

```
In [ ]: ## Load libraries
import pandas as pd
import numpy as np
import sys
import os
import matplotlib.pyplot as plt
import matplotlib.cm as cm
from keras.datasets import mnist
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler, RobustScaler, MinMaxScaler, On
from sklearn.pipeline import Pipeline
from sklearn.compose import ColumnTransformer
plt.style.use('dark_background')
%matplotlib inline
```

```
In [ ]: np.set_printoptions(precision=2)
```

```
In [ ]: import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
```

```
In [ ]: tf.__version__
```

```
Out[ ]: '2.15.0'
```

Mount Google Drive if running in Colab

```
In [ ]: ## Mount Google drive folder if running in Colab
if('google.colab' in sys.modules):
    from google.colab import drive
    drive.mount('/content/drive', force_remount = True)
    DIR = '/content/drive/MyDrive/Colab Notebooks/MAHE/MSIS Coursework/EvenSem20
    DATA_DIR = DIR + '/Data/'
    os.chdir(DIR)
else:
    DATA_DIR = 'Data/'
```

Load diabetes data

```
In [ ]: ## Load diabetes data
file = 'diabetes_regression1.csv'
df= pd.read_csv(file, header = 0)

print('Diabetes dataset')
print('-----')
print('Initial number of samples = %d'%(df.shape[0]))
print('Initial number of features = %d\n'%(df.shape[1]))
df.head(5)
```

Diabetes dataset

Initial number of samples = 442

Initial number of features = 11

```
Out[ ]:
```

	AGE	GENDER	BMI	BP	S1	S2	S3	S4	S5	S6	Y
0	59	2	32.1	101.0	157	93.2	38.0	4.0	4.8598	87	151
1	48	1	21.6	87.0	183	103.2	70.0	3.0	3.8918	69	75
2	72	2	30.5	93.0	156	93.6	41.0	4.0	4.6728	85	141
3	24	1	25.3	84.0	198	131.4	40.0	5.0	4.8903	89	206
4	50	1	23.0	101.0	192	125.4	52.0	4.0	4.2905	80	135

```
In [ ]: ## Create lists of ordinal, categorical, and continuous features
#categorical_features = ['GENDER', 'BMILEVEL']
categorical_features = ['GENDER']
continuous_features = df.drop(categorical_features, axis = 1).columns.tolist()
print(categorical_features)
print(continuous_features)
```

```
['GENDER']
```

```
['AGE', 'BMI', 'BP', 'S1', 'S2', 'S3', 'S4', 'S5', 'S6', 'Y']
```

Assign 'category' datatype to categorical columns

```
In [ ]: ## Assign 'category' datatype to ordinal and categorical columns
print(df.dtypes)
df[categorical_features] = df[categorical_features].astype('category')
print('----')
df.dtypes
```

```
AGE          int64
GENDER       int64
BMI          float64
BP           float64
S1           int64
S2           float64
S3           float64
S4           float64
S5           float64
S6           int64
Y            int64
```

```
dtype: object
```

```
----
```

```
Out[ ]: AGE          int64
        GENDER      category
        BMI         float64
        BP          float64
        S1          int64
        S2          float64
        S3          float64
        S4          float64
        S5          float64
        S6          int64
        Y           int64
dtype: object
```

Remove the target variable column from the list of continuous features

```
In [ ]: ## Remove the target variable column from the list of continuous features
        continuous_features.remove('Y')
```

```
In [ ]: ## Train and test split of the data
        X = df.drop('Y', axis = 1)
        y = df['Y']
        X_train, X_test, Y_train, Y_test = train_test_split(X, y, test_size = 0.2, random_state = 42)

        num_features = X_train.shape[0]
        num_samples = X_train.shape[1]

        print('Diabetes data set')
        print('-----')
        print('Number of training samples = %d'%(num_samples))
        print('Number of features = %d'%(num_features))
```

```
Diabetes data set
-----
Number of training samples = 10
Number of features = 353
```

