

Bilimsel Diller ve Otomata

Genel Bilgi:

① Finite Automata (Sonlu Otomata)

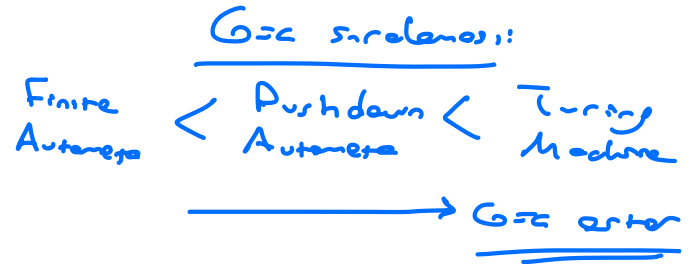
- * DFA, NFA
- * Hafıza yok.
- * Dil: Regular Diller

② Pushdown Automata

- * PDA
- * Hafıza: Stack (yığın)
- * Dil: Context-free

③ Turing Machines (Turing Makinesi)

- * Hafıza: Random Access Memory (RAM)
- * Dil: Turing Acceptable



Dil Kavramı:

Alfabe \rightarrow String \rightarrow Dil

Binary sayılar kavramı: $\Sigma = \{0, 1\} \rightarrow$ Bu kavramın alfabe'dir.

1011
String

1010
String

120
String
(fakat 2'ye bölünmüştür)
değildir!

String işlemleri:

$w = abba$
 $v = bbab$ } $wv = abbabbbab$
 $vw = bbbababba$

Reverse: $w^R \rightarrow$ Üss: "R" ile gösterilir.

$w = babb$ $w^R = bbab$

Uzunluk: $|w| \rightarrow$ Mutlak değer ile gösterilir.

$w = aba \rightarrow |w| = 3$, $|abba| = 4$

$|wv| = |w| + |v| = |v| + |w|$

Boş String:

" λ " veya " ϵ " ile gösterilir. $|\lambda| = 0$ $w\lambda = \lambda w = w$,

$$abob\lambda = ab\lambda ob = abob$$

Substring:

ab b o o b b
ab
b o o b
...

Prefix-Suffix

$$w = \underset{\substack{\downarrow \\ \text{prefix}}}{v} u \rightarrow \text{suffix}$$

$$w = aboba$$

Prefix

λ

a

...

aboba

Suffix

oboba

boba

...

λ

üs Alma:

$$w^n = \underbrace{w \cdot w \cdot w \cdot \dots \cdot w}_{n \text{ adet}}$$

$$(aba)^2 = abooba$$

$$w^0 = \lambda, (aba)^0 = \lambda$$

Yildiz (*) Operasyonu:

$$\Sigma = \{a, b\}$$

$$\Sigma^* = \{\lambda, a, b, aa, bb, ab, \dots\}$$

Artı (+) Operasyonu

$$\Sigma = \{a, b\}$$

$$\Sigma^+ = \Sigma^* - \lambda = \{a, b, aa, bb, ab, \dots\}$$

Dillerin kısımları:

$$\Sigma = \{a, b\}$$

$$L = \{a^n b^n : n \geq 0\}$$

$$\underbrace{aaa \dots aaa}_{n} \underbrace{bbb \dots bbb}_{n}$$

$$\lambda \in L$$

$$ab \in L$$

$$aebbb \in L$$

$$aaabbb \in L$$

$$aaabbb \notin L \text{ (n hem 3 hem 2 olamaz)}$$

• $|\{\epsilon\}| = |\emptyset| = 0$, $|\lambda| = 0$

• $|\{\lambda\}| = 1$

• Soru: w ve w^R biliyoruz ama L (yani dil) ve L^R biliyor muyuz?

$L^R = \{ab, aob, abob\}^R = \{ba, baa, babo\}$

• $u = a$, $w = uv = ab$
 $v = b$

↳ Soru: dil nedir?

