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1 ./headers/headers.h

```
#include <bits/stdc++.h>
using namespace std;
typedef long long 11;
typedef pair<int, int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;
typedef vector<vi> graph;
typedef vector<vii> wgraph;
#ifndef declaraciones_h
#define declaraciones_h
\#define\ rep(i,\ n)\ for\ (size\_t\ i=0;\ i++<(size\_t)n;)
#define repx(i, a, b) for (int i = a; i++ < (int)b;)
#define invrep(i, a, b) for (int i = b; i-- > (int)a;)
#define pb push_back
#define eb emplace_back
#define ppb pop_back
#define lg(x) (31 - __builtin_clz(x))
#define lgg(x) (63 - __buitlin_clzll(x))
#define gcd __gcd
#define umap unordered_map
#define uset unordered_set
//ios::sync_with_stdio(0); cin.tie(0);
//cout.setf(ios::fixed); cout.precision(4);
\#define\ debugx(x)\ cerr << \#x << ": " << x << endl
#define debugv(v)
                   \
    cerr << #v << ":";
   for (auto e : v)
        cerr << " " << e; \
    cerr << endl
#define debugm(m)
    cerr << #m << endl;</pre>
    rep(i, (int)m.size())
        cerr << i << ":";
```

2 ./strings/trie/trie.cpp

```
#include "../../headers/headers.h"
class Trie
  private:
    vector<unordered_map<char, int>> nodes;
    int next;
  public:
    Trie()
    {
        nodes.eb();
        next = 1;
    }
    bool build(string s)
        int i = 0;
        int v = 0;
        while (i < s.size())</pre>
            if (nodes[v].find(s[i]) == nodes[v].end())
                nodes.eb();
                v = nodes[v][s[i]] = next;
                next++;
            }
            else
                v = nodes[v][s[i]];
                i++;
            }
        }
   }
};
```

3 ./estructuras/segmentTree/lazySegmentTree.cpp

```
#include "../../headers/headers.h"
struct RSQ // Range sum query
    static 11 const neutro = 0;
    static ll op(ll x, ll y)
       return x + y;
    }
    static 11
    lazy_op(int i, int j, ll x)
       return (j - i + 1) * x;
    }
};
struct RMinQ // Range minimun query
    static ll const neutro = 1e18;
    static ll op(ll x, ll y)
        return min(x, y);
    static 11
    lazy_op(int i, int j, ll x)
       return x;
    }
};
template <class t>
class SegTreeLazy
    vector<ll> arr, st, lazy;
    int n;
    void build(int u, int i, int j)
        if (i == j)
        {
            st[u] = arr[i];
            return;
        int m = (i + j) / 2, l = u * 2 + 1, r = u * 2 + 2;
```

```
build(1, i, m);
    build(r, m + 1, j);
    st[u] = t::op(st[1], st[r]);
}
void propagate(int u, int i, int j, ll x)
    // nota, las operaciones pueden ser un and, or, ..., etc.
    st[u] += t::lazy_op(i, j, x); // incrementar el valor (+)
    // st[u] = t:: lazy_op(i, j, x); // setear el valor
    if (i != j)
    {
        // incrementar el valor
        lazy[u * 2 + 1] += x;
        lazy[u * 2 + 2] += x;
        // setear el valor
        //lazy[u * 2 + 1] = x;
        //lazy[u * 2 + 2] = x;
    }
    lazy[u] = 0;
}
11 query(int a, int b, int u, int i, int j)
    if (j < a \text{ or } b < i)
        return t::neutro;
    int m = (i + j) / 2, l = u * 2 + 1, r = u * 2 + 2;
    if (lazy[u])
        propagate(u, i, j, lazy[u]);
    if (a \le i \text{ and } j \le b)
        return st[u];
    11 x = query(a, b, l, i, m);
    11 y = query(a, b, r, m + 1, j);
    return t::op(x, y);
}
void update(int a, int b, ll value,
            int u, int i, int j)
    int m = (i + j) / 2, l = u * 2 + 1, r = u * 2 + 2;
    if (lazy[u])
        propagate(u, i, j, lazy[u]);
    if (a \le i \text{ and } j \le b)
        propagate(u, i, j, value);
    else if (j < a \text{ or } b < i)
        return;
```

```
else
        {
            update(a, b, value, 1, i, m);
            update(a, b, value, r, m + 1, j);
            st[u] = t::op(st[1], st[r]);
        }
    }
 public:
    SegTreeLazy(vector<11> &v)
    {
        arr = v;
        n = v.size();
        st.resize(n * 4 + 5);
        lazy.assign(n * 4 + 5, 0);
        build(0, 0, n - 1);
   }
    11 query(int a, int b)
        return query(a, b, 0, 0, n - 1);
    }
    void update(int a, int b, ll value)
        update(a, b, value, 0, 0, n - 1);
    }
};
```

