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## Load libraries
import pandas as pd
import numpy as np
import sys
import os
import matplotlib.pyplot as plt
import matplotlib.cm as cm
from keras.datasets import mnist
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler, RobustScaler, MinMaxScaler, OneHotEncoder
from sklearn.pipeline import Pipeline
from sklearn.compose import ColumnTransformer
plt.style.use('dark_background')
%matplotlib inline
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
## Load MNIST data
(X_train, y_train), (X_test, y_test) = mnist.load_data()
X_train = X_train.transpose(1, 2, 0)
X_test = X_test.transpose(1, 2, 0)
X_train = X_train.reshape(X_train.shape[0]*X_train.shape[1], X_train.shape[2])
X_test = X_test.reshape(X_test.shape[0]*X_test.shape[1], X_test.shape[2])
num_labels = len(np.unique(y_train))
num_features = X_train.shape[0]
num_samples = X_train.shape[1]
# One-hot encode class labels
Y_train = tf.keras.utils.to_categorical(y_train).T
Y_test = tf.keras.utils.to_categorical(y_test).T
# Normalize the samples (images)
xmax = np.amax(X_train)
xmin = np.amin(X_train)
X_{train} = (X_{train} - xmin) / (xmax - xmin) # all train features turn into a number between 0 and 1
X_test = (X_test - xmin)/(xmax - xmin)
print('MNIST set')
print('----')
print('Number of training samples = %d'%(num_samples))
print('Number of features = %d'%(num_features))
print('Number of output labels = %d'%(num_labels))
     Downloading data from <a href="https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz">https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz</a>
     11490434/11490434 [==========] - Os Ous/step
     MNIST set
     Number of training samples = 60000
     Number of features = 784
     Number of output labels = 10
class Layer:
  def __init__(self):
    self.input = None
    self.output = None
  def forward(self, input):
  def backward(self, output_gradient, learning_rate):
## Define the loss function and its gradient
def cce(Y, Yhat):
  return(np.mean(np.sum(-Y*np.log(Yhat), axis = 0)))
  #TensorFlow in-built function for categorical crossentropy loss
  #cce = tf.keras.losses.CategoricalCrossentropy()
  #return(cce(Y, Yhat).numpy())
def cce_gradient(Y, Yhat):
  return(-Y/Yhat)
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class Activation(Layer):
       def __init__(self, activation, activation_gradient):
              self.activation = activation
               self.activation_gradient = activation_gradient
      def forward(self, input):
              self.input = input
              self.output = self.activation(self.input)
              return(self.output)
       def backward(self, output_gradient, learning_rate = None):
              return(output_gradient * self.activation_gradient(self.input))
class Sigmoid(Activation):
              def sigmoid(z):
                     return 1 / (1 + np.exp(-z))
              def sigmoid_gradient(z):
                      a = sigmoid(z)
              super().__init__(sigmoid, sigmoid_gradient)
class Tanh(Activation):
       def __init__(self):
              def tanh(z):
                     return np.tanh(z)
              def tanh_gradient(z):
                     return 1 - np.tanh(z) ** 2
              super().__init__(tanh, tanh_gradient)
class ReLU(Activation):
      def __init__(self):
              def relu(z):
                     return z * (z > 0)
              def relu_gradient(z):
                      return 1. * (z > 0)
              super().__init__(relu, relu_gradient)
## Softmax activation layer class
class Softmax(Layer):
   def forward(self, input):
       self.output = tf.nn.softmax(input, axis = 0).numpy()
   def backward(self, output_gradient, learning_rate = None):
       ## Following is the inefficient way of calculating the backward gradient
       softmax_gradient = np.empty((self.output.shape[0], output_gradient.shape[1]), dtype = np.float64)
       for b in range(softmax_gradient.shape[1]):
          softmax_gradient[:, b] = np.dot((np.identity(self.output.shape[0])-np.atleast_2d(self.output[:, b])) * np.atleast_2d(self.output[
       return(softmax_gradient)
       ## Following is the efficient way of calculating the backward gradient
       #T = np.transpose(np.identity(self.output.shape[0]) - np.atleast_2d(self.output).T[:, np.newaxis, :], (2, 1, 0)) * np.atleast_2d(self.output).T[:, np.newaxis, :], (2, 1, 0) * np.atleast_2d(self.output).T[:, np.newaxis, :], (2, 1, 0) * np.atleast_2d(self.output).T[:, np.ne
       #return(np.einsum('jik, ik -> jk', T, output_gradient))
# Dropout laver class
class Dropout(Layer):
       def __init__(self, probability_dropout = 0.2):
               self.probability_dropout = probability_dropout
              self.dropout_matrix = None
       def forward(self, input):
              {\tt self.dropout\_matrix = (np.random.rand(input.shape[0], input.shape[1]) < (1 - self.probability\_dropout))}
               self. dropout_matrix = (self.dropout_matrix < (1 - self.probability_dropout))</pre>
              self.output = (input * self.dropout_matrix)/(1 - self.probability_dropout)
              return(self.output)
       def backward(self, output_gradient):
              return(self.dropout_matrix * output_gradient[:-1, :])
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## Dense layer class
class Dense(Layer):
              _init__(self, input_size, output_size, reg_strength):
            self.weights = 0.01*np.random.randn(output_size, input_size+1) # bias trick
           self.weights[:, -1] = 0.01 # set all bias values to the same nonzero constant
           self.reg_strength = reg_strength
