1 Mathematics

1.1 Modular Arithmetic

1.1.1 Chinese Remainder Theorem

```
1 #include "../../headers/headers.h"
   ll inline mod(ll x, ll m) { return ((x %= m) < 0) ? x + m : x; }
   ll inline mul(ll x, ll y, ll m) { return (x * y) % m; }
   ll inline add(ll x, ll y, ll m) { return (x + y) % m; }
   // extended euclidean algorithm
   // finds g, x, y such that
   // a * x + b * y = g = GCD(a,b)
   ll gcdext(ll a, ll b, ll &x, ll &y)
11
       ll r2, x2, y2, r1, x1, y1, r0, x0, y0, q;
12
       r2 = a, x2 = 1, y2 = 0;
13
       r1 = b, x1 = 0, v1 = 1;
14
       while (r1)
15
16
17
          q = r2 / r1;
          r0 = r2 \% r1:
18
19
          x0 = x2 - q * x1;
          v0 = v2 - q * v1;
20
          r2 = r1, x2 = x1, y2 = y1;
21
          r1 = r0, x1 = x0, y1 = y0;
22
       }
23
       11 g = r2;
^{24}
25
       x = x2, y = y2;
       if (g < 0)
26
          g = -g, x = -x, y = -y; // make sure g > 0
27
       // for debugging (in case you think you might have bugs)
28
       // assert (g == a * x + b * y);
       // assert (g == \_gcd(abs(a), abs(b)));
30
       return g:
31
32
33
    // CRT for a system of 2 modular linear equations
   // We want to find X such that:
   // 1) x = r1 (mod m1)
  // 2) x = r2 (mod m2)
  // The solution is given by:
41 // sol = r1 + m1 * (r2-r1)/g * x' (mod LCM(m1,m2))
  // where x' comes from
43 // m1 * x' + m2 * y' = g = GCD(m1, m2)
  // where x' and y' are the values found by extended euclidean
        algorithm (gcdext)
45 // Useful references:
46 // https://codeforces.com/blog/entry/61290
47 // https://forthright48.com/chinese-remainder-theorem-part-1-coprime-
        moduli
```

```
https://forthright48.com/chinese-remainder-theorem-part-2-non-
         coprime-moduli
49 // ** Note: this solution works if lcm(m1,m2) fits in a long long (64
   pair<11, 11> CRT(11 r1, 11 m1, 11 r2, 11 m2)
52
       ll g, x, y;
53
        g = gcdext(m1, m2, x, y);
        if ((r1 - r2) % g != 0)
           return {-1, -1}; // no solution
55
56
       11 z = m2 / g;
       11 lcm = m1 * z;
       ll sol = add(mod(r1, lcm), m1 * mul(mod(x, z), mod((r2 - r1) / g, z)
58
       // for debugging (in case you think you might have bugs)
       // assert (0 <= sol and sol < lcm);</pre>
       // assert (sol % m1 == r1 % m1);
       // assert (sol % m2 == r2 % m2);
62
63
        return {sol, lcm}; // solution + lcm(m1,m2)
64
65
    // CRT for a system of N modular linear equations
         r = array of remainders
71
           m = array of modules
72 //
           n = length of both arrays
   // Output:
           a pair {X, lcm} where X is the solution of the sytemm
               X = r[i] \pmod{m[i]} \text{ for } i = 0 \dots n-1
           and lcm = LCM(m[0], m[1], ..., m[n-1])
76
            if there is no solution, the output is \{-1, -1\}
   // ** Note: this solution works if LCM(m[0],...,m[n-1]) fits in a long
         long (64 bits)
    pair<11, 11> CRT(11 *r, 11 *m, int n)
81
       11 r1 = r[0], m1 = m[0];
        repx(i, 1, n)
82
83
            11 r2 = r[i], m2 = m[i];
84
            11 g, x, y;
85
            g = gcdext(m1, m2, x, y);
86
87
            if ((r1 - r2) % g != 0)
                return {-1, -1}; // no solution
88
           11 z = m2 / g;
            11 \ 1cm = m1 * z:
90
           ll sol = add(mod(r1, lcm), m1 * mul(mod(x, z), mod((r2 - r1) / g
91
                 , z), z), lcm);
            r1 = sol:
92
93
            m1 = 1cm;
94
        // for debugging (in case you think you might have bugs)
        // assert (0 <= r1 and r1 < m1);</pre>
        // rep(i, n) assert (r1 % m[i] == r[i]);
97
```

```
98 | return {r1, m1};
99 |}
```

