

# Lenet 實作解說

Speaker: Jerry  
Date: 2019/6/22

# 目錄

## 1. 簡介

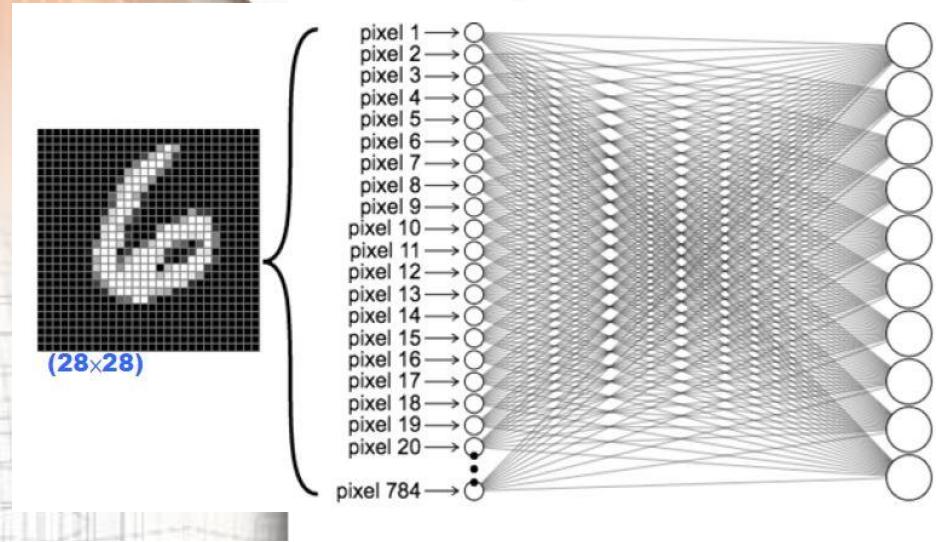
- FC v.s. CNN
- MNIST訓練資料
- Lenet架構解說

## 2. 程式碼解說

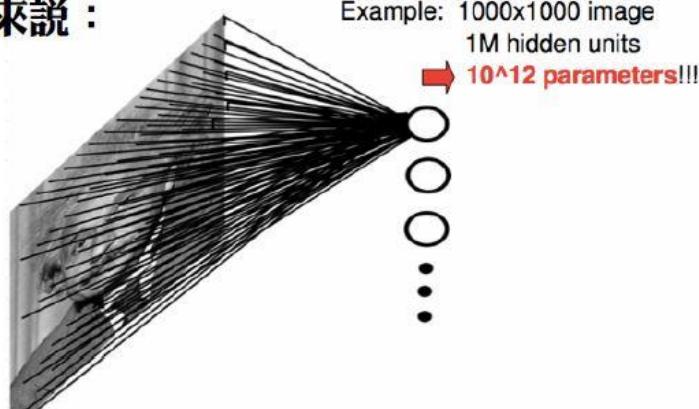
- 環境安裝
- Tensorflow版
- 補充
- 純Python

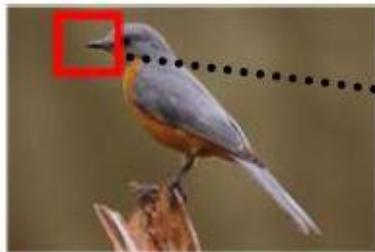
# 簡介

# Fully Connected NN

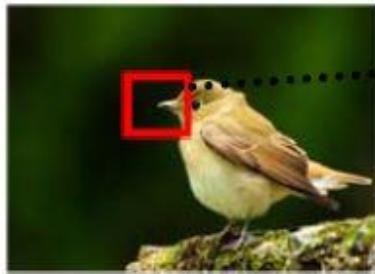


以一張具百萬像素的image來說：

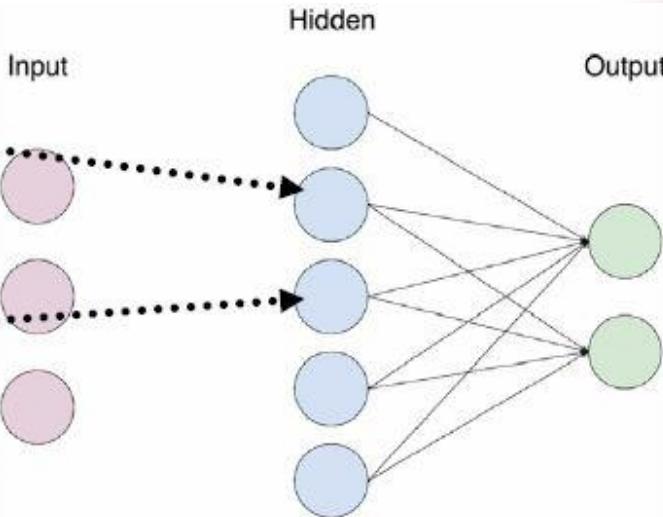
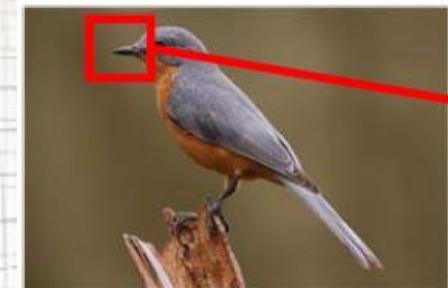




