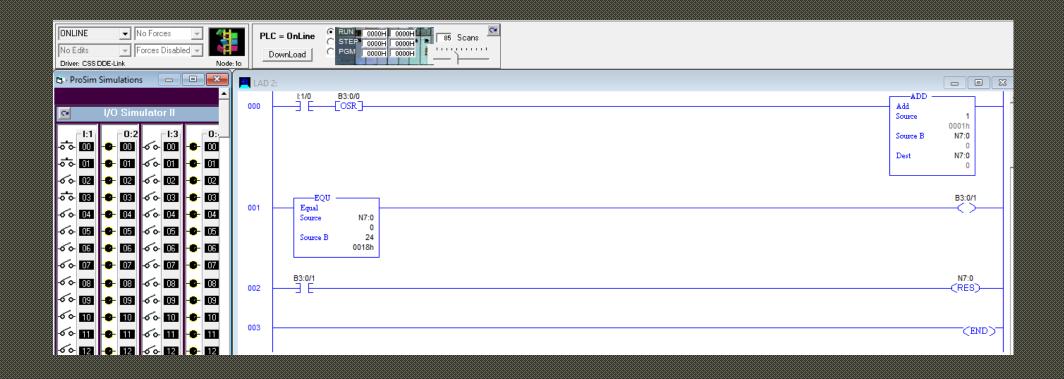


Problem 2. Reset a counter using the MOV instruction.





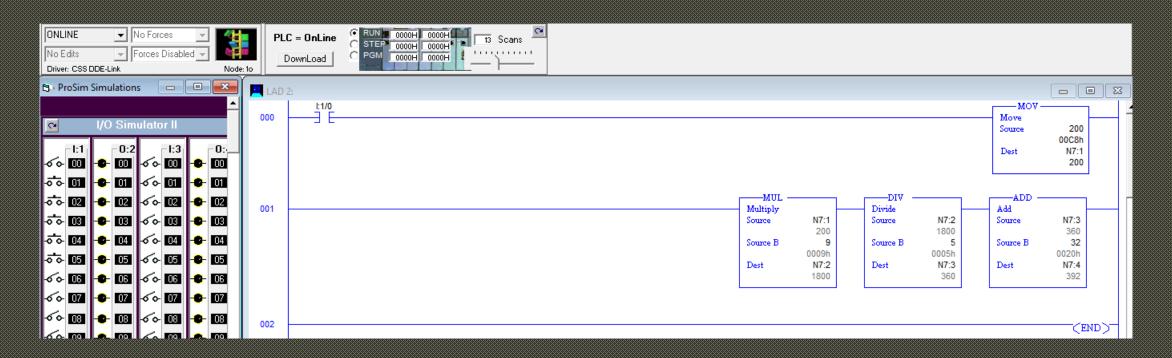
<u>Problem 3.</u> Using ADD instruction, write a counter program to count the number of bottles passing the sensor at the end of the conveyor. Reset the "counter" when the number of boxes reaches 24.



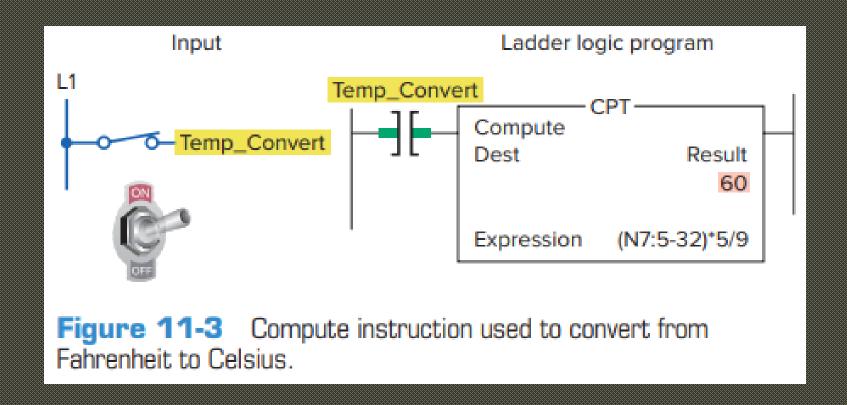


Problem 4. Using math and comparison instructions, write a program to convert the temperature from Celsius to Fahrenheit.

$$F^0 = 1.8 C^0 + 32$$



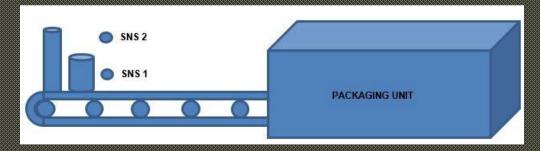
Problem 5. Write the program in Problem 4, using the **CPT** instruction instead of math instructions.

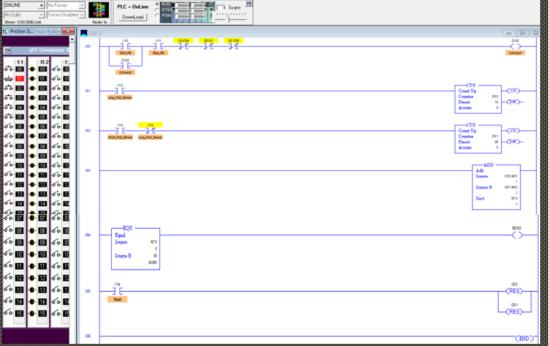




Problem 6. Two optical sensors are installed in the beginning of the conveyor to determine short and long parts.

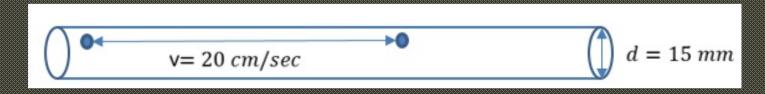
- The short part is recognized by the sensor 1 only, while the long one, by both sensors 1 and sensor 2.
- Momentary N.O. Start and N.C. Stop pushbuttons control the motion of the conveyor.
- A packaging unit at the end of the conveyor packs the parts into two boxes for both sizes.
- The conveyor must stop automatically if the number of long parts reaches 12, or the number of short parts reaches 25, or number of parts in both boxes is 30.
- All accumulated numbers must be reset by the N.O. Reset PB, and the system must be ready for the new batch.







Problem 7. The liquid flows through a pipe with a diameter of 15 mm with the velocity of 20 cm/sec. Write a program to calculate the amount of the liquid flowing out of the pipe in 15 minutes in liters (1L = 1000 cm3).



$$V=\frac{\pi*D^2}{4}*v*$$

Problem 8. Write a traffic lights control program with:

- RED $8 \sec$, Green $8 \sec$ and AMBER $4 \sec$ onds
- WALK light will be solid ON during the first 4 seconds of GREEN
- DO NOT WALK will be solid ON at RED light, and last 2 seconds of AMBER
- The DO NOT WALK will flash at the last 4 seconds of GREEN and first 2 seconds of AMBER
- Use one timer to control the traffic lights
- The flashing effect still can be written using 2 cascade timers sequence

PROGRAMMABLE LOGIC CONTROLLERS

Computation, Comparison and Data Transfer Instructions, Arrays

Erickson, K. (2016) Programmable logic controllers: An emphasis on design and application (3rd edition). Rolla MO: Dogwood Valley Press.

Chapter 7

Petruzella, F. (2017) Programmable Logic Controllers (5th Edition). McGraw-Hill Education, NY.

Chapter 10 Chapter 11 Chapter 15 Array Chapter 15 Part 5



PROGRAMMABLE LOGIC CONTROLLERS MENG 3500

Thank you!

Discussions?

