Observation: the span of a nonempty subset S of V
consists exactly of all vectors of the form
aut + + aptp, where k is some natural number,
a,,, ap are in R/C, and Vi,, Jr are in S
a vector v in S is redundant
= removing it doesn't change the span
= it's in the span of the nest of the westors
= there exist an,, ap in R/C and vi,, Up in S
such that $U = Q_1 U_1 + \cdots + Q_k U_k$
cet least one vextor in S13 redundant
= there exist U, U,, Up distinct elements of S
such that $0 = a_1 v_1 + \cdots + a_k v_k$ for some $a_1, \cdots, a_k$ in $R/C$
ar,, ap in RC
There exist U,, U distinct elements of S and
by,, be in R/C not all zero, such that
(D) V7 + + 6 L V = 0 Say by #0, +then by V2 + + by V2 = 0
= S 13 linearly dependent
J = 1 52 - 1 52
no vertor in S is redundant
= the only times bivi+-+ bivi = 0
for a positive ivitager l, real/complex numbers bi,, bi,
and vi,, vi distinct elements of S is when bi == = bi = 0
= S is Mearly independent

Dot. A	bais for	a vector s	pare V	13 Q	linearly	indopendent
		ose spom	1			

A There are usually infinitely many bases for one vector space, but they all have the same size, which is called the dimension of the vector space.

At there are vector spaces with infinite dimension E.g. the set of all polynomials with the usual +, a basis:  $\S 1, \times, \times^2, \dots \S$ 

but we will only work with finite dimensional vector spaces in this class.

Observation: if {e<sub>1</sub>,...,en<sup>3</sup> is a basis for a vector space V, then every or in V is equal to a<sub>1</sub>.e<sub>1</sub> + ... + a<sub>n</sub>.e<sub>n</sub> for unique a<sub>1</sub>,...,a<sub>n</sub> in R/O. Therefore, by choosing a basis, every vector space of domension in can be identified with R...