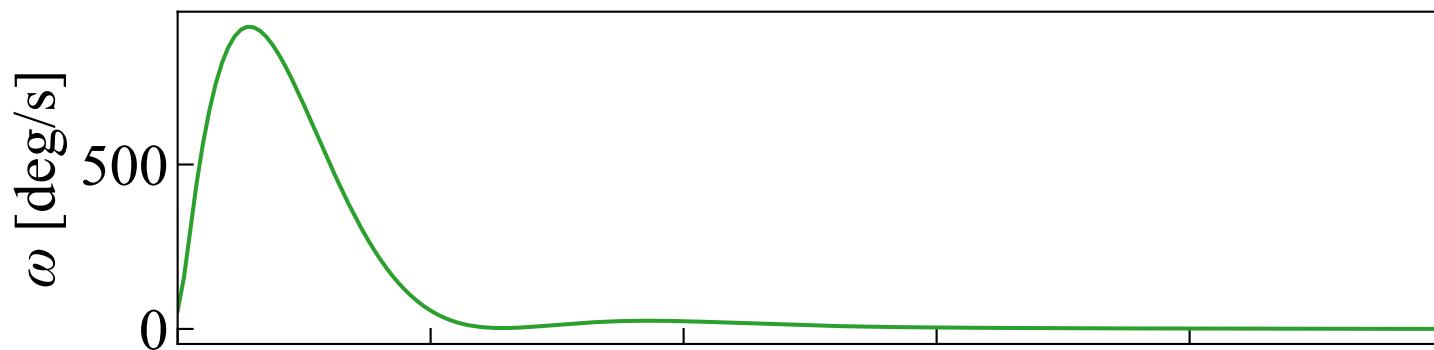
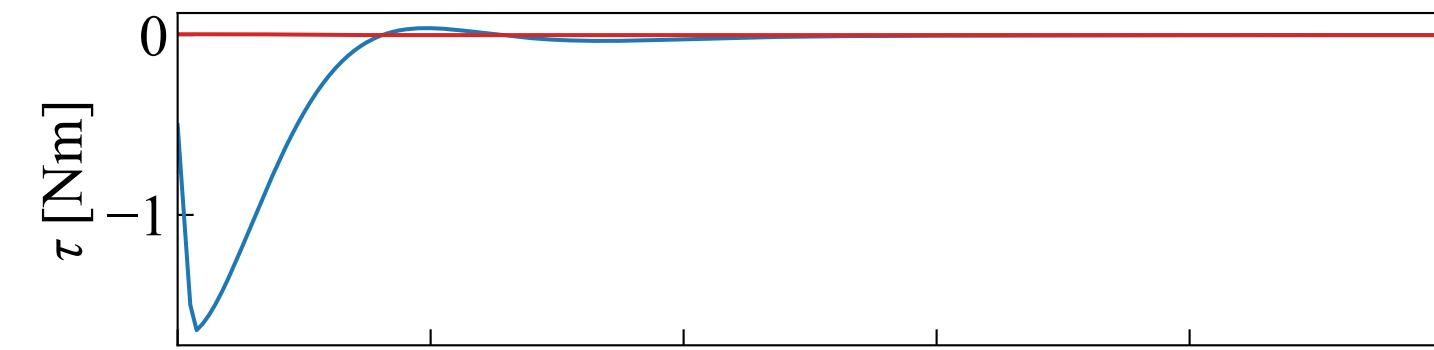


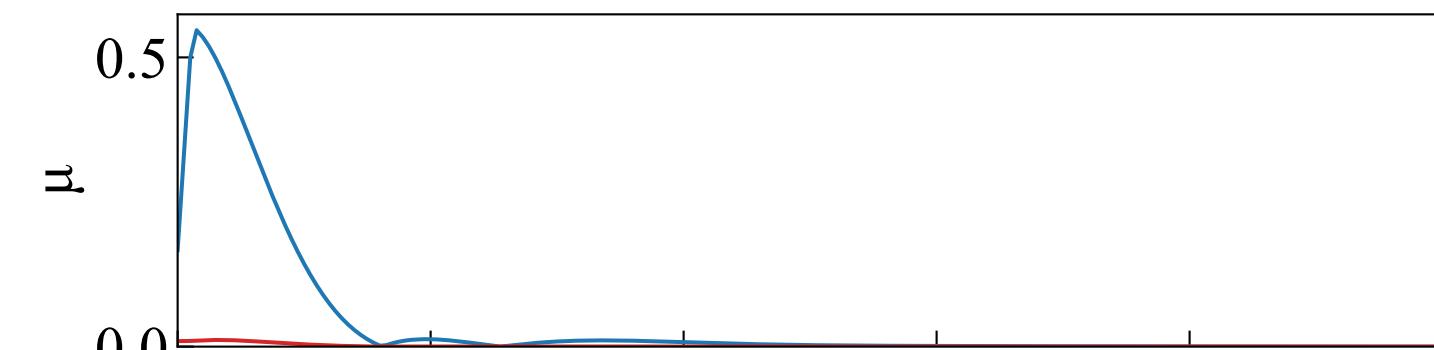
θ_{ref}
 θ_{out}



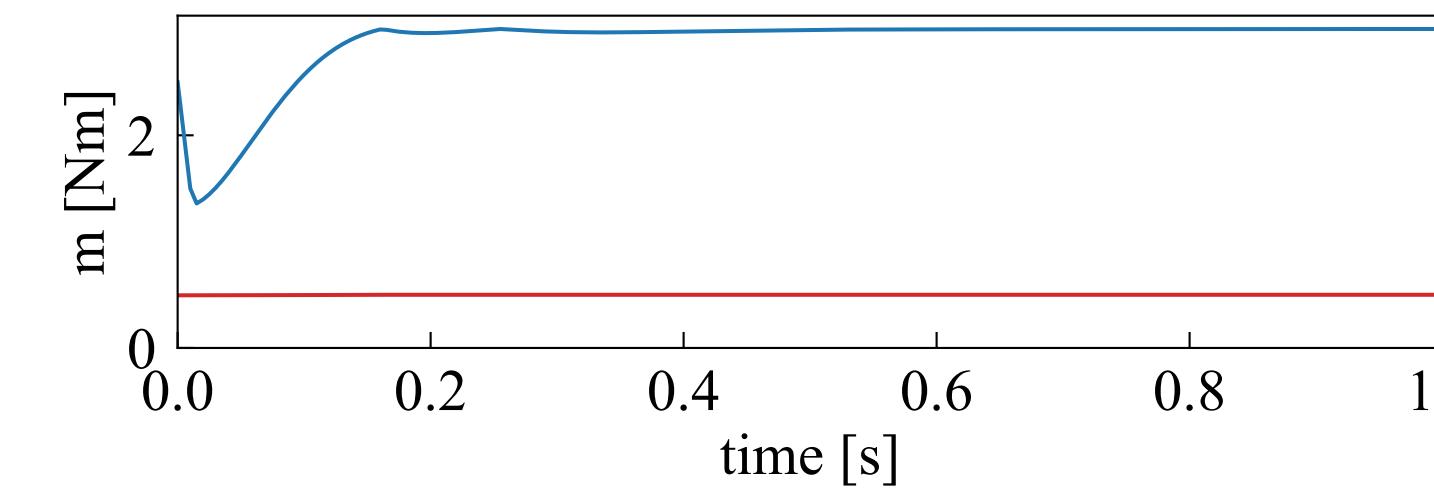
ω_{out}



τ_1
 τ_2



motor1
motor2



motor1
motor2