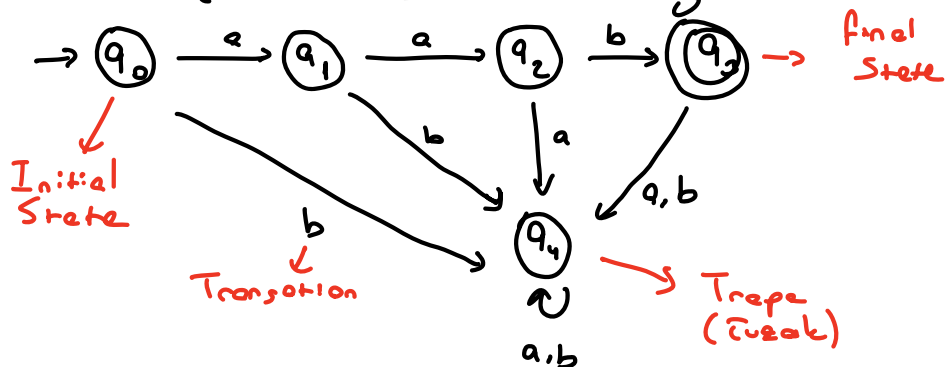
$L_1 = \{ab, ba\}$, $L_2 = \{a, baa\}$

$L_1 L_2 = \{aba, abbaa, baab, baabaa\}$

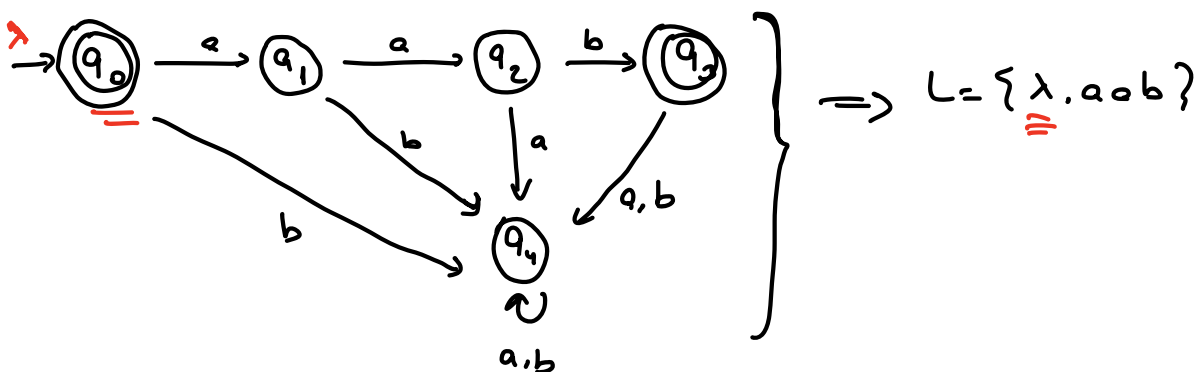
• $L = \{a, b\}$, $L^0 = \lambda$, $L^3 = \{a, b\} \{a, b\} \{a, b\}$

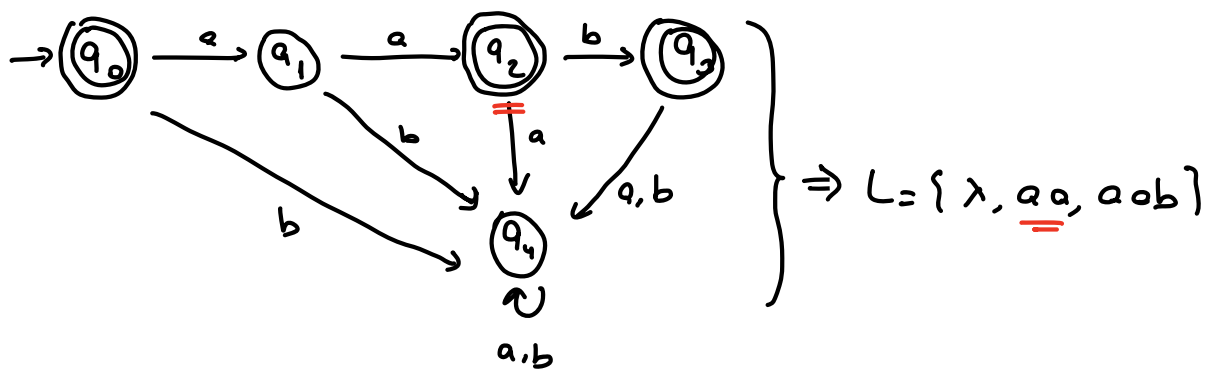
DFA (Deterministic Finite Automata):

Kontrol eder ve tek state'e gider.

