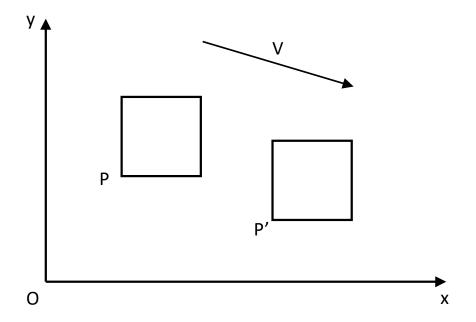
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B-MAT-100

• Create a function that takes two numbers x and y and returns a 3x1 vector in homogeneous coordinates:

$$\begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

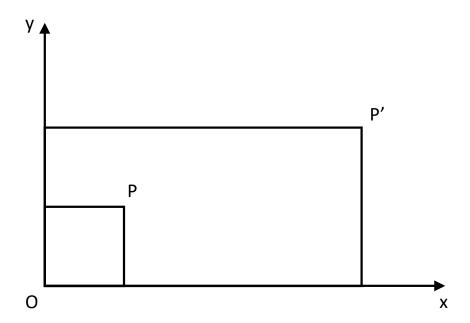
• Create a function that takes two number i and j and return a translation matrix



Translation along vector V(i, j)

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & i \\ 0 & 1 & j \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

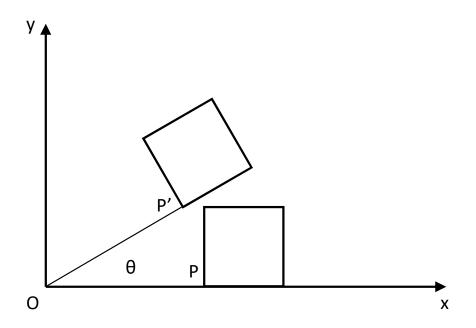
 \bullet Create a function that takes two numbers m and n and return a scaling matrix



Scaling by factors m and n

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} m & 0 & 0 \\ 0 & n & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

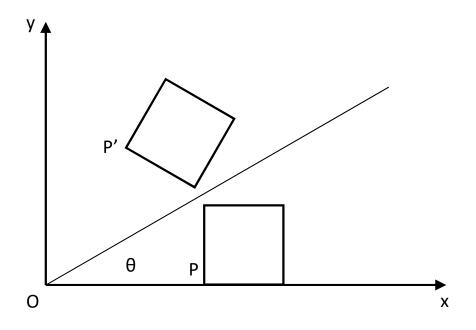
• Create a function that takes a number and return a rotation matrix



Rotation centered in O

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

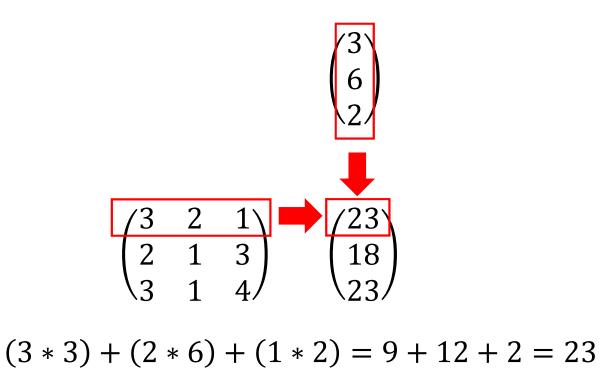
• Create a function that takes a number and return a reflection matrix



Reflection over an axis

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} \cos 2\theta & \sin 2\theta & 0 \\ \sin 2\theta & -\cos 2\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} * \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

• Create a function that multiplies a 3x3 matrix with a 3x1 vector



Create a function that multiplies two matrices

