



Edge detection design project

02203 - Design of Digital Systems (Fall 2014)

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Abstract

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Chapter 1

Introduction

Husk at bygge 2 gange for at referencer og sidetal opdaterer ellers er resultatet
??

Chapter 2

Theory

2.1 HW

PUT some text

put some cite [1, p.11 eq.2.6], [2, p.11 eq.2.6]

2.2 MEM

Put some picture figure 2.1



Figure 2.1: A picture of Bagsværd Sø

A picture more figure 2.2 a reference to section 2.1

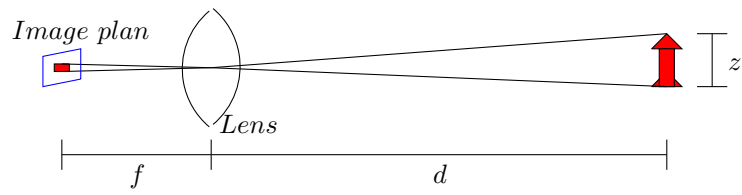


Figure 2.2: Some focal length stuff a tikz picture (we only like because of vector graphic)

Chapter 3

Results

In figure 3.1 the ASMD chart of the hardware accelerator of the Edge detector is seen.

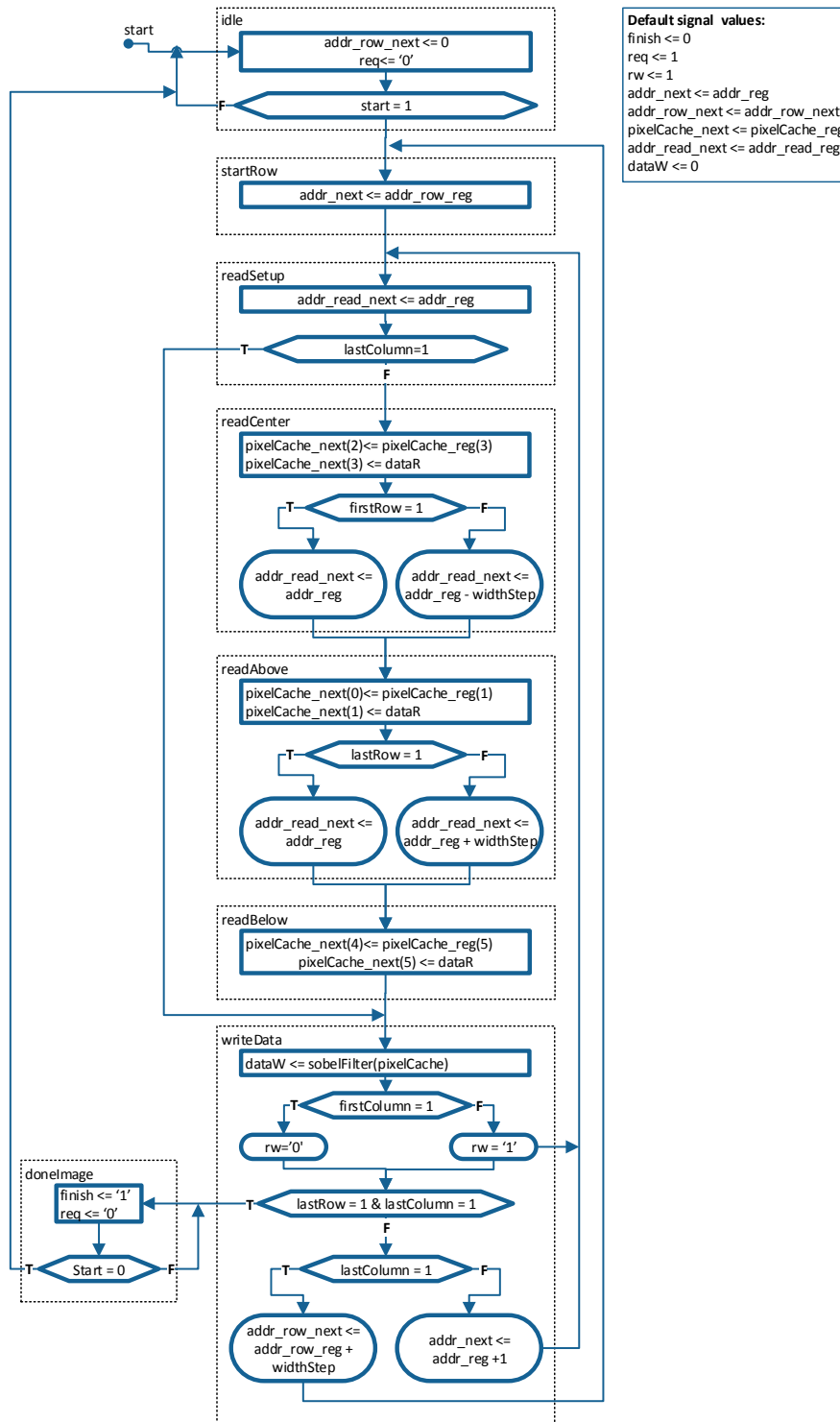


Figure 3.1: ASMD chart for the edge detector hardware accelerator

3.1 A

put some text

3.2 B

put some text

Chapter 4

Conclusion

put some text
And some more text
and some more text

Bibliography

- [1] Pong P. Chu *RTL HARDWARE DESIGN USING VHDL* 2006 Wiley
- [2] Jens Sparsø *Edge detector project description* 2014 Note