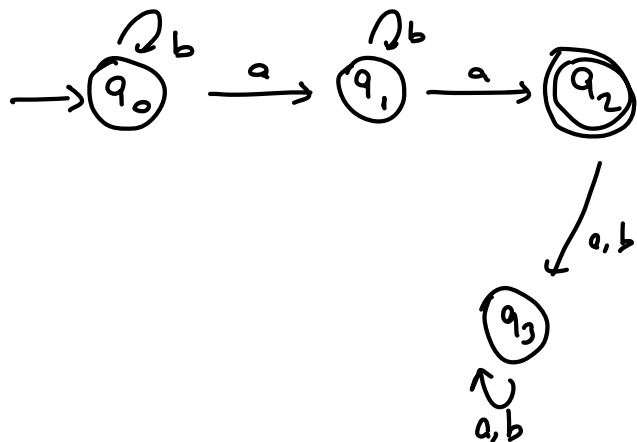


$L = \{aob\}$ $aob \checkmark$ $ab \times$ $aoba \times$





Örnek:



$\left. \begin{array}{l} \text{bob} \quad \times \\ \text{bab} \quad \checkmark \\ \text{bbabba} \quad \checkmark \\ \text{babbbba} \quad \checkmark \end{array} \right\} L = \{ \text{boba}, \text{bbobba}, \text{babbbba}, \dots \}$

$$L = \{ b^n a b^m a, n \geq 0, m \geq 0 \}$$

Formal Definition

$$M = (Q, \Sigma, \delta, q_0, F)$$

$$Q = \{ q_0, q_1, q_2, q_3 \}, \Sigma = \{ a, b \}$$

↳ Stateler kimosi

↳ Alfabe Limosi

$$\delta(q_0, a) = q_1$$

↳ Transition kimosi

q_0 'a a veriline a q_1 'e git.

$$q_0 = q_0$$

$$F = q_2$$

↳ Başlangıç state
(Initial State)

↳ Final state

Extended Transition

$\delta^*(q_0, abba) = q_3 \rightarrow q_0$ 'den sonra "abba" yazınca gidilen state

$\delta^*(q_1, bbabba) = q_4 \rightarrow q_1$ 'den sonra "bbabba" ile q_4 'e gider.

NFA (Non-Deterministic Finite Automata)

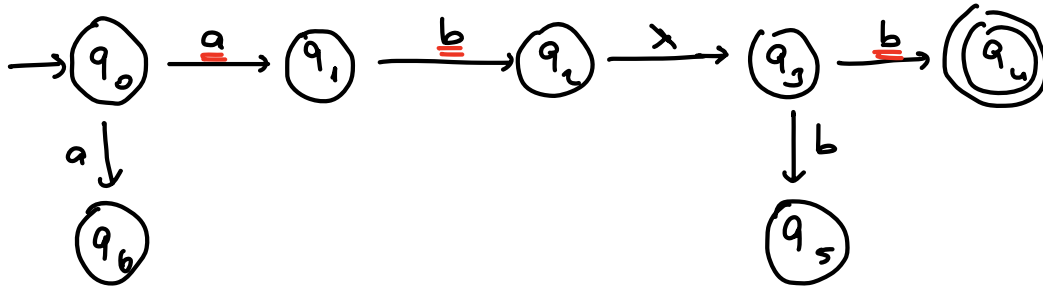


abb ✓ aba ✗ abbb ✗

↳ Formal Definition

$$M = (Q, \Sigma, \delta, q_0, F)$$

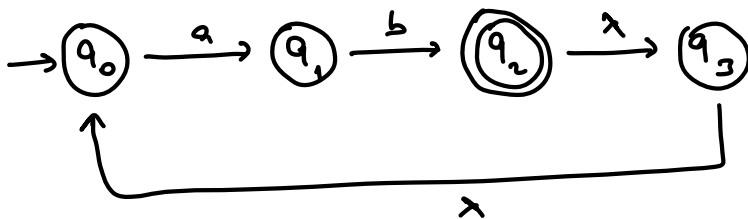
$$Q = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6\} \quad \Sigma = \{a, b\}$$

$$\delta(q_0, a) = \{q_1, q_6\} \rightarrow \text{Deterministic Finite Automata'dan tek farkı budur.}$$

