การควบคุมเครื่องจักรอัจฉริยะโดยใช้การสื่อสารระหว่างเครื่องจักรกับเครื่องจักร M2M - Intelligence Machine Control

ขื่อ-สกุล : นางสาวณัฐชยา ผ[่]องกุศล B6226718

5/5: -- คำถามท้ายบทเพื่อทดสอบความเข้าใจ

Quiz_301 – Start SCADA [ไม่ต้องทำเพราะไม่มี PLC]

- < รูปอุปกรณ์ที่ใช้ทดสอบ ขณะทำการทดสอบ >
- < รูปอุปกรณ์ที่ใช้ทดสอบ ขณะทำการทดสอบ >

รายยละเอียดการทดสอบ

- < โปรแกรมทดสอบ >
- < ผลการทดสอบ >

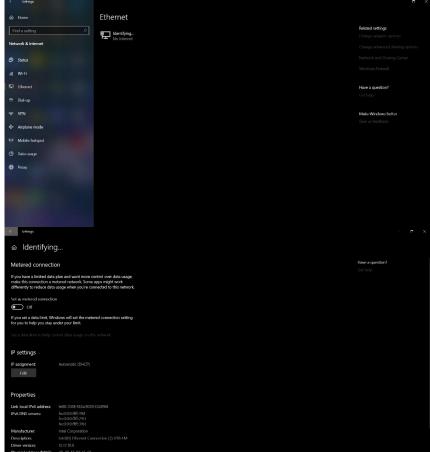
Quiz_302 – Modbus TCP Read/Write