4 ./estructuras/segmentTree/segmentTree.cpp

```
#include "../../headers/headers.h"
// Se requiere un struct para el nodo (ej: prodsgn).
// Un nodo debe tener tres constructores:
      Aridad O: Construye el neutro de la operación
//
      Aridad 1: Construye un nodo hoja a partir del input
//
      Aridad 2: Construye un nodo según sus dos hijos
// Construcción del segment tree:
      Hacer un arreglo de nodos (usar ctor de aridad 1).
       ST<miStructNodo> miSegmentTree(arregloDeNodos);
// Update:
      miSegmentTree.set_point(indice, miStructNodo(input));
//
// Query:
       miSegmentTree.query(l, r) es inclusivo exclusivo y da un nodo. Usar la info del nodo
// Logic And Query
struct ANDQ
    intt value;
    ANDQ() { value = -111; }
    ANDQ(intt x) { value = x; }
    ANDQ(const ANDQ &a,
        const ANDQ &b)
       value = a.value & b.value;
    }
};
// Interval Product (LiveArchive)
struct prodsgn {
   int sgn;
   prodsgn() {sgn = 1;}
   prodsgn(int x) {
        sgn = (x > 0) - (x < 0);
   prodsgn(const prodsgn &a,
            const prodsgn &b) {
        sgn = a.sgn*b.sgn;
    }
};
```

// Maximum Sum (SPOJ)

```
struct maxsum {
    int first, second;
    maxsum() {first = second = -1;}
    maxsum(int x) {
        first = x; second = -1;
    }
    maxsum(const maxsum &a,
           const maxsum &b) {
        if (a.first > b.first) {
            first = a.first;
            second = max(a.second,
                         b.first);
        } else {
            first = b.first;
            second = max(a.first,
                         b.second);
        }
    }
    int answer() {
        return first + second;
    }
};
// Range Minimum Query
struct rminq {
    int value;
    rminq() {value = INT_MAX;}
    rminq(int x) {value = x;}
    rminq(const rminq &a,
          const rminq &b) {
        value = min(a.value,
                    b.value);
    }
};
template <class node>
class ST
{
    vector<node> t;
    int n;
  public:
    ST(vector<node> &arr)
        n = arr.size();
        t.resize(n * 2);
```

```
copy(arr.begin(), arr.end(), t.begin() + n);
        for (int i = n - 1; i > 0; --i)
            t[i] = node(t[i << 1], t[i << 1 | 1]);
    }
    // O-indexed
    void set_point(int p, const node &value)
        for (t[p += n] = value; p > 1; p >>= 1)
            t[p >> 1] = node(t[p], t[p ^ 1]);
    }
    // inclusive exclusive, O-indexed
   node query(int 1, int r)
    {
        node ansl, ansr;
        for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1)
        {
            if (1 & 1)
                ansl = node(ansl, t[1++]);
            if (r & 1)
                ansr = node(t[--r], ansr);
        return node(ansl, ansr);
    }
};
```

5 ./estructuras/fenwickTree/fenwickTree2D.cpp

```
#include "../../headers/headers.h"
//Numeración en [0,n-1] y [0,m-1]
template <class T>
class FenwickTree2D
    vector<vector<T>> t;
    int n, m;
 public:
   FenwickTree2D() {}
   FenwickTree2D(int n, int m)
       t.assign(n, vector<T>(m, 0));
       this->n = n;
       this->m = m;
   }
   void add(int r, int c, T value)
       for (int i = r; i < n; i | = i + 1)
            for (int j = c; j < m; j |= j + 1)
               t[i][j] += value;
    }
    // sum[(0, 0), (r, c)]
   T sum(int r, int c)
       T res = 0;
        for (int i = r; i \ge 0; i = (i & (i + 1)) - 1)
            for (int j = c; j \ge 0; j = (j & (j + 1)) - 1)
               res += t[i][j];
       return res;
    }
    // sum[(r1, c1), (r2, c2)]
   T sum(int r1, int c1, int r2, int c2)
       return sum(r2, c2) - sum(r1 - 1, c2) - sum(r2, c1 - 1) + sum(r1 - 1, c1 - 1);
   T get(int r, int c)
       return sum(r, c, r, c);
```

```
void set(int r, int c, T value)
{
    add(r, c, -get(t, r, c) + value);
};
```