⋮

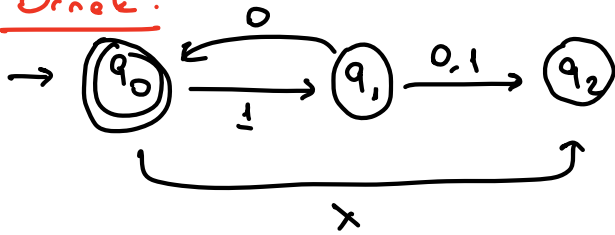
$$q_0 = q_0 \quad \text{ve} \quad F = q_4$$

Örnek:



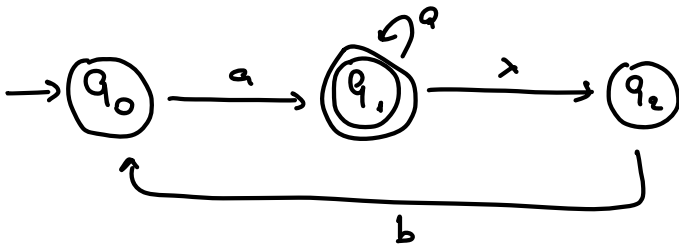
$$\left. \begin{array}{l} ab \checkmark \\ abab \checkmark \\ ababab \checkmark \end{array} \right\} L = \{ab, abab, ababab, \dots\} = (ab)^+$$

Örnek:

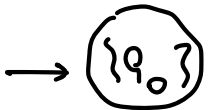


$$\left. \begin{array}{l} \lambda \quad \checkmark \\ 10 \quad \checkmark \\ 1010 \quad \checkmark \\ 101010 \quad \checkmark \end{array} \right\} L = \{ \lambda, 10, 1010, \dots \} = (10)^*$$

NFA'ya, DFA'ya çevirme

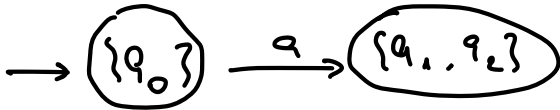


• Öncelik Initial State bulmek $\rightarrow \{q_0\}$ (Bu tek basına oluyordı!)!



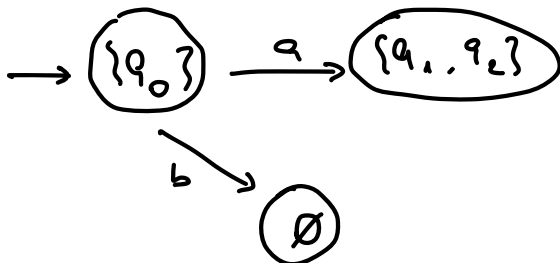
• Sonra $\int_{\{q_0\}, a}$ transition yapısına bak.

$$\int (\{q_0\}, a) = \{q_1, q_2\}$$



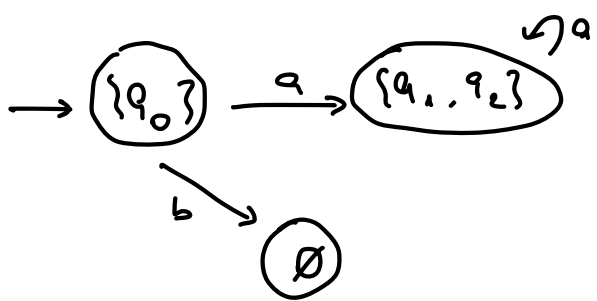
• Sonra $\int_{\{q_0\}, b}$ transition yapısına bak.

$$\int (\{q_0\}, b) = \emptyset \rightarrow \text{Genellikle trap state oluyor.}$$



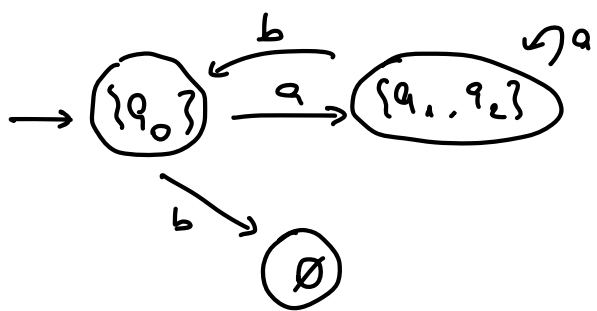
• Sonra $\{q_1, q_2\}_a$ transition yapısına bak.