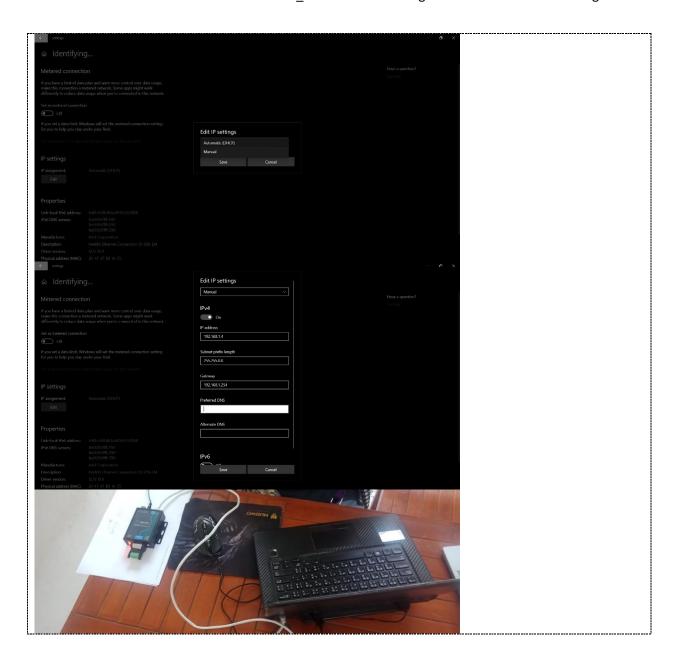
< รูปอุปกรณ์ที่ใช้ทดสอบ ขณะทำการทดสอบ >

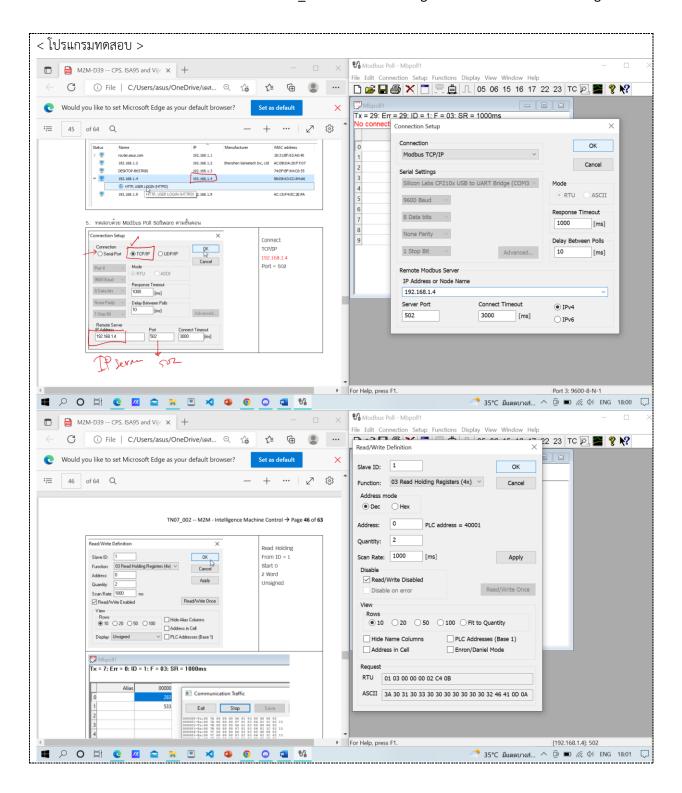


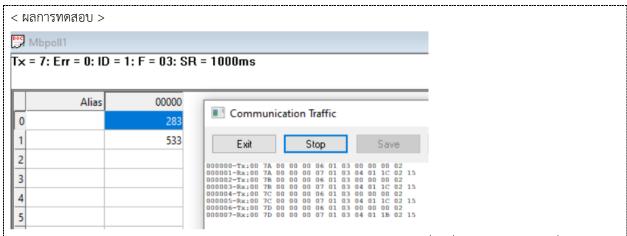


รายยละเอียดการทดสอบ

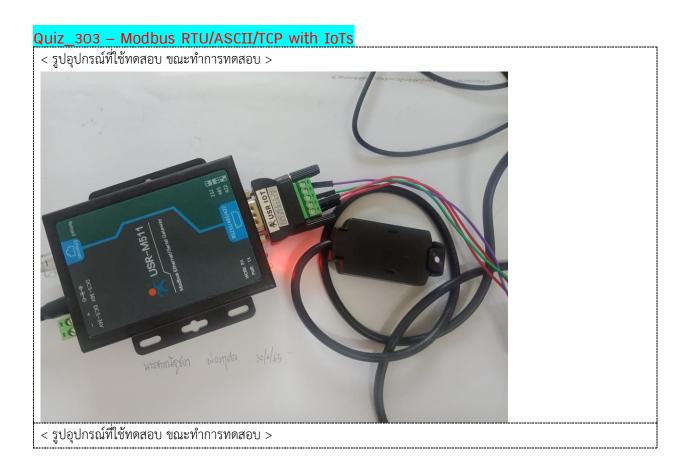


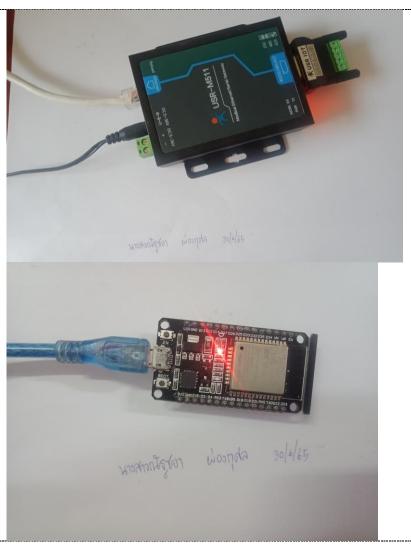




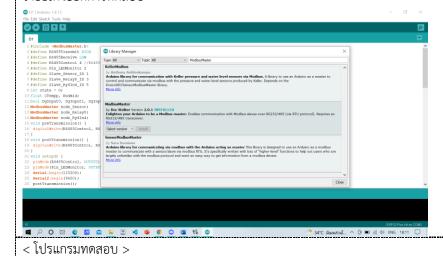


ถ้าสำเร็จจะได้ดังรูป คือจะต้องต่อ Modbus ethernet เข้ากับ modbus senser และอื่นๆที่อยากทราบค่าด้วย เมื่อเรียบร้อย ให้มาทดสอบใน modbus poll ก็จะได้ตามรูปอาจารย์