上方鳥嘴偵測

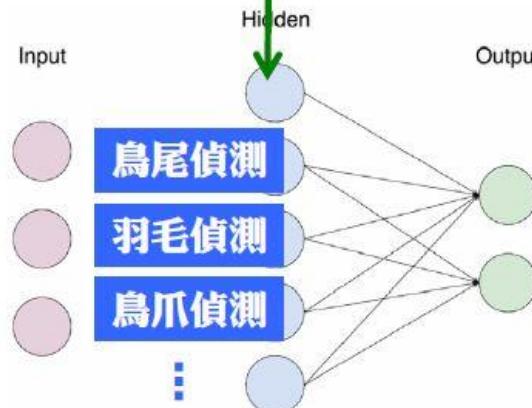


中間鳥嘴偵測

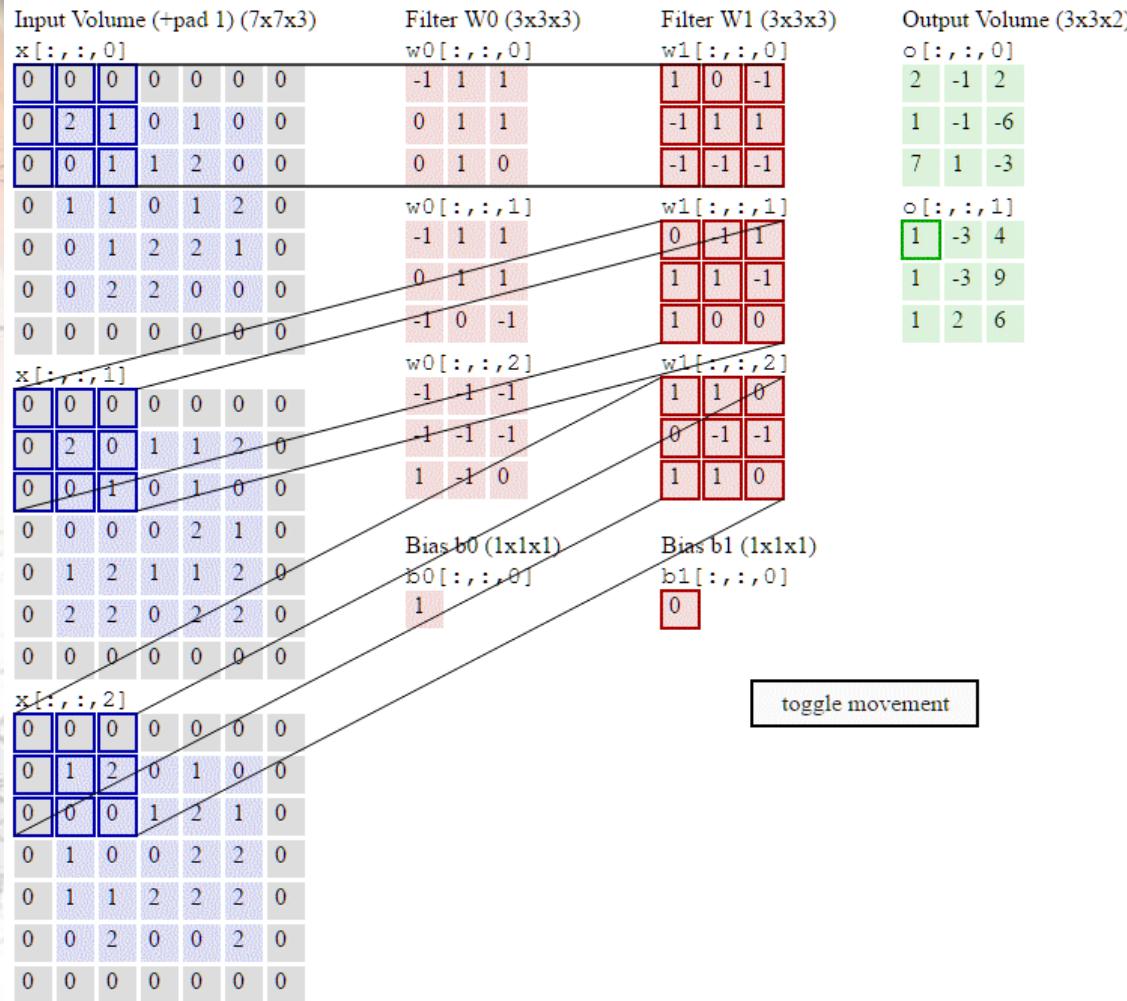


每個節點僅需以**較少的參數**，連  
結**部份區域**。

所有節點的偵測結果合併起來  
後，就可以得知圖片中是否有一  
隻鳥。

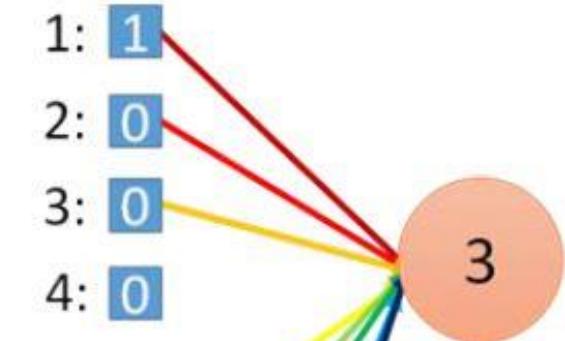
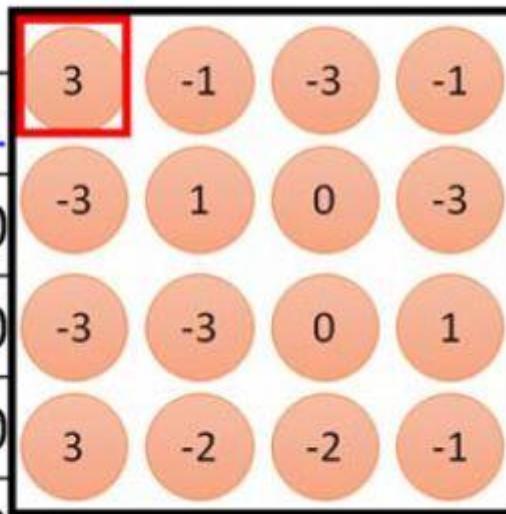
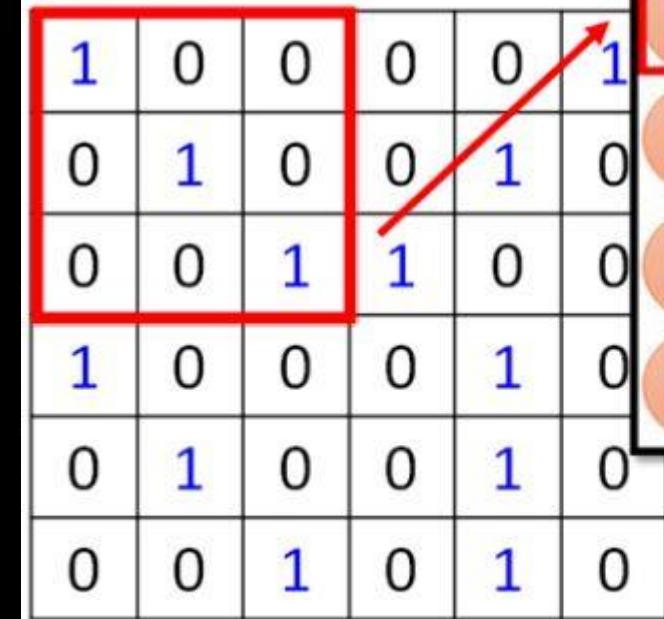


# Receptive Field and Shared weight





Filter 1



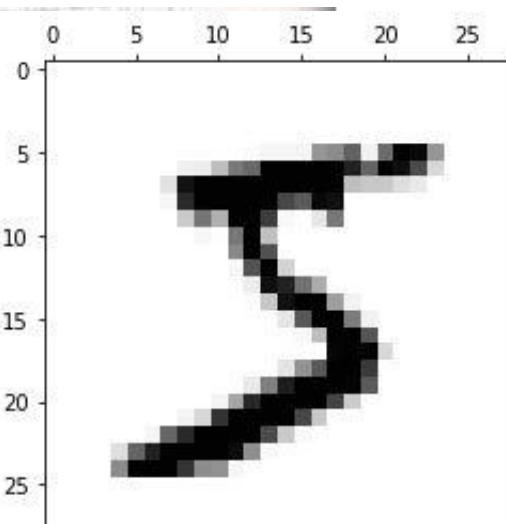
1:	1
2:	0
3:	0
4:	0
:	
7:	0
8:	1
9:	0
10:	0
:	
13:	0
14:	0
15:	1
16:	1
:	
36:	0

Only connect to 9  
input, not fully  
connected

# MNIST Dataset

Four files are available on this site:

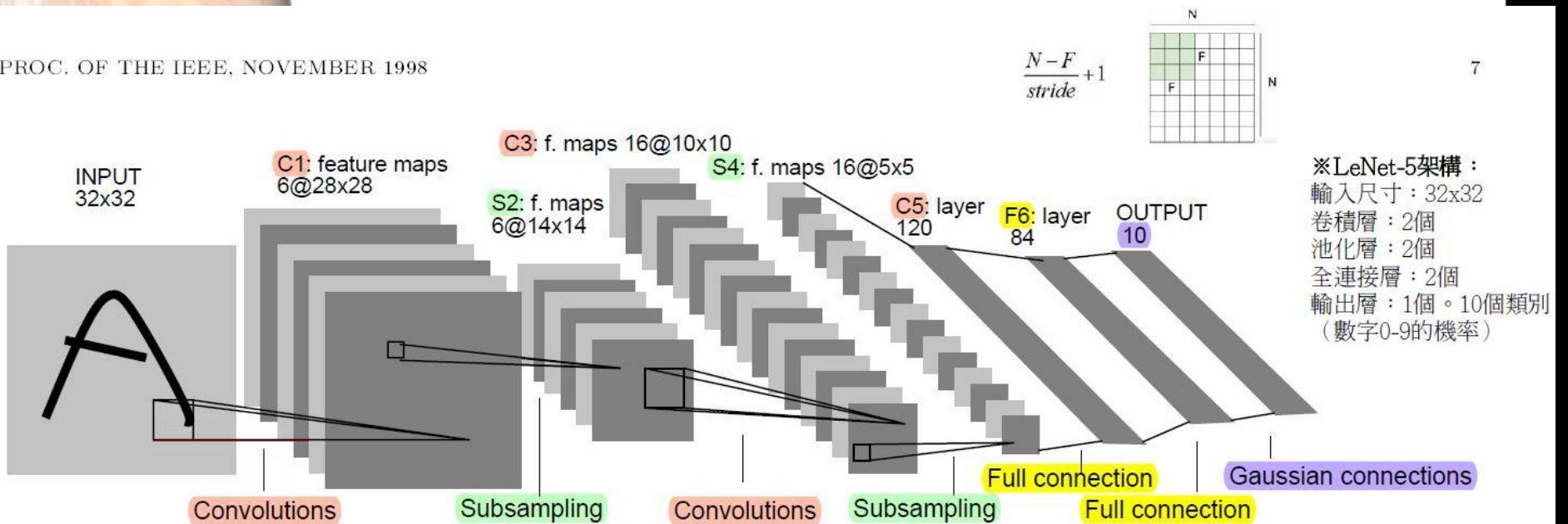
[train-images-idx3-ubyte.gz](#): training set images (9912422 bytes)  
[train-labels-idx1-ubyte.gz](#): training set labels (28881 bytes)  
[t10k-images-idx3-ubyte.gz](#): test set images (1648877 bytes)  
[t10k-labels-idx1-ubyte.gz](#): test set labels (4542 bytes)



# Lenet架構

PROC. OF THE IEEE, NOVEMBER 1998

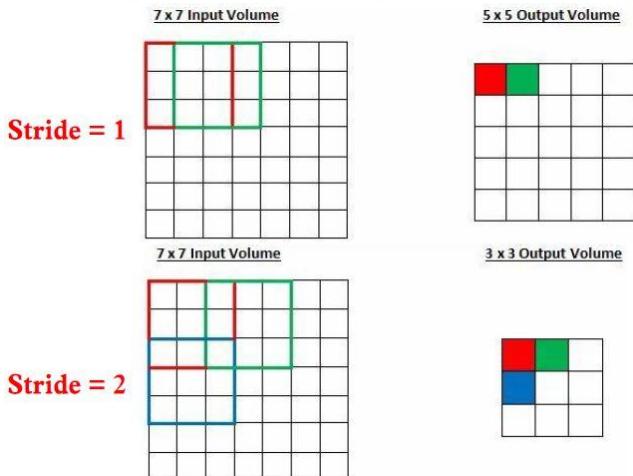
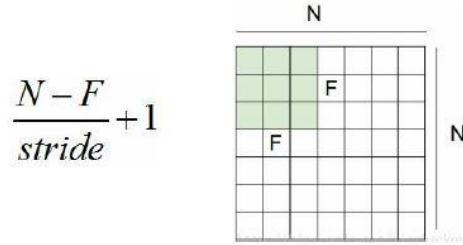
7



9

Layer	Feature Map	Size	Kernel Size	Stride	Activation
Input	Image	1	32x32	-	-
1	Convolution	6	28x28	5x5	1
2	Average Pooling	6	14x14	2x2	2
3	Convolution	16	10x10	5x5	1
4	Average Pooling	16	5x5	2x2	2
5	Convolution	120	1x1	5x5	1
6	FC	-	84	-	tanh
Output	FC	-	10	-	softmax

Output size at different stride...



# 程式碼解說

# 。環境安裝

到官方網站下載Anaconda，安裝後可進入到下面步驟!!

