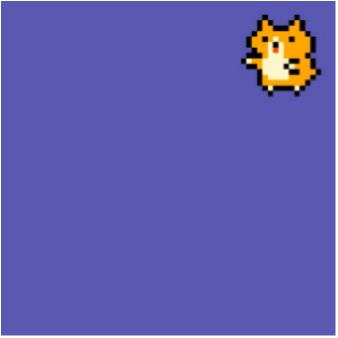
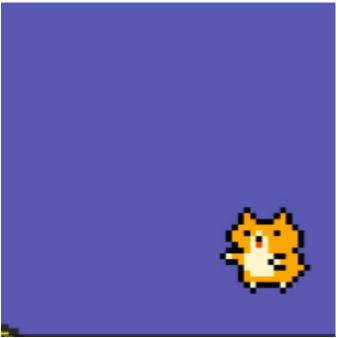
Two reward type

Reward (Animation Image)









+1 reward

-1 reward







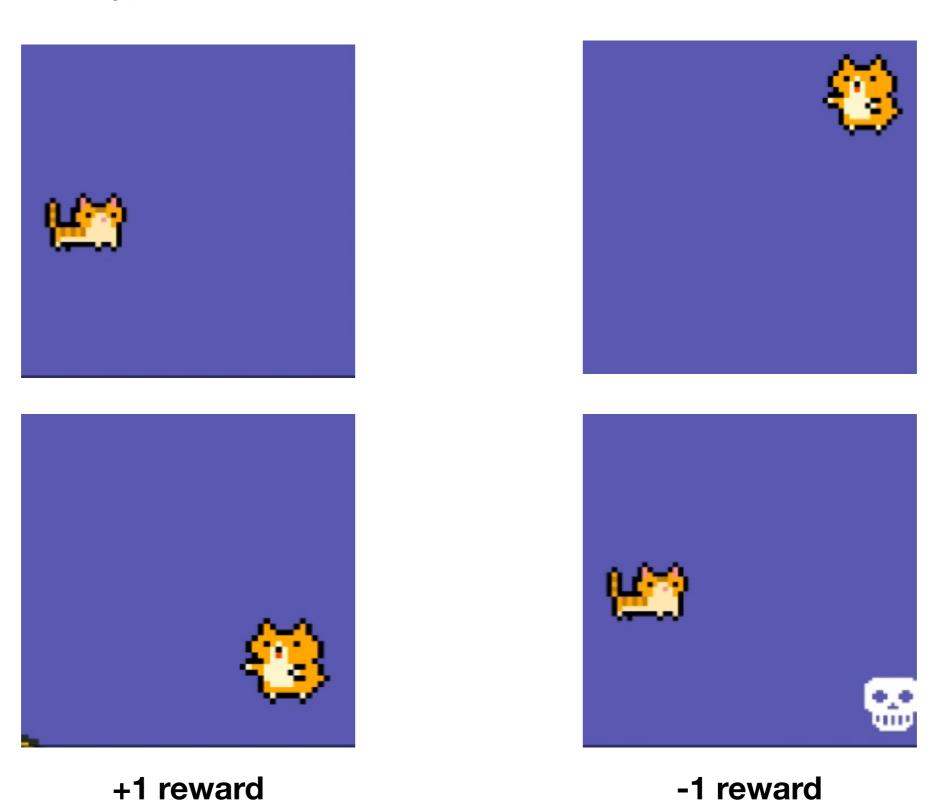






Reward (Animation Image)

■ Two reward type



Reinforcement Learning

- MDP & Bellman equation
 - Markov Decision Process
 - MDP is a model for sequential stochastic decision problems
 - with four tuples $\langle S, A, R, tr \rangle$ (State, Action, Reward, Transition probability)
 - Bellman Equation

$$v_{\pi}(s) \doteq \sum_{a \in A} \pi(a|s) \sum_{s',r} p(s',r|s,a)[r + \gamma v_{\pi}(s')], \quad \text{for all} \quad s \in S$$

state - value function

$$v_{\pi}(s) \doteq \mathbb{E}_{\pi} \left[\sum_{k=0}^{\infty} \gamma^{k} R_{t+k+1} \middle| S_{t} = s \right], \text{ for all } s \in \mathcal{S},$$

action - value function

$$q_{\pi}(s,a) \doteq \mathbb{E}_{\pi} \left[\sum_{k=0}^{\infty} \gamma^k R_{t+k+1} \mid S_t = s, A_t = a \right]$$