

All pairs Shortest path

Robin Jadoul



March 13, 2016

Table of Contents

Floyd-Warshall

Applications

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :
- ▶ For every pair of nodes (u, v) :

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :
- ▶ For every pair of nodes (u, v) :
- ▶ Can the distance between these pairs be improved by going to k first?

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :
- ▶ For every pair of nodes (u, v) :
- ▶ Can the distance between these pairs be improved by going to k first?
- ▶ $g[u][v] = \min(g[u][v], g[u][k] + g[k][v])$

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :
- ▶ For every pair of nodes (u, v) :
- ▶ Can the distance between these pairs be improved by going to k first?
- ▶ $g[u][v] = \min(g[u][v], g[u][k] + g[k][v])$
- ▶ Very easy implementation (4 lines)

Floyd-Warshall

All pairs Shortest path

- ▶ Adjacency matrix
- ▶ For every node k :
- ▶ For every pair of nodes (u, v) :
- ▶ Can the distance between these pairs be improved by going to k first?
- ▶ $g[u][v] = \min(g[u][v], g[u][k] + g[k][v])$
- ▶ Very easy implementation (4 lines)
- ▶ $O(|V|^3) \Rightarrow$ feasible for up to approx. 400 nodes

Floyd-Warshall

All pairs Shortest path

- ▶ Reconstructing the path:

Floyd-Warshall

All pairs Shortest path

- ▶ Reconstructing the path:
- ▶ Use another $|V| \times |V|$ matrix *parent*

Floyd-Warshall

All pairs Shortest path

- ▶ Reconstructing the path:
- ▶ Use another $|V| \times |V|$ matrix *parent*
- ▶ $parent[u][v]$ = The last node before v on the shortest path from u to v

Floyd-Warshall

All pairs Shortest path

- ▶ Reconstructing the path:
- ▶ Use another $|V| \times |V|$ matrix *parent*
- ▶ $parent[u][v]$ = The last node before v on the shortest path from u to v
- ▶ Update when improving a path ($parent[u][v] = parent[k][v]$)

Floyd-Warshall

All pairs Shortest path

- ▶ Reconstructing the path:
- ▶ Use another $|V| \times |V|$ matrix *parent*
- ▶ $parent[u][v]$ = The last node before v on the shortest path from u to v
- ▶ Update when improving a path ($parent[u][v] = parent[k][v]$)
- ▶ Traverse the *parent chain* upwards

Floyd-Warshall

Alternative

- ▶ Repeated execution of Dijkstra's algorithm

Floyd-Warshall

Alternative

- ▶ Repeated execution of Dijkstra's algorithm
- ▶ $O(|V| \times |E| \times \log |V|)$

Floyd-Warshall

Alternative

- ▶ Repeated execution of Dijkstra's algorithm
- ▶ $O(|V| \times |E| \times \log |V|)$
- ▶ Better on sparse graphs ($|E| \ll |V|^2$)

Table of Contents

Floyd-Warshall

Applications

All pairs Shortest path

Applications

- Compute the transitive closure

$$close[u][v] = close[u][v] \vee (close[u][k] \wedge close[k][v])$$

All pairs Shortest path

Applications

- ▶ Compute the transitive closure

$$close[u][v] = close[u][v] \vee (close[u][k] \wedge close[k][v])$$

- ▶ Minimax of the graph: The path with minimal highest cost along the path

$$g[u][v] = \min(g[u][v], \max(g[u][k], g[k][v]))$$

All pairs Shortest path

Applications

- ▶ Compute the transitive closure
$$close[u][v] = close[u][v] \vee (close[u][k] \wedge close[k][v])$$
- ▶ Minimax of the graph: The path with minimal highest cost along the path
$$g[u][v] = \min(g[u][v], \max(g[u][k], g[k][v]))$$
- ▶ Maximin of the graph: The path with maximal lowest cost along the path
$$g[u][v] = \max(g[u][v], \min(g[u][k], g[k][v]))$$

All pairs Shortest path

Applications

- ▶ Compute the transitive closure
$$close[u][v] = close[u][v] \vee (close[u][k] \wedge close[k][v])$$
- ▶ Minimax of the graph: The path with minimal highest cost along the path
$$g[u][v] = \min(g[u][v], \max(g[u][k], g[k][v]))$$
- ▶ Maximin of the graph: The path with maximal lowest cost along the path
$$g[u][v] = \max(g[u][v], \min(g[u][k], g[k][v]))$$
- ▶ Safest path: the path with highest survival probability (weights are probs along the edge)
$$g[u][v] = \max(g[u][v], g[u][k] * g[k][v])$$

All pairs Shortest path

Applications

- ▶ Compute the transitive closure
$$close[u][v] = close[u][v] \vee (close[u][k] \wedge close[k][v])$$
- ▶ Minimax of the graph: The path with minimal highest cost along the path
$$g[u][v] = \min(g[u][v], \max(g[u][k], g[k][v]))$$
- ▶ Maximin of the graph: The path with maximal lowest cost along the path
$$g[u][v] = \max(g[u][v], \min(g[u][k], g[k][v]))$$
- ▶ Safest path: the path with highest survival probability (weights are probs along the edge)
$$g[u][v] = \max(g[u][v], g[u][k] * g[k][v])$$
- ▶ Most dangerous path: the path with lowest survival probability (weights are probs along the edge)
$$g[u][v] = \min(g[u][v], g[u][k] * g[k][v])$$

All pairs Shortest path

Applications

- ▶ Detecting negative weight cycles

All pairs Shortest path

Applications

- ▶ Detecting negative weight cycles
- ▶ Run the normal *Floyd-Warshall* algorithm

All pairs Shortest path

Applications

- ▶ Detecting negative weight cycles
- ▶ Run the normal *Floyd-Warshall* algorithm
- ▶ If any element on the diagonal becomes negative \Rightarrow negative weight cycle found