6 ./estructuras/fenwickTree/fenwickTree.cpp

```
#include "../../headers/headers.h"
struct FenwickTree
    vector<int> FT;
    FenwickTree(int N)
        FT.resize(N + 1, 0);
    }
    int query(int i)
        int ans = 0;
       for (; i; i -= i & (-i))
            ans += FT[i];
       return ans;
    }
    int query(int i, int j)
        return query(j) - query(i - 1);
    }
    void update(int i, int v)
        int s = query(i, i);
        for (; i < FT.size(); i += i & (-i))
           FT[i] += v - s;
    }
    //Queries puntuales, Updates por rango
    void update(int i, int j, int v)
        update(i, v);
        update(j + 1, -v);
};
```

$7 \quad ./math/simpsonsMethod/simpsonsMethod.cpp$

```
#include "../../headers.h"
//Numerical Integration of f in interval [a,b]
double simpsons_rule(function<double(double)> f, double a, double b)
    double c = (a + b) / 2;
    double h3 = abs(b - a) / 6;
    return h3 * (f(a) + 4 * f(c) + f(b));
}
//Integrate f between a and b, using intervals of length (b-a)/n
double simpsons_rule(function<double(double)> f, double a, double b, int n)
    //n sets the precision for the result
    double ans = 0;
    double step = 0, h = (b - a) / n;
    rep(i, n)
        ans += simpsons_rule(f, step, step + h);
        step += h;
    return ans;
}
```

8 ./graphs/dinic/dinic.cpp

```
#include "../../headers/headers.h"
class Dinic
{
    struct edge
        int to, rev;
        11 f, cap;
    };
    vector<vector<edge>> g;
    vector<1l> dist;
    vector<int> q, work;
    int n, sink;
    bool bfs(int start, int finish)
    {
        dist.assign(n, -1);
        dist[start] = 0;
        int head = 0, tail = 0;
        q[tail++] = start;
        while (head < tail)</pre>
            int u = q[head++];
            for (const edge &e : g[u])
            {
                int v = e.to;
                if (dist[v] == -1 \text{ and } e.f < e.cap)
                    dist[v] = dist[u] + 1;
                     q[tail++] = v;
            }
        }
        return dist[finish] != -1;
    }
    11 dfs(int u, 11 f)
        if (u == sink)
            return f;
        for (int &i = work[u]; i < (int)g[u].size(); ++i)</pre>
            edge \&e = g[u][i];
            int v = e.to;
```

```
if (e.cap <= e.f or dist[v] != dist[u] + 1)</pre>
                 continue;
            11 df = dfs(v, min(f, e.cap - e.f));
            if (df > 0)
                e.f += df;
                g[v][e.rev].f -= df;
                return df;
        }
        return 0;
    }
  public:
    Dinic(int n)
        this->n = n;
        g.resize(n);
        dist.resize(n);
        q.resize(n);
    }
    void add_edge(int u, int v, ll cap)
    {
        edge a = {v, (int)g[v].size(), 0, cap};
        edge b = {u, (int)g[u].size(), 0, 0}; //Poner cap en vez de 0 si la arista es bidir
        g[u].pb(a);
        g[v].pb(b);
    }
    11 max_flow(int source, int dest)
    {
        sink = dest;
        11 \text{ ans} = 0;
        while (bfs(source, dest))
            work.assign(n, 0);
            while (ll delta = dfs(source, LLONG_MAX))
                ans += delta;
        }
        return ans;
    }
};
```

9 ./graphs/dijsktra/dijsktra.cpp

```
#include "../../headers/headers.h"
//g has vectors of pairs of the form (w, index)
int dijsktra(wgraph g, int start, int end)
    int n = g.size();
    vi cost(n, 1e9); //~INT_MAX/2
    priority_queue<ii, greater<ii>>> q;
    q.emplace(0, start);
    cost[start] = 0;
    while (not q.empty())
        int u = q.top().second, w = q.top().first;
        q.pop();
        for (auto v : g[u])
            if (cost[v.second] > v.first + w)
                cost[v.second] = v.first + w;
                q.emplace(cost[v.second], v.second);
        }
    }
    return cost[end];
}
```

$10 \quad ./graphs/dfs/dfsRecursive.cpp$

```
#include "../../headers/headers/headers.h"
//Recursive (create visited filled with 1s)
void dfs_r(graph &g, vi &visited, int u)
{
    cout << u << '\n';
    visited[u] = 0;

    for (int v : g[u])
        if (visited[v])
            dfs_r(g, visited, v);
}</pre>
```

11 ./graphs/dfs/dfsIterative.cpp

```
#include "../../headers/headers.h"
//Iterative
void dfs_i(graph &g, int start)
    int n = g.size();
   vi visited(n, 1);
   stack<int> s;
    s.emplace(start);
   visited[start] = 0;
   while (not s.empty())
       int u = s.top();
       s.pop();
       cout << u << '\n';
       for (int v : g[u])
           if (visited[v])
               s.emplace(v);
               visited[v] = 0;
           }
   }
}
```

