Equivalence of CFG and PDA

Pushdown Automata

Transition function

Input

- δ takes argument as a triple where δ = (q,a,x)
 - q is a state in Q
 - a is either an input symbol Σ or ϵ
 - x is a stack symbol, that is a member of Γ

Output

- Output of δ is a finite set of pairs (p, γ) where
- P is a new state
- γ is a string of stack symbols that replaces x at the top of the stack
- If
 - $\gamma = \epsilon$ then the stack is popped
 - $\gamma = x$ then the stack is unchanged
 - γ = yz then x is replaced by z and y is pushed onto the stack.

Equivalence of CFG and PDA

- CFG to PDA
- PDA to CFG

- $S \rightarrow OBB$
- B \rightarrow 0S | 1S | 0

We will generate the transition function of PDA from the given CFG

$$CFG = \{V, \Sigma, S, P\}$$

Two types of rules:

1.
$$\delta$$
 (q, ϵ , S) = {(q, α) | A $\rightarrow \alpha$ in P}

2.
$$\delta$$
 (q, a, a) = {(q, ϵ) | for every a $\in \Sigma$ }

- $S \rightarrow OBB$
- B \rightarrow 0S | 1S | 0

We will generate the transition function of PDA from the given CFG

R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, OBB)

R2 =
$$\delta$$
 (q, ϵ , B) = δ (q, 0S)

R3 =
$$\delta$$
 (q, ϵ , B) = δ (q, 1S)

$$R4 = \delta (q, \epsilon, B) = \delta (q, 0)$$

2 types of rules:

1.
$$\delta$$
 (q, ϵ , S) = {(q, α) | A $\rightarrow \alpha$ in P}

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 (q, a, a) = {(q, ϵ) | for every a $\in \Sigma$ }

- $S \rightarrow OBB$
- B \rightarrow 0S | 1S | 0

We will generate the transition function of PDA from the given CFG

$$R5 = \delta (q, 0, 0) = \delta (q, \epsilon)$$

R6 =
$$\delta$$
 (q, 1, 1) = δ (q, ϵ)

2 types of rules:

1.
$$\delta$$
 (q, ϵ , S) = {(q, α) | A $\rightarrow \alpha$ in P}

2.
$$\delta$$
 (q, a, a) = {(q, ϵ) | for every a $\in \Sigma$ }

- $S \rightarrow OBB$
- $B \rightarrow 0S \mid 1S \mid 0$

We will generate the transition function of PDA from the given CFG

R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, OBB)

$$R2 = \delta (q, \epsilon, B) = \delta (q, OS)$$

R3 =
$$\delta$$
 (q, ϵ , B) = δ (q, 1S)

$$R4 = \delta (q, \epsilon, B) = \delta (q, 0)$$

R5 =
$$\delta$$
 (q, 0, 0) = δ (q, ϵ)

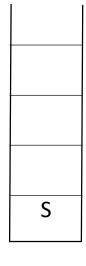
R6 =
$$\delta$$
 (q, 1, 1) = δ (q, ϵ)

2 types of rules:

1.
$$\delta$$
 (q, ϵ , S) = {(q, α) | A $\rightarrow \alpha$ in P}

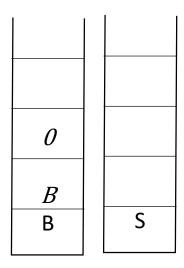
2.
$$\delta$$
 (q, a, a) = {(q, ϵ) | for every a $\in \Sigma$ }

O10000(q, 010000, S)



R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, OBB)
R2 = δ (q, ϵ , B) = δ (q, OS)
R3 = δ (q, ϵ , B) = δ (q, 1S)
R4 = δ (q, ϵ , B) = δ (q, 0)
R5 = δ (q, 0, 0) = δ (q, ϵ)
R6 = δ (q, 1, 1) = δ (q, ϵ)

• O10000
(q, 010000, S) R1
(q, 010000, OBB)



