## Assignment3QT1\_Only

```
install.packages("lpSolveAPI")
library(lpSolveAPI)
Let us set up the problem. Note that we have two decision variables, and three constraints. In the first
formulation, we will directly create the objective function and constraints
install.packages("lpSolveAPI")
## Warning: package 'lpSolveAPI' is in use and will not be installed
library(lpSolveAPI)
library(lpSolveAPI)
# make an lp object with 0 constraints and 9 decision variables
lprec <- make.lp(0, 9)</pre>
# Now create the objective function. The default is a minimization problem.
set.objfn(lprec, c(420, 360, 300, 420, 360, 300, 420, 360,300))
library(lpSolveAPI)
# As the default is a minimization problem, we change the direction to set maximization
lp.control(lprec, sense='max')
## $anti.degen
## [1] "fixedvars" "stalling"
## $basis.crash
## [1] "none"
## $bb.depthlimit
## [1] -50
## $bb.floorfirst
## [1] "automatic"
## $bb.rule
## [1] "pseudononint" "greedy"
                                       "dynamic"
                                                      "rcostfixing"
## $break.at.first
```

```
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
## $epsilon
##
         epsb
                    epsd
                               epsel
                                         epsint epsperturb
                                                              epspivot
##
        1e-10
                   1e-09
                               1e-12
                                          1e-07
                                                                 2e-07
                                                     1e-05
##
## $improve
## [1] "dualfeas" "thetagap"
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##
      1e-11
               1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
## $pivoting
## [1] "devex"
                  "adaptive"
## $presolve
## [1] "none"
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric"
                    "equilibrate" "integers"
##
## $sense
## [1] "maximize"
## $simplextype
## [1] "dual"
                "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"
# Add the three Squared Footage constraints
# Plant production by day
```

```
add.constraint(lprec,c(1,1,1,0,0,0,0,0,0), "<=",750)
add.constraint(lprec,c(0,0,0,1,1,1,0,0,0), "<=",900)
add.constraint(lprec,c(0,0,0,0,0,1,1,1), "\leq=",450)
#Land storage for products by day
add.constraint(lprec,c(20,15,12,0,0,0,0,0,0), "<=",13000)
add.constraint(lprec,c(0,0,0,20,15,12,0,0,0), "<=",12000)
add.constraint(lprec,c(0,0,0,0,0,0,20,15,12), "\leq=",5000)
#Sales for products by day
add.constraint(lprec,c(1,1,1,0,0,0,0,0,0), "\leq=",900)
add.constraint(lprec,c(0,0,0,1,1,1,0,0,0), "\leq=",1200)
add.constraint(lprec,c(0,0,0,0,0,1,1,1), "<=",750)
# plants with the same % capacity
add.constraint(lprec,c(6,6,6,-5,-5,-5,0,0,0), "=",0)
add.constraint(lprec,c(3,3,3,0,0,0,-5,-5,-5), "=",0)
RN<-c("Ccon1", "Ccon2", "Ccon3", "SCon1", "SCon2", "SCon3", "saCon1", "saCon2", "saCon3", "%C1", "%C2")
CN<-c("P1L","P1M","P1S","P2L","P2M","P2S","P3L","P3M","P3S")</pre>
dimnames(lprec)<-list(RN, CN)</pre>
lprec
## Model name:
   a linear program with 9 decision variables and 11 constraints
We now solve the above LP problem
"r
solve(lprec)
## [1] 0
get.objective(lprec)
## [1] 696000
get.variables(lprec)
## [1] 516.6667 177.7778
                           0.0000
                                     0.0000 666.6667 166.6667
                                                                 0.0000
                                                                          0.0000
## [9] 416.6667
```