Build pipeline for categorical and continuous features

```
In [ ]: ## Build pipeline for categorical and continuous features

        # Pipeline object for categorical (features)
        categorical_transformer = Pipeline(steps = [('onehotenc', OneHotEncoder(handle_unknown='ignore'))])

        # Pipeline object for continuous features
        continuous_transformer = Pipeline(steps = [('scaler', RobustScaler())])

        # Create a preprocessor object for all features
        preprocessor = ColumnTransformer(transformers = [('continuous', continuous_transformer, continuous_features),
                                                         ('categorical', categorical_transformer, categorical_features)],
                                         remainder = 'passthrough')
```

Fit and transform train data using preprocessor followed by transforming test data

```
In [ ]: ## Fit and transform train data using preprocessor
X_train_transformed = preprocessor.fit_transform(X_train).T
# Update number of features
num_features = X_train_transformed.shape[0]
# Transform training data using preprocessor
X_test_transformed = preprocessor.transform(X_test).T
# Convert Y_train and Y_test to numpy arrays
Y_train = Y_train.to_numpy()
Y_test = Y_test.to_numpy()
```

A generic layer class with forward and backward methods

```
In [ ]: class Layer:
    def __init__(self):
        self.input = None
        self.output = None

    def forward(self, input):
        pass

    def backward(self, output_gradient, learning_rate):
        pass
```

Mean squared error (MSE) loss and its gradient

```
In [ ]: ## Define the Loss function and its gradient
def mse(Y, Yhat):
    return(np.mean(0.5*(Y - Yhat)**2))
#TensorFlow in-built function for mean squared error loss
#mse = tf.keras.losses.MeanSquaredError()
#mse(Y, Yhat).numpy()

def mse_gradient(Y, Yhat):
    return(Yhat - Y)
```

Generic activation layer class

```
In [ ]: class Activation(Layer):
    def __init__(self, activation, activation_gradient):
        self.activation = activation
        self.activation_gradient = activation_gradient

    def forward(self, input):
        self.input = input
        self.output = self.activation(self.input)
        return(self.output)
```

```
def backward(self, output_gradient, learning_rate = None):
    return(output_gradient[:,-1, :] * self.activation_gradient(self.input))
```

Specific activation layer classes

```
In [ ]: class Sigmoid(Activation):
    def __init__(self):
        def sigmoid(z):
            return 1 / (1 + np.exp(-z))

        def sigmoid_gradient(z):
            a = sigmoid(z)
            return a * (1 - a)

        super().__init__(sigmoid, sigmoid_gradient)

class Tanh(Activation):
    def __init__(self):
        def tanh(z):
            return np.tanh(z)

        def tanh_gradient(z):
            a = np.tanh(z)
            return 1 - a**2

        super().__init__(tanh, tanh_gradient)

class ReLU(Activation):
    def __init__(self):
        def relu(z):
            return z * (z > 0)

        def relu_gradient(z):
            return 1. * (z > 0)

        super().__init__(relu, relu_gradient)
```

Dense layer class

```
In [ ]: ## Dense Layer class
class Dense(Layer):
    def __init__(self, input_size, output_size, reg_strength):
        self.weights = 0.01*np.random.randn(output_size, input_size+1) # bias tr
        self.weights[:, -1] = 0.01 # set all bias values to the same nonzero con
        self.reg_strength = reg_strength
        self.reg_loss = None

    def forward(self, input):
        self.input = np.vstack([input, np.ones((1, input.shape[1]))]) # bias tri
        self.output = np.dot(self.weights, self.input)
        # Calculate regularization loss
        self.reg_loss = self.reg_strength * np.sum(self.weights[:, :-1] * self.w
```

```

def backward(self, output_gradient, learning_rate):
    ## Following is the inefficient way of calculating the backward gradient
    #weights_gradient = np.zeros((self.output.shape[0], self.input.shape[0]))
    #for b in range(output_gradient.shape[1]):
    # weights_gradient += np.dot(output_gradient[:, b].reshape(-1, 1), self
    #weights_gradient = (1/output_gradient.shape[1])*weights_gradient

    ## Following is the efficient way of calculating the weights gradient w.
    weights_gradient = (1/output_gradient.shape[1])*np.dot(np.atleast_2d(out
    # Add the regularization gradient here
    weights_gradient += 2 * self.reg_strength * np.hstack([self.weights[:, :

    input_gradient = np.dot(self.weights.T, output_gradient)
    self.weights = self.weights + learning_rate * (-weights_gradient)

    return(input_gradient)

