

view\_frames Result

Recorded at time: 6100.325

robot\_footprint

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 6100.325 sec old)  
Buffer length: 0.000 sec

chassis

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 6100.325 sec old)  
Buffer length: 0.000 sec

camera

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 6100.325 sec old)  
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 6100.304 ( 0.021 sec old)  
Buffer length: 4.900 sec

left\_wheel

Broadcaster: /robot\_state\_publisher  
Average rate: 10.204 Hz  
Most recent transform: 6100.304 ( 0.021 sec old)  
Buffer length: 4.900 sec

right\_wheel