

# Single source Shortest path

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BFS

Dijkstra

Bellman-Ford

Path reconstruction

# BFS

## Breath First Search

- ▶ Unweighted graphs
- ▶ Works with a queue (*First in - First out*)
- ▶ Take the next unexplored node from the frontier
- ▶ Goal reached: shortest path found
- ▶ Refer to *Unit 14 - Graph traversals*
- ▶  $O(|V| + |E|)$

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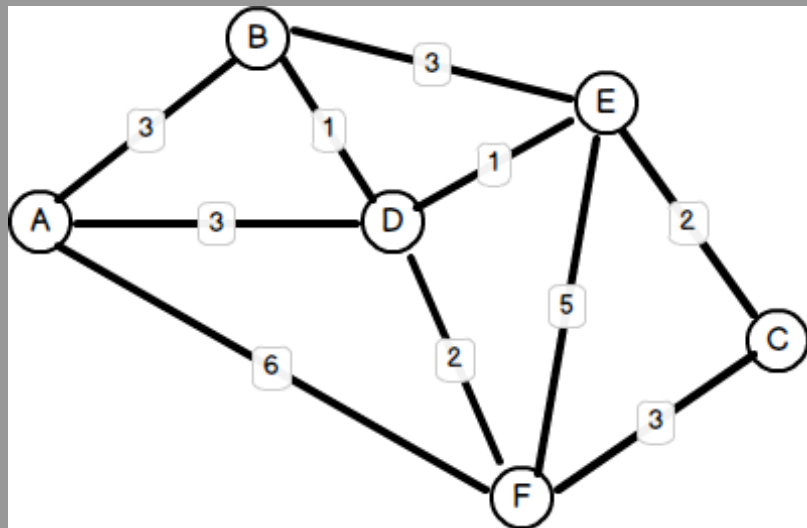
# Dijkstra

## Single source Shortest path

- ▶ Weighted graphs
- ▶ Doesn't work with negative edges / cycles
- ▶ Works with a priority queue (*min-heap*)
- ▶ Only add to the heap if shorter than current shortest = a *relax* operation
- ▶ Don't process again (cf. BFS)

# Dijkstra

Example



# Dijkstra

## Extra remarks

- ▶ Degrades to BFS on unweighted graphs
  - ▶ all distances from start needed → don't stop until everything is visited
  - ▶ This is the *greedy* approach
  - ▶  $O(|E| \times \log |V|)$
- 
- ▶ Why do negative weights fail?

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# Bellman-Ford

## Single source Shortest path

- ▶ Weighted graphs - with negative weights
- ▶ Can detect negative weight cycles
- ▶ No special datastructure needed
- ▶ Keep the current minimal distance from the start to each node
- ▶  $|V| - 1$  times:
  - ▶ Relax every edge
$$dist[v] = \min(dist[v], dist[u] + weight[u, v])$$
- ▶ After  $|V| - 1$  iterations: every minimal distance from source found
- ▶  $O(|V||E|)$

# Bellman-Ford

## Negative weight cycle detection

- ▶ Run the normal Bellman-Ford algorithm
- ▶ Do one more iteration
- ▶ If the iteration finds a shorter path  $\Rightarrow$  a negative weight cycle was found

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# Path reconstruction

## Breath First Search

- ▶ For all these algorithms
- ▶ Keep mapping *parent*
- ▶ When expanding/relaxing to node  $v$ :
- ▶  $parent[v] =$  the node from where you came
- ▶ Goal found  $\Rightarrow$  move up the *parent chain* until the starting node