

# BeOI training - carnival 2015

## Data structures II

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19 février 2015

# A short reminder

A short reminder

Sets and Maps

Heaps

Union find

Segment Trees

Fenwick Tree

Sparse table

# You should already know...

- Arrays
- Linked Lists
- Stack & Queues

# Array

- Keys :  $\{0, \dots, n - 1\}$
- Access in  $\mathcal{O}(1)$
- Modify in  $\mathcal{O}(1)$

With dynamic array (`ArrayList` or `std::vector`),  $n$  is not fixed.

- Add in amortized  $\mathcal{O}(1)$
- Remove in  $\mathcal{O}(n)$  if not at the end

# Linked list

- Access and modify in  $\mathcal{O}(n)$
- Modify and modify in  $\mathcal{O}(1)$  at extremities
- Add and remove in  $\mathcal{O}(1)$

# Stack and Queue

Specific Linked List (a bit faster and limited capability)

**Stack** LIFO, Last in First out.

```
1 Stack<Integer> s = new Stack<Integer>();  
2 q.push(1);  
3 int top = q.peek(); // just watch  
4 top = q.pop();
```

**Queue** FIFO, First in First out.

```
1 Queue<Integer> q = new LinkedList<Integer>();  
2 q.add(1);  
3 int first = q.peek(); // just watch  
4 first = q.poll();
```

# Sets and Maps

A short reminder

Sets and Maps

Some definitions

Hash maps & sets

Binary Search Tree

Heaps

Union find

Segment Trees

Fenwick Tree

Sparse table

# Sets

"A collection that contains no duplicate elements" (Java 7 doc)

Three main actions :

- Add element
- Delete element
- Check presence of element



# Maps

"An object that maps keys to values. A map cannot contain duplicate keys; each key can map to at most one value." (Java 7 doc)

Four main actions :

- Add (key,value) pair
- Delete value from its key
- Check presence of value by its key
- Get value from its key

# Overview of the implementations

## Unique key

	sorted	unsorted
existence	<code>std::set</code> <code>TreeSet</code>	<code>std::unordered_set</code> <code>HashSet</code>
association	<code>std::map</code> <code>TreeMap</code>	<code>std::unordered_map</code> <code>HashMap</code>
complexity	$\mathcal{O}(\log(n))$	$\mathcal{O}(1)$ on average

## Different elements can have the same key

	sorted	unsorted
existence	<code>std::multiset</code>	<code>std::unordered_multiset</code>
association	<code>std::multimap</code>	<code>std::unordered_multimap</code>
complexity	$\mathcal{O}(\log(n))$	$\mathcal{O}(1)$ on average

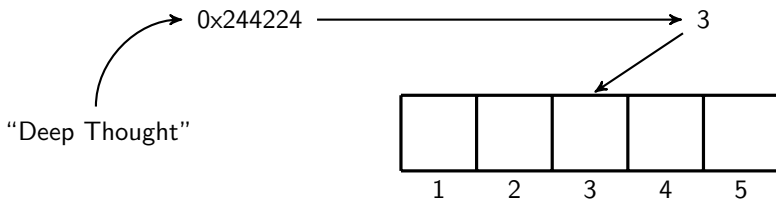
# Hash maps I

## Principle

There is a number  $N$  of buckets. The key is mapped to a bucket by hashing it to a number between 0 and  $N - 1$ .

1. Transform the key to a number  $k$  of type `size_t`;
2. Get that number between 0 and  $N - 1$  (e.g.  $k \pmod N$ );
3. Access the bucket with that index.

For now,  $\mathcal{O}(1)$ !



# Hash maps II

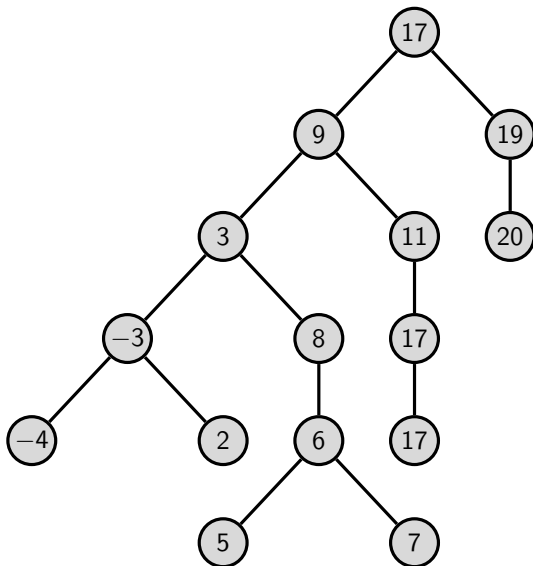
## Collision

But there can be collision so it is  $\mathcal{O}(1)$  on average! In case of collision, 2 solutions

- Store in each bucket all the collisions ;
- Probe a empty spot (linear probing, quadratic probing, ...).