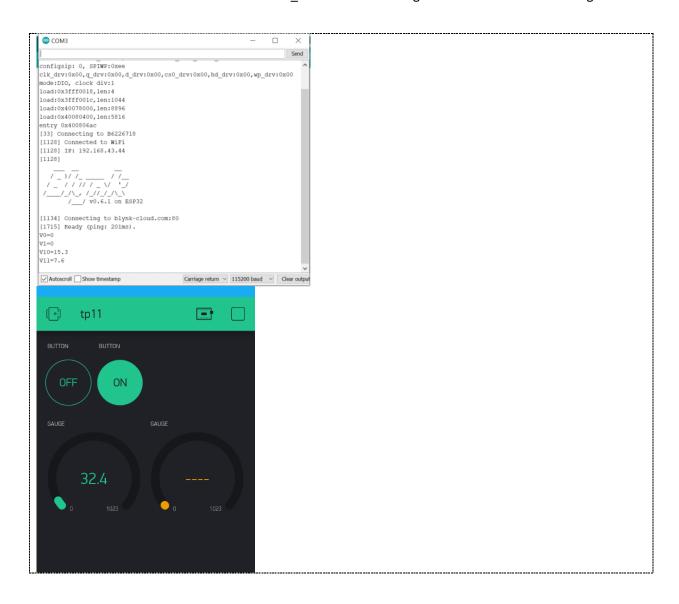


```
D1 | Arduino 1.8.13
  1// esp32ModbusTCP >> https://github.com/bertmelis/esp32ModbusTCP 2// AsyncTCP.h >> https://github.com/me-no-dev/AsyncTCP 3 #define BLYNK_PRINT Serial
 3 #deefine BLYMK_PRINT Serial
4 #include <MLF1.h>
5 #include <MLF1.h>
6 #include <MLF1.h>
6 #include <Arduino.h>
8 #include <Arduino.h>
9 char ssid[] = "B6226718";
10 char pass[] = "pungpingjerry";
11 char auth[] = "WPa2mtFT_6qi9Rgfh3Nxc8AXS-ylfnoe";
12 bool WiFiconnected = false;
13 int Value VO. Value VI;
  13 int Value V0, Value V1;
14 esp32ModbusTCP sunnyboy(1, {192, 168, 1, 4}, 502);
  15 enum smaType {
16 ENUM, // enumeration
17 UFIXO, // unsigned 2 Byte, no decimals
  18 SFIXO, // signed 4 Byte, no decimals
  20 struct smaData {
 20 struct smaData {
21 const char* name;
22 uint16_t address;
23 uint16_t length;
24 smaType type;
  25 uint16_t packetId;
// esp32ModbusTCP >> https://github.com/bertmelis/esp32ModbusTCP
// AsyncTCP.h >> https://github.com/me-no-dev/AsyncTCP
#define BLYNK PRINT Serial
#include <WiFi.h>
#include <WiFiClient.h>
#include <BlynkSimpleEsp32.h>
#include <Arduino.h>
#include <esp32ModbusTCP.h>
char ssid[] = "Mue.Home";
char pass[] = "pk1212312121";
char auth[] = "YD3FmnLEk5vdhs-BeQlWwrACl8gXNgXK";
bool WiFiConnected = false;
int Value V0, Value V1;
esp32ModbusTCP sunnyboy(1, {192, 168, 1, 4}, 502);
enum smaType {
 ENUM, // enumeration
 UFIX0, // unsigned 2 Byte, no decimals
 SFIX0, // signed 4 Byte, no decimals
struct smaData {
 const char* name;
 uint16 t address;
```

```
uint16_t length;
smaType type;
uint16 t packetld;
smaData smaRegisters[] = {
"Tempp", 0, 1, UFIX0, 0,
"Humid", 1, 1, UFIX0, 0
uint8 t numberSmaRegisters = sizeof(smaRegisters) / sizeof(smaRegisters[0]);
uint8 t currentSmaRegister = 0;
uint16_t ResultData[3];
BLYNK WRITE(V0) {
int temp = param.asInt();
if (temp != Value V0) {
Value_V0 = temp;
RelayControl(801 + temp * 10);
BLYNK_WRITE(V1) {
int temp = param.asInt();
if (temp != Value V1) {
Value V1 = temp;
RelayControl(802 + temp * 10);
}
void RelayControl(int Code) {
Serial.println("Code is = " + String(Code));
void setup() {
Serial.begin(115200);
WiFi.disconnect(true); // delete old config
sunnyboy.onData([](uint16 t packet, uint8 t slave, esp32Modbus::FunctionCode fc , uint8 t* data ,
uint16 t len) {
for (uint8 t i = 0; i < numberSmaRegisters; ++i) {
if (smaRegisters[i].packetId == packet) {
```

```
smaRegisters[i].packetId = 0;
switch (smaRegisters[i].type) {
case ENUM:
case UFIX0: {
uint32 t value = 0; // 2-Byte Data
value = (data[0] << 8) | (data[1]); // 2-Byte Data</pre>
Serial.printf("%s: %u\n", smaRegisters[i].name, value);
ResultData[i] = value;
break;
case SFIX0: {
int32_t value = 0;
value = (data[0] << 24) | (data[1] << 16) | (data[2] << 8) | (data[3]);
Serial.printf("%s: %i\n", smaRegisters[i].name, value);
break;
}
return;
}
});
sunnyboy.onError([](uint16 t packet, esp32Modbus::Error e) {
Serial.printf("Error packet %u: %02x\n", packet, e);
});
delay(1000);
WiFi.onEvent([](WiFiEvent t event, WiFiEventInfo t info) {
Serial.print("WiFi connected. IP: ");
Serial.println(IPAddress(info.got_ip.ip_info.ip.addr));
WiFiConnected = true;
}, WiFiEvent_t::SYSTEM_EVENT_STA_GOT_IP);
WiFi.onEvent([](WiFiEvent_t event, WiFiEventInfo_t info) {
Serial.print("WiFi lost connection. Reason: ");
Serial.println(info.disconnected.reason);
WiFi.disconnect();
WiFiConnected = false;
```

```
}, WiFiEvent t::SYSTEM EVENT STA DISCONNECTED);
WiFi.begin(ssid, pass);
Serial.println();
Serial.println("Connecting to WiFi... ");
int loopCont = 20;
void loop() {
if (loopCont < 0 && WiFiConnected) {
loopCont = 20;
Serial.print("\nreading registers\n");
for (uint8 t i = 0; i < numberSmaRegisters; ++i) {
uint16 t packetId = sunnyboy.readHoldingRegisters(smaRegisters[i].address, smaRegisters[i].length);
if (packetId > 0) {
smaRegisters[i].packetId = packetId;
} else {
Serial.print("reading error\n");
delay(5000);
//Blynk.config(auth);
float CTempp = ResultData[0] / 10.0;
float Hudmid = ResultData[1] / 10.0;
Blynk.virtualWrite(V10, CTempp);
Blynk.virtualWrite(V11, Hudmid);
Serial.println("V0=" + String(Value V0));
Serial.println("V1=" + String(Value V1));
Serial.println("V10=" + String(CTempp, 1));
Serial.println("V11=" + String(Hudmid, 1));
Serial.print(String(loopCont--) + ",");
//Blynk.run();
delay(500);
< ผลการทดสอบ >
```



