

CODE

```
#include<stdio.h>

#include<conio.h>

#define INFINITY 9999

#define MAX 10

void dijkstra(int G[MAX][MAX],int n,int startnode);

int main()
{
    int G[MAX][MAX],i,j,n,u;
    printf("Enter no. of vertices:");
    scanf("%d",&n);
    printf("\nEnter the adjacency matrix:\n");

    for(i=0;i<n;i++)
        for(j=0;j<n;j++)
            scanf("%d",&G[i][j]);

    printf("\nEnter the starting node:");
    scanf("%d",&u);
    dijkstra(G,n,u);

    return 0;
}

void dijkstra(int G[MAX][MAX],int n,int startnode)
{
```

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int cost[MAX][MAX],distance[MAX],pred[MAX];
int visited[MAX],count,mindistance,nextnode,i,j;

//pred[] stores the predecessor of each node
//count gives the number of nodes seen so far
//create the cost matrix
for(i=0;i<n;i++)
    for(j=0;j<n;j++)
        if(G[i][j]==0)
            cost[i][j]=INFINITY;
        else
            cost[i][j]=G[i][j];

//initialize pred[],distance[] and visited[]
for(i=0;i<n;i++)
{
    distance[i]=cost[startnode][i];
    pred[i]=startnode;
    visited[i]=0;
}

distance[startnode]=0;
visited[startnode]=1;
count=1;

while(count<n-1)
{
    mindistance=INFINITY;

    //nextnode gives the node at minimum distance
    for(i=0;i<n;i++)
        if(distance[i]<mindistance&&!visited[i])

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        {
            mindistance=distance[i];
            nextnode=i;
        }

//check if a better path exists through nextnode

visited[nextnode]=1;
for(i=0;i<n;i++)
    if(!visited[i])
        if(mindistance+cost[nextnode][i]<distance[i])
        {
            distance[i]=mindistance+cost[nextnode][i];
            pred[i]=nextnode;
        }

    count++;
}

//print the path and distance of each node
for(i=0;i<n;i++)
    if(i!=startnode)
    {
        printf("\nDistance of node%d=%d",i,distance[i]);
        printf("\nPath=%d",i);

        j=i;
        do
        {
            j=pred[j];
            printf("<-%d",j);
        }while(j!=startnode);
    }

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    }  
}
```

This C program implements Dijkstra's algorithm to find the shortest path from a starting node to all other nodes in a given graph represented by an adjacency matrix. Here's an analysis of the code structure and documentation of how each function works:

Code Structure Analysis

1. Includes and Definitions:

- `#include <stdio.h>`: Includes the standard input/output library.
- `#include <conio.h>`: Includes console input/output functions (not used in this program).
- `#define INFINITY 9999`: Defines a large value to represent infinity.
- `#define MAX 10`: Defines the maximum number of vertices in the graph.

2. Function Declarations:

- `void dijkstra(int G[MAX][MAX], int n, int startnode);`: Declaration of the Dijkstra function.

3. Main Function:

- Reads the number of vertices (`n`) and the adjacency matrix (`G`).
- Reads the starting node (`u`).
- Calls the `dijkstra` function to compute shortest paths from the starting node.

4. Dijkstra Function:

- Computes the shortest paths from the starting node to all other nodes using Dijkstra's algorithm.
- Prints the shortest path and distance to each node from the starting node.

Function Documentation

Main Function

C

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```
int main() {
    int G[MAX][MAX], i, j, n, u;
    printf("Enter no. of vertices:");
    scanf("%d", &n);
    printf("\nEnter the adjacency matrix:\n");

    for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
            scanf("%d", &G[i][j]);

    printf("\nEnter the starting node:");
    scanf("%d", &u);
    dijkstra(G, n, u);

    return 0;
}
```

- **Purpose:** Reads input from the user and calls the `dijkstra` function to compute shortest paths.
- **Input:**
 - Number of vertices (`n`).
 - Adjacency matrix (`G`).
 - Starting node (`u`).
- **Output:** Calls `dijkstra` to print shortest paths and distances.

Dijkstra Function

C

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```
void dijkstra(int G[MAX][MAX], int n, int startnode) {
    int cost[MAX][MAX], distance[MAX], pred[MAX];
    int visited[MAX], count, mindistance, nextnode, i,
    j;

    // Create the cost matrix
    for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
            if (G[i][j] == 0)
                cost[i][j] = INFINITY;
            else
                cost[i][j] = G[i][j];

    // Initialize pred[], distance[] and visited[]
    for (i = 0; i < n; i++) {
        distance[i] = cost[startnode][i];
        pred[i] = startnode;
        visited[i] = 0;
    }

    distance[startnode] = 0;
    visited[startnode] = 1;
    count = 1;

    while (count < n - 1) {
        mindistance = INFINITY;

        // nextnode gives the node at minimum distance
        for (i = 0; i < n; i++)
```

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        if (distance[i] < mindistance &&
!visited[i]) {
            mindistance = distance[i];
            nextnode = i;
        }

        // Check if a better path exists through
nextnode
        visited[nextnode] = 1;
        for (i = 0; i < n; i++)
            if (!visited[i])
                if (mindistance + cost[nextnode][i] <
distance[i]) {
                    distance[i] = mindistance +
cost[nextnode][i];
                    pred[i] = nextnode;
                }
        count++;
    }

    // Print the path and distance of each node
    for (i = 0; i < n; i++)
        if (i != startnode) {
            printf("\nDistance of node%d=%d", i,
distance[i]);
            printf("\nPath=%d", i);

            j = i;
            do {
                j = pred[j];
                printf("<-%d", j);
            } while (j != startnode);
        }
    }
}

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        } while (j != startnode);
    }
}

```

- **Purpose:** Implements Dijkstra's algorithm to compute the shortest path from the starting node to all other nodes.
- **Input:**
 - Adjacency matrix (**G**).
 - Number of vertices (**n**).
 - Starting node (**startnode**).
- **Output:** Prints the shortest path and distance to each node from the starting node.
- **Process:**
 - **Cost Matrix Creation:** Converts the adjacency matrix to a cost matrix, where **INFINITY** represents no direct path.
 - **Initialization:** Initializes distance, predecessor, and visited arrays.
 - **Algorithm Execution:** Repeatedly selects the nearest unvisited node and updates distances.
 - **Output Results:** Prints the shortest path and distance to each node.