It is only  $\mathcal{O}(1)$  on average if the load factor is good (e.g.  $\ll 1$ ). When load factor get close to 1, increase  $N$ .

# Binary Search Tree I



# Binary Search Tree II

To get  $\mathcal{O}(\log(n))$

- Balanced
- Comparison in  $\mathcal{O}(1)$  (strings have  $\mathcal{O}(m \log(n))$  where  $m$  is their length)
- Balancing operation in  $\log(n)$

Balanced trees are tricky to code! Use `std::set`, `TreeSet` and `std::map`, `TreeMap`!

# Array, TreeMap, or HashMap ?

## When to use a BST or a hash map

- When you want an array to be indexed by another thing than an int
- When there is lot of empty "key" space in your array

## Choosing between HashMap and TreeMap

- HashMap is "magically"  $\mathcal{O}(1)$ , most of the time faster than TreeMap
- But TreeMap can provide you all the values, ordered by keys

# Heaps

A short reminder

Sets and Maps

Heaps

- Introduction

- Definition

- Example

Union find

Segment Trees

Fenwick Tree

Sparse table



# A short introduction

Read problem 10954 from UVA !

## A naive method

With a linked list or an array

1. Sort everything ( $\mathcal{O}(n \log(n))$ )
2. Take the two smallest numbers ( $\mathcal{O}(1)$ )
3. Make the sum ( $\mathcal{O}(1)$ )
4. Add the result to the collection (keeping it sorted) ( $\mathcal{O}(n)$ )
5. Go back to step 2 (do this  $n$  times)

$$\mathcal{O}(n^2)$$

## We can do better

We want a structure such that...

1. Sort the collection ( $\mathcal{O}(n \log(n))$ )
2. Take the two smallest numbers ( $\mathcal{O}(\log(n))$ )
3. Make the sum ( $\mathcal{O}(1)$ )
4. Add the result to the collection (keeping it sorted) ( $\mathcal{O}(\log(n))$ )
5. Go back to step 2 (do this  $n$  times)

$$\mathcal{O}(n \log(n))$$

# Heap

(here we explain Binary Heap, but there are more types of heaps)

A binary tree that satisfies these properties :

## Shape

The tree is a complete binary tree (only the last level can be not fully filled)

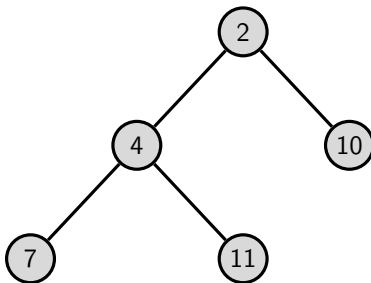
## Heap property

All nodes are lesser than (or any other comparison you may choose) each of their children

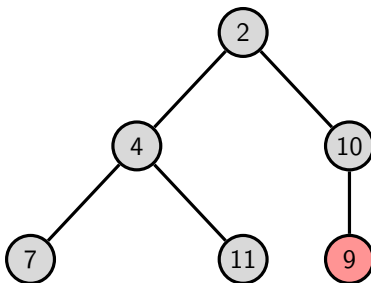
# Heap vs. BST

- BST is for **searching**, Heap is for **sorting**
- BST is always fully sorted
- Only the first element of Heap is sorted
- Optimal BST is very difficult to implement, while Heap is very simple and effective
- Always choose the simplest data structure for what you want to do !

