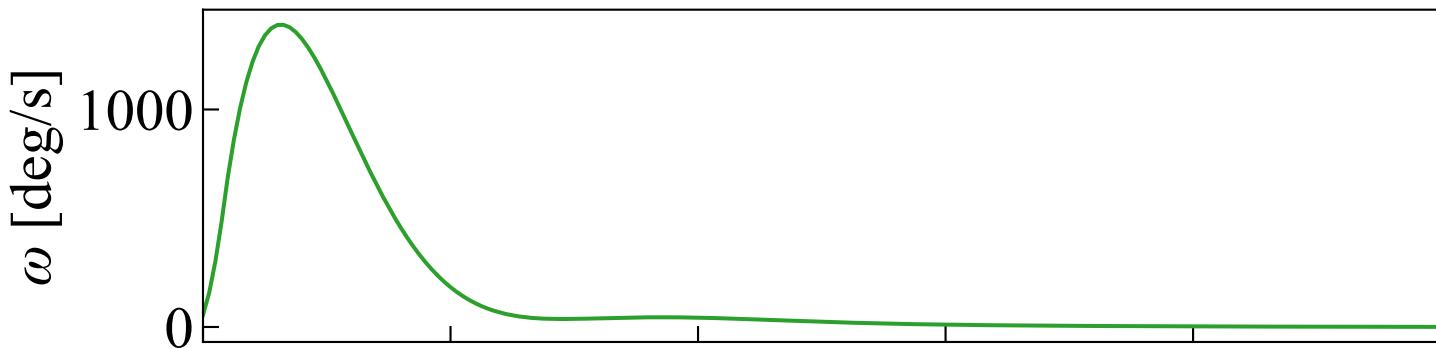


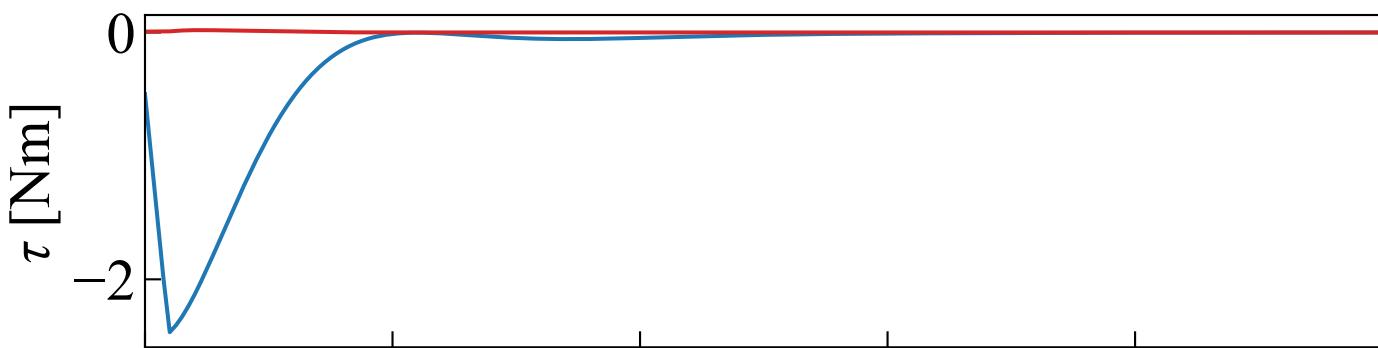
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$\theta_{\text{ref}}$   
 $\theta_{\text{out}}$



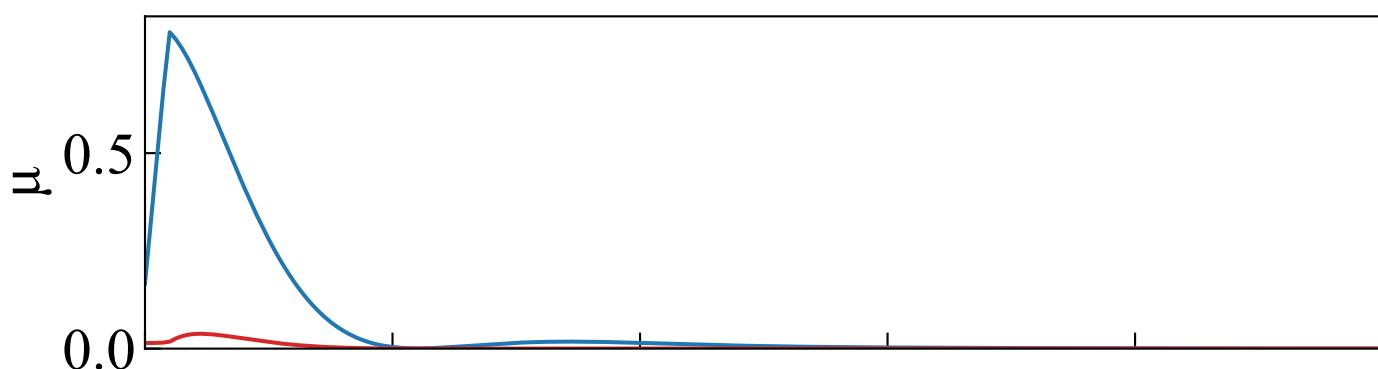
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$\omega_{\text{out}}$



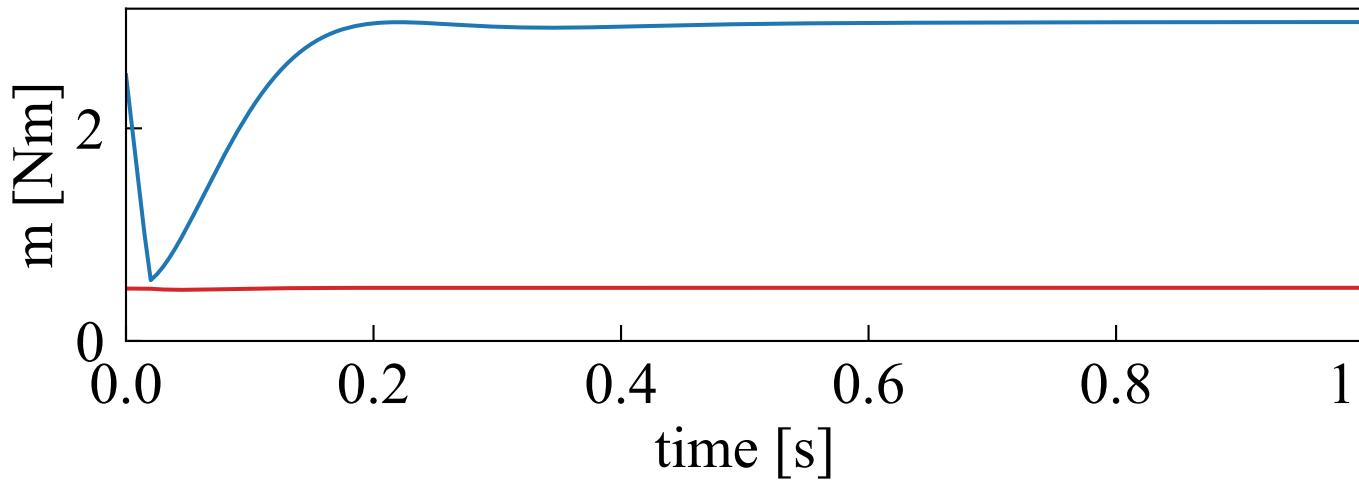
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$\tau_1$   
 $\tau_2$



—  
—

motor1  
motor2



—  
—

motor1  
motor2

time [s]