

ELC 2137 Lab 11: FSM Guessing Game

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Summary

This lab's purpose is to get a better understanding of the role of finite state machines (FSM), the difference between a Mealy output and a Moore output, how to implement state in Verilog. First part of the lab is to implement guess_FSM module to the given guessing game state diagram. Next, board module is implemented to convert guess_FSM module output to the seven-segment display output. Then, the counter module is modified to output only a tick instead of the two most significant numbers. Finally, guessing_game module is implemented using debounce module for the buttons, counter modules to adjust the difficulty of the game, guess_FSM as logic, and board module to output to the board. Afterward, create test file for guess_FSM, and guessing_game, then test the game using the Basys3 board.

Simulation Waveform

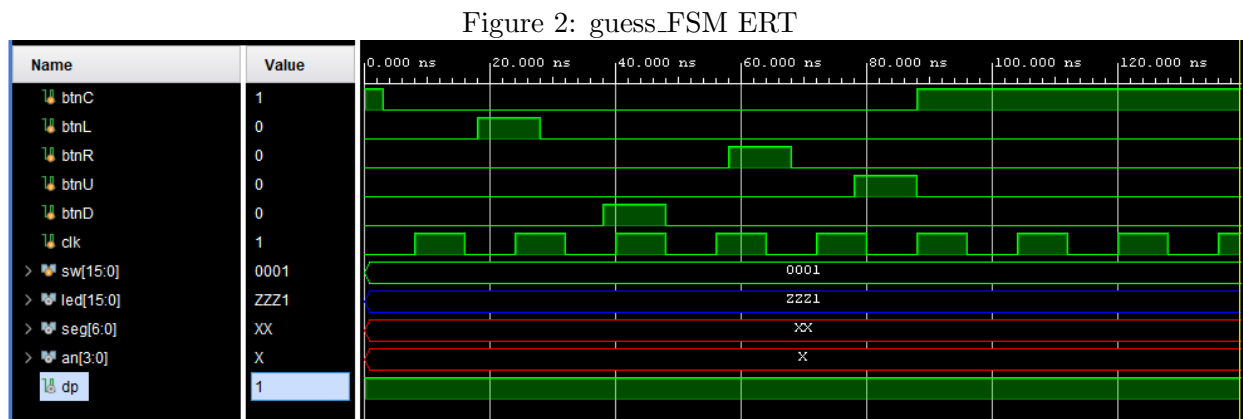
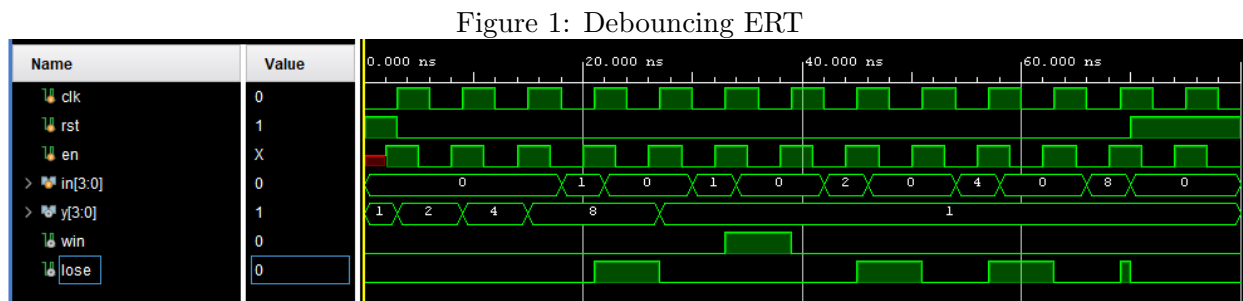
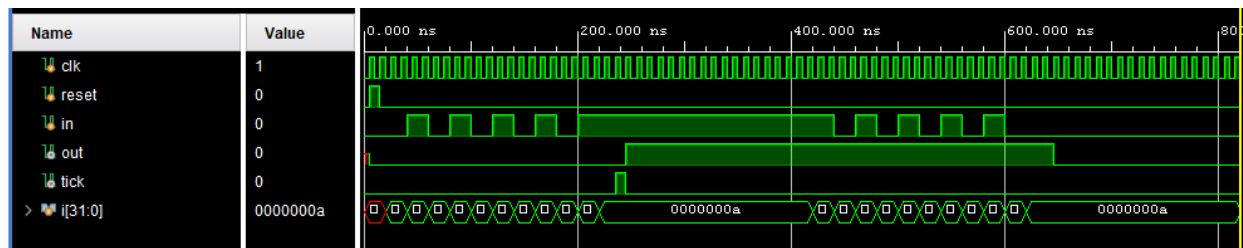
Code