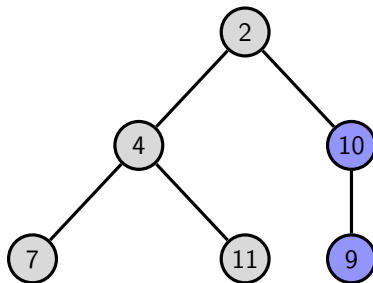
# An example of Binary Heap



# Push I

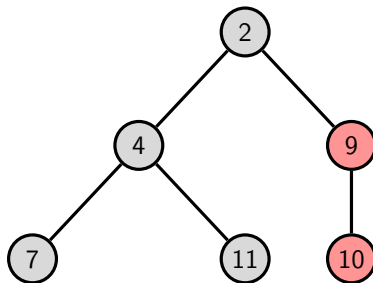


# Push II

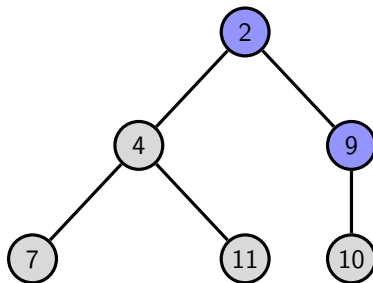




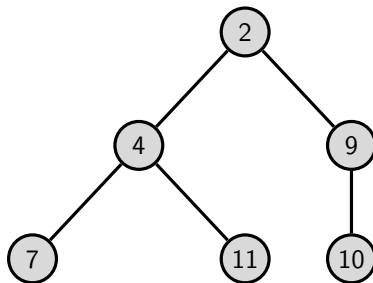
# Push III



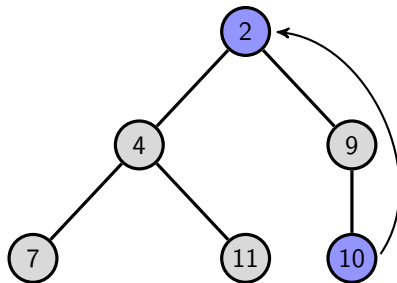
## Push IV



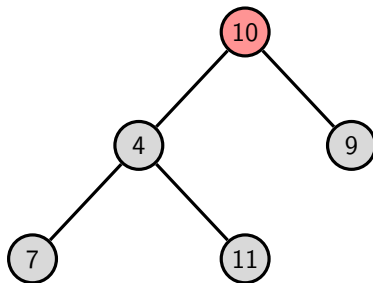
## Push V



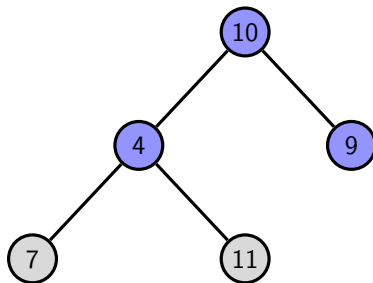
# Pop I



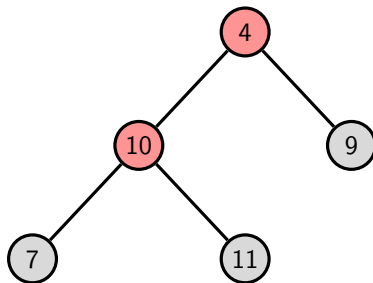
# Pop II



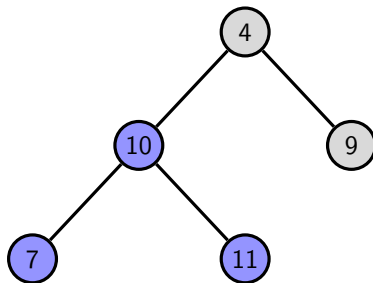
## Pop III



## Pop IV

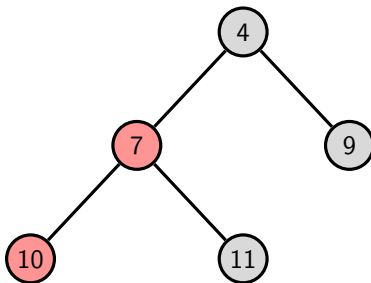


# Pop V

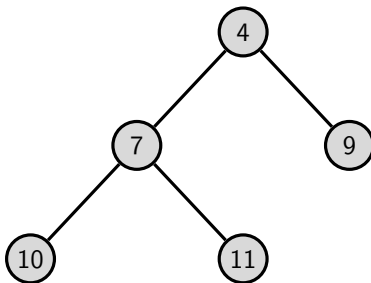




## Pop VI



# Pop VII



# Implémentation I

```

1  int hsize;
2  int hid[MAX]; // give id from index
3  int hval[MAX]; // give val from index
4  int hlookup[MAX]; // give index from id
5
6  void heap_swap (int a, int b) { // a and b are the indexes
7      int tmp = hval[a];
8      hval[a] = hval[b];
9      hval[b] = tmp;
10
11     hlookup[hid[a]] = b;
12     hlookup[hid[b]] = a;
13
14     tmp = hid[a];
15     hid[a] = hid[b];
16     hid[b] = tmp;
17 }
18
19 void heap_up (int a) { // a is the index
20     int up = (a-1)/2;
21     if (0 < a && hval[a] < hval[up]) {
22         heap_swap(a, up);
23         heap_up(up);
24     }
25 }
26

