Requirements:

* Thermal Fluid Outlet Temperatre MUST stay between 680-700K
* Cooling Medium enters jacket @ 600K
* Require steady minimum methanol production of 1 kmol/h after 10s
* Control flow rate, everything else is disturbance
* Reactant inlet flow rate 80 kmol/h
* Cooling medium flow rate 400 kmol/h
* Reactant inlet temp 760K +/- 30 K
* Cooling Medium inlet temperature +/- 30K

Assume network of FOPTD transfer functions g11, g12, g21 and g22 between Reactant Flowrate (RF), Coolant Flowrate (CF), Methanol Flowrate (MF) and Coolant Outlet Temperature (CT).

Notes on Step Tests for Reactant Flow Rate effecting Methanol flow via g11 and coolant outlet temp via g21

* Average time delay for g11 is 4.431s, average time constant is 6.149s.
* Both of these values vary polynomially with the step change. Time delay seems to vary via 3rd order polynomial, time constant via 5th order.
* Average gain is around 1, and this does not vary substantially
* Try first with just average time delay/ time constant, then try adjusting these values based on input
* Average time delay for g21 is 4.430s, average time constant is 5.909s.
* These values also vary according to a 3rd/5th order polynomial respectively.
* Average gain is 0.667 and this varies minimally

Note: At this point I discovered that the methanol output was out by a factor of 100. This means that the gain of g11 should be 0.01.

Notes on Step Tests for Coolant Flow Rate effecting Methanol flow via g12 and coolant outlet temp via g22

* Seems to be no effect of CF on MF, g12 = 0
* Average time delay for g22 is 4.165s, average gain is -0.138 (inverse response as expected)
* Time constant varies, average is 3.045s including one anomalous value. Excluding this value brings the average to 2.949s and the values approximate a 2nd order polynomial trend.

Version 1 does not work, the feedback controllers simply continue to increase the flowrates. (NB controllers tuned using SIMC). Version 2 also does not work, the addition of gc3 gives some weird behaviour. As expected, control more complex than simple feedback loops are required.

One last thing to try with the simple feedback approach will be to account for the varying time delays and time constants, dynamically calculating the SIMC tuning parameters (probably won’t work)

Whilst Programming version 3, realised that the PI controllers were not set to ideal. This was changed, but had little effect.

Also somehow my spreadsheet had reverted to having the wrong gain for g11 (not accounting for the fact it was out by a factor of 100). Adjusting this allowed version 1 to reach the set points, however the transient was inadequate. Version 2 also now reaches the correct steady state but has an (even worse) transient.

Version 3 did not work, avoid using variable parameters. Next avenue should be to build on version 1 (probably the best version so far) with smith predictors.

Smith predictors might do something with the steady-state, but the transient is still inadequate. For version 5 I’ll experiment using Cohen-coon PI tuning and version 6 I’ll use cohen-coon PID.

Version 5 Still takes over 30 seconds to reach steady state. I also suspect the scope is currently in the wrong place.

To begin with version 6, I added a max module to ensure that flowrates could not go negative, as this was something I was seeing. The system still took longer than 30 seconds to reach steady state, and much longer than 10 seconds to reach 1kmol/h methanol.

The implementation of PID made the system unstable. As an experiment I reverted to PI control but kept the PID tuning parameters, the result was much more oscillatory than before.

Two more things I want to try at this point are feedforward control, and cascade control (which on further thought probably wouldn’t work). Feedforward would require step tests in the disturbances to determine their transfer functions, which will be time consuming so I’ll try that tomorrow.

For version 7 I will take version 5 and use SIMC tuning with lambda = 3Td. The result takes much longer to reach steady state, indicating cohen-coon is the better tuning method. Thus I returned to cohen-coon tuning and varied the parameters to see if any improvement could be made. The best parameters I could find still took ~30 seconds for MF to reach 1kmol/h. The inverse response may effect this, as could the fact I’ve neglected g21.

For fun, I implemented a harsh step change of +30K in both temperatures at 60s to see how my tuned controller fared. Although the system went out of range, it quickly returned and I was impressed. However I’d ideally like to avoid going outside at all for pertubations in the range of +/- 30K. Running the same disturbance with the original cohen-coon params, the system took longer to return.

To improve further I could add feedforward or include g21. Version 9 will do the latter, using a cohen-coon tuned PI controller as a basis with a smith predictor accounting for g21, and version 10 will seek to further tune gc3. Version 9 shows a significant improvement in terms of speed, but perhaps a little bit less stable.

Unhappy with this instability, version 10 originally returned all controllers to their cohen-coon parmeters. This was even worse, so a compromise is evidently needed. I further tuned all 3 controllers until I was happy.

Of course, saving of the files went tits up so version 9 doesn’t actually have this controller. I can’t seem to recreate my initial success so have reverted to not accounting for g21, instead only controlling g11 & g22. In version 11 I will try incorporate g21 into my smith predictor. This shows some improvement.

One thing that occurred to me is that the methanol flowrate is to be maximised; nothing specifies that the set point needs to be 1kmol/h. I initially tried changing the set point to 2kmol/h, however this led to a highly oscillatory transient and inadequate response to a strong pertubation. 1.5 was acceptable, so I set the set point to 1.4 kmol/h to be sure.

Version 11 reached 1 kmol/h production rate in 10s and entered the temperature range in 18s. Version 12 makes this controller fit the test.

Testing version 12 is ok, but the controller still falls out of range on occasion. I may try when I next have time to run some other versions with the test to see how they fare. Perhaps going back to a less-tuned version and increasing the MF set point is worth a try. I should try ZN tuning, could look at MPC, and could try ff control mayhaps.

Considering that I started at 2:30, I took 9 hours to produce a controller that works as well if not better than our original one. bruh. (excluding 1-2 hours for dinner etc, and 3-4 hours were step tests).