```

Function to generate sample indices for batch processing according to batch size

```

In [ ]: ## Function to generate sample indices for batch processing according to batch s
def generate_batch_indices(num_samples, batch_size):
    # Reorder sample indices
    reordered_sample_indices = np.random.choice(num_samples, num_samples, replace
    # Generate batch indices for batch processing
    batch_indices = np.split(reordered_sample_indices, np.arange(batch_size, len(r
    return(batch_indices)

```

Train the 3-layer neural network (8/8/1 structure) using batch training with batch size = 16

```

In [ ]: ## Train the 2-hidden layer neural network (8 nodes, 8 nodes followed by 1 node)
## using batch training with batch size = 100
learning_rate = 1e-04 # Learning rate
batch_size = 32 # batch size
nepochs = 10000 # number of epochs
reg_strength = 1.0 # regularization strength
# Create empty array to store training losses over each epoch
loss_train_epoch = np.empty(nepochs, dtype = np.float64)
# Create empty array to store test losses over each epoch
loss_test_epoch = np.empty(nepochs, dtype = np.float64)

# Neural network architecture

dlayer1 = Dense(num_features, 16, reg_strength) # define dense layer 1
alayer1 = Tanh() # ReLU activation layer 1
dlayer2 = Dense(16, 1, reg_strength) # define dense layer 2

# Steps: run over each sample in the batch, calculate loss, gradient of loss,
# and update weights.

```

```

epoch = 0
while epoch < nepochs:
    batch_indices = generate_batch_indices(num_samples, batch_size)
    loss = 0
    for b in range(len(batch_indices)):
        # Forward propagation for training data
        dlayer1.forward(X_train_transformed[:, batch_indices[b]]) # forward prop den
        alayer1.forward(dlayer1.output) # forward prop activation layer 1
        dlayer2.forward(alayer1.output) # forward prop dense layer 2
        # Calculate training data loss
        loss += mse(Y_train[batch_indices[b]], dlayer2.output)
        # Add the regularization losses
        loss += dlayer1.reg_loss + dlayer2.reg_loss

        # Backward prop starts here
        grad = mse_gradient(Y_train[batch_indices[b]], dlayer2.output)
        grad = dlayer2.backward(grad, learning_rate)
        grad = alayer1.backward(grad)
        grad = dlayer1.backward(grad, learning_rate)
    # Calculate the average training loss for the current epoch
    loss_train_epoch[epoch] = loss/len(batch_indices)

    # Forward propagation for test data
    dlayer1.forward(X_test_transformed)
    alayer1.forward(dlayer1.output)
    dlayer2.forward(alayer1.output)

    # Calculate test data loss plus regularization loss
    loss_test_epoch[epoch] = mse(Y_test, dlayer2.output) + dlayer1.reg_loss + dlayer2.reg_loss

    print('Epoch %d: train loss = %f, test loss = %f'%(epoch+1, loss_train_epoch[epoch], loss_test_epoch[epoch]))
    epoch = epoch + 1

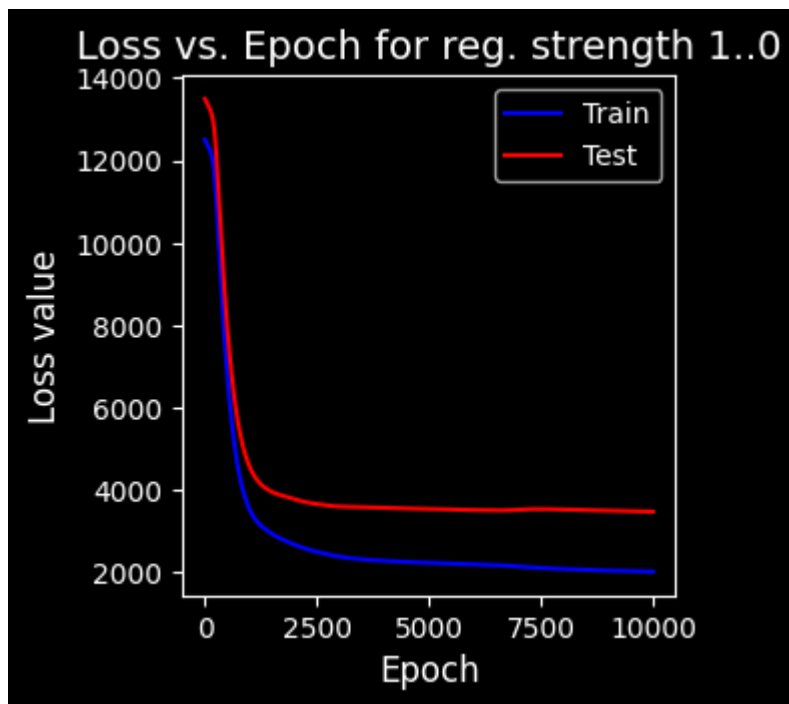
```