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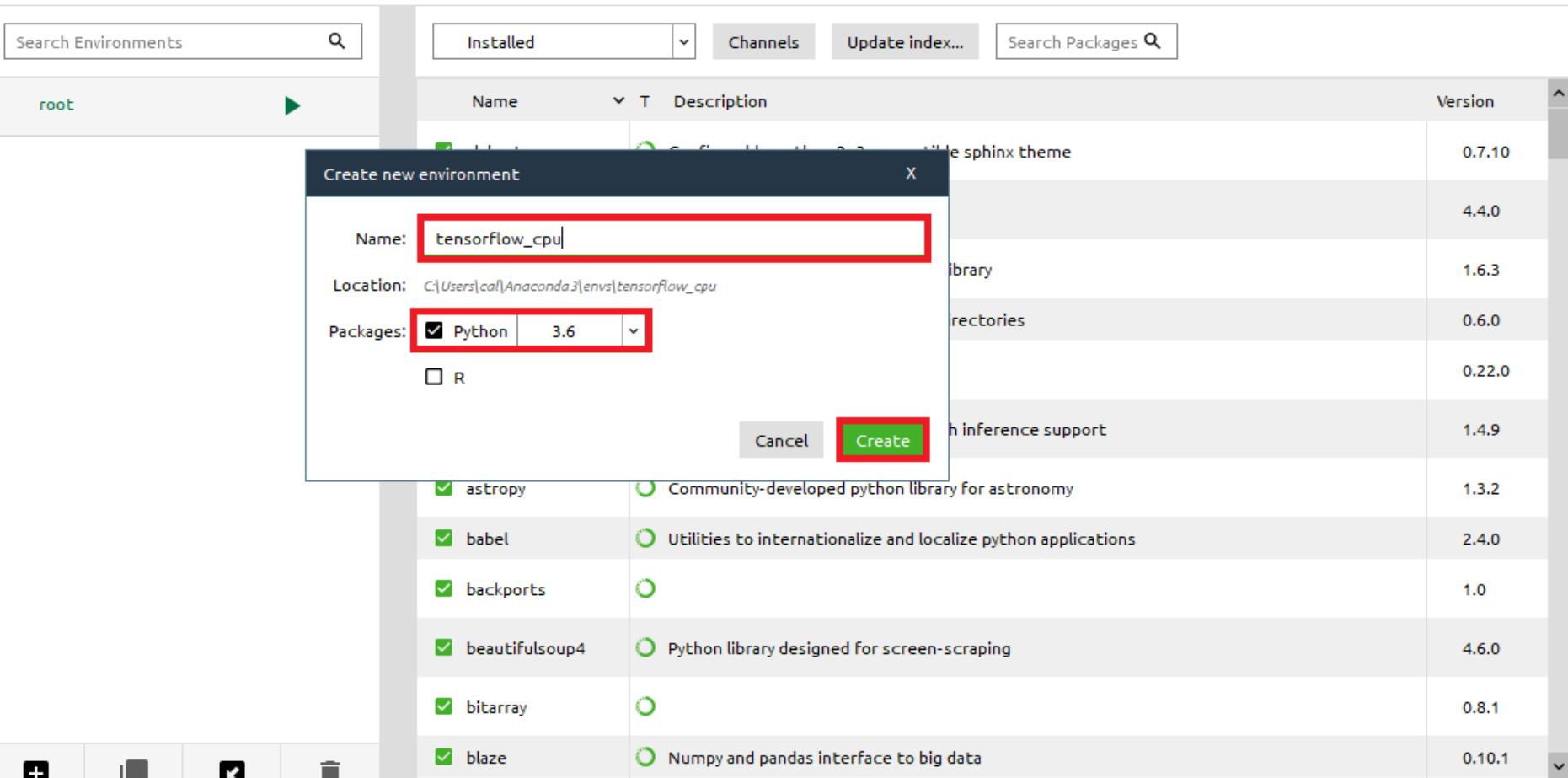
Update index...

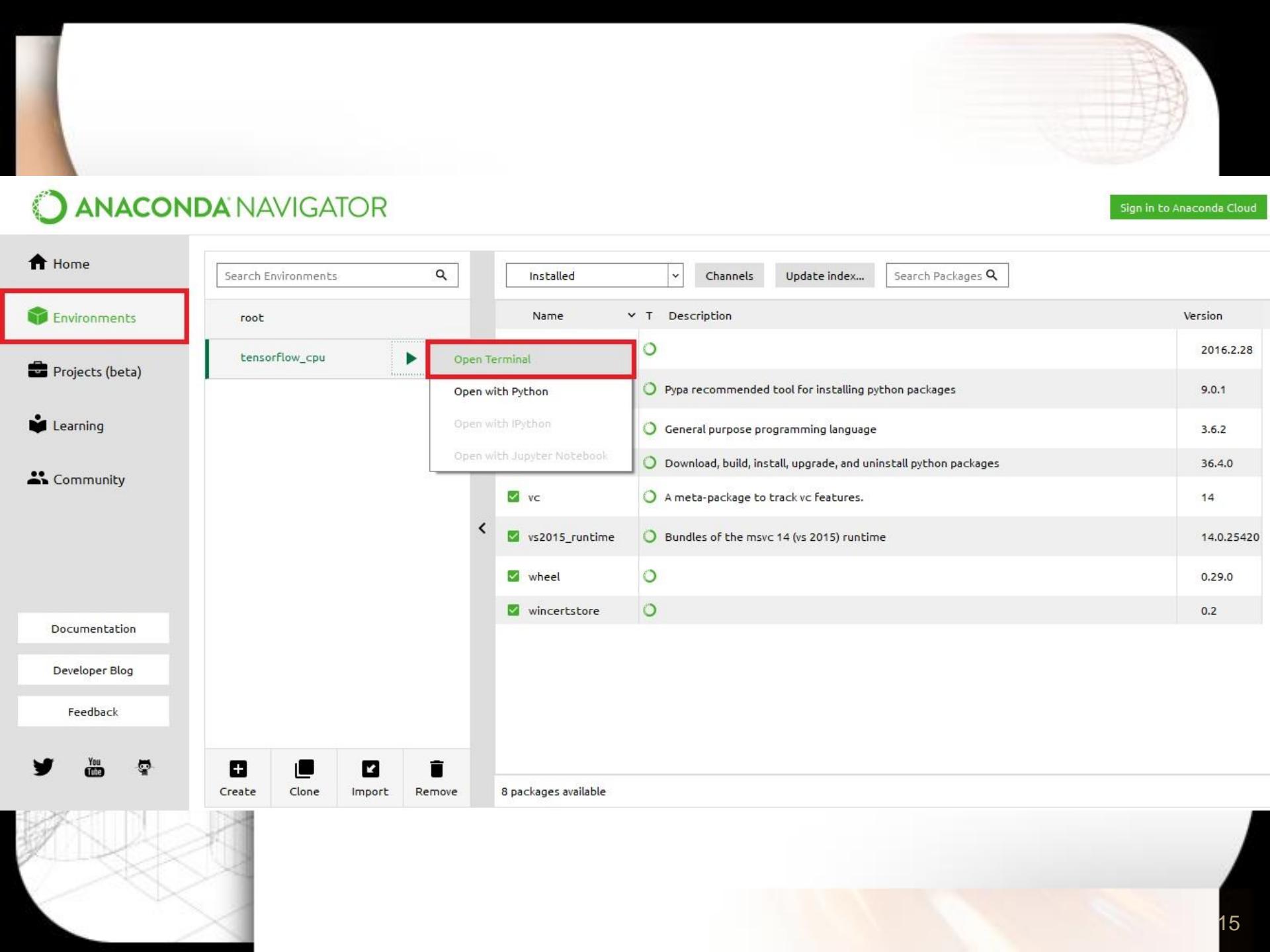
Search Packages

root

Name	Description	Version
alabaster	Configurable, python 2+3 compatible sphinx theme	0.7.10
anaconda		4.4.0
anaconda-client	Anaconda.org command line client library	1.6.3
anaconda-project	Reproducible, executable project directories	0.6.0
asn1crypto		0.22.0
astroid	Abstract syntax tree for python with inference support	1.4.9
astropy	Community-developed python library for astronomy	1.3.2
babel	Utilities to internationalize and localize python applications	2.4.0
backports		1.0
beautifulsoup4	Python library designed for screen-scraping	4.6.0
bitarray		0.8.1
blaze	Numpy and pandas interface to big data	0.10.1

178 packages available



A large, semi-transparent globe graphic is positioned at the top right of the interface, showing a wireframe mesh against a light blue gradient.

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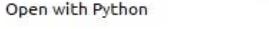
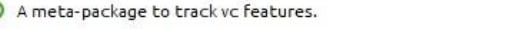
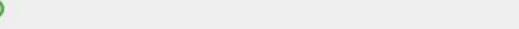


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Search Environments 		Installed	Channels	Update index...	Search Packages 
root		Name	T	Description	Version
	 tensorflow_cpu		 Open Terminal	 Open with Python	2016.2.28
				 Open with IPython	9.0.1
				 Open with Jupyter Notebook	3.6.2
			 vc	 Pypy recommended tool for installing python packages	36.4.0
			 vs2015_runtime	 General purpose programming language	14
			 wheel	 Download, build, install, upgrade, and uninstall python packages	14.0.25420
			 wincerstore	 A meta-package to track vc features.	0.29.0
					0.2

8 packages available

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tensorflow\_cpu

root

✓ tensorflow\_cpu

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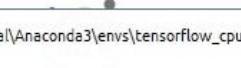
Refresh



glueviz

0.10.4

Multidimensional data visualization across files. Explore relationships within and among related datasets.

[Install](#)

notebook

5.0.0

Web-based, interactive computing notebook environment. Edit and run human-readable docs while describing the data analysis.

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orange3

3.4.1

Component based data mining framework. Data visualization and data analysis for novice and expert. Interactive workflows with a large toolbox.

[Install](#)

qtconsole

4.3.1

PyQt GUI that supports inline figures, proper multiline editing with syntax highlighting, graphical calltips, and more.

[Install](#)

rstudio

1.1.456

A set of integrated tools designed to help you be more productive with R. Includes R essentials and notebooks.



spyder

3.2.3

Scientific PYthon Development Environment. Powerful Python IDE with advanced editing, interactive testing,

# 打開Terminal



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root

tensorflow\_cpu

Open Terminal

Open with Python

Open with IPython

Open with Jupyter Notebook



vc



vs2015\_runtime



wheel



wincerstore



Pypa recommended tool for installing python packages

2016.2.28

General purpose programming language

9.0.1

Download, build, install, upgrade, and uninstall python packages

36.4.0

A meta-package to track vc features.

14

Bundles of the msvc 14 (vs 2015) runtime

14.0.25420



8 packages available

# 安裝pip和cpu版tensorflow

```
(C:\Users\cal\Anaconda3\envs\tensorflow_cpu) C:\Users\cal>conda install -c anaconda pip  
Fetching package metadata .....  
Solving package specifications: .
```

```
C:\Users\chinja>pip install tensorflow == 1.13.1
```

# 安裝 Spyder

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0.10.4

Multidimensional data visualization across files. Explore relationships within and among related datasets.

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5.0.0

Web-based, interactive computing notebook environment. Edit and run human-readable docs while describing the data analysis.

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qtconsole

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PyQt GUI that supports inline Figures, proper multiline editing with syntax highlighting, graphical calltips, and more.