$$\delta(\{q_1, q_2\}, a) = \underbrace{\delta(q_1, a) = q_1 \text{ ve } \delta(q_2, a) = \emptyset}_{= \{q_1, q_2\}}$$

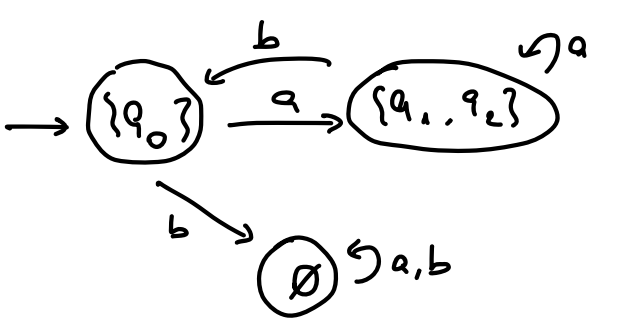


• Sonra $\{q_1, q_2\}_b$ transition yapısına bak.

$$\delta(\{q_1, q_2\}, b) = \underbrace{\delta(q_1, b) = \emptyset \text{ ve } \delta(q_2, b) = q_0}_{= \{q_0\}}$$



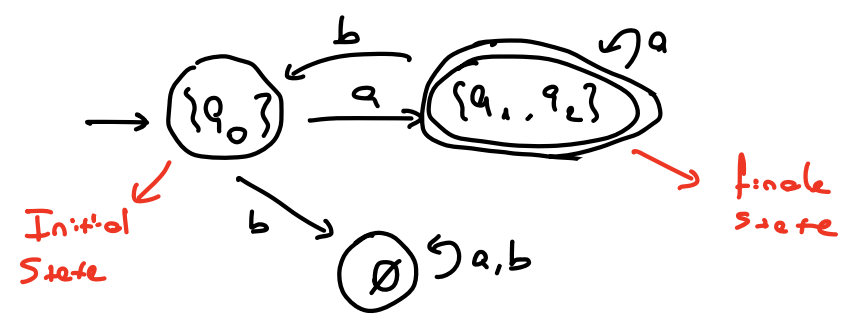
• Sonra trap gncellenir.



• En son final state/ler belirlenir.

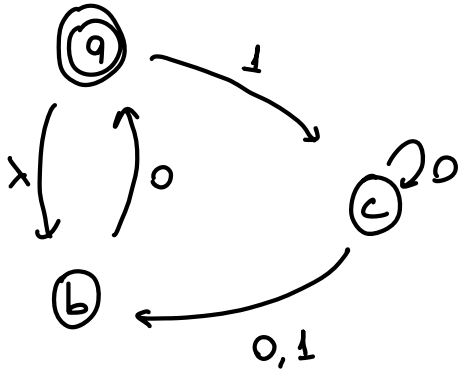
NFA'da final state/ler: $\{q_1\}$ olup q_1 : azer b-ten state/ler final state olarak kabul edilir.

Çözel Hal:



Örnek 2:

① Initial State: $\{a, b\}$



② $\{a, b\} \xrightarrow{1} \{c\}$
 $\{a, b\} \xrightarrow{0} \{a, b\}$

②.1 $\{c\} \xrightarrow{0} \{c, b\}$
 $\{c\} \xrightarrow{1} \{b\}$

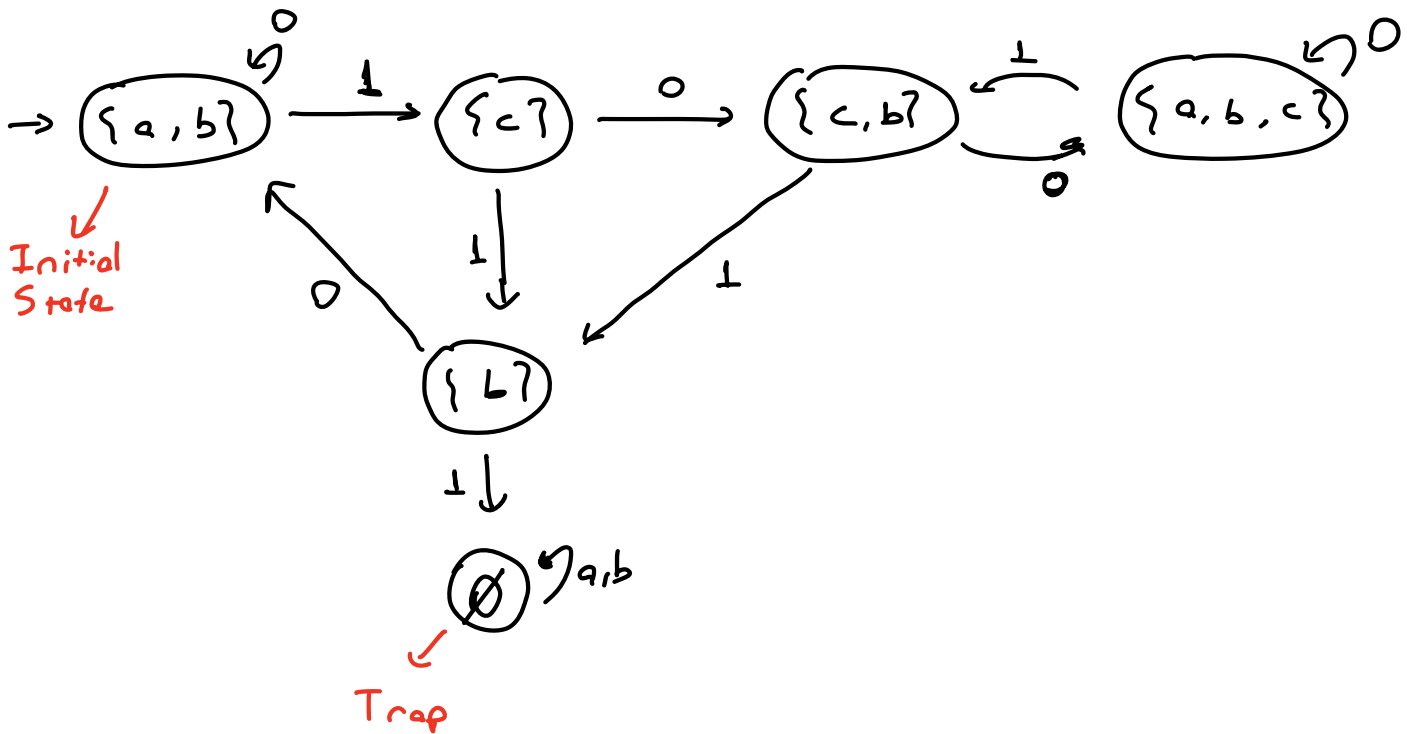
2.2 state

②.2 $\{c, b\} \xrightarrow{0} \{a, b, c\}$
 $\{c, b\} \xrightarrow{1} \{b\}$

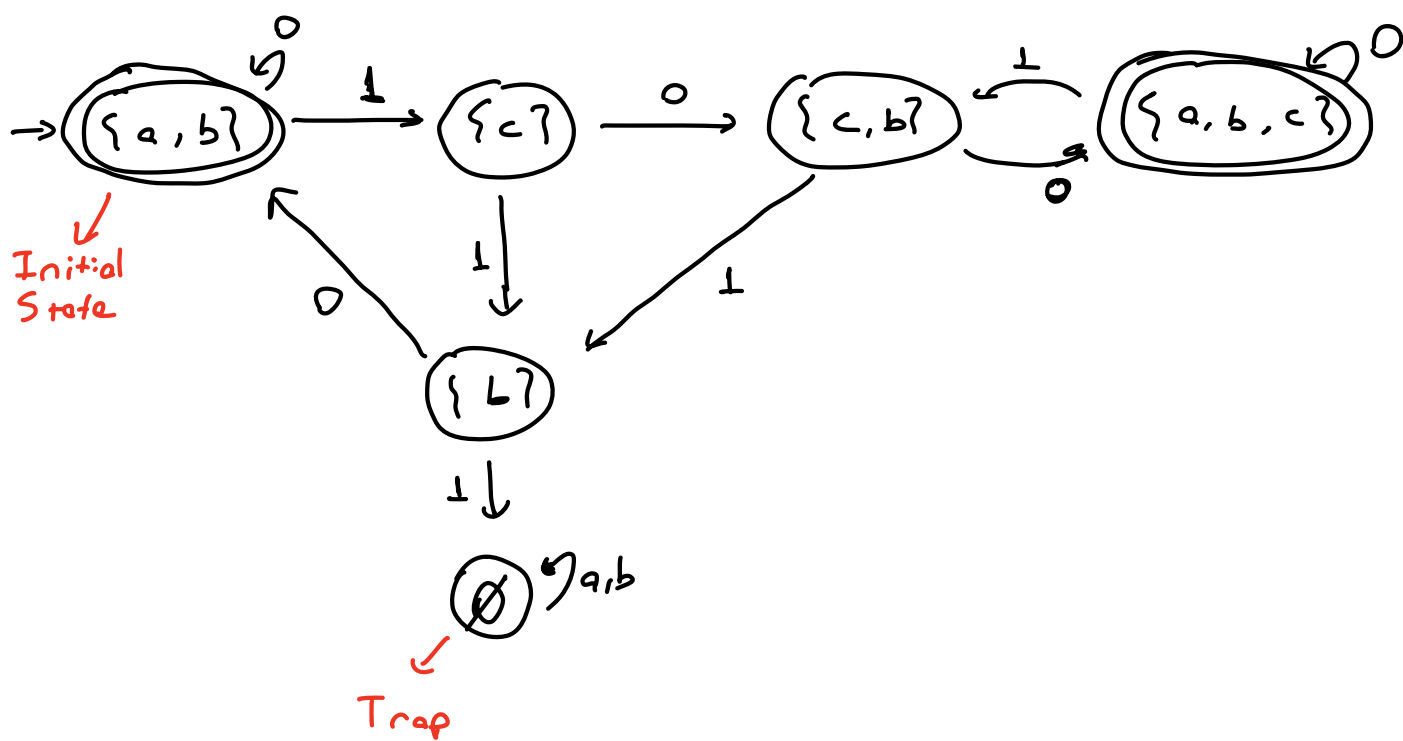