           self.reg_loss = None
      def forward(self, input):
           self.input = np.vstack([input, np.ones((1, input.shape[1]))]) # bias trick
           self.output= np.dot(self.weights, self.input)
            # Calculate the regularization loss
           #self.reg_loss = (self.reg_strength)*np.sum((self.weights**2) - (self.weights[:, -1]**2))
            #self.reg_loss = (self.reg_strength)*np.sum((self.weights[:, :-1]*self.weights[:, :-1]))
      def backward(self, output_gradient, learning_rate):
            ## Following is the inefficient way of calculating the backward gradient
            for b in range(output_gradient.shape[1]):
              weights_gradient += np.dot(output_gradient[:, b].reshape(-1, 1), self.input[:, b].reshape(-1, 1).T)
           weights_gradient = (1/output_gradient.shape[1])*weights_gradient''
           ## Following is the efficient way of calculating the backward gradient
           weights\_gradient = (1/output\_gradient.shape[1])*np.dot(np.atleast\_2d(output\_gradient), np.atleast\_2d(self.input).T) \\
            # add regularization gradient here weights should not contain bias weights
           weights_gradient += 2*self.reg_strength*np.hstack([self.weights[:, :-1], np.zeros((self.weights.shape[0], 1))])
            #weights_gradient += (1/output_gradient.shape[1])*np.dot(np.atleast_2d(output_gradient), np.atleast_2d(self.input).T)
           input_gradient = np.dot(self.weights.T, output_gradient)
            # Update weights using gradient descent step
            self.weights = self.weights + learning_rate * (-weights_gradient)
           return(input_gradient)
## Function to generate sample indices for batch processing according to batch size
def generate_batch_indices(num_samples, batch_size):
  # Reorder sample indices
  reordered_sample_indices = np.random.choice(num_samples, num_samples, replace = False)
   # Generate batch indices for batch processing
  batch_indices = np.split(reordered_sample_indices, np.arange(batch_size, len(reordered_sample_indices), batch_size))
   return(batch_indices)
learning_rate = 1e-1 # learning rate
batch_size = 100 # batch size
nepochs = 100 # number of epochs
reg_strength = 0
loss\_train\_epoch = np.empty(nepochs, dtype = np.float64) \# create empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty array to store training losses over each epoch empty empty expect expects the expect expects of the expect expect expects of the expect expect expects of the expect expects of the expect expect expects of the expect
loss_test_epoch = np.empty(nepochs, dtype = np.float64) # create empty array to store testing losses over each epoch
dlayer1 = Dense(num_features, 128, reg_strength=0) # define dense layer 1
alayer1 = ReLU() # ReLU activation layer 1
dropout1 = Dropout(probability_dropout=0.5)
dlayer2 = Dense(128, num_labels, reg_strength=0) # define dense layer 2
softmax = Softmax() # define softmax activation layer
      # Steps: run over each sample in the batch, calculate loss, gradient of loss,
      # and update weights.
epoch = 0
while epoch < nepochs:
  batch_indices = generate_batch_indices(num_samples, batch_size)
   loss = 0
   for b in range(len(batch_indices)):
   #Forward Propagation for training data
      {\tt dlayer1.forward(X\_train[:, batch\_indices[b]]) \# forward prop \ dense \ layer \ 1 \ with \ batch \ feature \ added}
      alayer1.forward(dlayer1.output) # forward prop activation layer 1
      dropout1.forward(alayer1.output) # dropout after layer 1
      dlayer2.forward(dropout1.output) # forward prop dense layer 2
      softmax.forward(dlayer2.output) # Softmax activate
      loss += cce(Y_train[:, batch_indices[b]], softmax.output) # calculate training data loss
   # Backward propagation for training data starts here
      grad = cce_gradient(Y_train[:, batch_indices[b]], softmax.output)
      grad = softmax.backward(grad)
      grad = dlayer2.backward(grad, learning_rate)
      grad = dropout1.backward(grad)
      grad = alayer1.backward(grad)
      grad = dlayer1.backward(grad, learning_rate)
   # Calculate average training loss for the current epoch
      loss_train_epoch[epoch] = loss/len(batch_indices)
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# Forward Propagation for test data
    dlayer1.forward(X_{test}) # forward prop dense layer 1 with batch feature added
    alayer1.forward(dlayer1.output) \# forward prop activation layer 1
    dlayer2.forward(alayer1.output) # forward prop dense layer 2
    softmax.forward(dlayer2.output) # Softmax activate
  # Calculate test data loss and Add regularization loss
    loss_test_epoch[epoch] = cce(Y_test, softmax.output)
   print('Epoch %d: training loss = %f test loss = %f'%(epoch+1, loss_train_epoch[epoch], loss_test_epoch[epoch]))
    epoch = epoch + 1
Epoch 1: training loss = 0.914136 test loss = 0.363347
Epoch 2: training loss = 0.407051 test loss = 0.275035
Epoch 3: training loss = 0.334474 test loss = 0.230061
Epoch 4: training loss = 0.291750 test loss = 0.202149
Epoch 5: training loss = 0.264158 test loss = 0.180719
Epoch 95: training loss = 0.069416 test loss = 0.072347
Epoch 96: training loss = 0.070380 test loss = 0.072125
Epoch 97: training loss = 0.068103 test loss = 0.071517
Epoch 98: training loss = 0.067580 test loss = 0.070613
Epoch 99: training loss = 0.067036 test loss = 0.072185
Epoch 100: training loss = 0.065866 test loss = 0.072736
# Plot training loss as a function of epoch:
plt.plot(loss_train_epoch, label = 'Training loss')
plt.plot(loss_test_epoch, label = 'Test loss')
plt.xlabel('Epoch')
plt.ylabel('Loss value')
plt.legend()
plt.show()
```

