**How to operate/run missions on the boat ?**

//Run the roscore

roscore

//Run the boat simulator

rosrun boatsim sim

//launch the navigation.launch file foremost during actual run

roslaunch boat\_launch navigation.launch

//launch the controller.launch file

roslaunch boat\_launch controller. launch

//launch the run.launch file

roslaunch boat\_launch run.launch

//Run the desired mission file as follows:

//retract\_hydrophone is the name of the mission file here

rosrun mission\_core run\_missions boat\_launch.mission.retract\_hydrophone

Authored on 2/13/2015 :: Khimya Khetarpal