深度学习快速入门

09 池化层

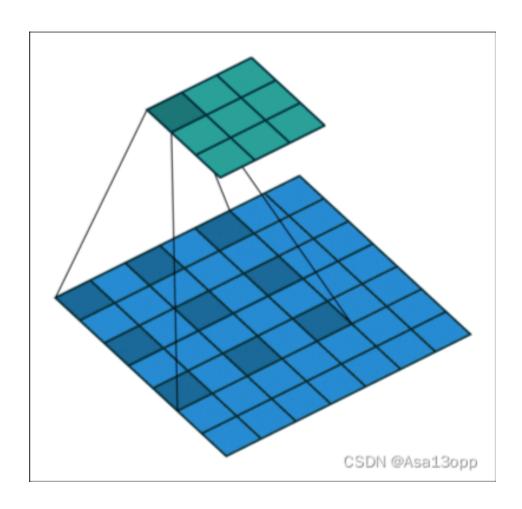
POET

2024年2月13日

1 池化层原理 2

1 池化层原理

- 1. 最大池化层有时也被称为下采样。
- 2. dilation 为空洞卷积,如下图所示。
- 3. Ceil_ model 为当超出区域时,只取最左上角的值。
- 4. 池化使得数据由 5 * 5 变为 3 * 3, 甚至 1 * 1 的,这样导致计算的参数会大大减小。例如 1080P 的电影经过池化的转为 720P 的电影、或360P 的电影后,同样的网速下,视频更为不卡。



2 torch.nn.MaxPool2d

```
torch.nn.MaxPool2d(kernel size, stride=None, padding
     =0, dilation =1,
2
  return indices=False, ceil mode=False)
3
     kernel_size (Union[int, Tuple[int, int]]) - the
5
        size of the window to take a max over
     stride (Union[int, Tuple[int, int]]) - the stride
7
        of the window. Default value is kernel_size
     padding (Union[int, Tuple[int, int]]) - Implicit
        negative infinity padding to be added on both
        sides
10
     dilation (Union[int, Tuple[int, int]]) - a
11
        parameter that controls the stride of elements
       in the window
12
     return_indices (bool) - if True, will return the
13
       max indices along with the outputs. Useful for
        torch.nn.MaxUnpool2d later
14
     ceil_mode (bool) - when True, will use ceil
15
        instead of floor to compute the output shape
16
     当 ceil mode=True 时,如果滑动窗口在左填充内边距内
        启动,则允许它们越界或输入。将在右侧填充区域开始
        的滑动窗口将被忽略。
```

3 池化层处理图片

```
Shape:  \begin{aligned} &\bullet \text{ Input: } (N,C,H_{in},W_{in}) \text{ or } (C,H_{in},W_{in}) \\ &\bullet \text{ Output: } (N,C,H_{out},W_{out}) \text{ or } (C,H_{out},W_{out}), \text{ where} \\ \\ &H_{out} = \left \lfloor \frac{H_{in}+2*\operatorname{padding}[0]-\operatorname{dilation}[0]\times(\operatorname{kernel\_size}[0]-1)-1}{\operatorname{stride}[0]}+1 \right \rfloor \\ &W_{out} = \left \lfloor \frac{W_{in}+2*\operatorname{padding}[1]-\operatorname{dilation}[1]\times(\operatorname{kernel\_size}[1]-1)-1}{\operatorname{stride}[1]}+1 \right \rfloor \\ &\text{ CSDN @Assi3ppp} \end{aligned}
```

3 池化层处理图片

```
import torch
1
      import torchvision
2
      from torch import nn
3
      from torch.nn import MaxPool2d
      from torch.utils.data import DataLoader
5
      from torch.utils.tensorboard import SummaryWriter
6
7
       dataset = torchvision.datasets.CIFAR10("./dataset
          ", train=False, transform=torchvision.transforms.
          ToTensor(), download=True)
       dataloader = DataLoader (dataset, batch_size=64)
9
10
       class Tudui (nn. Module):
11
           def ___init___(self):
12
               super(Tudui, self).__init__()
13
                self.maxpool = MaxPool2d(kernel_size=3,
14
                  ceil_mode=True)
15
           def forward (self, input):
16
               output = self.maxpool(input)
17
               return output
18
```

3 池化层处理图片

```
19
       tudui = Tudui()
20
       writer = SummaryWriter("logs")
21
       step = 0
22
23
       for data in dataloader:
24
           imgs, targets = data
           writer.add_images("input", imgs, step)
26
           output = tudui(imgs)
27
           writer.add_images("output", output, step)
28
           step = step + 1
29
```





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