

## **Arming the motors**

Before arming the motors, make sure all people and objects are clear of the propellers.

1 Turn on your transmitter

2 Plug in your LiPo battery. The red and blue lights should flash for a few seconds as the gyros are calibrated (do not move the copter)

3 If the red arming light is double blinking then the copter has failed the pre-arm checks.

4 Connect ARM to Mission Planner

5 Once connected click on the Action tab

6 under actions there will be a ARM/DISARM button.

Note make sure throttle is all the way down before going to this step

7 Click on the arm and wait until the screen says ARMED

8 Disconnect the ARM from the computer

9. Push up slowly on throttle to begin flight