การควบคุมเครื่องจักรอัจฉริยะโดยใช้การสื่อสารระหว[่]างเครื่องจักรกับเครื่องจักร M2M - Intelligence Machine Control

ขื่อ-สกุล : นางสาวณัฐชยา ผ[่]องกุศล B6226718

4/4: -- คำถามท้ายบทเพื่อทดสอบความเข้าใจ

Quiz_401 – test Blynk







```
pinMode(testLED, OUTPUT);
   pinMode(testSW, INPUT PULLUP);
  Blynk.begin(auth, ssid, pass);
int loopCount = 10;
void loop() {
  Blynk.run();
  if (loopCount < 0) {
  loopCount = 20;
  //int stsTestSW = digitalRead(testSW);
  int stsTestSW = random(2);
   Serial.println("stsTestSW = " + String(stsTestSW));
  if (stsTestSW == 0)
   LED V4.off();
   else
  LED_V4.on();
  delay(100);
  loopCount--;
< โปรแกรมทดสอบ >
D1 | Arduino 1.8.13
     D1
| #define BLYNK_PRINT Serial
| #define BLYNK_PRINT Serial
| #include <Mifichent.h>
| #include
9 #define testsW 0

WidgetLED LED_V4(V4);

11 BLYNK_WKITE(V0);

12 int Value_V0 = param.asInt();

3 digitalWrite(testLED, Value_V0);

14 }

15 void setup() {

Serial.begin(115200);

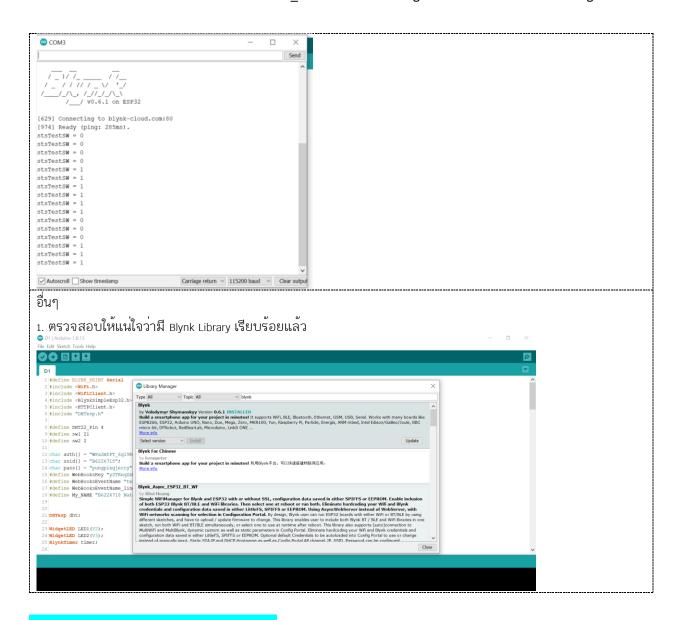
pinMode(testLED, OUTPUT);

pinMode(testLED, OUTPUT);

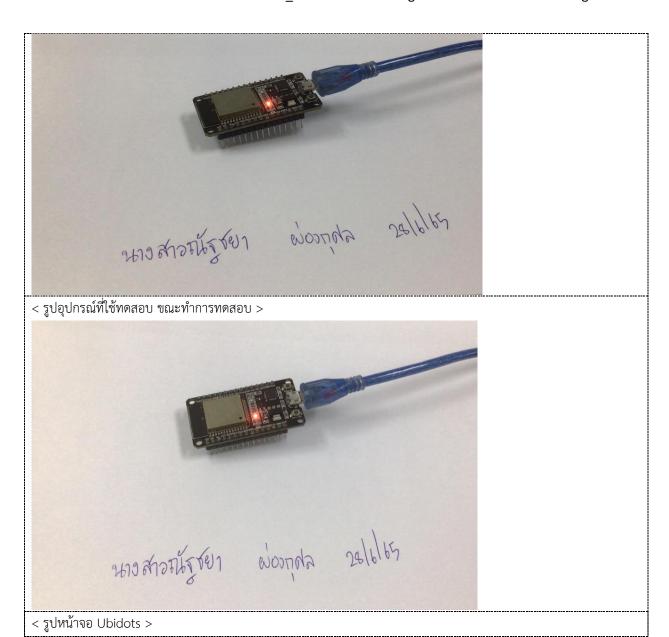
pinMode(testSW, INPUT_PULLUP);

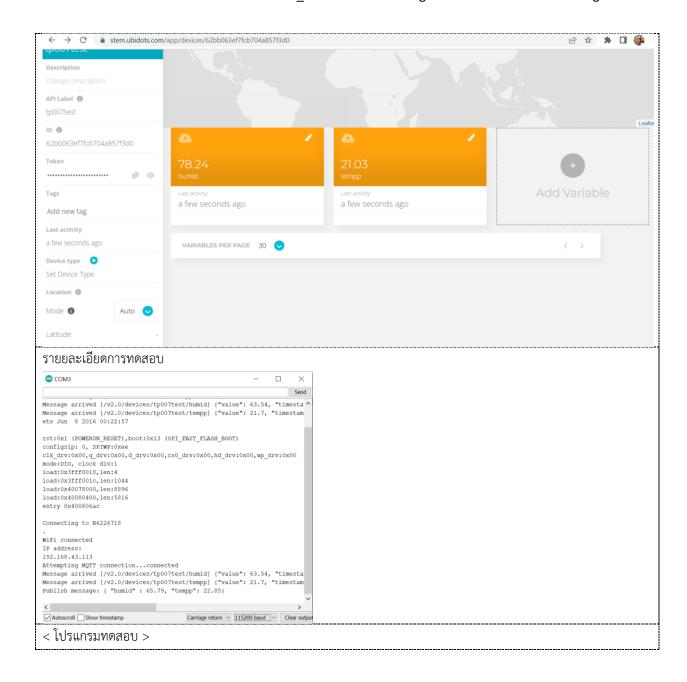
Blynk.begin(auth, ssid, pass);

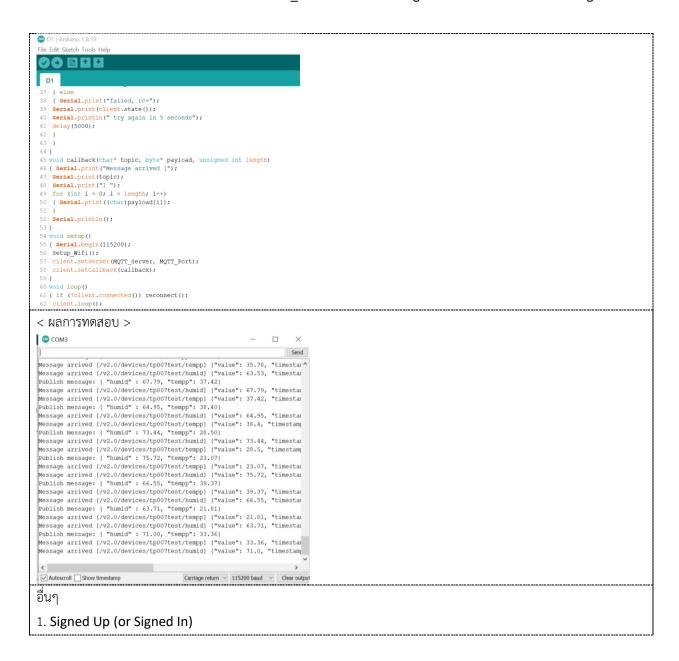
0)
  20 )
21 int loopCount = 10;
22 woid loop() {
23 Blynk.run();
4 if (loopCount < 0) {
25 loopCount = 20;
26 //int stsTestSW = digitalRead(testSW);
< ผลการทดสอบ >
```

