

# Graph traversal

DFS, BFS, applications

beOI Training



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DFS and BFS

Connected components

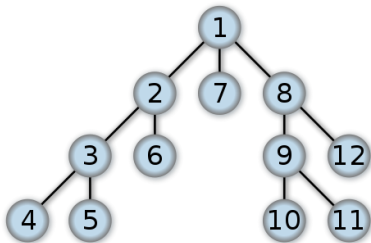
Topological sort

Bipartite check

Kosaraju SCC

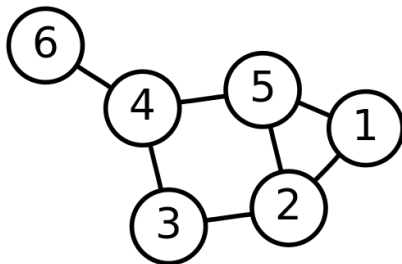
# Depth-first principle

- ▶ Go in depth, backtrack when stuck
- ▶ Visit everything before switching



## DFS example

Do not visit a node twice!



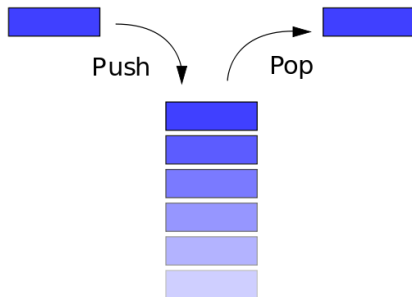
**1** → **2** → **3** → **4** → **5** → 4 → **6** → 4 → 3 → 2 → 1

# DFS recursive implementation

```
vector<int> neigh[MAXN];  
bitset<MAXN> visited;  
  
void dfs(int u)  
{  
    if (visited[u])  
        return;  
    visited[u] = true;  
  
    for (int v : neigh[u])  
        dfs(v);  
}
```

# DFS visit order

- ▶ Always travels locally: parent  $\rightarrow$  child  $\rightarrow$  parent
- ▶ The last discovered are the first visited  $\Rightarrow$  we can also use a *Last In First Out* structure (stack)

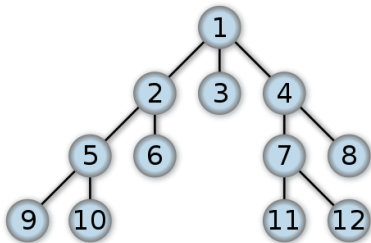


# DFS stack implementation

```
stack<int> st;  
st.push(start);  
  
while (!st.empty())  
{  
    int u = st.top();  
    st.pop();  
  
    for (int v : neigh[u])  
    {  
        if (!visited[v])  
        {  
            visited[v] = true;  
            st.push(v);  
        }  
    }  
}
```

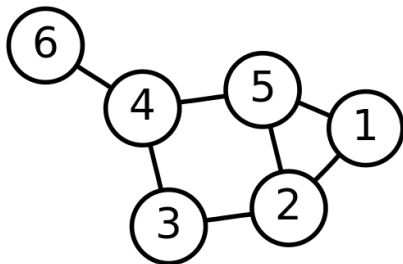
# Breadth-first principle

- ▶ Go layer by layer
- ▶ Visit the closest nodes first





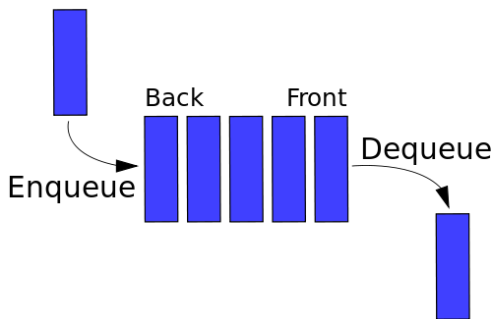
## BFS example



$1 \rightarrow 2 \rightarrow 5 \rightarrow 3 \rightarrow 4 \rightarrow 6$

# BFS visit order

The first discovered are the first visited  $\Rightarrow$  we can use a *First In First Out* structure (queue)



# BFS implementation

```
queue<int> q; // different
q.push(start);

while (!q.empty())
{
    int u = q.front(); // different
    q.pop();

    for (int v : neigh[u])
    {
        if (!visited[v])
        {
            visited[v] = true;
            q.push(v);
        }
    }
}
```

# BFS for shortest path

BFS traverses graph with nondecreasing distance!

- ▶ Add two tables `dist[]` and `parent[]`
- ▶ When adding to queue:
  - ▶  $\text{dist}[v] = \text{dist}[u] + 1$
  - ▶  $\text{parent}[v] = u$
- ▶ Trace path back using `parent[]`

# Comparison

Complexity: both  $O(V + E)$ .

