

Segment Tree and Lazy Propagation

beOI Training



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Motivating problem

You are given an integer array A of size n ($n < 10^6$).

Given two integers a and b , can you give the minimum value of A between indices a and b ?

$$\min_{i=a\dots b} A[i]$$

Well that's easy, just iterate over the interval and return the minimum!

Motivating problem

You are given an integer array A of size n ($n < 10^6$).
Given two integers a and b , can you give the minimum value of A between indices a and b ?

$$\min_{i=a \dots b} A[i]$$

100000 times?

This is called the **range minimum query** (RMQ) problem.

Naive solution

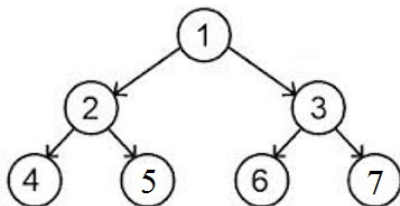
For each query, iterate over the corresponding range and return the minimum.

If k is the number of queries, time complexity is $\mathcal{O}(nk)$.

TLE

Array representation of a binary tree

- ▶ 1-based array, index 1 = root
- ▶ For each node of index p ,
 - ▶ left child has index $2p$
 - ▶ right child has index $2p + 1$



Segment Tree

Each node is responsible of one segment

Root represents the whole array $[0 \cdots n - 1]$

Given a node representing segment $[l \cdots r]$

- ▶ left child represents the segment's first half $[l \cdots \frac{l+r}{2}]$
- ▶ right child represents the segment's second half $[\frac{l+r}{2} + 1 \cdots r]$

The value of a node will be the **index of the minimum element in segment** $[l \cdots r]$.

Querying

When we query the minimum value in an interval, we look for **big segments that are contained within the query range**, and among those segments, take the minimum value.

Recursively,

- ▶ segment is within query range \Rightarrow return value of the node;
- ▶ segment and query range are disjoint \Rightarrow do nothing;
- ▶ otherwise, return minimum among both children.

Querying implementation

```
// p is array index of current node,  
// [L..R] is current segment,  
// [i..j] is search interval  
int query(int p, int L, int R, int i, int j) {  
    // inside query range  
    if(L >= i && R <= j) return st[p];  
    // outside query range  
    if(i > R || j < L) return -1;  
  
    // compute the min position in the left  
    // and right part of the interval  
    int p1 = query(2*p, L, (L+R)/2, i, j);  
    int p2 = query(2*p+1, (L+R)/2+1, R, i, j);  
  
    // if we try to access segment outside query  
    if(p1 == -1) return p2;  
    if(p2 == -1) return p1;  
    return (A[p1] <= A[p2]) ? p1 : p2;  
}
```

Querying complexity

At each level, at most 4 nodes are visited (see coach for proof).

There are exactly $\lceil \log_2 n \rceil$ levels.

$$\mathcal{O}(4 \times \lceil \log_2 n \rceil) = \mathcal{O}(\log n)$$

Overall complexity $\mathcal{O}(k \log n)$ is now reasonable!

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Building

Building the Segment Tree is also done recursively.

For each node,

- ▶ if no child, store current index;
- ▶ otherwise,
 - ▶ build left child;
 - ▶ build right child;
 - ▶ store minimum child.

Building implementation

```
void build(int p, int L, int R) {  
    if(L == R)  
        // leaf node  
        st[p] = L;  
    else {  
        // build children  
        build(2*p, L, (L+R)/2);  
        build(2*p+1, (L+R)/2+1, R);  
        // take minimum among them  
        int p1 = st[2*p], p2 = st[2*p+1];  
        st[p] = (A[p1] <= A[p2]) ? p1 : p2;  
    }  
}
```

Building complexity

We visit every node once.

In general, the number of nodes is

$N + \frac{N}{2} + \frac{N}{4} + \cdots + 2 + 1 \approx 2N$, so time complexity is

$$\mathcal{O}(2 \times N) = \mathcal{O}(N)$$

This also proves memory is $\mathcal{O}(N)$ (in practice one always takes an array of $4 \times N$ for safety).

Segment Trees are extremely powerful!

We saw how to solve the range **minimum** query problem.
But we can do much more than that!

- ▶ Range maximum query
- ▶ Range sum query
- ▶ Range *insert any function here* query

One last operation

Suppose that, between queries, the array is being **updated**.
Naive solution: re-build the Segment Tree in $\mathcal{O}(N)$.

TLE

Segment Trees allow efficient **updating**!

Updating

To update p , we only need to update the segments that contain p .

Update the leaf to root path in $\mathcal{O}(\log N)$!

Updating implementation

```
// i is the node that is to be updated
void update(int p, int L, int R, int i) {
    // if leaf node
    if(L == R) return;
    // if i is in segment
    if(i >= L && i <= R) {
        // if new value is smaller, update
        if(A[i] <= st[p])
            st[p] = i;
        update(2*p, L, (L+R)/2, i);
        update(2*p+1, (L+R)/2+1, R, i);
    }
}
```

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Motivating problem

In the Range Sum Query (RSQ) problem, we add one operation: range update.

We want to update a range (e.g. increment every value in range by k) efficiently.

Naive solution

At each range update query, re-build tree in $\mathcal{O}(N)$.

TLE

Let's be lazy!

Key idea behind lazy Segment Tree: don't update everything at once; put a flag on segments that need to be updated, and leave it for another traversal.

Propagation

Keep an array `lazy` that stores for each segment by how much each value needs to be incremented.

Every time we visit a node p (in query or update) where `lazy[p] != 0`,

- ▶ increment current segment by `lazy[p]` times size of segment;
- ▶ if node is not leaf,
 - ▶ increment `lazy[2*p]` by `lazy[p]`
 - ▶ increment `lazy[2*p+1]` by `lazy[p]`
- ▶ reset `lazy[p]`.

That is called **propagation**.

Obviously, complexity is $\mathcal{O}(1)$.

Propagation implementation

```
void propagate(int p, int L, int R) {  
    if (lazy[p] != 0) {  
        st[p] += (L-R+1)*lazy[p];  
  
        if (L != R) {  
            lazy[2*p] += lazy[p];  
            lazy[2*p+1] += lazy[p];  
        }  
  
        lazy[p] = 0;  
    }  
}
```

Querying

We do exactly the same, but we propagate at each node!
Complexity $\mathcal{O}(\log N)$.

Querying implementation

```
int query(int p, int L, int R, int i, int j) {  
    propagate(p, L, R);  
  
    if(i > R || j < L) return 0;  
    if(L >= i && R <= j) return st[p];  
  
    return query(2*p, L, (L+R)/2, i, j)  
        + query(2*p+1, (L+R)/2+1, i, j);  
}
```

Updating

For each node,

- ▶ propagate
- ▶ if outside of range, return
- ▶ if inside of range, set the lazy flag, and return
- ▶ otherwise
 - ▶ update left child
 - ▶ update right child
- ▶ merge both children (add them up)

Complexity $\mathcal{O}(\log N)$.

Updating implementation

```
void update(int p, int L, int R, int i, int j, int k) {  
    propagate(p, L, R);  
  
    if (i > R || j < L) return;  
    if (L >= i && R <= j) {  
        lazy[p] = k;  
        return;  
    }  
  
    update(2*p, L, (L+R)/2, i, j, k);  
    update(2*p+1, (L+R)/2+1, R, i, j, k);  
  
    st[p] = st[2*p] + st[2*p+1];  
}
```