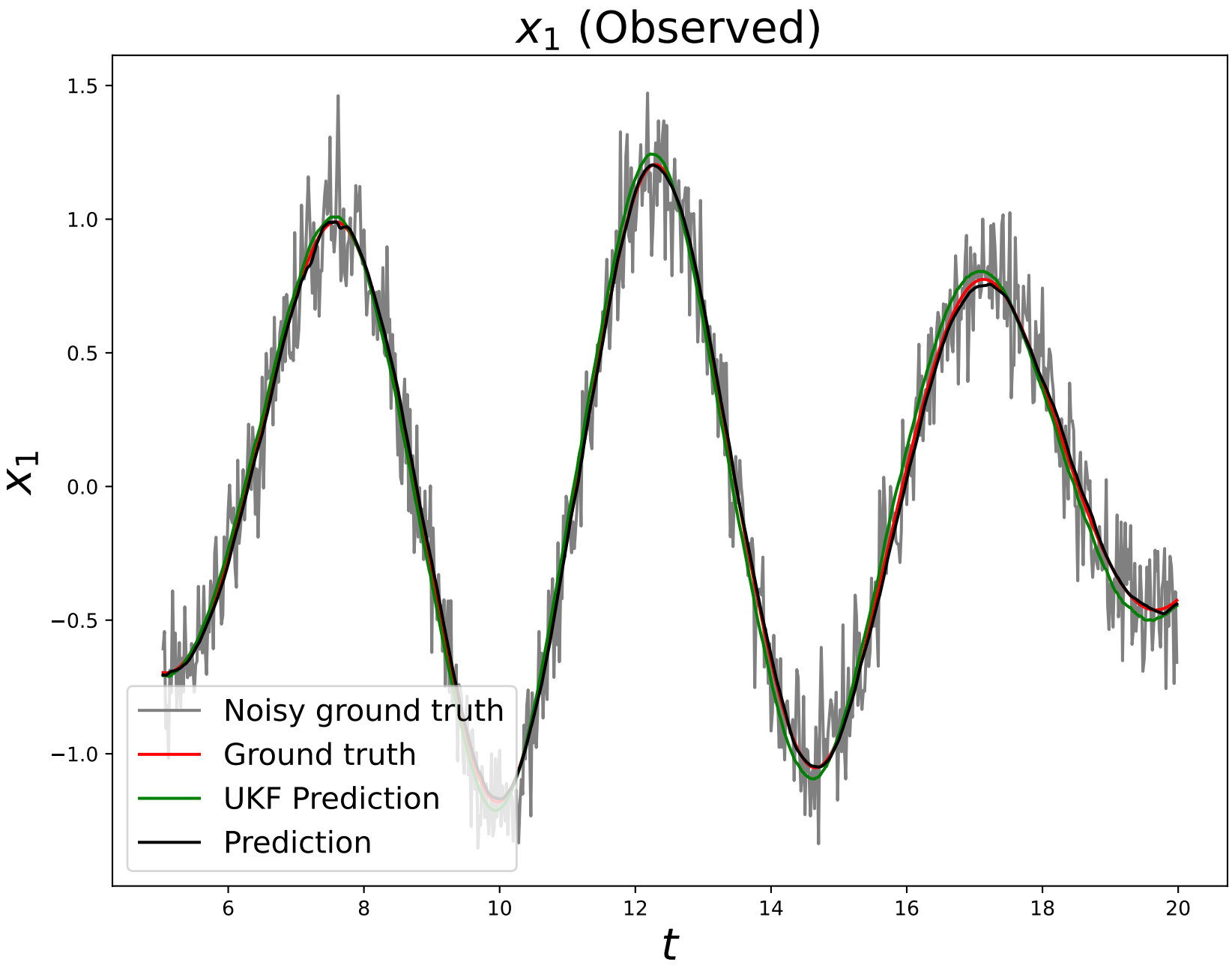
x_1 (Observed)
1.5
1.0
0.5
0.0
−0.5
−1.0
x_1
6
8
10
12
14
16
18
20
t
Noisy ground truth
Ground truth
UKF Prediction
Prediction