How to choose:

- ▶ If distance / shortest path necessary  $\Rightarrow$  BFS
- ▶ Otherwise  $\Rightarrow$  DFS (shorter)

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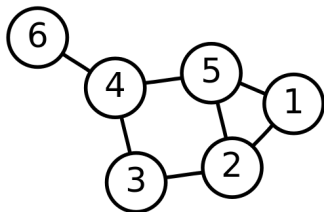
Topological sort

Bipartite check

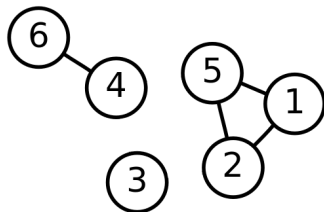
Kosaraju SCC

# Connected components

- ▶ On **undirected graphs**, “ $u$  connected to  $v$ ” is an equivalence relation
- ▶ So it forms a partition of the vertices



1 connected component



3 connected components

# Finding connected components

One run of DFS/BFS visits a whole component!

- ▶ Go through nodes and check if visited
- ▶ In `dfs()`, store nodes in a vector

```
for (int i = 0; i < n; i++)  
{  
    if (!visited[i]) // new CC  
    {  
        vector<int> cc;  
        dfs(i, &cc); // adds nodes to cc  
        // process cc  
    }  
}
```



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DFS and BFS

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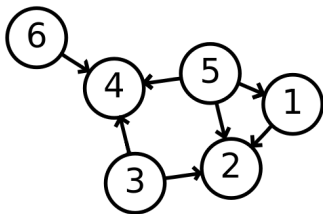
Topological sort

Bipartite check

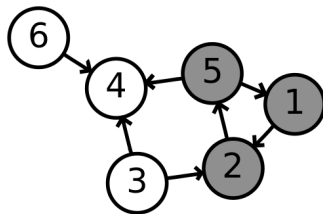
Kosaraju SCC

# Directed acyclic graphs

Directed graphs without cycles



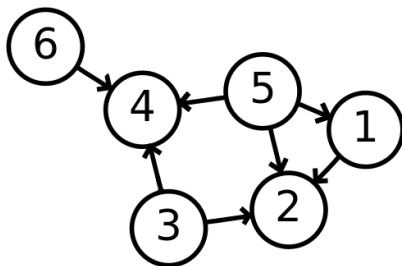
DAG



not DAG

# Topological sort

- ▶ There are no cycles, so we can order the nodes so that edge  $u \rightarrow v \Rightarrow u$  before  $v$
- ▶ Example: course prerequisites, how to take them all in order
- ▶ Not unique:  $\{3, 5, 6, 4, 1, 2\}, \{5, 3, 1, 6, 2, 4\}, \dots$



# Toposort with zero in-degree

If  $u$  does not have edges pointing to it, it can go first!

- ▶ Start at nodes with  $\deg_{\text{in}} = 0$
- ▶ Remove edges as we find them
- ▶ Continue until no node is left

## Zero in-degree implementation

```
int in_degree[MAXN];    // pre-filled
queue<int> zero_in;      // pre-filled
vector<int> toposort;

while (!zero_in.empty())
{
    int u = zero_in.front();
    zero_in.pop();
    toposort.push_back(u);

    for (int v : neigh[u])
    {
        in_degree[v]--;
        if (in_degree[v] == 0)
            zero_in.push(v);
    }
}
```

# Toposort with DFS

Use DFS to build the toposort backwards

- ▶ Call `dfs()` on every node
- ▶ Add a node *after* recursing

Thus every node is

- ▶ after its children in the *backward* toposort
- ▶ before its children in the *forward* toposort

# Toposort DFS implementation

```
void dfs(int u, vector<int> *toposort)
{
    if (visited[u]) return;
    visited[u] = true;
    // recurse as usual...
    toposort->push_back(u);
}

vector<int> toposort;
for (int i = 0; i < n; i++)
    dfs(i, &toposort); // no need to check visited[i]

for (int i = n-1; i >= 0; i--)
    // use toposort[i]
```

# Comparison

Complexity: both  $O(V + E)$

Use the zero in-degree method only if needed:

- ▶ Additional conditions on the order
- ▶ Enumerate all possible toposorts



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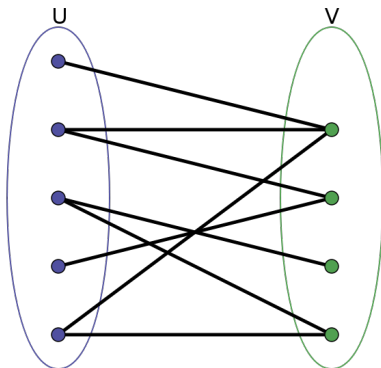
Topological sort