②.3 $\{b\} \xrightarrow{0} \{a, b\}$
 $\{b\} \xrightarrow{1} \emptyset$

②.4 $\{a, b, c\} \xrightarrow{0} \{a, b, c\}$
 $\{a, b, c\} \xrightarrow{1} \{c, b\}$

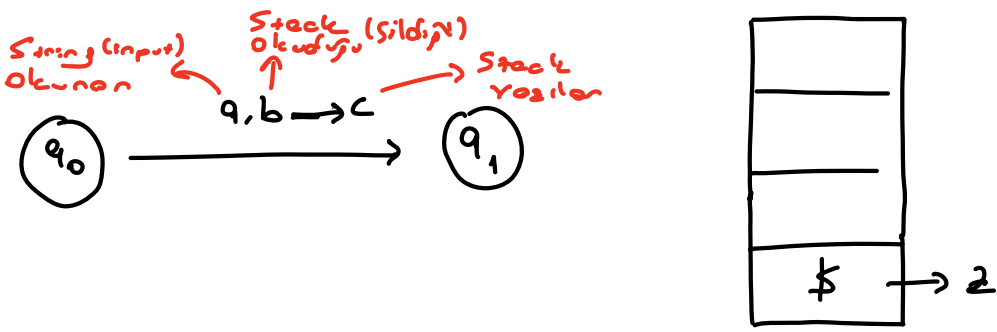
②.5. DFA çizim:



③ Finite State bulma (a'nın olduğu bütün durumlar)

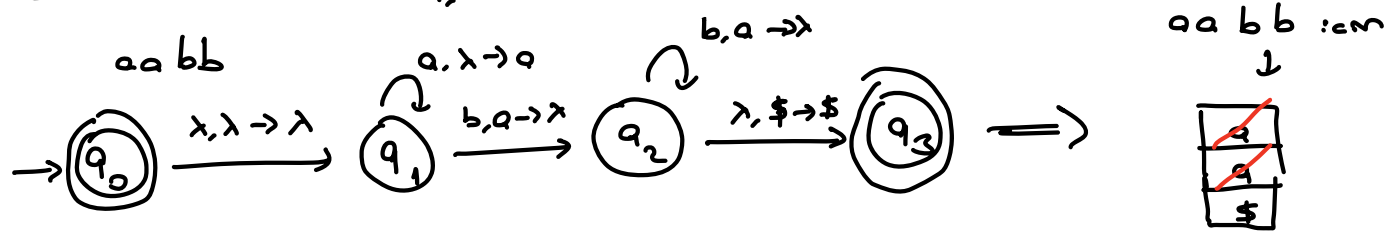


PDA (Push Down Automate)