Plot training loss vs. epoch

```

In [ ]: # Plot train and test loss as a function of epoch:
fig, ax = plt.subplots(1, 1, figsize = (4, 4))
fig.tight_layout(pad = 4.0)
ax.plot(loss_train_epoch, 'b', label = 'Train')
ax.plot(loss_test_epoch, 'r', label = 'Test')
ax.set_xlabel('Epoch', fontsize = 12)
ax.set_ylabel('Loss value', fontsize = 12)
ax.legend()
ax.set_title('Loss vs. Epoch for reg. strength 1..0', fontsize = 14);

```



Test performance on test data

```
In [ ]: dlayer1.forward(X_test_transformed)
        alayer1.forward(dlayer1.output)
        dlayer2.forward(alayer1.output)
        ypred = dlayer2.output.flatten()
        ytrue = Y_test
```

Define neural network architecture for regression

```
In [ ]: # Define neural network architecture for regression
        model = keras.Sequential([
            layers.Dense(16, activation='relu', input_shape=(X_train_transformed.T.shape[1],)),
            layers.Dense(1)
        ])
```

```
In [ ]: model = keras.Sequential([
        layers.Dense(16, activation='relu', input_shape=(X_train_transformed.T.shape[1],)),
        layers.Dense(32, activation='relu'),
        layers.Dense(64, activation='relu'),
        layers.Dense(1)
    ])
```

Compile the neural network

```
In [ ]: # Compile the neural network model
        opt = tf.keras.optimizers.Adam(learning_rate = 1e-04)
        model.compile(optimizer = opt, loss = 'mean_squared_error')
```

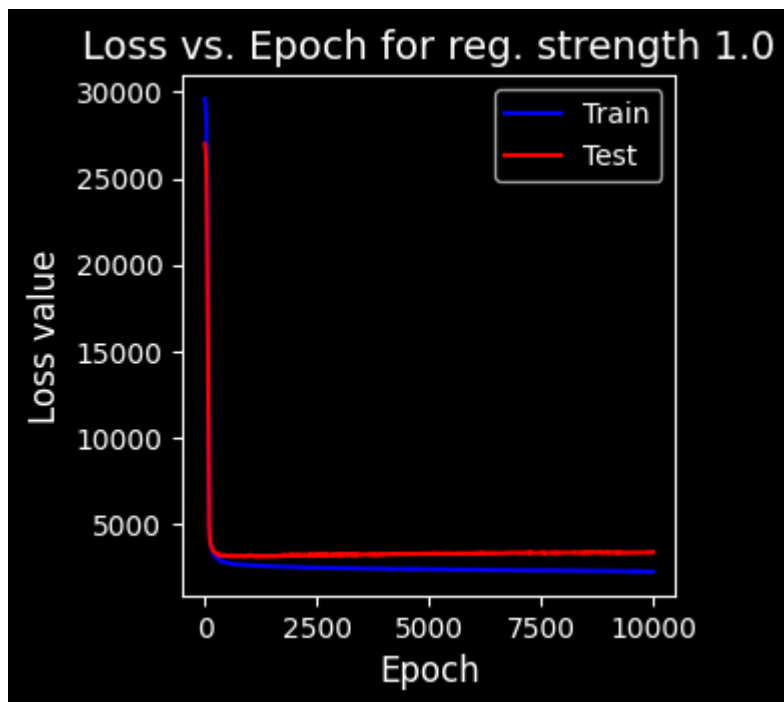
Train the model

```
In [ ]: # Train the model
history = model.fit(X_train_transformed.T, Y_train, epochs = 10000, batch_size =
```

