## Assignment2QT#1

```
install.packages("lpSolveAPI")
library(lpSolveAPI)
Let us set up the problem. Note that we had two decision variables, and three constraints. In the first
formulation, we will directly create the objective function and constraints
install.packages("lpSolveAPI")
## Warning: package 'lpSolveAPI' is in use and will not be installed
library(lpSolveAPI)
# make an lp object with 0 constraints and 2 decision variables
lprec <- make.lp(0, 2)</pre>
# Now create the objective function. The default is a minimization problem.
set.objfn(lprec, c(32, 24))
# As the default is a minimization problem, we change the direction to set maximization
lp.control(lprec,sense='max')
## $anti.degen
## [1] "fixedvars" "stalling"
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
## $bb.rule
## [1] "pseudononint" "greedy"
                                       "dynamic"
                                                       "rcostfixing"
##
## $break.at.first
## [1] FALSE
## $break.at.value
```

```
## [1] 1e+30
##
## $epsilon
##
                                      epsint epsperturb epspivot
        epsb
                   epsd
                              epsel
##
        1e-10
                   1e-09
                              1e-12
                                         1e-07
                                                    1e-05
                                                               2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
## $infinite
## [1] 1e+30
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##
     1e-11 1e-11
##
## $negrange
## [1] -1e+06
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex"
                  "adaptive"
## $presolve
## [1] "none"
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric" "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual" "primal"
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"
# Add the three Plant constraints
add.constraint(lprec, c(3, 2), "<=", 5000)
add.constraint(lprec, c(45, 4), "<=", 84000)
```

```
# Set bounds for variables.
# that all variables had to be non-negative. We don't need to to do it here, as that is the default,
# we can set bounds explicitly
set.bounds(lprec,lower=c(0, 0),columns=c(1, 2)) #Not really needed
# To identify the variables and constraints, we can
\# set variable names and name the constraints
RowNames<-c("Plant1","Plant2")</pre>
ColNames<-c("Product1", "Product2")</pre>
dimnames(lprec)<-list(RowNames,ColNames)</pre>
# Now, print out the model
lprec
## Model name:
##
             Product1 Product2
## Maximize
               32
## Plant1
                   3
                              2 <=
                                       5000
## Plant2
                   45
                              4 <= 84000
## Kind
                  Std
                            Std
## Type
                 Real
                           Real
## Upper
                  Inf
                            Inf
## Lower
                    0
                               0
We now solve the above LP problem
solve(lprec)
## [1] 0
get.objective(lprec)
## [1] 60000
get.variables(lprec)
```

0 2500

## [1]