Install



rstudio

1.1.456

A set of integrated tools designed to help you be more productive with R. Includes R essentials and notebooks.

Install



spyder



Scientific PYthon Development EnviRonment. Powerful Python IDE with advanced editing, interactive testing, debugging and introspection features

Install

Install application spyder==3.2.3 on C:\Users\cal\Anaconda3\envs\tensorflow\_cpu Fetching spyder-3.2.3-p...

Editor - C:\Users\cal\Desktop\Pytorch\_Taiwan\2019\_06\_22\LeNet\_New\test.py

temp.py LeNet\_train.py testpy

Source Console Object

```
1 # -*- coding: utf-8 -*-
2 """
3 Created on Thu Jun 20 22:45:51 2019
4
5 @author: cal
6 """
7
8 import tensorflow as tf
9 hello = tf.constant('Hello, tensorflow')
10 sess = tf.Session()
11 print(sess.run(hello))
```

Usage

Variable explorer File explorer Help

History log

history.py

```
## ---(Fri Jun 21 18:48:03 2019)---
runfile('C:/Users/cal/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New/test.py', wdir='C:/Users/cal/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New')
```

IPython console

Console I/A

```
Python 3.6.2 |Continuum Analytics, Inc.| (default, Jul 20 2017, 12:30:02) [MSC v.1900 64 bit (AMD64)]
Type "copyright", "credits" or "license" for more information.

IPython 6.1.0 -- An enhanced Interactive Python.

In [1]: runfile('C:/Users/cal/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New/test.py', wdir='C:/Users/cal/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New')
b'Hello, tensorflow'
```

顯示此字樣代表安裝成功!!

Permissions: RW End-of-lines: CRLF Encoding: UTF-8 Line: 11 Column: 21 Memory: 52%

2019/6/21

# Numpy 安裝

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Not installed

Upgradable

Selected

All

numpy

輸入numpy

選擇Not installed

description

Version

	Description	Version
<input type="checkbox"/> netcdf4	Python/numpy interface to netcdf library	1.2.4
<input type="checkbox"/> numba	Numpy aware dynamic python compiler using llvmlite	0.33.0
<input type="checkbox"/> numexpr	Fast numerical expression evaluator for numpy	2.6.2
<input type="checkbox"/> numpy	Array processing for numbers, strings, records, and objects	1.11.3
<input type="checkbox"/> snuggs	S-expressions for numpy	1.4.0

8 packages available matching "numpy"

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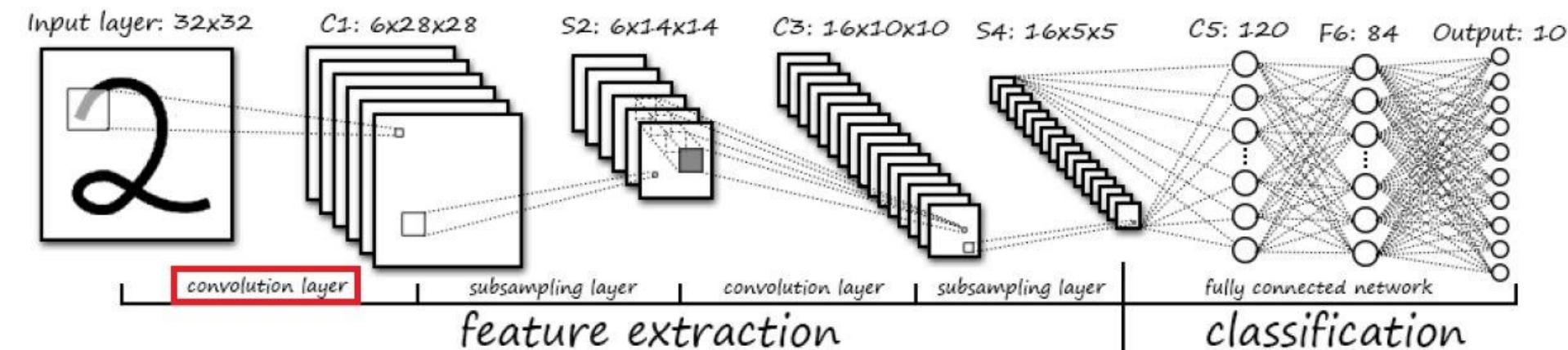
# Tensorflow版

# Layer 1: Convolution

```
#Layer 1: Convolution (32x32x1 -> 28x28x6)
```

```
conv1_w = tf.Variable(tf.random_normal([5,5,1,6]))  
conv1_b = tf.Variable(tf.zeros([6]))  
conv1 = tf.nn.conv2d(x, conv1_w, strides = [1,1,1,1], padding = 'VALID') + conv1_b  
## Activation function  
conv1 = tf.nn.sigmoid(conv1)
```

Layer C1 is a convolutional layer with 6 feature maps. Each unit in each feature map is connected to a 5x5 neighborhood in the input. The size of the feature maps is 28x28

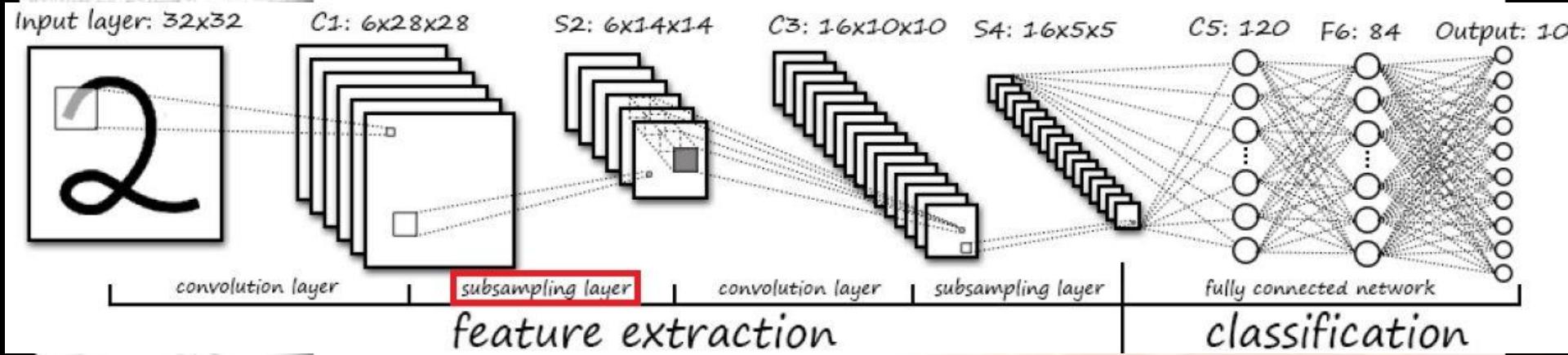


# Layer 2: Max pooling

#Layer 2: Max pooling (28x28x6 -> 14x14x6)

```
conv1 = tf.nn.max_pool(conv1, ksize = [1,2,2,1], strides = [1,2,2,1], padding = 'VALID')
```

Layer S2 is a sub-sampling layer with 6 feature maps of size 14x14. Each unit in each feature map is connected to a 2x2 neighborhood in the corresponding feature map in C1.



# Layer 3: Convolution

```
#Layer 3: Convolution (14x14x6 -> 10x10x16)
```

```
conv2_w = tf.Variable(tf.random_normal([5,5,6,16]))
```

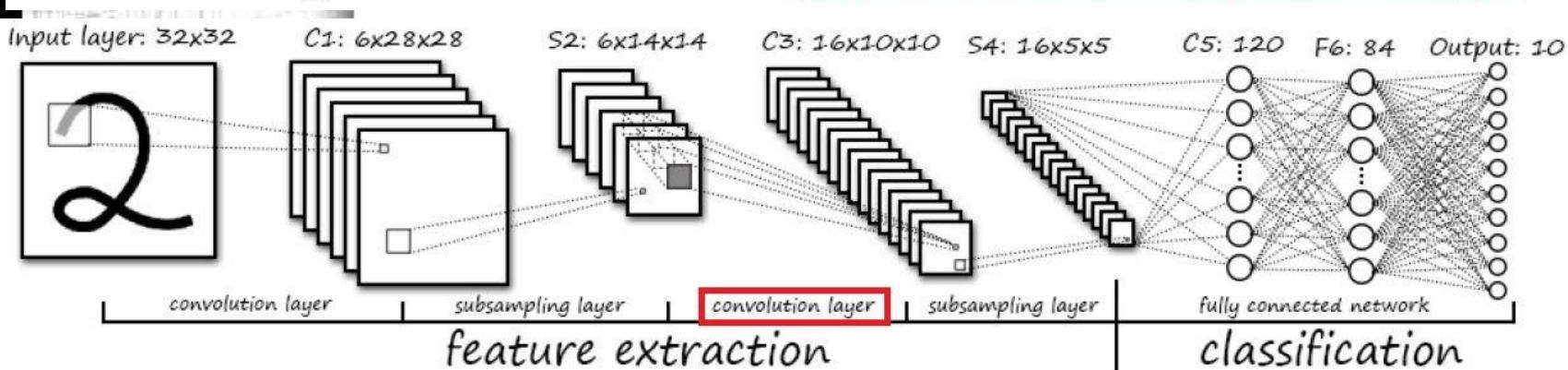
```
conv2_b = tf.Variable(tf.zeros([16]))
```

```
conv2 = tf.nn.conv2d(conv1, conv2_w, strides = [1,1,1,1], padding = 'VALID') + conv2_b
```

```
## Activation function
```

```
conv2 = tf.nn.sigmoid(conv2)
```

Layer C3 is a convolutional layer with 16 feature maps. Each unit in each feature map is connected to several 5x5 neighborhoods at identical locations in a subset of S2's feature maps. Table I shows the set of S2 feature maps





**Layer C3:**

**1516 trainable parameters.**

$$=(3*5*5+1)*6+(4*5*5+1)*9+(6*5*5+1)$$

**Connections: 151600**

$$(3*5*5+1)*6*10*10+(4*5*5+1)*9*10*10$$

$$+(6*5*5+1)*10*10$$

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	X			X	X	X			X	X	X	X		X	X	
1	X	X			X	X	X			X	X	X	X		X	
2	X	X	X			X	X	X			X		X	X	X	
3		X	X	X		X	X	X	X		X		X	X	X	
4		X	X	X		X	X	X	X		X	X		X	X	
5			X	X	X		X	X	X	X		X	X	X	X	