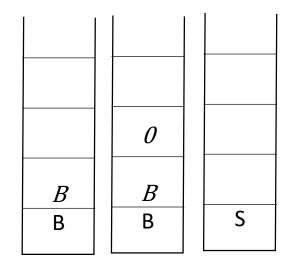
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R3 = δ (q, ϵ , B) = δ (q, 1S)
R4 = δ (q, ϵ , B) = δ (q, 0)
R5 = δ (q, 0, 0) = δ (q, ϵ)
R6 = δ (q, 1, 1) = δ (q, ϵ)

O10000

(q, 010000, S) R1

(q, 010000, 0BB) R5

(q, 10000, BB)



R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, 0BB)
R2 = δ (q, ϵ , B) = δ (q, 0S)
R3 = δ (q, ϵ , B) = δ (q, 1S)
R4 = δ (q, ϵ , B) = δ (q, 0)
R5 = δ (q, 0, 0) = δ (q, ϵ)
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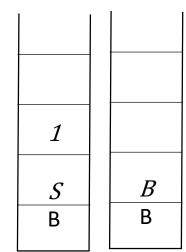
O10000

(q, 010000, S) R1

(q, 010000, 0BB) R5

(q, 10000, BB) R3

(q, 10000, 1SB)



R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, OBB)
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O10000

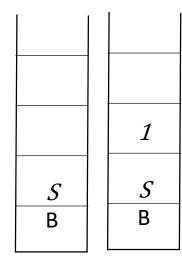
(q, 010000, S) R1

(q, 010000, 0BB) R5

(q, 10000, BB) R3

(q, 10000, 1SB) R6

(q, 0000, SB)



R1 =
$$\delta$$
 (q, ϵ , S) = δ (q, OBB)
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O10000

(q, 010000, S) R1

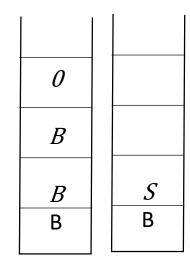
(q, 010000, 0BB) R5

(q, 10000, BB) R3

(q, 10000, 1SB) R6

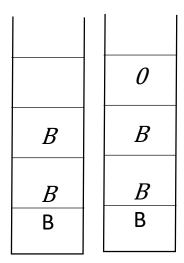
(q, 0000, SB) R1

(q, 0000, 0BBB)



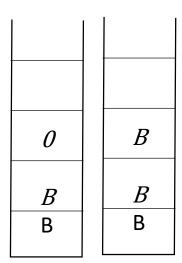
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- O10000
- (q, 010000, S) R1
- (q, 010000, 0BB) R5
- (q, 10000, BB) R3
- (q, 10000, 1SB) R6
- (q, 0000, SB) R1
- (q, 0000, OBBB) R5
- (q, 000, BBB)



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- O10000
- (q, 010000, S) R1
- (q, 010000, OBB) R5
- (q, 10000, BB) R3
- (q, 10000, 1SB) R6
- (q, 0000, SB) R1
- (q, 0000, OBBB) R5
- (q, 000, BBB) R4
- (q, 000, 0BB)



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$$\delta$$
 (q, ϵ , S) = δ (q, OBB)
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R5 = δ (q, 0, 0) = δ (q, ϵ)
R6 = δ (q, 1, 1) = δ (q, ϵ)

O10000

(q, 010000, S) R1

(q, 010000, 0BB) R5

(q, 10000, BB) R3

(q, 10000, 1SB) R6

(q, 0000, SB) R1

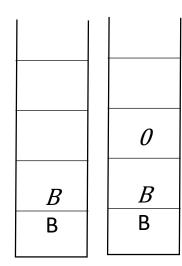
(q, 0000, 0BBB) R5

(q, 000, BBB) R4

(q, 000, 0BB) R5

(q, 00, BB) R4

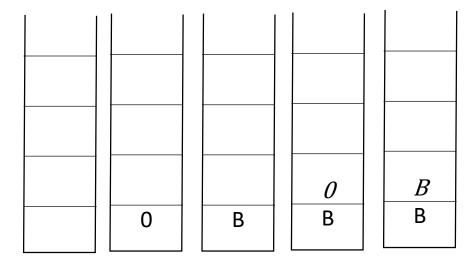
(q, 00, 0B)



