Position Tracking Error
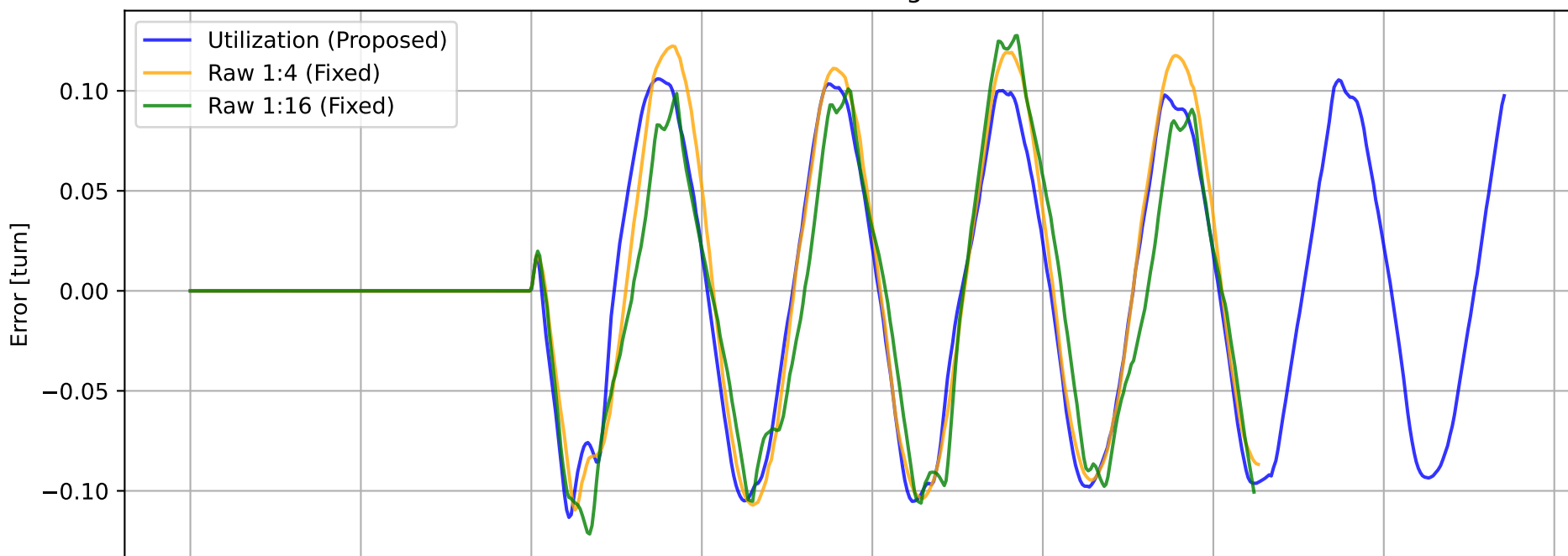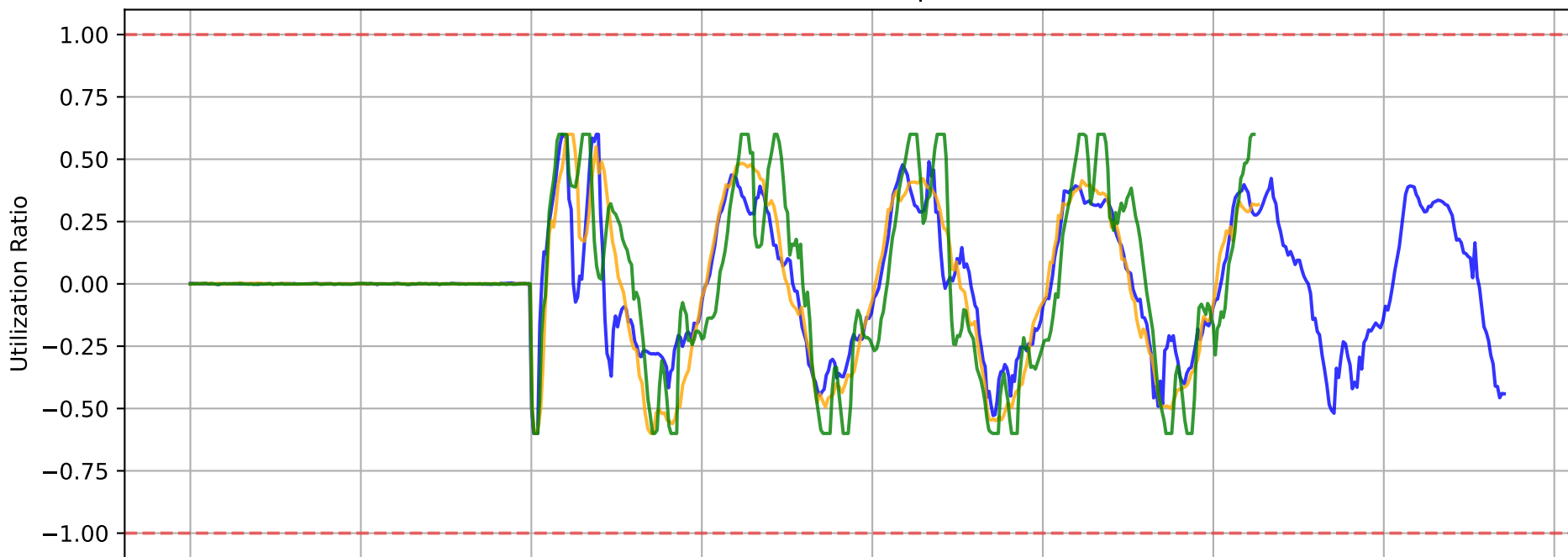
Motor 1 Utilization (Torque / 1.0 Nm)

Motor 2 Utilization (Torque / 0.5 Nm)