Plot train and test loss as a function of epoch

```
In [ ]: # Plot train and test loss as a function of epoch:
fig, ax = plt.subplots(1, 1, figsize = (4, 4))
fig.tight_layout(pad = 4.0)
ax.plot( history.history['loss'], 'b', label = 'Train')
ax.plot( history.history['val_loss'], 'r', label = 'Test')
ax.set_xlabel('Epoch', fontsize = 12)
ax.set_ylabel('Loss value', fontsize = 12)
ax.legend()
ax.set_title('Loss vs. Epoch for reg. strength 1.0', fontsize = 14)
```

Out[]: Text(0.5, 1.0, 'Loss vs. Epoch for reg. strength 1.0')



Compare the true and predicted values

```
In [ ]: ## Compare the true and predicted values
ypred_TF = model.predict(X_test_transformed.T)
np.column_stack((Y_test, ypred, ypred_TF))
```

```
In [ ]: # sir madsid
b = 8 # batch size
nl = 10 # number of nodes in layer L
```

```
probability_dropout = 0.2 # probability of dropout

# simulate an activated scores matrix
z = np.random.randint(1, 20, ( n1, b))
print(z)
print('-----')

# dropout matrix
dropout_matrix = np.random.rand(z.shape[0], z.shape[1]) #< probability_dropout #
print(dropout_matrix)
print('-----')

# binary dropout matrix
binary_dropout_matrix = (dropout_matrix <(1- probability_dropout))
print(binary_dropout_matrix)
print('-----')
# dropout applied to the activated scores matrix
z = z * binary_dropout_matrix
print(z)
```

```

[[10  4  1  2  3 17 16 14]
 [19 18  6 10 11  2 19  8]
 [ 9  9  5  4 15 12  6 19]
 [13 12  7 19 13  7 14 10]
 [13  3 18 14 16  3 13 15]
 [19 18  2  8  4  7  4 18]
 [ 5  2 12  8  9  6  1 11]
 [18  1 18  5 11 15 11  1]
 [13  2 10 12 10 13 16 12]
 [ 1  6 12  6 18  1 19  1]]

-----

[[3.57e-01 9.76e-01 2.19e-01 6.14e-01 1.93e-02 3.72e-01 1.09e-01 9.51e-01]
 [1.14e-02 4.63e-01 5.56e-01 5.67e-01 4.55e-01 8.81e-01 8.33e-02 7.32e-01]
 [9.14e-01 7.05e-01 1.22e-01 8.25e-02 6.81e-01 1.96e-01 4.90e-01 8.22e-01]
 [1.09e-02 1.83e-01 1.68e-01 4.95e-01 8.44e-01 4.15e-01 9.48e-01 8.87e-02]
 [4.36e-01 9.23e-01 2.85e-01 8.91e-01 8.15e-01 4.88e-01 2.43e-01 4.42e-01]
 [6.76e-01 2.56e-02 4.14e-02 8.63e-01 3.70e-01 8.94e-01 8.60e-01 4.25e-01]
 [2.64e-01 9.26e-01 7.70e-01 8.70e-01 3.97e-01 7.00e-01 1.96e-01 7.54e-02]
 [1.35e-01 7.79e-01 3.07e-01 4.10e-01 6.08e-02 2.51e-01 3.39e-01 7.86e-01]
 [9.18e-01 5.47e-01 5.40e-01 7.18e-01 5.78e-01 6.37e-01 8.52e-01 2.43e-01]
 [6.05e-01 9.96e-01 8.68e-01 3.22e-04 3.65e-02 3.51e-01 5.03e-01 9.77e-01]]

-----

[[ True False  True  True  True  True  True False]
 [ True  True  True  True  True False  True  True]
 [False  True  True  True  True  True  True False]
 [ True  True  True  True False  True False  True]
 [ True False  True False False  True  True  True]
 [ True  True  True False  True False False  True]
 [ True False  True False  True  True  True  True]
 [ True  True  True  True  True  True  True  True]
 [False  True  True  True  True  True False  True]
 [ True False False  True  True  True  True False]]

-----

[[10  0  1  2  3 17 16  0]
 [19 18  6 10 11  0 19  8]
 [ 0  9  5  4 15 12  6  0]
 [13 12  7 19  0  7  0 10]
 [13  0 18  0  0  3 13 15]
 [19 18  2  0  4  0  0 18]
 [ 5  0 12  0  9  6  1 11]
 [18  1 18  5 11 15 11  1]
 [ 0  2 10 12 10 13  0 12]
 [ 1  0  0  6 18  1 19  0]]

