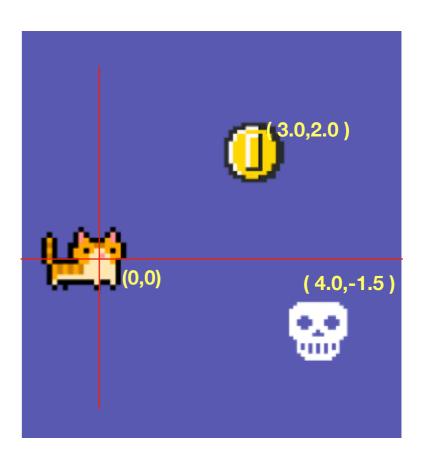
State (observation)

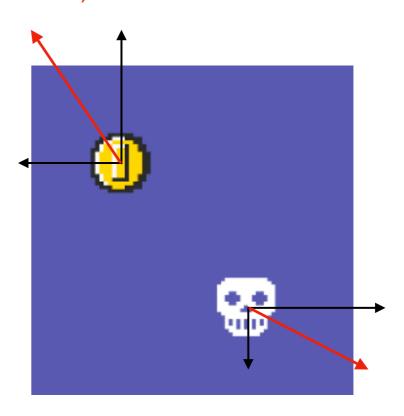
- 11 states
 - Relative distances
 - Skull X
 Agent X position Skull object X position
 - 2. Skull Y
 Agent Y position Skull object Y position
 - 3 Coin X Agent X position - Coin object X position
 - 4. Coin YAgent Y position Coin object Y position



State (observation)

- 11 states
 - Velocities
 - 5. Skull X *v* Skull object X velocity
 - 6. Skull Y *v* Skull object Y velocity
 - 7. Coin X *v*Coin object X velocity
 - 8. Coin Y *v*Coin object Y velocity

(coin X v, coin Y v)



(skull X v, skull Y v)