Bipartite check

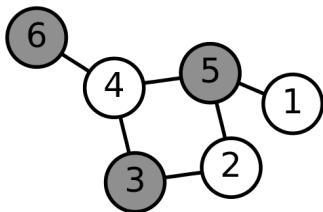
Kosaraju SCC

# Bipartite graphs

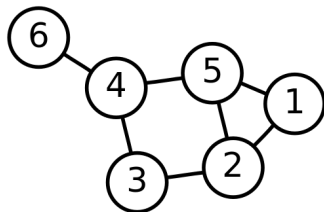
- ▶ Can be split in two without internal edges
- ▶ Equivalent: no odd-length cycle



## Bipartite examples



bipartite



not bipartite

# Bipartite check with DFS/BFS

Put an arbitrary node  $u$  on the left then traverse the graph:

- ▶ If  $v$  is on the left, put all its neighbors on the right
- ▶ If  $v$  is on the right, put all its neighbors on the left
- ▶ Continue until conflict or finished

Note:  $v$  on left  $\Leftrightarrow \text{dist}(u, v)$  even

# Bipartite check correctness

$G$  is not bipartite  $\Leftrightarrow$  the assignment fails

- ▶ If  $G$  is not bipartite the assignment will clearly fail
- ▶ If there is a conflict between  $u$  and  $v$  adjacent
  - ▶ Let  $p$  be their common parent in the DFS
  - ▶  $\text{dist}(p, u)$  and  $\text{dist}(p, v)$  have the same parity
  - ▶ Cycle  $p - u - v$  has odd length  $\text{dist}(p, u) + 1 + \text{dist}(p, v)$
  - ▶ Thus  $G$  is not bipartite

# Bipartite check implementation

```
int color[MAXN];

bool dfs(int u)
{
    for (int v : neigh[u])
    {
        if (color[v] == -1) // unassigned
        {
            color[v] = !color[u];
            if (!dfs(v))
                return false;
        }
        else if (color[u] == color[v]) // conflict
            return false;
    }
    return true;
}
```

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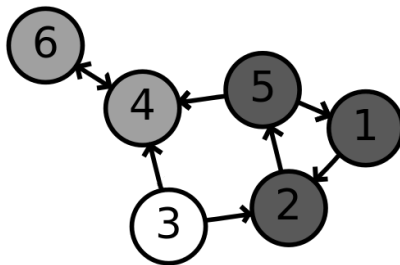
Topological sort

Bipartite check

Kosaraju SCC

# Strongly connected components

Nodes  $u, v$  in same SCC  $\Leftrightarrow$  path  $u \rightarrow v$  **and** path  $v \rightarrow u$

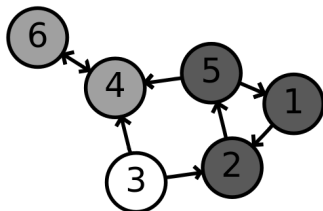


3 strongly connected components

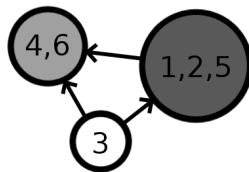


# Contracted graph

- ▶ If we contract the SCCs into one node, a DAG appears
- ▶ This is because all cycles have been contracted
- ▶ Useful for DP (as we will see later)



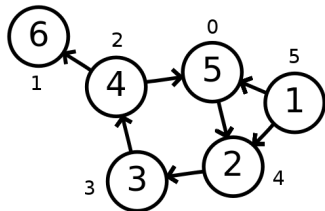
original



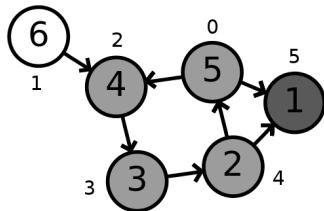
contracted

# Kosaraju's algorithm

- ▶ Run the DFS toposort algorithm on  $G$
- ▶ Use that order and flood with the transpose of  $G$



raw toposort order



flood with decreasing index

# Kosaraju implementation

```
void dfs(int u, vector<int> neigh[], vector<int> *st)
{
    // ... (use neigh[] to flood)
    st->push_back(u);
}

vector<int> toposort; // not valid toposort!
for (int i = 0; i < n; i++)
    dfs(i, neigh, &toposort);
visited.reset();
for (int i = n-1; i >= 0; i--)
{
    if (!visited[toposort[i]])
    {
        vector<int> scc;
        dfs(toposort[i], neighT, &scc);
    }
}
```

## Source of figures

- ▶ <https://en.wikipedia.org/wiki/File:6n-graf.svg>
- ▶ <http://en.wikipedia.org/wiki/File:Depth-first-tree.svg>
- ▶ [http://en.wikipedia.org/wiki/File:Data\\_stack.svg](http://en.wikipedia.org/wiki/File:Data_stack.svg)
- ▶ <http://en.wikipedia.org/wiki/File:Breadth-first-tree.svg>
- ▶ [http://en.wikipedia.org/wiki/File:Data\\_Queue.svg](http://en.wikipedia.org/wiki/File:Data_Queue.svg)
- ▶ <https://commons.wikimedia.org/wiki/File:Simple-bipartite-graph.svg>