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 (q, ϵ , S) = δ (q, OBB)
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R4 = δ (q, ϵ , B) = δ (q, 0)
R5 = δ (q, 0, 0) = δ (q, ϵ)
R6 = δ (q, 1, 1) = δ (q, ϵ)



- (q, 010000, S) R1
- (q, 010000, 0BB) R5
- (q, 10000, BB) R3
- (q, 10000, 1SB) R6
- (q, 0000, SB) R1
- (q, 0000, 0BBB) R5
- (q, 000, BBB) R4
- (q, 000, 0BB) R5
- (q, 00, BB) R4
- (q, 00, 0B) R5
- (q, 0, B) R4
- (q, 0, B) R5
- (q, 0, 0) R4
- (q, ϵ, ϵ)



R1 =
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 (q, ϵ , S) = δ (q, OBB)
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R4 =
$$\delta$$
 (q, ϵ , B) = δ (q, 0)

R5 =
$$\delta$$
 (q, 0, 0) = δ (q, ϵ)

$$R6 = \delta (q, 1, 1) = \delta (q, \epsilon)$$

$$A = \{(q_0, q_1), (a,b), (z_0, z), \delta, q_0, z_0, F\}$$

1.
$$\delta(q_0, b, z_0) = (q_0, zz_0)$$

2.
$$\delta(q_0, \epsilon, z_0) = (q_0, \epsilon)$$

3.
$$\delta(q_0, b, z) = (q_0, zz)$$

4.
$$\delta(q_0, a, z) = (q_1, z)$$

5.
$$\delta(q_1, b, z) = (q_1, \epsilon)$$

6.
$$\delta(q_1, a, z_0) = (q_0, z_0)$$

Three rules for creating production from the transition of PDA

- 1. For start symbol $S \rightarrow [q_0, z_0, q]$ for every $q \in Q$
- 2. For $\delta(q_0, a, z) = (q', \epsilon)$ $[q, z, q'] \rightarrow a$
- 3. For δ (q, a, z) = (q', zz....) [q, z, q''] \rightarrow a [q', z, q'''] [q''', z, q''] q'' = for every q ϵ Q q''' = for every q ϵ Q

- $S \to [q_0, z_0, q_0]$ or A
- $S \rightarrow [q_0, z_0, q_1]$ or B
- $S \rightarrow A \mid B$

1. For start symbol $S \rightarrow [q_0, z_0, q]$ for every $q \in Q$

1.
$$\delta (q_0, b, z_0) = (q_0, zz_0)$$

 $[q_0, z_0,] \rightarrow b[, z,][, z_0,]$

```
3. For \delta ( q, a, z) = ( q', zz....) 
 [ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] ....... 
 q'' = for every q \epsilon Q 
 q''' = for every q \epsilon Q
```

1.
$$\delta(q_0, b, z_0) = (q_0, z_0)$$

 $[q_0, z_0,] \rightarrow b[, z,][, z_0,]$
 $[q_0, z_0,] \rightarrow b[q_0, z,][, z_0,]$

```
3. For \delta ( q, a, z) = ( q', zz....) 
 [ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] ....... 
 q'' = for every q \epsilon Q 
 q''' = for every q \epsilon Q
```

```
1. \delta(q_0, b, z_0) = (q_0, zz_0)

[q_0, z_0, ] \rightarrow b[, z, ][, z_0, ]

[q_0, z_0, ] \rightarrow b[q_0, z, ][, z_0, ]

[q_0, z_0, q_0] \rightarrow b[q_0, z, ][, z_0, q_0]
```

```
1. \delta(q_0, b, z_0) = (q_0, zz_0) <sub>3</sub>
[q_0, z_0, ] \to b[, z, ][, z_0, ]
[q_0, z_0, ] \to b[q_0, z, ][, z_0, ]
[q_0, z_0, q_0] \to b[q_0, z, ][, z_0, q_0]
[q_0, z_0, q_0] \to b[q_0, z, q_0][q_0, z_0, q_0]
```

```
3. For \delta ( q, a, z) = ( q', zz....) 
 [ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] ....... 
 q'' = for every q \epsilon Q 
 q''' = for every q \epsilon Q
```

