# Technical Documentation Avionics Bay Elpis MK IIb

#### Mytikas

### Hardware

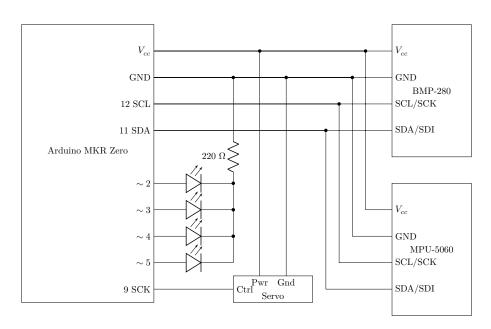
#### Components

Microcontroller Arduino MKR Zero

Barometer BMP 280 Accelerometer MPU 5060

Servo

#### Circuit diagram



## Pinmap

Printed name	Compiler name	Variable name	Use
$\overline{V_{cc}}$	n/a	n/a	Power supply voltage
GND	n/a	n/a	Ground
12  SCL	n/a	n/a	Clock signal for I <sup>2</sup> C
11 SDA	n/a	n/a	Data signal for I <sup>2</sup> C
9 SCK	9	SERVO_PIN	Signal for parachute servo
$\sim 2$	2	LED_PIN	Status LED
$\sim 3$	3	ERROR_LED_PIN	Error LED
$\sim 4$	4	LAUNCH_LED_PIN	Launch LED
$\sim 5$	5	CARD_LED_PIN	Card LED

## Software