Listing 1: debounce Test Bench

```
#20 in=~in;
end
// hold input = 1 for a while
in = 1; #200;
// bounce
for (i=0; i<10; i=i+1) begin
    #20 in=~in;
end
// hold input = 0 for a while
in = 0; #200;
$finish;
end
endmodule // debounce_test
```

Listing 2: guess_FSM Implementation

```
module guess_FSM(
    input clk, rst, en,
    input [3:0] in, //buttons
    output reg [3:0] y, // led[3:0]
    output reg win, lose // indicator of win and lose
);
    localparam [2:0]
        s0 = 3'b000,
```



```
s1 = 3'b001,
s2 = 3'b011,
s3 = 3'b010,
swin  = 3'b110,
slope = 3'b111;

// internal signals
reg [2:0] state, state_next;

// state memory (register)
always @(posedge clk, posedge rst)
    if (rst)
        state <= s0;
    else if (en) // need an en to modulate the ticks
        state <= state_next;

// combined next-state and output logic
always @* begin
```

```

// default behavior
state_next = state;
win = 1'b0;
lose = 1'b0;

case(state)
  //s0 state
  s0: begin
    y = 4'b0001;
    if (in == y)
      state_next = swin;
    else if (in == 4'b0000)
      state_next = s1;
    else
      state_next = slose;
  end
  //s1 state
  s1: begin
    y = 4'b0010;
    if (in == y)
      state_next = swin;
    else if (in == 4'b0000)
      state_next = s2;
    else
      state_next = slose;
  end
  //s2 state
  s2: begin
    y = 4'b0100;
    if (in == y)
      state_next = swin;
    else if (in == 4'b0000)
      state_next = s3;
    else
      state_next = slose;
  end
  //s3 state
  s3: begin
    y = 4'b1000;
    if (in == y)
      state_next = swin;
    else if (in == 4'b0000)
      state_next = s0;
    else
      state_next = slose;
  end
  //win state
  swin: begin
    win = 1'b1; // set win state to 1
    if (in == 4'b0000)
      state_next = s0;
    else
      state_next = swin;
  end
end

```

```

        //lose state
    slose: begin
        lose = 1'b1; //set lose state to 1
        if (in == 4'b0000)
            state_next = s0;
        else
            state_next = slose;
        end
    endcase
end
endmodule

```

Listing 3: guess_FSM Test Bench

```

module test_guess_FSM();
    reg clk, rst, en;
    reg [3:0] in; //buttons
    wire [3:0] y; // led[3:0]
    wire win, lose; // led[15:14] // counter for how many time win/lose

    guess_FSM dut(
        .clk(clk),
        .rst(rst),
        .en(en),
        .in(in),
        .y(y),
        .win(win),
        .lose(lose)
    );

    //clk and en module
    always begin
        clk = ~clk ; #2;
        en = clk - 1; #1;
    end

    initial begin
        clk = 0; rst = 1; in = 4'b0000; #3;
        rst = 0; #15; //set up the initial condition
        in = 4'b0001; #4; // pressing the first button which loses
        in = 4'b0000; #8; // wait for the next guess
        in = 4'b0001; #4; // pressing the first button which wins
        in = 4'b0000; #8; // wait for the next guess
        in = 4'b0010; #4; // pressing the second button which loses
        in = 4'b0000; #8; // wait for the next guess
        in = 4'b0100; #4; // pressing the third button which loses
        in = 4'b0000; #8; // wait for the next guess
        in = 4'b1000; #4; // pressing the fourth button which loses
        in = 4'b0000; rst = 1; #10; //rest everything
        $finish;
    end
end
endmodule

