More Related to Workshop ib Problem 2b: [A|b]
$$A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix}, \ \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \text{ then } A\vec{x} = \vec{b} \text{ is inconsistent.}$$

Want to find & that minimizes ||Ax-till.

1st Approach:

Let W = column span of A. $A\vec{x} = \vec{c}$ has a solution exactly when \vec{c} is in W.

Let $\vec{w} = U_{\mathbf{W}}(\vec{b})$, then $A\vec{x} = \vec{w}$ will have a solution \vec{x}_0 , $||A\vec{x}_0 - \vec{b}|| = ||\vec{w} - \vec{b}||$ (this is as small as $||A\vec{x} - \vec{b}||$ can get!)

 $\vec{0} = A^T \vec{z} = A^T (\vec{b} - \vec{w}) = A^T \vec{b} - A^T \vec{w} = A^T \vec{b} - A^T A \vec{x}_0$ So solve $A^T A \vec{x} = A^T \vec{b}$!

2nd Approach:

Use multivariable calculus.

Def. A matrix A with real entries is called symmetric if

 $A^{\mathsf{T}} = A$.

Theorem. Symmetric matrices are diagonalizable over IR. A In particular, all eigenvalues of symmetric matrices are real.

> Eigenspaces will have dimension = multiplicities of > Theorem. If it and is are eigenvectors of a symmetric matrix A with distinct eigenvalues λ, μ , then $\vec{u} \cdot \vec{v} = 0$ Proof: $(AB)^T = B^TA^T$ basis

each

eigenspote

 $A\vec{u} = \lambda \vec{u}, A\vec{v} = \mu \vec{v}$ $(A\vec{u}) \cdot \vec{v} = \lambda \vec{u} \cdot \vec{v}, \vec{u} \cdot A\vec{v} = \mu \vec{u} \cdot \vec{v}$

 $(A\vec{u})^T\vec{v} = \vec{u}^T A^T \vec{v} = \vec{u}^T A \vec{v}$ $\Rightarrow \lambda \vec{u} \cdot \vec{v} = \mu \vec{u} \cdot \vec{v}$, i.e., $(\lambda - \mu) \vec{u} \cdot \vec{v} = 0$

orthonormal eigenbasiz:

Corollary. Symmetric matrices are orthogonally diagonalizable, i.e., there exist an orthogonal matrix Q and diagonal matrix D Such that A=QDQT.