1.2 Primality Checks

1.2.1 Miller Rabin

```
1 | #include "../../headers/headers.h"
    ll mulmod(ull a, ull b, ull c)
 4
        ull x = 0, y = a % c;
        while (b)
            if (b & 1)
                x = (x + y) \% c;
            y = (y << 1) \% c;
10
            b >>= 1;
11
12
        return x % c;
13
14
15
    11 fastPow(11 x, 11 n, 11 MOD)
16
17
18
        ll ret = 1;
        while (n)
19
20
21
                ret = mulmod(ret, x, MOD);
22
            x = mulmod(x, x, MOD);
23
            n >>= 1;
24
        }
25
26
        return ret;
27
28
    bool isPrime(ll n)
29
30
        vi a = {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37};
31
32
        if (binary_search(a.begin(), a.end(), n))
33
            return true;
34
35
        if ((n \& 1) == 0)
36
            return false;
37
38
39
        int s = 0;
        for (ll m = n - 1; !(m & 1); ++s, m >>= 1)
40
41
42
        int d = (n - 1) / (1 << s);
43
44
        for (int i = 0; i < 7; i++)
45
46
            11 fp = fastPow(a[i], d, n);
47
            bool comp = (fp != 1);
48
```

```
49
                for (int j = 0; j < s; j++)
50
51
                    if (fp == n - 1)
52
                    {
53
                        comp = false;
54
55
                        break;
56
57
                    fp = mulmod(fp, fp, n);
58
59
            if (comp)
60
61
               return false;
62
63
       return true;
64 }
        Sieve of Eratosthenes
   #include "../../headers/headers.h"
2
   // O(n log log n)
   vi sieve(int n)
4
5
        vi primes;
6
7
        vector<bool> is_prime(n + 1, true);
8
        int limit = (int)floor(sqrt(n));
9
10
       repx(i, 2, limit + 1) if (is_prime[i]) for (int j = i * i; j <= n; j</pre>
              += i)
            is_prime[j] = false;
11
12
       repx(i, 2, n + 1) if (is_prime[i]) primes.eb(i);
13
14
        return primes;
15
16 }
1.2.3
       trialDivision
   #include "../../headers/headers.h"
2
   // O(sqrt(n)/log(sqrt(n))+log(n))
   vi trialDivision(int n, vi &primes)
   |{
5
        vi factors;
6
7
        for (auto p : primes)
8
9
            if (p * p > n)
               break;
10
            while (n \% p == 0)
11
12
                primes.pb(p);
13
                if ((n /= p) == 1)
14
```

return factors;

15

16

}

1.3 Others

1.3.1 Polynomials

```
#include "../../headers/headers.h"
    template <class T>
    class Pol
5
    private:
        vector<T> cofs;
        int n;
    public:
10
        Pol(vector<T> cofs) : cofs(cofs)
11
12
            this->n = cofs.size() - 1;
13
        }
14
15
        Pol<T> operator+(const Pol<T> &o)
16
17
            vector<T> n_cofs;
18
            if (n > o.n)
19
20
                n_cofs = cofs;
21
                rep(i, o.n + 1)
22
23
                    n_cofs[i] += o.cofs[i];
24
25
            }
26
            else
27
28
                n_cofs = o.cofs;
29
                rep(i, n + 1)
30
31
                    n_cofs[i] += cofs[i];
32
33
34
            return Pol(n_cofs);
35
        }
36
37
        Pol<T> operator-(const Pol<T> &o)
38
39
            vector<T> n_cofs;
40
            if (n > o.n)
41
42
                n_cofs = cofs;
43
                rep(i, o.n + 1)
44
```

```
45
                    n_cofs[i] -= o.cofs[i];
46
47
48
            else
49
50
51
                n_cofs = o.cofs;
                rep(i, n + 1)
52
53
                    n_cofs[i] *= -1;
54
                    n_cofs[i] += cofs[i];
55
56
57
            return Pol(n_cofs);
58
       }
59
60
61
        Pol<T> operator*(const Pol<T> &o) //Use Fast Fourier Transform when
             we implement it
62
        {
            vector<T> n_cofs(n + o.n + 1);
63
            rep(i, n + 1)
64
65
                rep(j, o.n + 1)
66
67
                    n_{cofs}[i + j] += cofs[i] * o.cofs[j];
68
69
70
            return Pol(n_cofs);
71
       }
72
73
        Pol<T> operator*(const T &o)
74
75
            vector<T> n_cofs = cofs;
76
            for (auto &cof : n_cofs)
77
78
79
                cof *= o;
80
            return Pol(n_cofs);
81
82
83
        double operator()(double x)
84
85
            double ans = 0;
86
87
            double temp = 1;
88
            for (auto cof : cofs)
89
                ans += (double)cof * temp;
90
91
                temp *= x;
92
            return ans;
93
94
95
        Pol<T> integrate()
96
97
            vector<T> n_cofs(n + 2);
98
```

```
repx(i, 1, n_cofs.size())
 99
100
                 n_{cofs[i]} = cofs[i - 1] / T(i);
101
102
             return Pol<T>(n_cofs);
103
         }
104
105
         double integrate(T a, T b)
106
107
             Pol<T> temp = integrate();
108
             return temp(b) - temp(a);
109
         }
110
111
         friend ostream &operator<<(ostream &str, const Pol &a);</pre>
112
113
     };
114
115
     ostream &operator<<(ostream &strm, const Pol<double> &a)
116
         bool flag = false;
117
         rep(i, a.n + 1)
118
119
             if (a.cofs[i] == 0)
120
                 continue;
121
122
             if (flag)
123
                  if (a.cofs[i] > 0)
124
                      strm << " + ";
125
                 else
126
                      strm << " - ";
127
             else
128
                 flag = true;
129
             if (i > 1)
130
131
                 if (abs(a.cofs[i]) != 1)
132
                      strm << abs(a.cofs[i]);</pre>
133
                 strm << "x^" << i;
134
135
             else if (i == 1)
136
137
                 if (abs(a.cofs[i]) != 1)
138
                      strm << abs(a.cofs[i]);</pre>
139
                 strm << "x";
140
             }
141
             else
142
143
                 strm << a.cofs[i];</pre>
144
145
146
147
         return strm;
148 }
```

1.3.2 Factorial Factorization

```
#include "../../headers/headers.h"
```

```
4
   umap<int, int> factorialFactorization(int n, vi &primes)
   {
5
        umap<int, int> p2e;
6
       for (auto p : primes)
7
8
            if (p > n)
9
                break:
10
            int e = 0;
11
            int tmp = n;
12
            while ((tmp /= p) > 0)
13
14
                e += tmp;
           if (e > 0)
15
16
               p2e[p] = e;
       }
17
       return p2e;
18
19 }
```