TABLE I

EACH COLUMN INDICATES WHICH FEATURE MAP IN S2 ARE COMBINED

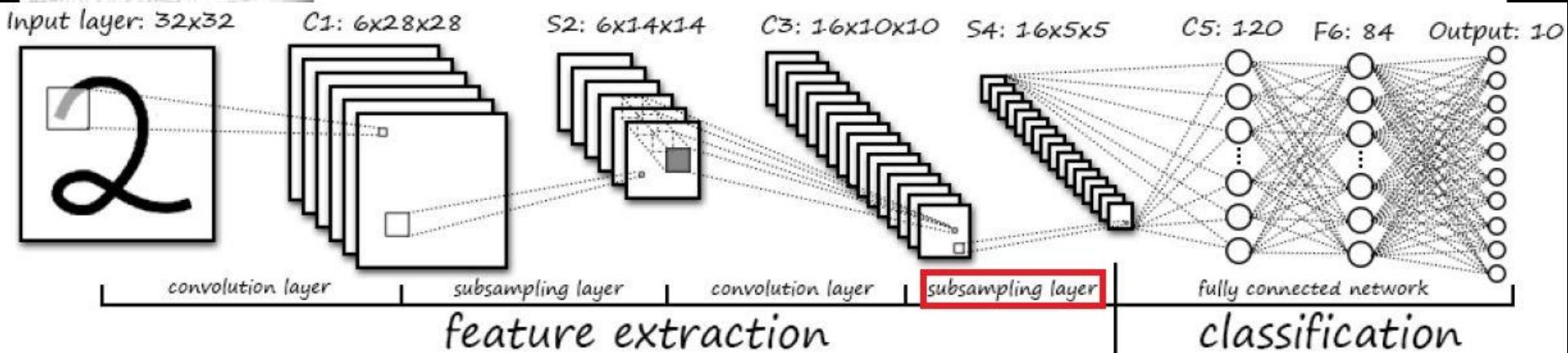
BY THE UNITS IN A PARTICULAR FEATURE MAP OF C3.

# Layer 4: Max pooling

#Layer 4: Max pooling (10x10x16 -> 5x5x16)

```
conv2 = tf.nn.max_pool(conv2, ksize = [1,2,2,1], strides = [1,2,2,1], padding = 'VALID')
```

Layer S4 is a sub-sampling layer with 16 feature maps of size 5x5. Each unit in each feature map is connected to a 2x2 neighborhood in the corresponding feature map in C3, in a similar way as C1 and S2. Layer S4 has 32 trainable

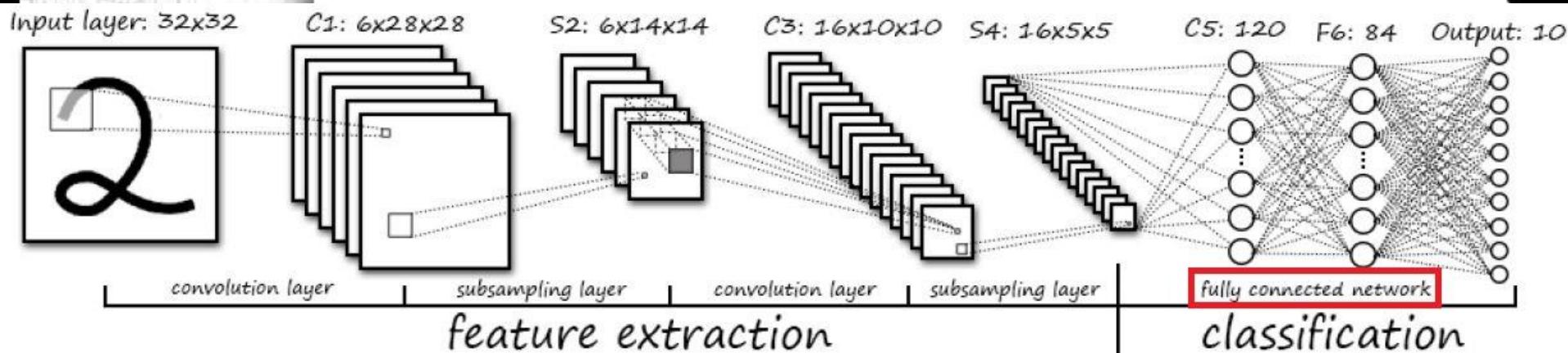


# Layer 5: Fully Connected

```
#Layer 5: Fully Connected (5x5x16 = 400 -> 120)
dense1_w = tf.Variable(tf.random_normal([400,120]))
dense1_b = tf.Variable(tf.zeros([120]))
conv2 = flatten(conv2)
dense1 = tf.matmul(conv2, dense1_w) + dense1_b
## Activation function
dense1 = tf.nn.sigmoid(dense1)
```

Layer C5 is a convolutional layer with 120 feature maps. Each unit is connected to a 5x5 neighborhood on all 16 of S4's feature maps. Here, because the size of S4 is also 5x5, the size of C5's feature maps is 1x1; this amounts to a full connection between S4 and C5. C5 is labeled

湊巧變成FC!!!

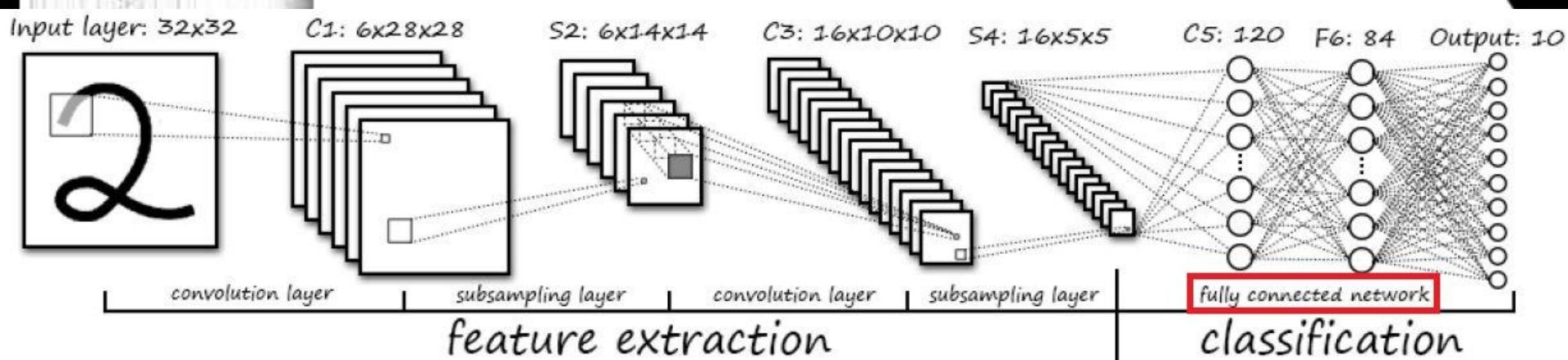


# Layer 6: Fully Connected

```
#Layer 6: Fully Connected (120 -> 84)
```

```
dense2_w = tf.Variable(tf.random_normal([120, 84]))  
dense2_b = tf.Variable(tf.zeros([84]))  
dense2 = tf.matmul(dense1, dense2_w) + dense2_b  
## Activation function  
dense2 = tf.nn.sigmoid(dense2)
```

Layer F6, contains 84 units (the reason for this number comes from the design of the output layer, explained below) and is fully connected to C5. It has 10,164 trainable parameters.



# Layer 7: Fully Connected

```
#Layer 7: Fully Connected (84 -> 10)
dense3_w = tf.Variable(tf.random_normal([84,10]))
dense3_b = tf.Variable(tf.zeros([10]))
dense3 = tf.matmul(dense2, dense3_w) + dense3_b

return dense3
```

In other words, each output RBF unit computes the Euclidean distance between its input vector and its parameter vector. The further away is the input from the parameter vector, the larger is the RBF output. The output of a 7x12 bitmap (hence the number 84)

**Output layer:** 10RBF (One for each digit)

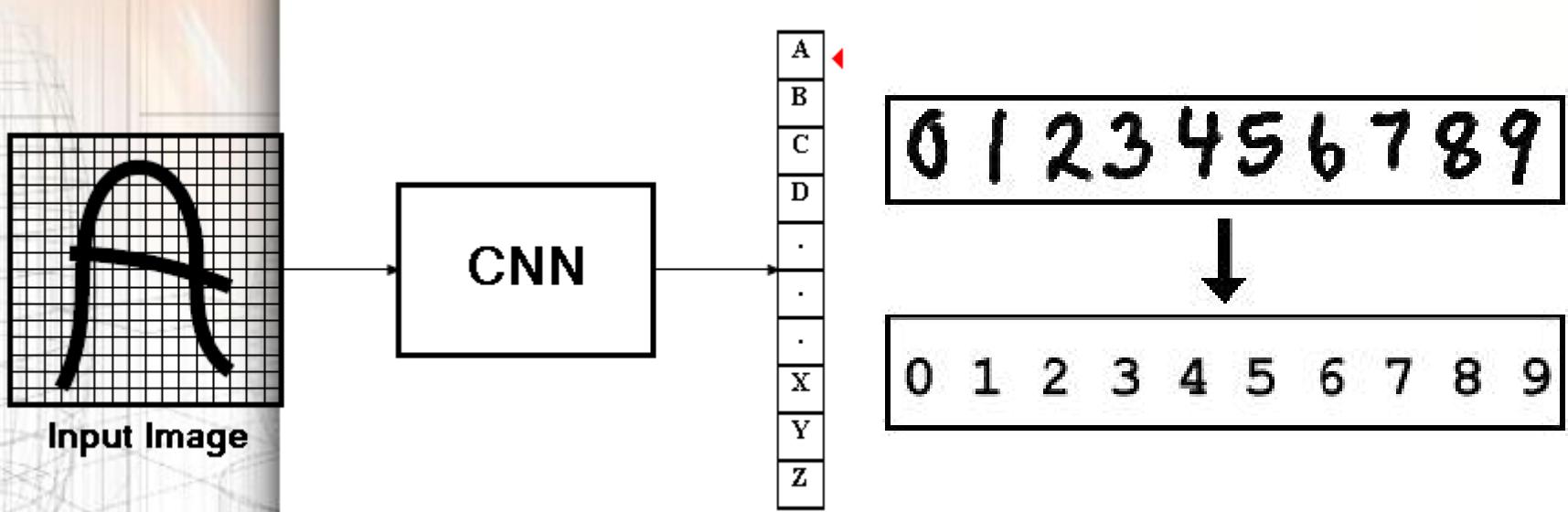
$$y_i = \sum_{j=1}^{84} (x_j - w_{ij})^2, \quad i = 1, \dots, 10.$$