```

## Implémentation II

```
27 void heap_down (int a) { // a is the index
28   int left = 2*a+1, right = 2*a+2;
29   if (left < hsize && (hsize <= right || hval[left] < hval[right]) &&
        hval[left] < hval[a]) {
30     heap_swap(a, left);
31     heap_down(left);
32   }
33   else if (right < hsize && hval[right] < hval[a]) {
34     heap_swap(a, right);
35     heap_down(right);
36   }
37 }
```

# In C++/Java

- Do not implement it yourself! Most of the time not needed.
- Java : `PriorityQueue`
- C++ : `std::priority_queue`

We are nearly done with heaps...

... Finish the problem 10954 from  
**UVA !** (and/or do a short break before we view the union-find)

# Union find

A short reminder

Sets and Maps

Heaps

Union find

Problem

Algorithm

Exemples

Segment Trees

Fenwick Tree

Sparse table

## A wild problem appear

$n$  objects  $0, \dots, n-1$  are initially alone in their respective sets.

We have two types of query

**Union** We merge 2 sets designated by 2 respective members

**Find** We ask if 2 objects are in the same set

	{1}	{2}	{3}	{4}	{5}
(1, 5)	{1, 5}	{2}	{3}	{4}	
(2, 4)	{1, 5}	{2, 4}	{3}		
(2, 3)	{1, 5}	{2, 3, 4}			
(3, 4)	{1, 5}	{2, 3, 4}			
(4, 5)	{1, 2, 3, 4, 5}				



## A *naive* solution

- Array + Linked Lists
- Array containing linked list entries
- Class = first element of the list
- *Union* : merge two linked lists ( $\mathcal{O}(n)$ )
- *Find* : move to the first node of the list ( $\mathcal{O}(n)$ )

$$\mathcal{O}(n)$$

## A *less naive* solution

- Array + Trees
- Array containing tree nodes
- Class = root of the tree
- *Union* : merge two trees by connecting one root to the other( $\mathcal{O}(n)$ )
- *Find* : move to the root of the tree ( $\mathcal{O}(n)$ )

(a better)  $\mathcal{O}(n)$

## A *non-that-naive* solution

- Array + Trees
- Array containing tree nodes
- Class = root of the tree
- *Union* : merge two trees by connecting root ***of the smaller tree*** to the other, ***which is taller, minimizing the resulting height*** ( $\mathcal{O}(\log(n))$ )
- *Find* : move to the root of the tree ( $\mathcal{O}(\log(n))$ )

$$\mathcal{O}(\log(n))$$

# A perfect solution

- Array + Trees
- Array containing tree nodes
- Class = root of the tree
- *Union* : merge two trees by connecting root of the smaller tree to the other, which is taller, minimizing the resulting height ( $\mathcal{O}(\alpha(n))$ )
- *Find* : move to the root of the tree, ***and move all nodes in the path to the root of the tree*** ( $\mathcal{O}(\alpha(n))$ )

$$\mathcal{O}(\alpha(n))!$$

$$\alpha(n)$$

$$\alpha(n) = f^{-1}(n)$$

where

$$f(n) = A(n, n)$$

where

$$A(m, n) = \begin{cases} n + 1 & \text{si } m = 0 \\ A(m - 1, 1) & \text{si } m > 0 \text{ et } n = 0 \\ A(m - 1, A(m, n - 1)) & \text{si } m > 0 \text{ et } n > 0. \end{cases}$$

## Arckermann's function grows rapidly

$n$	$A(n, n)$
0	1
1	3
2	7
3	61
4	$2^{2^{2^{65536}}}$
5	[insert a very big number here]

$$\alpha(n) \leq 4 \text{ for } n \leq 2^{2^{2^{65536}}} !!!$$

(for all  $n$  in fact...)

# Union find solution

```
1 class UnionFind {
2     int rank[MAX_N];
3     int leader[MAX_N];
4     UnionFind(int n) {
5         memset(rank, 0, n * sizeof(int));
6         for(int i = 0; i < n; i++) leader[i] = i;
7     }
8     int find(int a) {
9         if(a != leader[a])
10             leader[a] = find(leader[a]);
11         return leader[a];
12     }
13     void union(int a, int b) {
14         int leaderA = find(a);
15         int leaderB = find(b);
16         if(leaderA == leaderB) return;
17         if(rank[leaderA] > rank[leaderB]) {
18             union(leaderB, leaderA); return;
19         }
20         leader[leaderA] = leaderB;
21         if (rank[leaderA] == rank[leaderB])
22             rank[leaderB]++;
23     }
24 };
```

## Example : gridland I

Grid  $n \times m$  avec  $1 \leq n, m \leq 1 \times 10^3$ . Two squares are connected if they are activated and there is a path of activated square from one to the other. Initially, squares are only connected to themselves.