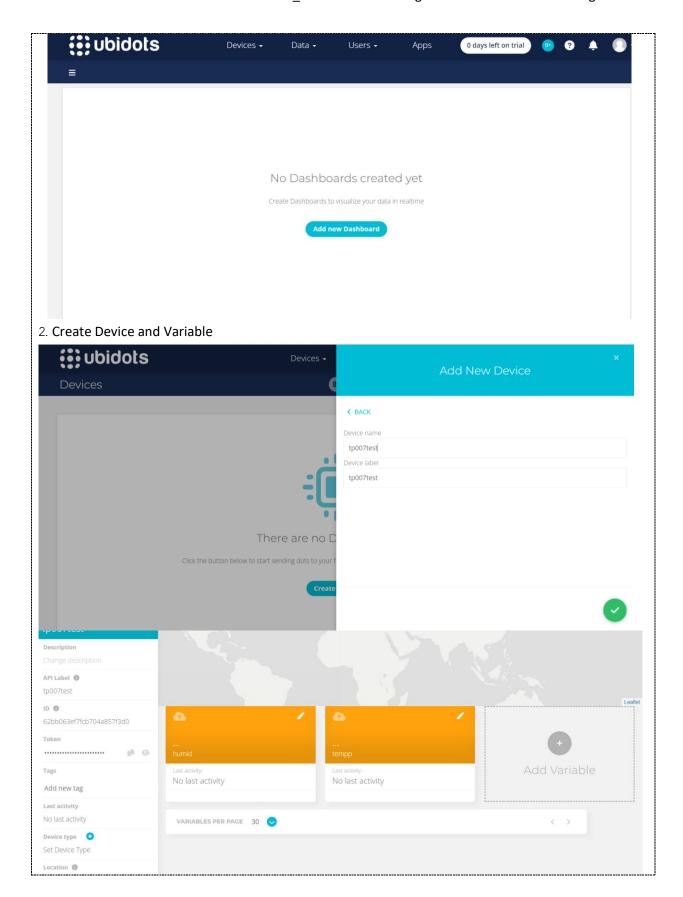


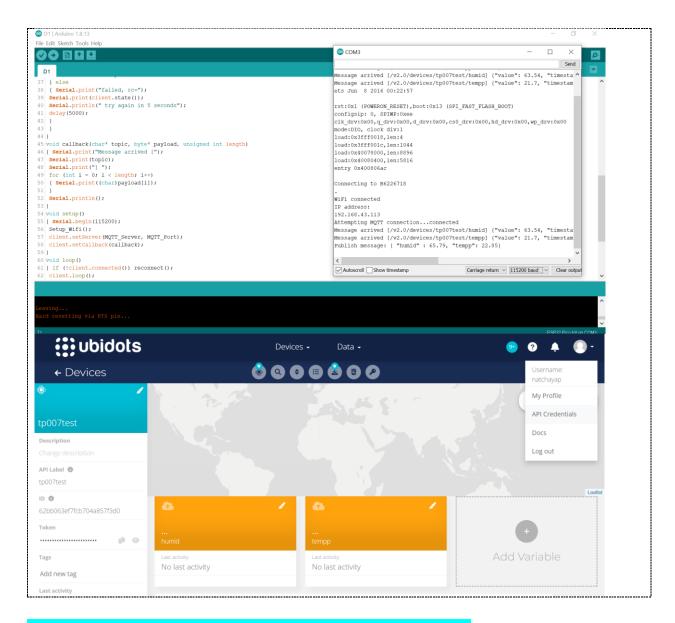
Quiz_402 - test Ubidot with ESP32



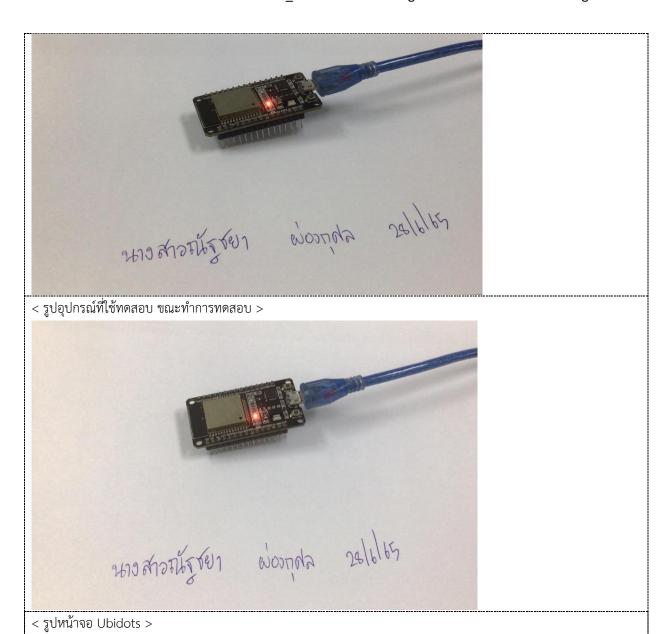


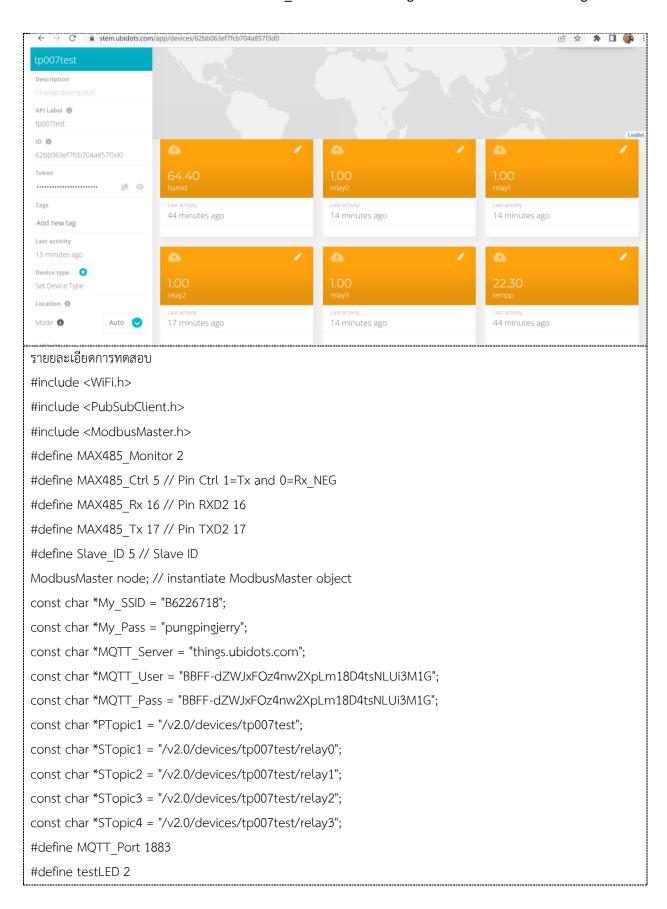






Quiz_403 - Modbus RTU/ASCII/TCP with Ubidots IoTs Platform

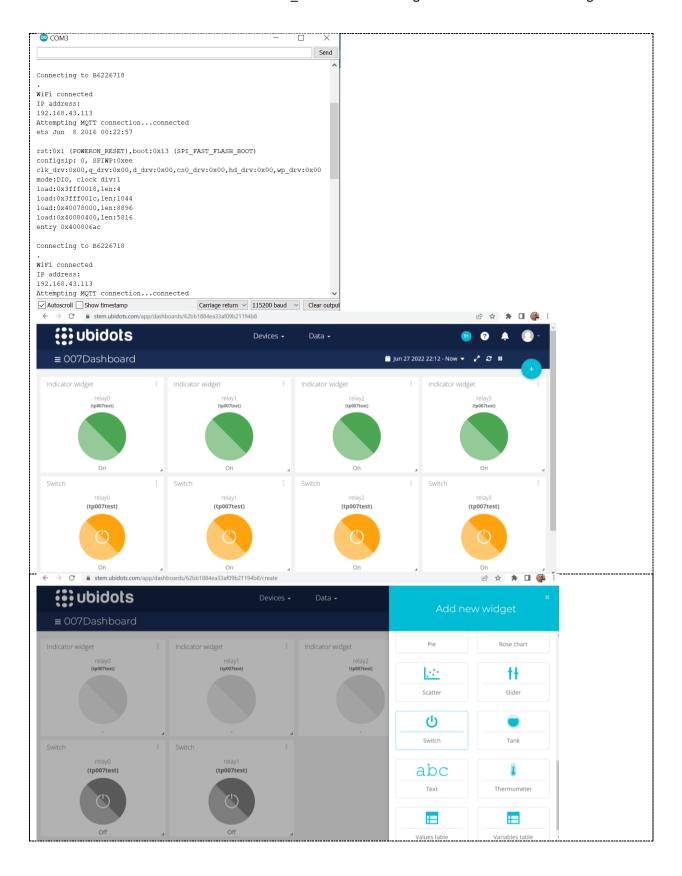


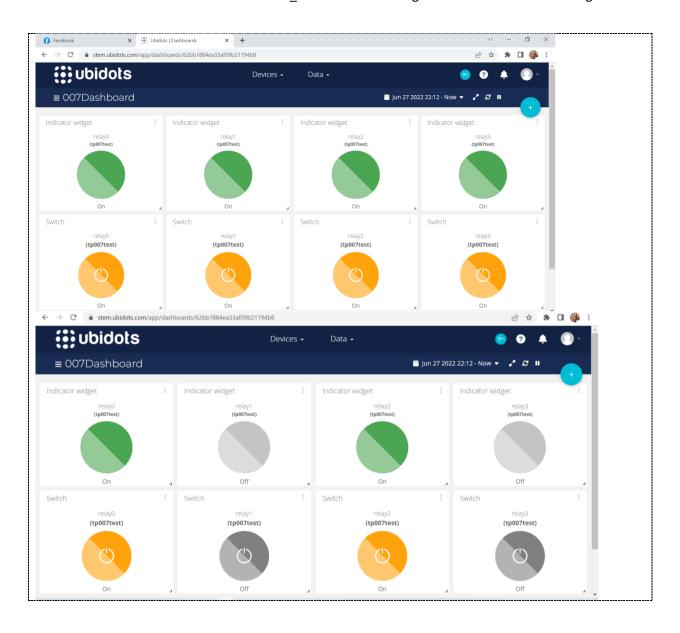


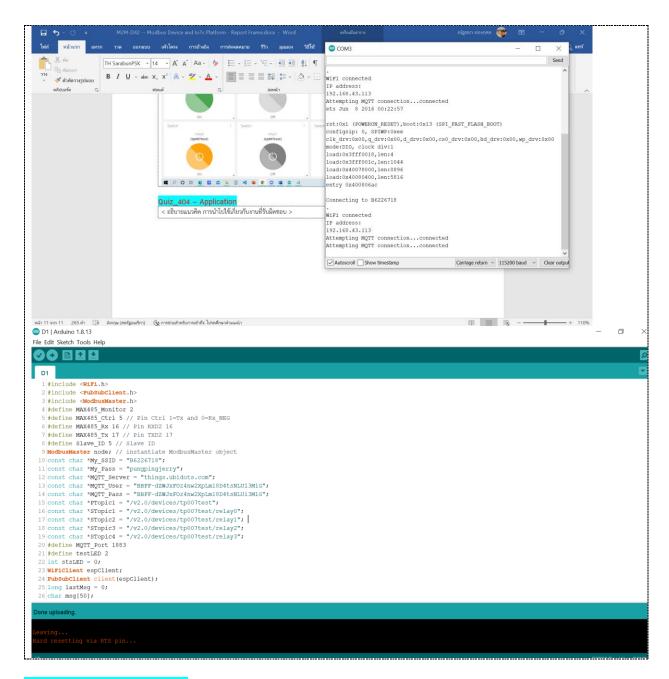
```
int stsLED = 0;
WiFiClient espClient;
PubSubClient client(espClient);
long lastMsg = 0;
char msg[50];
void Setup_Wifi() {
delay(10); Serial.println();
Serial.print("Connecting to ");
Serial.println(My SSID);
WiFi.begin(My_SSID, My_Pass);
while (WiFi.status() != WL CONNECTED) {
delay(500); Serial.print(".");
randomSeed(micros());
Serial.println(""); Serial.println("WiFi connected");
Serial.println("IP address: "); Serial.println(WiFi.localIP());
void reconnect()
{ while (!client.connected()) // Loop until we're reconnected
{ Serial.print("Attempting MQTT connection...");
String clientId = "ESP32 Client-";
clientId += String(random(0xffff), HEX); // Create a random client ID
if (client.connect(clientId.c str(), MQTT User, MQTT Pass)) // Attempt to connect
{ Serial.println("connected"); // Once connected, publish an announcement...
client.subscribe(STopic1);