```

Listing 4: guessing_game Implementation

```

module guessing_game(
    input btnC, btnL, btnR, btnU, btnD, clk,
    input [15:0] sw,
    output [15:0] led,
    output [6:0] seg,
    output [3:0] an,
    output dp
);

    //debouncing the buttons
    wire [3:0] tmp;
    wire [3:0] debounced_buttons;
    debounce #(.N(21)) debounce0(
        .clk(clk),
        .reset(btnC),
        .in(btnL),
        .out(debounced_buttons[0]),
        .tick(tmp[0])
    );

    debounce #(.N(21)) debounce1(
        .clk(clk),
        .reset(btnC),
        .in(btnD),
        .out(debounced_buttons[1]),
        .tick(tmp[1])
    );

    debounce #(.N(21)) debounce2(
        .clk(clk),
        .reset(btnC),
        .in(btnR),
        .out(debounced_buttons[2]),
        .tick(tmp[2])
    );

    debounce #(.N(21)) debounce3(
        .clk(clk),
        .reset(btnC),
        .in(btnU),
        .out(debounced_buttons[3]),
        .tick(tmp[3])
    );

    //creating two counter of different size for mux2 element
    wire counter_in0;
    count #(.N(25)) c0(
        .clk(clk),
        .en(1'b1),
        .rst(btnC),
        .tick(counter_in0)
    );

```

```

wire counter_in1;
count #(.N(23)) c1(
    .clk(clk),
    .en(1'b1),
    .rst(btnC),
    .tick(counter_in1)
);

//mux2 element sending out signal for guess_FSM
wire mux_guess;
mux2 #(.BITS(1)) mux0(
    .sel(sw[0]), //use to adjust difficulty
    .in1(counter_in1),
    .in0(counter_in0),
    .out(mux_guess)
);

wire win, lose;
guess_FSM main(
    .clk(clk),
    .rst(btnC),
    .en(mux_guess),
    .in(debounced_buttons),
    .y(led[3:0]),
    .win(win),
    .lose(lose)
);

board b(
    .win(win),
    .lose(lose),
    .clk(clk),
    .en(mux_guess),
    .rst(btnC),
    .seg(seg),
    .an(an),
    .dp(dp)
);
endmodule

```

Listing 5: guessing_game Test Bench

```

module test_guessing_game();
    reg btnC, btnL, btnR, btnU, btnD, clk;
    reg [15:0] sw;
    wire [15:0] led;
    wire [6:0] seg;
    wire [3:0] an;
    wire dp;

    guessing_game dut(
        .btnC(btnC),
        .btnL(btnL),
        .btnR(btnR),

```

```

        .btnU(btnU),
        .btnD(btnD),
        .clk(clk),
        .sw(sw),
        .led(led),
        .seg(seg),
        .an(an),
        .dp(dp)
    );

    //clk and en module
    always begin
        clk = ~clk ; #8;
    end
    initial begin
        clk = 0; sw = 16'h0001; btnC = 1'b1; btnL = 1'b0; btnD = 1'b0;
        btnR = 1'b0; btnU = 1'b0;#3;
        btnC = 0; #15; //set up the initial condition
        btnL = 1'b1; btnD = 1'b0; btnR = 1'b0; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b0; btnR = 1'b0; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b1; btnR = 1'b0; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b0; btnR = 1'b0; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b0; btnR = 1'b1; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b0; btnR = 1'b0; btnU = 1'b0; #10;
        btnL = 1'b0; btnD = 1'b0; btnR = 1'b0; btnU = 1'b1; #10;
        btnC = 1'b1; btnL = 1'b0; btnD = 1'b0; btnR = 1'b0; btnU = 1'b0
            ;#10;
    end
endmodule

```

Data List

Table 1: Lists of Games Played

Game	N = 25	N = 23
1	win	win
2	lose	win
3	win	lose
4	lose	win
5	lose	lose
6	lose	lose
7	win	win
8	lose	win
9	lose	win
10	lose	lose
Winrate	30%	60%

Q&A

1. In the simulation the debounce circuit reach each of the four states around 621ns

2. This game can't be implemented using sequential logic because the game state must run independently from the the buttons and the output, if not, the game will be very glitchy.
3. I used both Mealy and Moore output for my design. I used Moore output to control the led indicating which state the program was in, because there is no further condition needed for it to be true. For everything else like determining the next state, and win/lose condition, I used Mealy output. I did this because there are multiple variable that needed to consider when determining next state for guess_FSM, because a button could reset the state, get the correct guess or the wrong guess. Meanwhile, for my "board" module, Moore output is also used to determine next state since it need win/lose flag to do so.