1.
$$\delta(q_0, b, z_0) = (q_0, zz_0)$$

 $[q_0, z_0, q_0] \rightarrow b[q_0, z, q_0][q_0, z_0, q_0]$

```
3. For \delta ( q, a, z) = ( q', zz....)

[ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] .......

q'' = for every q \epsilon Q

q''' = for every q \epsilon Q
```

1.
$$\delta(q_0, b, z_0) = (q_0, zz_0)$$

 $[q_0, z_0, q_0] \rightarrow b[q_0, z, q_0][q_0, z_0, q_0]$
 $[q_0, z_0, q_0] \rightarrow b[q_0, z,][, z_0, q_0]$

3. For
$$\delta$$
 (q, a, z) = (q', zz....)
[q, z, q''] \rightarrow a [q', z, q'''] [q''', z, q'']
q'' = for every q ϵ Q
q''' = for every q ϵ Q

1.
$$\delta (q_0, b, z_0) = (q_0, zz_0)$$

 $[q_0, z_0, q_0] \rightarrow b [q_0, z, q_0] [q_0, z_0, q_0]$
 $[q_0, z_0, q_0] \rightarrow b [q_0, z, q_1] [q_1, z_0, q_0]$

```
3. For \delta ( q, a, z) = ( q', zz....) 
 [ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] ....... 
 q'' = for every q \epsilon Q 
 q''' = for every q \epsilon Q
```

```
1. \delta(q_0, b, z_0) = (q_0, zz_0)

[q_0, z_0, q_0] \rightarrow b[q_0, z, q_0][q_0, z_0, q_0]

[q_0, z_0, q_0] \rightarrow b[q_0, z, q_1][q_1, z_0, q_0]

[q_0, z_0, q_1] \rightarrow b[q_0, z, ][, z_0, q_1]

[q_0, z_0, q_1] \rightarrow b[q_0, z, ][, z_0, q_1]
```

```
3. For \delta ( q, a, z) = ( q', zz....)

[ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] .......

q'' = for every q \epsilon Q

q''' = for every q \epsilon Q
```

1.
$$\delta (q_0, b, z_0) = (q_0, zz_0)$$

 $[q_0, z_0, q_0] \rightarrow b [q_0, z, q_0] [q_0, z_0, q_0]$
 $[q_0, z_0, q_0] \rightarrow b [q_0, z, q_1] [q_1, z_0, q_0]$

$$[q_0, z_0, q_1] \rightarrow b [q_0, z, q_0] [q_0, z_0, q_1]$$

 $[q_0, z_0, q_1] \rightarrow b [q_0, z, q_1] [q_1, z_0, q_1]$

```
3. For \delta ( q, a, z) = ( q', zz....)

[ q, z, q''] \rightarrow a [q', z, q''' ] [ q''', z, q'' ] .......

q'' = for every q \epsilon Q

q''' = for every q \epsilon Q
```