client.subscribe(STopic2);
client.subscribe(STopic3);
client.subscribe(STopic4);
} else
{ Serial.print("failed, rc=");
Serial.print(client.state());
Serial.println(" try again in 5 seconds");
delay(5000);
}
```

```
void callback(char *topic, byte *payload, unsigned int length)
{ Serial.print("Message arrived [");
Serial.print(topic);
Serial.print("] ");
for (int i = 0; i < length; i++)
{ Serial.print((char)payload[i]);
int RlyID = (int)topic[29] - 0x30; // '0'
int RlySts = (int)payload[10] - 0x30; // '0'
Serial.println("\nRlyID-" + (String)(RlyID) + " >> RlyStatus-" + (String)(RlySts));
node.writeSingleCoil(RlyID, RlySts);
void preTransmission() {
digitalWrite(MAX485_Monitor, 1);
digitalWrite(MAX485 Ctrl, 1);
void postTransmission() {
digitalWrite(MAX485_Monitor, 0);
digitalWrite(MAX485_Ctrl, 0);
void setup()
{ pinMode(testLED, OUTPUT);
pinMode(MAX485_Monitor, OUTPUT);
pinMode(MAX485 Ctrl, OUTPUT);
postTransmission(); // Init in receive mode
Serial.begin(115200);
Serial2.begin(9600, SERIAL_8N1, MAX485_Rx, MAX485_Tx);
node.begin(Slave ID, Serial2); // Modbus slave ID Setting
// Callbacks allow us to configure the RS485 transceiver correctly
node.preTransmission(preTransmission);
node.postTransmission(postTransmission);
Setup Wifi();
client.setServer(MQTT_Server, MQTT_Port);
client.setCallback(callback);
```

```
void loop()
{ if (!client.connected()) reconnect();
client.loop();
long now = millis();
if (now - lastMsg > 5000)
{ lastMsg = now;
digitalWrite(testLED, stsLED);
stsLED = 1 - stsLED;
< โปรแกรมทดสอบ >
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                                                                                                                        B ☆ * □ ●
Description
API Label 🕦
tp007test
ID 🔞
62bb063ef7fcb704a857f3d0
 Token
 Tags
                               44 minutes ago
                                                                    14 minutes ago
                                                                                                         14 minutes ago
 Add new tag
 15 minutes ago
Device type 🕠
Set Device Type
Location (
 Mode 🚯
                               17 minutes ago
                                                                    14 minutes ago
                                                                                                         44 minutes ago
< ผลการทดสอบ >
```







Quiz_404 - Application

ยังไม่มีงานที่รับผิดชอบ แต่สามารถคิดไอเดียเพื่อนำไปต่อยอดได้ คือการออกแบบควบคุมวงจรต่างๆบน dashboard รวมถึง สามารถควบคุมการแสดงผลบนอุปกรณ์จริงผ่าน ubidot ได้