```

```
In [ ]: z = (z * binary_dropout_matrix)/(1 - probability_dropout)
        print(z)
```

```

[[12.5  0.  1.25  2.5  3.75 21.25 20.  0. ]
 [23.75 22.5  7.5 12.5 13.75  0. 23.75 10. ]
 [ 0.  11.25 6.25  5.  18.75 15.  7.5  0. ]
 [16.25 15.  8.75 23.75  0.  8.75  0. 12.5 ]
 [16.25  0.  22.5  0.  0.  3.75 16.25 18.75]
 [23.75 22.5  2.5  0.  5.  0.  0. 22.5 ]
 [ 6.25  0.  15.  0. 11.25  7.5  1.25 13.75]
 [22.5  1.25 22.5  6.25 13.75 18.75 13.75  1.25]
 [ 0.  2.5 12.5 15. 12.5 16.25  0. 15. ]
 [ 1.25  0.  0.  7.5 22.5  1.25 23.75  0. ]]

```

```
In [ ]: # on house price dataset, lm model ge close iro ond model build madbeku
        # implement a dropout layer
```

```
# build a nn model to mnist dataset using tensorflow and keras use only dropout
# backward propogation madbeku
```

```
In [ ]: # Dropout layer class
class Dropout(Layer):

    def __init__(self, probability_dropout = 0.2):
        self.probability_dropout = probability_dropout
        self.dropout_matrix = None

    def forward(self, input):
        self.dropout_matrix = (np.random.rand(input.shape[0], input.shape[1]) <
        self.probability_dropout).astype('float32')
        self.dropout_matrix = (self.dropout_matrix < (1 - self.probability_dropout)).astype('float32')
        self.output = (input * self.dropout_matrix)/(1 - self.probability_dropout)
        return(self.output)

    def backward(self, output_gradient):
        return(self.dropout_matrix * output_gradient[:, :-1])
```

```
In [ ]: class Activation(Layer):
    def __init__(self, activation, activation_gradient):
        self.activation = activation
        self.activation_gradient = activation_gradient

    def forward(self, input):
        self.input = input
        self.output = self.activation(self.input)
        return(self.output)

    def backward(self, output_gradient, learning_rate = None):
        return(output_gradient[:, :-1, :] * self.activation_gradient(self.input))
```

```
In [ ]: ## Train the 2-hidden layer neural network (8 nodes, 8 nodes followed by 1 node)
## using batch training with batch size = 100
learning_rate = 0.5 # learning rate
batch_size = 100 # batch size
nepochs = 100 # number of epochs