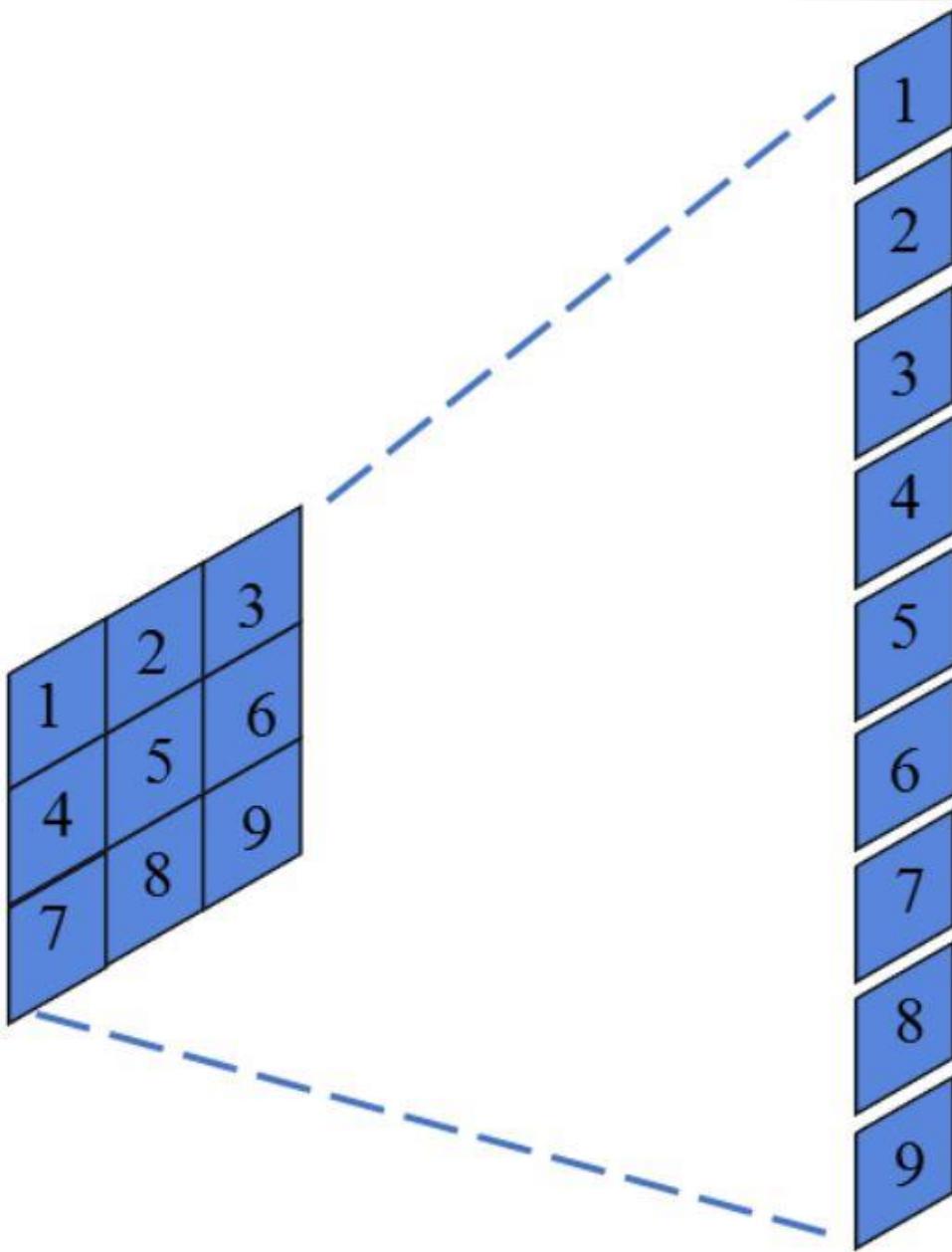
84=7x12, stylized image.

From F6

84 parameters, 84\*10 connections

# Fully Connected





# 補充

	<b>Underfitting</b>	<b>Just right</b>	<b>Overfitting</b>
<b>Symptoms</b>	<ul style="list-style-type: none"> <li>- High training error</li> <li>- Training error close to test error</li> <li>- High bias</li> </ul>	<ul style="list-style-type: none"> <li>- Training error slightly lower than test error</li> </ul>	<ul style="list-style-type: none"> <li>- Low training error</li> <li>- Training error much lower than test error</li> <li>- High variance</li> </ul>
<b>Regression</b>			
<b>Classification</b>			
<b>Deep learning</b>			
<b>Remedies</b>	<ul style="list-style-type: none"> <li>- Complexify model</li> <li>- Add more features</li> <li>- Train longer</li> </ul>		<ul style="list-style-type: none"> <li>- Regularize</li> <li>- Get more data</li> </ul>

# Validation Dataset

- Validation dataset 用來挑選模型
- Testingdataset 檢驗模型的普遍性(generalization)  
避免模型過度學習 training dataset

## 理論上

手邊收集到的資料



Testing

挑選出最好的模型後，拿 testing 檢驗 generalization



Training

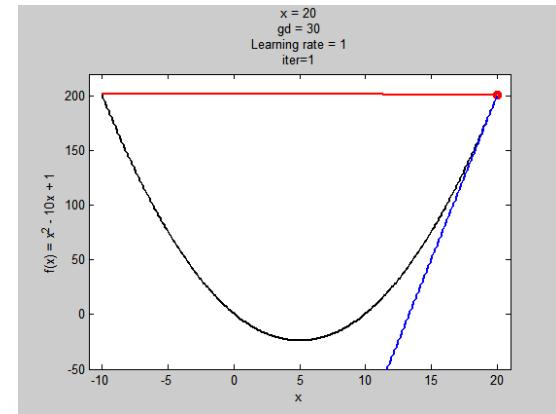
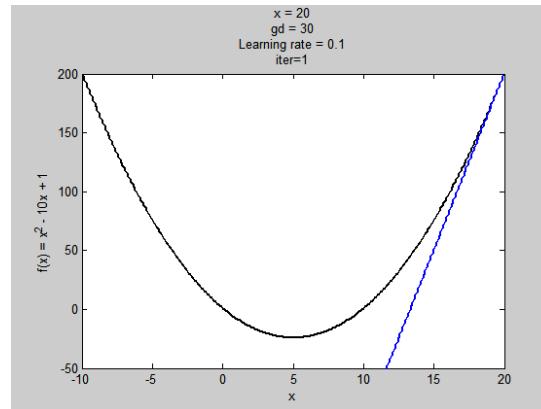
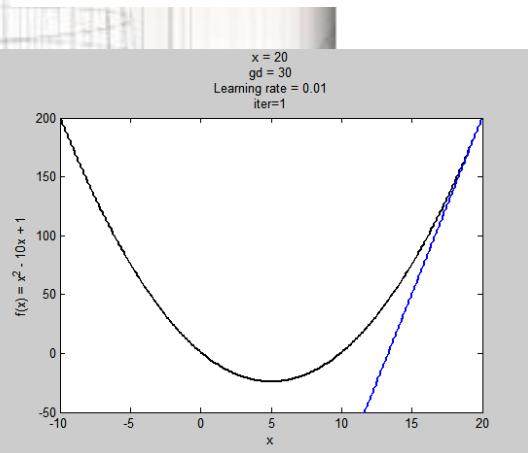
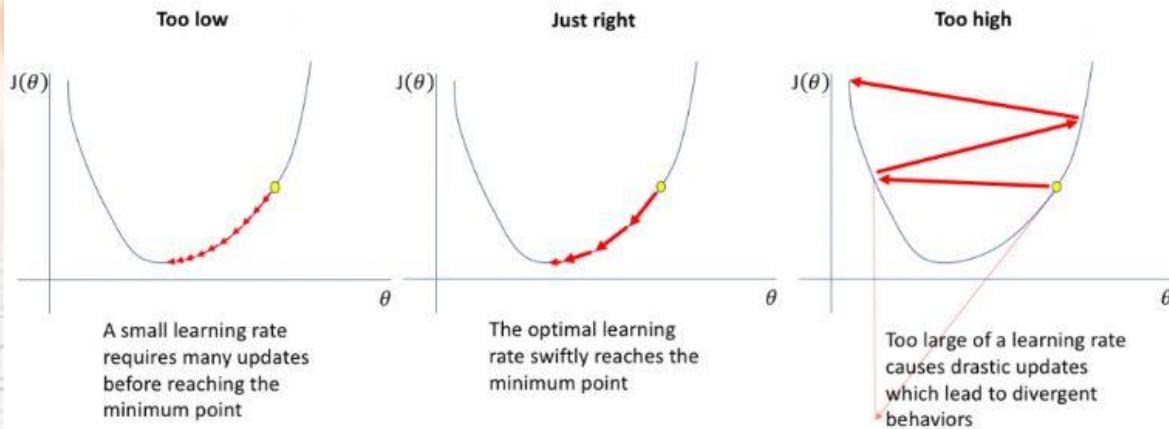
Val

Cross validation:

切出很多組的 (training, validation) 再拿不同組訓練模型，挑選最好的模型

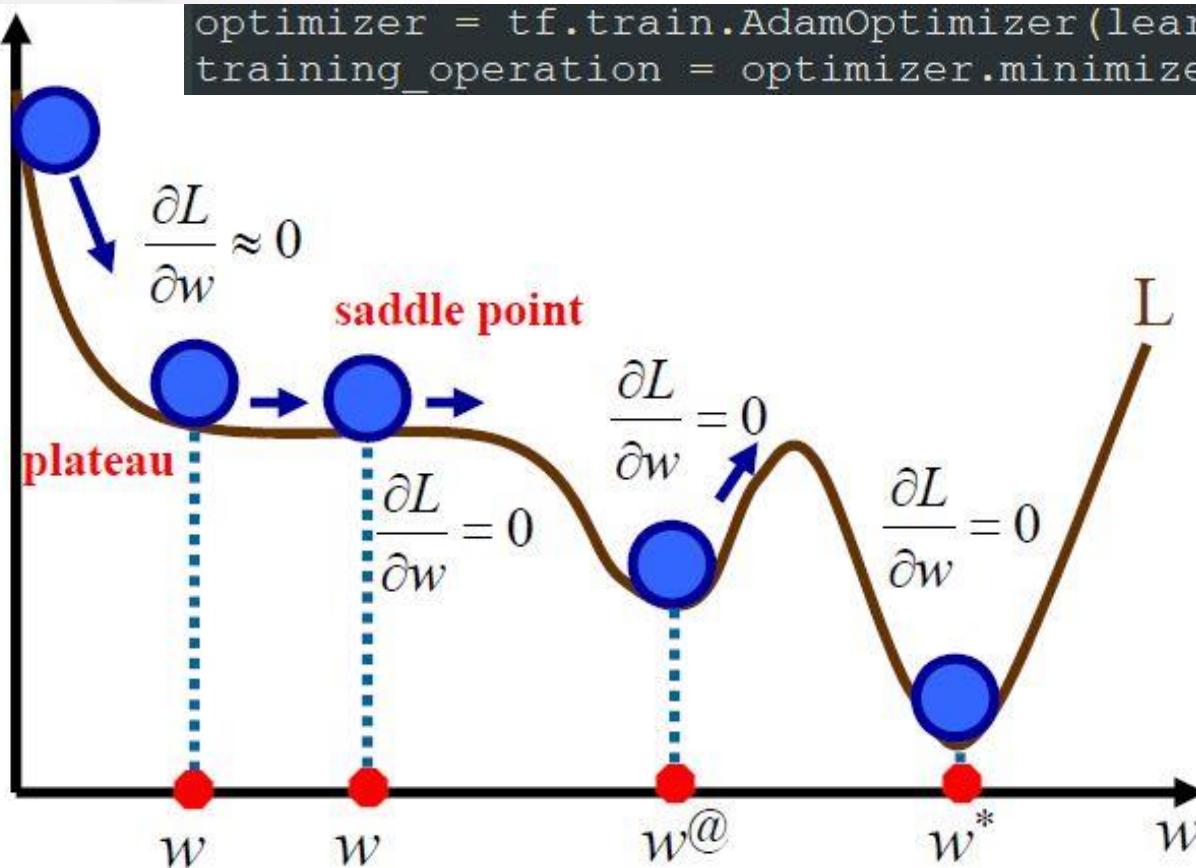


# Learning Rate



# Optimizer

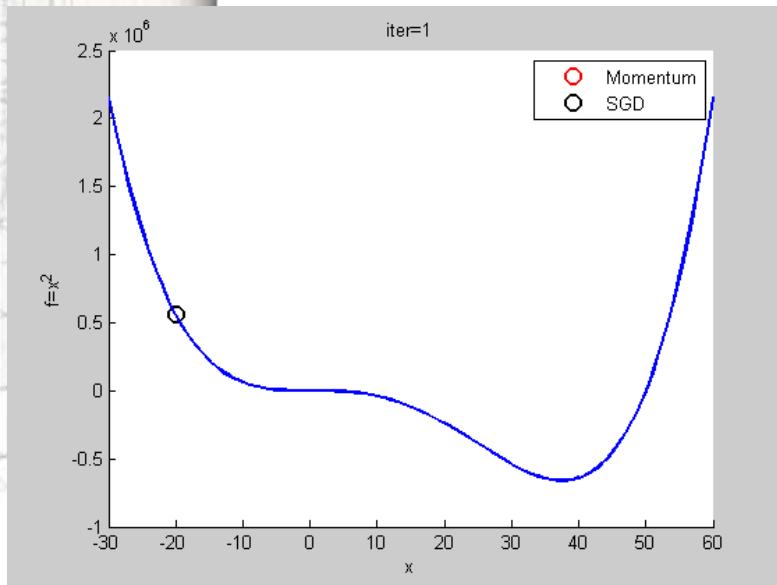
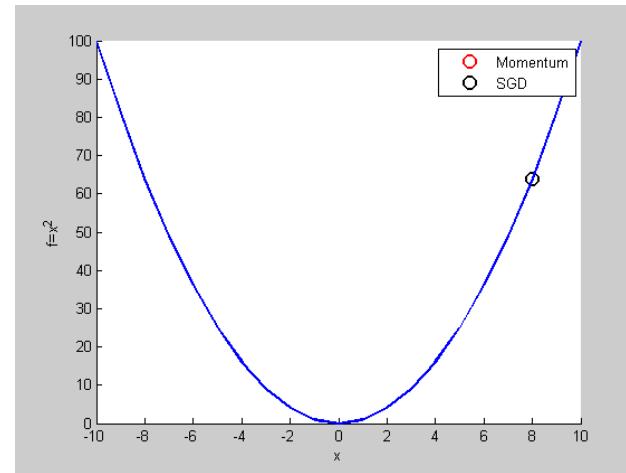
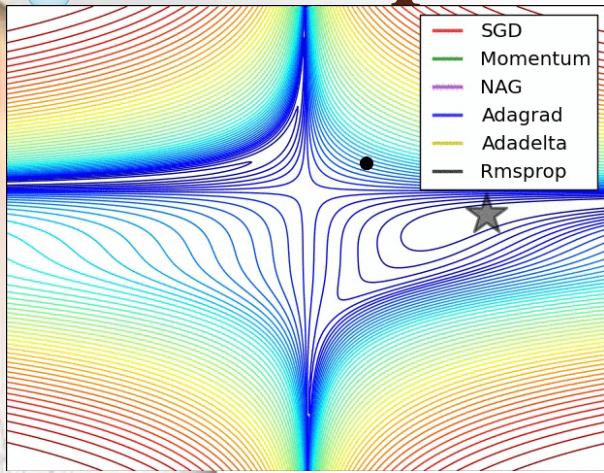
```
optimizer = tf.train.AdamOptimizer(learning_rate = rate)
training_operation = optimizer.minimize(loss_operation)
```



Local  
Optimal

Global  
Optimal

# SGD, Momentum, AdaGrad, Adam Optimizer



# 純Python版

# 1\_Layer

```
1 from numpy import *
2
3 #建立 [Size x Size] x Numbers Neurons 的 Layer
4 class Layer(object):
5     def __init__(self, layer_size = []):
6         self.layer_size = layer_size
7         self.maps = []
8
9         for map_size in layer_size:
10             self.maps.append(zeros(map_size))
11         self.maps = array(self.maps)
```

# 2\_CovLayer

```
18 class CovLayer(Layer):
19     def __init__(self, layer_size = [], cov_core_sizes = [], mapcombindex = []):
20         Layer.__init__(self, layer_size)
21         self.covcores = []
22         self.covbias = []
23         self.mapcombindex = mapcombindex
24
25     # 初始化Parameters.
26     #-2.4/Fi 和 2.4/Fi 的值都來自於論文的 Appendices A.
27     for cov_core_size in cov_core_sizes:
28         #Fi is from the definition in paper
29         Fi = cov_core_size[0] * cov_core_size[1] + 1
30         #Make random filters
31         self.covcores.append(random.uniform(-2.4/Fi, 2.4/Fi, cov_core_size))
32         #Make random biases
33         self.covbias.append(random.uniform(-2.4/Fi, 2.4/Fi)) #卷積的bias
34
35     self.covcores = array(self.covcores)
```

Before training, the weights are initialized with random values using a uniform distribution between  $-2.4/F_i$  and  $2.4/F_i$  where  $F_i$  is the number of inputs (fan-in) of the unit which the connection belongs to. Since several connections

```

37     def cov_op(self, pre_maps, covcore_index):
38         pre_map_shape = pre_maps.shape
39         covcore_shape = self.covcores[covcore_index].shape
40         map_shape = self.maps[covcore_index].shape
41         # 檢查輸入size
42         # 如果輸入size和輸出size相符合
43         # 計算卷積層
44         if not(map_shape[-2] == pre_map_shape[-2] - covcore_shape[-2] + 1 \
45             and map_shape[-1] == pre_map_shape[-1] - covcore_shape[-2] + 1):
46             return None;
47         for i in range(map_shape[-2]):
48             for j in range(map_shape[-1]):
49                 # Filter caculation
50                 localrecept = pre_maps[:, i : i + covcore_shape[-2], j : j + covcore_shape[-1]]
51                 val = sum(localrecept * self.covcores[covcore_index]) + self.covbias[covcore_index]
52
53                 # Use tanh(x) as activation function.
54                 # Remark that tanh(x) = ((e^2x)/(e^2x)+1)
55                 # We use the parameters in the paper
56                 # f(a) = Atanh(Sa), where A = 1.7159 * (val - 1)/(val + 1)
57
58                 val = exp((4.0/3)*val)
59                 self.maps[covcore_index][i][j] = 1.7159 * (val - 1) / (val + 1)

```

directions [116]. For our simulations, we use  $A = 1.7159$  and  $S = \frac{2}{3}$  (see [20], [34]). With this choice of parameters, the equalities  $f(1) = 1$  and  $f(-1) = -1$  are satisfied.

```

def back_propagation(self, pre_mapset, current_error, learn_rate, isweight_update):
    self.current_error = current_error

    #Flatten the array into one dim(把array拉成一維vector)
    selfmap_line = self.maps.reshape([self.maps.shape[0] * self.maps.shape[1] * self.maps.shape[2]])
    currenterror_line = current_error.reshape([current_error.shape[0] * current_error.shape[1] * current_error.shape[2]])

    # Backward : df/da = 2/3 * 1.7159 * (1-(tanh(2/3*a)^2))
    # Where tanh(2/3*a) = selfmap_line[i]/1.7159
    pcurrent_error = array([(2.0/3)*(1.7159 - (1/1.7159) * selfmap_line[i]**2))*currenterror_line[i]\n        for i in range(len(selfmap_line))]).reshape(self.maps.shape)

```

directions [116]. For our simulations, we use  $A = 1.7159$  and  $S = \frac{2}{3}$  (see [20], [34]). With this choice of parameters, the equalities  $f(1) = 1$  and  $f(-1) = -1$  are satisfied.