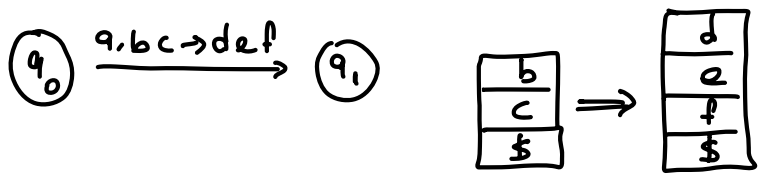


Örnek 1:

$$L(M) = \{a^n b^n : n \geq 0\}$$

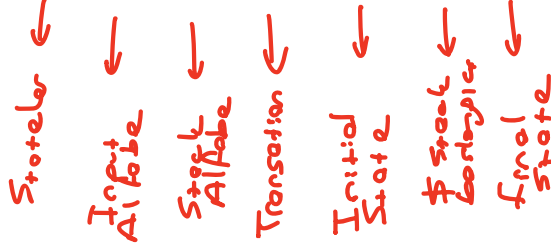


Örnek 2:

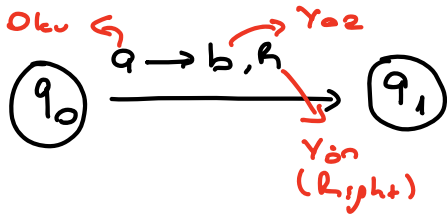


PDA'nın formal definitionı şudur:

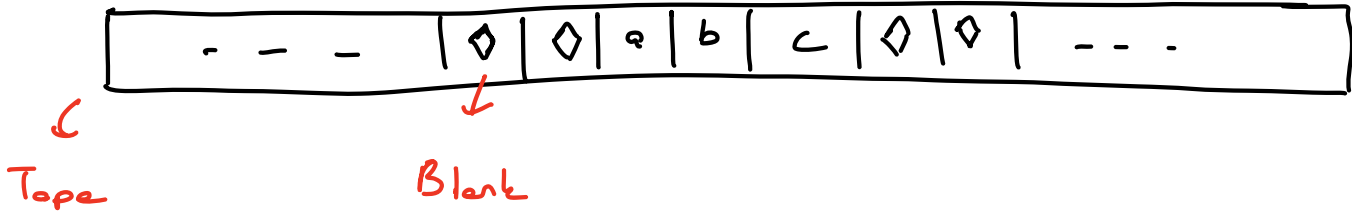
$$M = (Q, \Sigma, \Gamma, \delta, q_0, z, f)$$



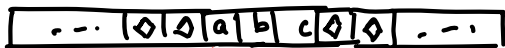
Turing Makinesi:



↳ Turing makinesinde sapa/sola hareket edebilme! Söyler.



Örnek: * Y-karidolu tape'e göre;



1. a bulunduğün yere "c" yaz "R" sapa koy



2. b bulunduğün yere "a" yaz "L" sapa koy



Halt (İlerlemenin Durması)

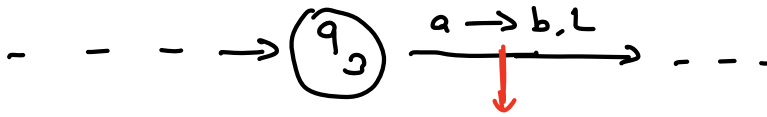
Bu durum ya bütün state yollarının sonuna gelinilmiş ya da bir state durum ile aşılmış ve ilerlenilemez duruma sokulmuştur.

①



Bu durum "Halt" olmuştur.

②



Bu durum "Halt" olmuştur.
"a" değeri yoktur. Bu durum sola/sağa kaymada da yapılabilir.

Örnek:

$f(x, y) = x + y$ (Bunu 1'lerle yap) Yani: $\left. \begin{array}{l} 2 = 11 \\ 3 = 111 \end{array} \right\} \text{gibi}$

$2+3=5=11111 \rightarrow 06001$