reg_strength = 0 # regularization strength
# Create empty array to store training losses over each epoch
loss_train_epoch = np.empty(nepochs, dtype = np.float64)
# Create empty array to store test losses over each epoch
loss_test_epoch = np.empty(nepochs, dtype = np.float64)

# Neural network architecture

dlayer1 = Dense(num_features, 128, reg_strength) # define dense layer 1
alayer1 = ReLU() # ReLU activation layer 1
dropout1 = Dropout(probability_dropout=0.5) # dropout layer
dlayer2 = Dense(128, 1, reg_strength) # define dense layer 2

epoch = 0
while epoch < nepochs:
    batch_indices = generate_batch_indices(num_samples, batch_size)
    loss = 0
    for b in range(len(batch_indices)):
        # Forward propagation for training data
```

```

dlayer1.forward(X_train_transformed[:, batch_indices[b]]) # forward prop den
dlayer1.forward(dlayer1.output) # forward prop activation layer 1
dlayer2.forward(dlayer1.output) # forward prop dense layer 2
# Calculate training data loss
loss += mse(Y_train[batch_indices[b]], dlayer2.output)
# Add the regularization losses
loss += dlayer1.reg_loss + dlayer2.reg_loss

# Backward prop starts here
grad = mse_gradient(Y_train[batch_indices[b]], dlayer2.output)
grad = dlayer2.backward(grad, learning_rate)
grad = dlayer1.backward(grad)
grad = dlayer1.backward(grad, learning_rate)
# Calculate the average training loss for the current epoch
loss_train_epoch[epoch] = loss/len(batch_indices)

# Forward propagation for test data
dlayer1.forward(X_test_transformed)
dlayer1.forward(dlayer1.output)
dlayer2.forward(dlayer1.output)

# Calculate test data loss plus regularization loss
loss_test_epoch[epoch] = mse(Y_test, dlayer2.output) + dlayer1.reg_loss + dlayer2.reg_loss

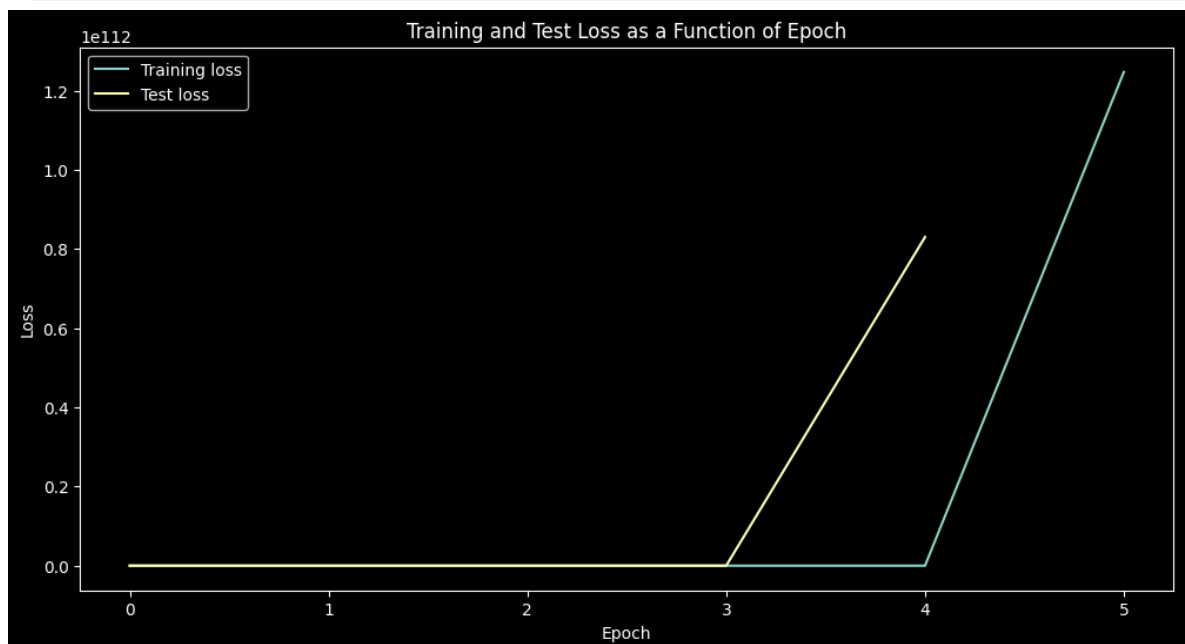
print('Epoch %d: train loss = %f, test loss = %f'%(epoch+1, loss_train_epoch[epoch], loss_test_epoch[epoch]))
epoch = epoch + 1

```

```

In [ ]: plt.figure(figsize=(12, 6))
plt.plot(loss_train_epoch, label='Training loss')
plt.plot(loss_test_epoch, label='Test loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title('Training and Test Loss as a Function of Epoch')
plt.legend()
plt.show()

```



```

In [ ]:

```