12 ./graphs/lca/lca.cpp

```
#include "../../headers/headers.h"
class LcaTree
    int n;
    vi parent;
    vi level;
    vi root;
    graph P;
public:
    LcaTree(int n){
        this->n = n;
        parent.assign(n,-1);
        level.assign(n,-1);
        P.assign(n,vi(lg(n)+1,-1));
        root.assign(n,-1);
    }
    void addLeaf(int index, int par){
        parent[index] = par;
        level[index] = level[par] + 1;
        P[index][0] = par;
        root[index] = root[par];
        for(int j=1; (1 << j) < n; ++j){
            if(P[index][j-1] != -1)
                P[index][j] = P[P[index][j-1]][j-1];
        }
    }
    void addRoot(int index){
        parent[index] = index;
        level[index] = 0;
        root[index] = index;
    }
    int lca(int u, int v){
        if(root[u] != root[v] || root[u] == -1)
            return -1;
        if(level[u] < level[v])</pre>
            swap(u,v);
        int dist = level[u] - level[v];
        while(dist != 0){
            int raise = lg(dist);
            u = P[u][raise];
            dist -= (1<<raise);</pre>
        if(u == v)
            return u;
```

```
for(int j = lg(n); j>=0; --j){
    if(P[u][j] != -1 && P[u][j] != P[v][j]){
        u=P[u][j];
        v=P[v][j];
    }
}
return parent[u];
};
```

13 ./graphs/kruskal/kruskal.cpp

```
#include "../../headers/headers.h"
struct edge
{
    int u, v;
    11 w;
    edge(int u, int v, ll w) : u(u), v(v), w(w) {}
    bool operator<(const edge &o) const</pre>
        return w < o.w;
    }
};
class Kruskal
  private:
    ll sum;
    vi p, rank;
  public:
  //Amount of Nodes n, and unordered vector of Edges E
    Kruskal(int n, vector<edge> E)
    {
        sum = 0;
        p.resize(n);
        rank.assign(n, 0);
        rep(i, n) p[i] = i;
        sort(E.begin(), E.end());
        for (auto &e : E)
            UnionSet(e.u, e.v, e.w);
    }
    int findSet(int i)
    {
        return (p[i] == i) ? i : (p[i] = findSet(p[i]));
    }
    bool isSameSet(int i, int j)
        return findSet(i) == findSet(j);
    void UnionSet(int i, int j, ll w)
        if (not isSameSet(i, j))
        {
            int x = findSet(i), y = findSet(j);
```

14 ./graphs/unionFind/unionFind.cpp

```
#include "../../headers/headers.h"
class UnionFind
 private:
   int numSets;
   vi p, rank, setSize;
 public:
   UnionFind(int n)
    {
        numSets = n;
        rank.assign(n, 0);
       setSize.assign(n, 1);
        p.resize(n);
        rep(i, n) p[i] = i;
    }
   int findSet(int i)
        return (p[i] == i) ? i : (p[i] = findSet(p[i]));
    }
   bool isSameSet(int i, int j)
        return findSet(i) == findSet(j);
    }
   void UnionSet(int i, int j)
        if (not isSameSet(i, j))
            numSets--;
            int x = findSet(i), y = findSet(j);
            if (rank[x] > rank[y])
            {
                p[y] = x;
                setSize[x] += setSize[y];
            }
            else
                p[x] = y;
                setSize[y] += setSize[x];
                if (rank[x] == rank[y])
                    rank[y]++;
            }
        }
   }
```

```
int numSets()
{
     return numSets;
}
int setOfSize(int i)
{
     return setSize[i];
};
```

15 ./graphs/bfs/bfs.cpp

```
#include "../../headers/headers.h"
void bfs(graph &g, int start)
    int n = g.size();
   vi visited(n, 1);
   queue<int> q;
   q.emplace(start);
   visited[start] = 0;
   while (not q.empty())
       int u = q.front();
       q.pop();
       for (int v : g[u])
           if (visited[v])
               q.emplace(v);
               visited[v] = 0;
       }
   }
}
```

16 ./graphs/bellmanFord/bellmanFord.cpp

```
#include "../../headers/headers.h"
bool bellman_ford(wgraph &g, int start)
{
    int n = g.size();
    vector<int> dist(n, 1e9); //~INT_MAX/2
    dist[start] = 0;
    rep(i, n - 1) rep(u, n) for (ii p : g[u])
    {
        int v = p.first, w = p.second;
        dist[v] = min(dist[v], dist[u] + w);
    }
    bool hayCicloNegativo = false;
   rep(u, n) for (ii p : g[u])
        int v = p.first, w = p.second;
        if (dist[v] > dist[u] + w)
            hayCicloNegativo = true;
    }
    return hayCicloNegativo;
}
```