There is  $1 \leq q \leq 1 \times 10^6$  queries

**add** a x y activate the square at  $(x, y)$

**connected?** c xa ya xb yb see if  $(xa, ya)$  and  $(xb, yb)$  are connected.



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## Example : gridland II

5 5 15

a 1 1

a 2 3

a 2 4

a 2 5

a 3 3

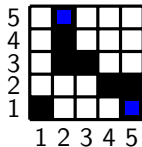
a 4 2

a 5 2

a 5 1

c 2 5 5 1

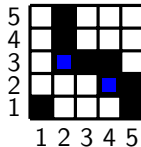
&gt;&gt; 0



a 4 3

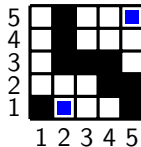
c 2 3 4 2

&gt;&gt; 1



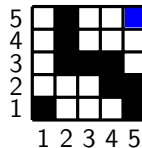
c 2 1 5 5

&gt;&gt; 0



c 4 4 4 4

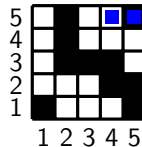
&gt;&gt; 1



a 5 5

c 4 5 5 5

&gt;&gt; 0



## Other examples

- 11503 from UVA (do it!)
- [uhunt.felix-halim.net](http://uhunt.felix-halim.net) 2.4.2.
- Kruskal (impossible to get  $\mathcal{O}(n \log(n))$  without it)

# Segment Trees

A short reminder

Sets and Maps

Heaps

Union find

Segment Trees

Motivation

Solution

Implementation

Fenwick Tree

Sparse table

# Range Minimum Query

You have an array  $A$  of size  $n$ , with integer values inside.

Given two integer  $a$  and  $b$  ( $a < b$ ), can you give me the minimum value of  $A$  between  $A[a]$  and  $A[b]$ ?

$$\min A[i] \text{ for } a \leq i \leq b$$

# Range Minimum Query

You have an array  $A$  of size  $n$ , with integer values inside.

Given two integer  $a, b$ , can you give me the minimum value of  $A$  between  $A[a]$  and  $A[b]$ ?

$$\min A[i] \text{ for } a \leq i \leq b$$

100000 times?

## Similar problems

- Dynamic Range Minimum Query
- Dynamic Range Sum Query (Fenwick Tree is simpler)
- Dynamic Range [insert any function here] Query

# I love naive solutions

Using an array...

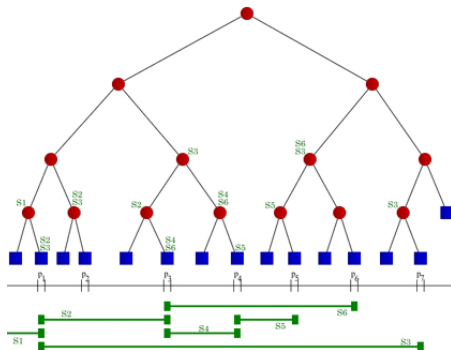
Spatial complexity  $\mathcal{O}(n)$

Update time complexity  $\mathcal{O}(1)$

Query time complexity  $\mathcal{O}(n)$

Total Query time complexity  $\mathcal{O}(mn) \Rightarrow \textbf{TLE}$

# A better solution : the segment tree



Spatial complexity  $\mathcal{O}(n \log(n))$

Update time complexity  $\mathcal{O}(\log(n))$

Query time complexity  $\mathcal{O}(\log(n))$

Total Query time complexity  $\mathcal{O}(m \log(n)) \Rightarrow \mathbf{AC}$



# Segment Tree implementation I

```

1  class SegmentTree {
2      int[] st, A;
3      int n;
4      int left (int p) { return p << 1; }
5      int right(int p) { return (p << 1) + 1; }
6
7      void build(int p, int L, int R) {
8          if (L == R)
9              st[p] = L; // or R
10         else {
11             int mid = (L + R) / 2;
12             build(left(p), L, mid);
13             build(right(p), mid + 1, R);
14             int p1 = st[left(p)], p2 = st[right(p)];
15             st[p] = (A[p1] <= A[p2]) ? p1 : p2;
16         } }
17
18     int rmq(int p, int L, int R, int i, int j) { // O(log n)
19         if (i > R || j < L) return -1; // outside query range
20         if (i <= L && R <= j) return st[p]; // inside query range
21         int mid = (L + R) / 2;
22         int p1 = rmq(left(p), L, mid, i, j);
23         int p2 = rmq(right(p), mid + 1, R, i, j);
24
25         if (p1 == -1) return p2; // outside query range
26         if (p2 == -1) return p1;

