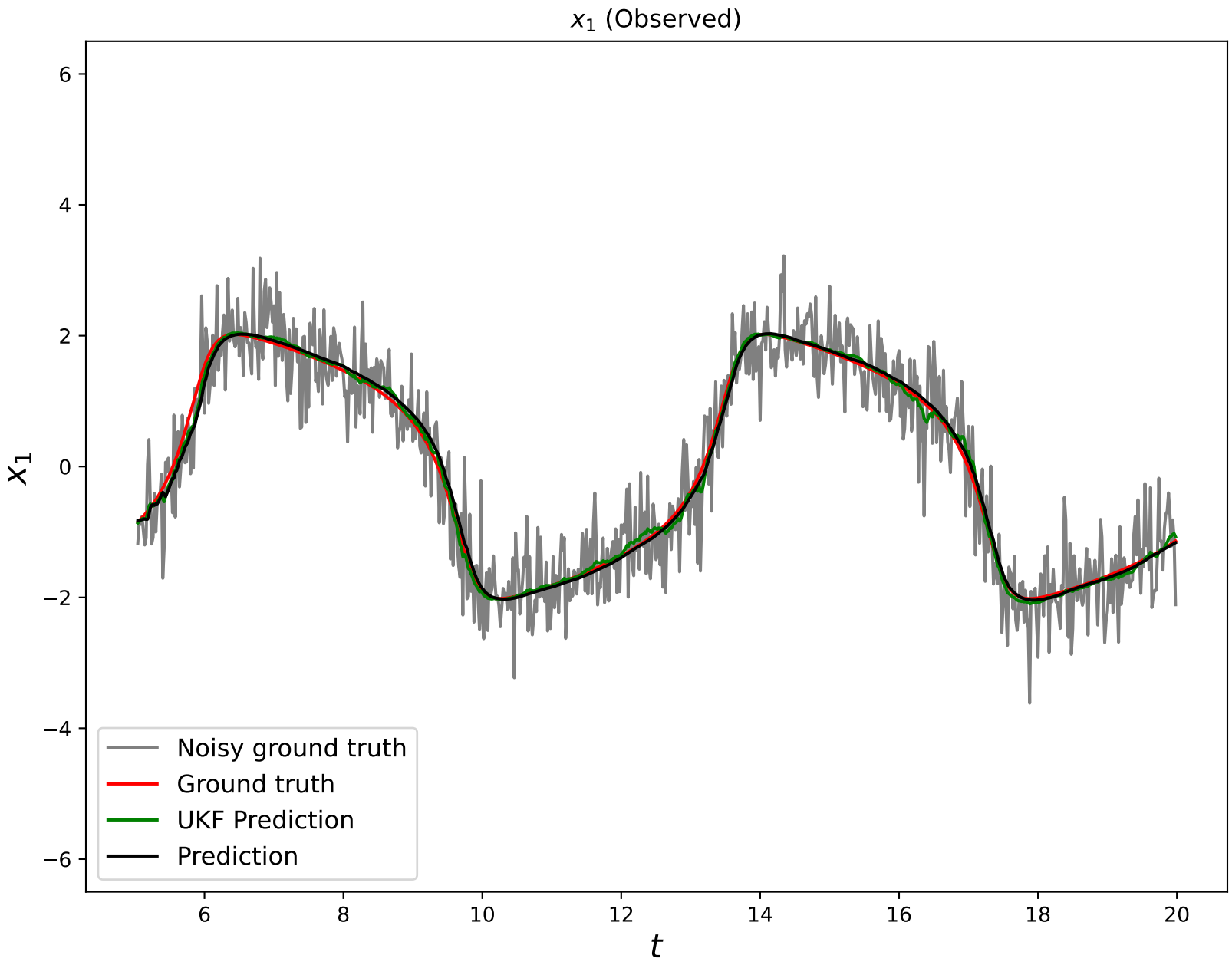
x_1 (Observed)
6
4
2
0
−2
−4
−6
x_1
6
8
10
12
14
16
18
20
t
Noisy ground truth
Ground truth
UKF Prediction
Prediction