# 3\_Pooling\_Layer

10	15	80	12
18	30	11	20
11	19	48	51
30	31	45	59

$\max(10, 15, 18, 30) = 30$	$\max(80, 12, 11, 20) = 80$
$\max(11, 19, 30, 31) = 31$	$\max(48, 51, 45, 59) = 59$

30	80
31	59

```
10 class PoolingLayer(Layer) :
11     def __init__(self, lay_size = [], pool_core_sizes = []):
12         Layer.__init__(self, lay_size)
13         Fi = pool_core_sizes[0][0] * pool_core_sizes[0][1] + 1
14         self.poolparas = random.uniform(-2.4/Fi, 2.4/Fi, [len(lay_size), 2])
15         self.poolcore_sizes = array(pool_core_sizes)
16
17     def pool_op(self, pre_map, pool_index):
18         pre_map_shape = pre_map.shape
19         poolcore_size = self.poolcore_sizes[pool_index]
20         for i in range(int(pre_map_shape[0] / poolcore_size[0])):
21             for j in range(int(pre_map_shape[1] / poolcore_size[1])):
22                 val = self.poolparas[pool_index][0] * sum(pre_map[i*poolcore_size[0]: (i+1)*poolcore_size[0],\n23                                                 j*poolcore_size[1]: (j+1)*poolcore_size[1]]) + self.poolparas[pool_index][1]
24                 val = exp((4.0/3)*val)
25                 self.maps[pool_index][i][j] = 1.7159 * (val - 1) / (val + 1)
```

# 4 FullyConLayer

```
11 class FcLayer(Layer) :
12     def __init__(self, layer_len, pre_nodesnum) :
13         Layer.__init__(self, [[1, layer_len]])
14         Fi = pre_nodesnum + 1
15         self.weight = random.uniform(-2.4/Fi, 2.4/Fi, [layer_len, pre_nodesnum]) # 84x120
16         self.bias = random.uniform(-2.4/Fi, 2.4/Fi, [layer_len]) #84
17
18         val = sum(self.weight[node_index] * pre_nodes) + self.bias[node_index] #
19         val = exp((4.0/3)*val)
20         self.maps[0][0][node_index] = 1.7159 * (val -1) / (val + 1)
21
22     def calc_maps(self, pre_mapset) :
23         for i in range(len(self.maps[0][0])) : #84
24             self.fc_op(pre_mapset, i)
25
26     def back_propagation(self, pre_mapset, current_error, learn_rate, isweight_update) :
27         self.current_error = current_error
28         pcurrent_error = [(2.0/3)*(1.7159 - (1/1.7159) * self.maps[0][0][i]**2))*current_error[0][0][i]\
29         for i in range(self.maps.shape[-1])]
30
31         # 1x84 > 84x1 dot 1x120 > 84x120
32         weight_update = dot(matrix(pcurrent_error).T, \
33                             matrix(pre_mapset.reshape([1, pre_mapset.shape[0] * pre_mapset.shape[1] * pre_mapset.shape[2]])))
34
35         bias_update = array(pcurrent_error)
36
37         if isweight_update :
38             self.weight -= learn_rate * weight_update
39             self.bias -= learn_rate * bias_update
40         pre_error = array(dot(matrix(pcurrent_error), matrix(self.weight))).reshape(pre_mapset.shape)
41         return pre_error
```

# 6 ConNet

```
14 class CovNet(object) :
15     def __init__(self) :
16
17         cov3_core_sizes = [[3, 5, 5]] * 6
18         cov3_core_sizes.extend([[4, 5, 5]] * 9)
19         cov3_core_sizes.extend([[6, 5, 5]])
20
21         cov3_mapcombindex = [[0,1,2],[1,2,3],[2,3,4],[3,4,5],[4,5,0],[5,0,1],\
22             [0,1,2,3],[1,2,3,4],[2,3,4,5],[3,4,5,0],[4,5,0,1],[5,0,1,2],[0,1,3,4],[1,2,4,5],[0,2,3,5],[0,1,2,3,4,5]]
23
24         self.covlay1 = CovLayer([[28, 28]] * 6, [[1, 5, 5]] * 6)
25         self.poolinglay2 = PoolingLayer([[14, 14]] * 6, [[2, 2]] * 6)
26
27         self.covlay3 = CovLayer([[10, 10]] * 16, cov3_core_sizes, cov3_mapcombindex)
28         self.poolinglay4 = PoolingLayer([[5, 5]] * 16, [[2, 2]] * 16)
29
30         self.covlay5 = CovLayer([[1, 1]] * 120, [[16, 5, 5]] * 120)
31         self.fclay6 = FcLayer(84, 120)
32
33         self.outputlay7 = OutputLayer(10, 84)
```

Input image



32 x 32 x 1



# 7\_Net\_TrainAndTest

```
14 #mnist has a training set of 60,000 examples, and a test set of 10,000 examples.
15 #log檔作用:紀錄檔案(logfile)是一個記錄了發生在執行中的作業系統或其他軟體中的事件的檔案
16 def train_net(train_covnet, logfile, cycle, learn_rate, case_num = -1):
17     # Read data
18     # Change it to your own dataset path
19     trainim_filepath = '../data/raw/train-images.idx3-ubyte' #training的資料(按照自己的路徑修改)
20     trainlabel_filepath = '../data/raw/train-labels.idx1-ubyte' #label的資料(按照自己的路徑修改)
21
22     trainimfile = open(trainim_filepath, 'rb') #open()開啟檔案
23     trainlabelfile = open(trainlabel_filepath, 'rb') #使用'rb'按照二進位制位進行讀取的，不會將讀取的位元組轉換成字元
24
25     train_im = trainimfile.read() # 讀取文件內容 f.read(size) - 回傳檔案內容,
26     train_label = trainlabelfile.read() #size為要讀取進來的字串長度，若不填則讀取整份文件
27     im_index = 0
28     label_index = 0
29     magic, numImages, numRows, numColumns = struct.unpack_from('>IIII', train_im, im_index)
30     magic, numLabels = struct.unpack_from('>II', train_label, label_index)
31     print ('train_set:', numImages)
32
33     train_btime = time.time()
34     logfile.write('learn_rate:' + str(learn_rate) + '\t')
35     logfile.write('train_cycle:' + str(cycle) + '\t')
```

```
37 # Begin to train
38 for c in range(cycle) :
39     im_index = struct.calcsize('>IIII')
40     label_index = struct.calcsize('>II')
41     train_case_num = numImages
42     if case_num != -1 and case_num < numImages :
43         train_case_num = case_num
44     logfile.write("trainset_num:" + str(train_case_num) + '\t')
45     for case in range(train_case_num) :
46         im = struct.unpack_from('>784B', train_im, im_index)
47         label = struct.unpack_from('>1B', train_label, label_index)
48         im_index += struct.calcsize('>784B')
49         label_index += struct.calcsize('>1B')
50         im = array(im)
51         im = im.reshape(28,28)
52         bigim = list(ones((32, 32)) * -0.1)
53         for i in range(28) :
54             for j in range(28) :
55                 if im[i][j] > 0 :
56                     bigim[i+2][j+2] = 1.175
57         im = array([bigim])
58         label = label[0]
59         print (case, label)
60         train_covnet.fw_prop(im, label)
61         train_covnet.bw_prop(im, label, learn_rate[c])
```

```
91 # 測試
92 for case in range(testcase_num) :
93     im = struct.unpack_from('>784B', test_im, im_index)
94     label = struct.unpack_from('>1B', test_label, label_index)
95     im_index += struct.calcsize('>784B')
96     label_index += struct.calcsize('>1B')
97     im = array(im)
98     im = im.reshape(28,28)
99     bigim = list(ones((32, 32)) * -0.1)
100    for i in range(28) :
101        for j in range(28) :
102            if im[i][j] > 0 :
103                bigim[i+2][j+2] = 1.175
104    im = array([bigim])
105    label = label[0]
106    print(case, label)
107    train_covnet.fw_prop(im)
108    if argmax(train_covnet.outputlay7.maps[0][0]) == label :
109        correct_num += 1
110    correct_rate = correct_num / float(testcase_num)
111    print('test_correct_rate:', correct_rate)
112    logfile.write('test_correct_rate:' + str(correct_rate) + '\t')
113    logfile.write('\n')
```

# 結果

IPython console

Console I/A

```
In [2]: runfile('C:/Users/chinja/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New/LeNet_train.py',  
wdir='C:/Users/chinja/Desktop/Pytorch_Taiwan/2019_06_22/LeNet_New')
```

Reloaded modules: ConvNet, CovLayer, Layer, PoolingLayer, FullyConLayer, OutLayer

C:\Users\chinja\Desktop\Pytorch\_Taiwan\2019\_06\_22\LeNet\_New

train\_set: 60000

```
0 5  
1 0  
2 4  
3 1  
4 9  
5 2  
6 1  
7 3  
8 1  
9 4  
10 3  
11 5  
12 3  
13 6  
14 1  
15 7
```

IPython console

Console I/A

```
2974 1  
2975 8  
2976 6  
2977 2  
2978 3  
2979 9  
2980 6  
2981 2  
2982 1  
2983 9  
2984 1  
2985 3  
2986 5  
2987 5  
2988 0  
2989 3  
2990 8  
2991 3  
2992 3  
2993 7  
2994 6  
2995 6  
2996 0  
2997 1  
2998 4  
2999 0  
test_correct_rate: 0.9336666666666666
```

In [4]:

感謝聆聽！