2.
$$\delta (q_0, \epsilon, z_0) = (q_0, \epsilon)$$

 $[q_0, z_0, q_0] \rightarrow \epsilon$

2. For
$$\delta$$
 (q, a, z) = (q' , ϵ) [q, z, q'] \rightarrow a

```
3. \delta(q_0, b, z) = (q_0, zz)

[q_0, z, ] \rightarrow b[, z, ][, z, ]

[q_0, z, ] \rightarrow b[, z, ][, z, ]

[q_0, z, ] \rightarrow b[, z, ][, z, ]

[q_0, z, ] \rightarrow b[, z, ][, z, ]
```

```
3. \delta(q_0, b, z) = (q_0, zz)

[q_0, z, ] \rightarrow b[q_0, z, ][ , z, ]

[q_0, z, ] \rightarrow b[q_0, z, ][ , z, ]

[q_0, z, ] \rightarrow b[q_0, z, ][ , z, ]

[q_0, z, ] \rightarrow b[q_0, z, ][ , z, ]
```

```
3. \delta(q_0, b, z) = (q_0, zz)

[q_0, z, q_0] \rightarrow b[q_0, z, ][, z, q_0]

[q_0, z, q_0] \rightarrow b[q_0, z, ][, z, q_0]

[q_0, z, q_1] \rightarrow b[q_0, z, ][, z, q_1]

[q_0, z, q_1] \rightarrow b[q_0, z, ][, z, q_1]
```

```
3. \delta(q_0, b, z) = (q_0, zz)

[q_0, z, q_0] \rightarrow b[q_0, z, q_0][q_0, z, q_0]

[q_0, z, q_0] \rightarrow b[q_0, z, q_1][q_1, z, q_0]

[q_0, z, q_1] \rightarrow b[q_0, z, q_0][q_0, z, q_1]

[q_0, z, q_1] \rightarrow b[q_0, z, q_1][q_1, z, q_1]
```

4.
$$\delta (q_0, a, z) = (q_1, z)$$

 $[q_0, z, q_0] \rightarrow a [q_1, z, q_0]$
 $[q_0, z, q_1] \rightarrow a [q_1, z, q_1]$

5.
$$\delta (q_1, b, z) = (q_1, \epsilon)$$

 $[q_1, z, q_1] \to b$

6.
$$\delta (q_1, a, z_0) = (q_0, z_0)$$

 $[q_1, z_0, q_0] \rightarrow a [q_0, z_0, q_0]$
 $[q_1, z_0, q_1] \rightarrow a [q_0, z_0, q_1]$

```
S \rightarrow A \mid B
[q_0, z_0, q_0] \rightarrow b [q_0, z, q_0] [q_0, z_0, q_0]
                                                                or A \rightarrow bCA
[q_0, z_0, q_0] \rightarrow b [q_0, z, q_1] [q_1, z_0, q_0]
                                                              or A \rightarrow bDF
                                                              or B \rightarrow bCB
[q_0, z_0, q_1] \rightarrow b [q_0, z, q_0] [q_0, z_0, q_1]
[q_0, z_0, q_1] \rightarrow b [q_0, z, q_1] [q_1, z_0, q_1]
                                                              or B \rightarrow bDG
                                                                 or A \rightarrow \epsilon
[q_0, z_0, q_0] \rightarrow \epsilon
[q_0, z, q_0] \rightarrow b [q_0, z, q_0] [q_0, z, q_0] or C \rightarrow bCC
[q_0, z, q_0] \rightarrow b [q_0, z, q_1] [q_1, z, q_0] or C \rightarrow bDH
[q_0, z, q_1] \rightarrow b [q_0, z, q_0] [q_0, z, q_1] or D \rightarrow bCD
[q_0, z, q_1] \rightarrow b [q_0, z, q_1] [q_1, z, q_1] or D \rightarrow bDE
                                                                 or A \rightarrow aH
[q_0, z, q_0] \rightarrow a [q_1, z, q_0]
                                                                 or B \rightarrow aE
[q_0, z, q_1] \to a [q_1, z, q_1]
                                                                  or E \rightarrow b
[q_1, z, q_1] \rightarrow b
[q_1, z_0, q_0] \rightarrow a [q_0, z_0, q_0]
                                                                  or F \rightarrow aA
                                                                  or G \rightarrow aB
[q_1, z_0, q_1] \rightarrow a [q_0, z_0, q_1]
```

$$\begin{aligned} &[q_0,z_0,q_0] = \mathsf{A} \\ &[q_0,z_0,q_1] = \mathsf{B} \\ &[q_0,z_0,q_0] = \mathsf{C} \\ &[q_0,z_0,q_1] = \mathsf{D} \\ \\ &[q_1,z_0,q_0] = \mathsf{F} \\ &[q_1,z_0,q_1] = \mathsf{G} \end{aligned}$$

$$[q_1, z, q_0] = H$$