```

# Segment Tree implementation II

```

27     return (A[p1] <= A[p2]) ? p1 : p2; }
28
29 int update(int p, int L, int R, int i, int j, int v) {
30     if (i > R || j < L) // outside update range
31         return st[p];
32     //if (i <= L && R <= j) // could be lazy here !! Depends on
        application
33     if (L == R) {
34         A[i] = v;
35         return st[p] = L; // or R
36     }
37     int mid = (L + R) / 2;
38     int p1 = update(left(p), L, mid, i, j, v);
39     int p2 = update(right(p), mid + 1, R, i, j, v);
40     return st[p] = (A[p1] <= A[p2]) ? p1 : p2;
41 }
42
43 public:
44
45 SegmentTree(int[] _A) {
46     A = _A; n = A.length;
47     st = new int[4 * n];
48     for (int i = 0; i < 4 * n; i++) st[i] = 0;
49     build(1, 0, n - 1);
50 }
51 int rmq(int i, int j) { return rmq(1, 0, n - 1, i, j); }
52 int update_point(int i, int v) {

```

# Segment Tree implementation III

```
53     return update(1, 0, n - 1, i, i, v); }  
54 int update_interval(int i, int j, int v) {  
55     return update(1, 0, n-1, i, j, v); }  
56 };
```

- IOI-2013 day 2 : “game”
- <http://codeforces.com/problemset/problem/474/E>

# Fenwick Tree

A short reminder

Sets and Maps

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Fenwick Tree

Sparse table

# Fenwick Tree I

## Dynamic Range Sum Query

What are the numbers smaller that 1011001000?

- 1011000???
- 1010???????
- 100????????
- 0??????????

$$\text{rsq}(1011001000) = \text{ft}(1011001000) + \text{ft}(1011000000) \\ + \text{ft}(1010000000) + \text{ft}(1000000000)$$

```

1  adjust(01011001000,1):
2      ft[01011010000]++
3      ft[01011100000]++
4      ft[01100000000]++
5      ft[10000000000]++

```

```

1  x          0000000000000000000010010110100000
2  ~x         1111111111111111111101101001011111
3  -x or (~x)+1 1111111111111111111101101001100000
4  x & (-x)    00000000000000000000000000000100000

```

# Fenwick Tree II

```

1  class FenwickTree {
2      int *ft;
3      int n;
4      int LSOne(int S) { return (S & (-S)); }
5      public:
6      FenwickTree(int n) { // ignore index 0
7          this->n = n;
8          ft = new int[n+1];
9          for (int i = 0; i <= n; i++) ft[i] = 0;
10     }
11     int rsq(int b) {          // returns RSQ(1, b)      PRE 1 <= b <= n
12         int sum = 0; for (; b > 0; b -= LSOne(b)) sum += ft[b];
13         return sum;
14     }
15     int rsq(int a, int b) { // returns RSQ(a, b)      PRE 1 <= a,b <= n
16         return rsq(b) - (a == 1 ? 0 : rsq(a - 1));
17     }
18     void adjust(int k, int v) { // n = ft.size() - 1 PRE 1 <= k <= n
19         for (; k <= n; k += LSOne(k)) ft[k] += v;
20     }
21 };

```

# Fenwick Tree III

Exemples :

- NWERC 2011 Problem C
- <http://codeforces.com/contest/504/problem/B>
- <http://codeforces.com/problemset/problem/459/D>

# Sparse table

A short reminder

Sets and Maps

Heaps

Union find

Segment Trees

Fenwick Tree

Sparse table



# Sparse Table

## Static Range Minimum Query

$m[i][j]$  stores the smallest of  $[i; i + 2^j[$ .

$\min([a; b[) = \min(m[a][k], m[b - 2^k][k])$  for  $k$  such that

$$2^{k-1} < b - a \leq 2^k$$

## Tricky example

Get a tree flat with DFS then apply RSQ and RMQ.

- Least Common Ancestor : LCA
- <http://codeforces.com/contest/383/problem/C>