Appendix

A1 gcd.vhdl

```
1  ---
2  ---
3  --- Title      : Finite state machine and datapath of the GCD
4  ---           :
5  --- Developers : Anders Greve(s073188) and Nicolas Bøtkjær (s918819)
6  ---           :
7  --- Purpose    : This design is the FSM and Datapath of the Greatest
8  ---             Common Divisor
9  ---           :
10 --- Notes      : Implementation of Euclids GCD algorithm with
11 ---             repeated subtration.
12 ---           : Basic implementation without any optimization.
13 ---           :
14 --- Revision   : 02203 fall 2014 v.1
15 ---
16 library IEEE;
17 use IEEE.STD_LOGIC_1164.ALL;
18 use IEEE.NUMERIC_STD.ALL;
19
20 ENTITY gcd IS
21     PORT (clk:      IN std_logic;      -- The clock signal.
22           reset:    IN std_logic;      -- Reset the module.
23           req:       IN std_logic;      -- Start computation.
24           AB:        IN unsigned(7 downto 0); -- The two operands.
25           ack:       OUT std_logic;     -- Computation is
26                               complete.
27           C:         OUT unsigned(7 downto 0)); -- The result.
28 END gcd;
29
30 architecture FSM of gcd is
31     -- FSM States
```

```
31 type state_type is ( InputA, LoadA, RegAdone, InputB, LoadB, CmpAB,  
    UpdateA, UpdateB, DoneC );  
32 — Declare signals  
33 signal reg_a,next_reg_a,next_reg_b,reg_b : unsigned(7 downto 0);  
34 signal state, next_state : state_type;  
35  
36 begin  
37     — Combinatorial logic  
38     CL: process (req,AB,state,reg_a,reg_b,reset)  
39     begin  
40         next_reg_a <= reg_a;  
41         next_reg_b <= reg_b;  
42         ack <= '0';  
43         C <= (others =>'Z');  
44  
45         case (state) is  
46             When InputA =>  
47                 if req = '1' then  
48                     next_state <= LoadA;  
49                 else  
50                     next_state <= InputA;  
51                 end if;  
52  
53             When LoadA =>  
54                 next_state <= RegAdone;  
55                 next_reg_a <= AB;  
56  
57             When RegAdone =>  
58                 ack <= '1';  
59                 if req = '0' then  
60                     next_state <= InputB;  
61                 else  
62                     next_state <= RegAdone;  
63                 end if;  
64  
65             When InputB =>  
66                 if req = '1' then  
67                     next_state <= LoadB;  
68                 else  
69                     next_state <= InputB;  
70                 end if;  
71  
72             When LoadB=>  
73                 next_reg_b <= AB;  
74                 next_state <= CmpAB;  
75  
76             When CmpAB =>  
77                 if reg_a = reg_b then  
78                     next_state <= DoneC;
```

```
79         elsif reg_a > reg_b then
80             next_state <= UpdateA;
81         else
82             next_state <= UpdateB; -- A < B
83         end if;
84
85     When UpdateA =>
86         next_reg_a <= reg_a - reg_b;
87         next_state <= CmpAB;
88
89     When UpdateB =>
90         next_reg_b <= reg_b - reg_a;
91         next_state <= CmpAB;
92
93     When DoneC =>
94         C <= reg_a;
95         ack <= '1';
96         if req = '0' then
97             next_state <= InputA;
98         else
99             next_state <= DoneC;
100        end if;
101
102    end case;
103 end process CL;
104
105 -- Registers
106 seq: process (clk, reset)
107 begin
108     if reset = '1' then
109         state <= InputA; -- Reset to initial state
110     elsif rising_edge(clk) then
111         -- Update all registers
112         state <= next_state;
113         reg_a <= next_reg_a;
114         reg_b <= next_reg_b;
115     end if;
116 end process seq;
117
118 end fsmd;
```

A2.1 gcd_res_shr.vhdl

```
1  ---
2  ---
3  --- Title      : Finite state machine and datapath of the GCD
4  ---           :
5  --- Developers : Anders Greve(s073188) and Nicolas Bøtkjær (s918819)
6  ---           :
7  --- Purpose    : This design is the FSM and Datapath of the Greatest
8  ---             : Common Divisor
9  ---           :
9  --- Notes      : Implementation of Euclids GCD algorithm with
10 ---             : repeated subtraction.
10 ---            : Operator sharing is implementetd for both
11 ---             : subtraction
11 ---            : and multiplexing.
12 ---           :
13 --- Revision   : 02203 fall 2014 v.1
14 ---
15 ---
16
17 library IEEE;
18 use IEEE.STD_LOGIC_1164.ALL;
19 use IEEE.NUMERIC_STD.ALL;
20
21 ENTITY gcd IS
22     PORT (clk:      IN std_logic;      -- The clock signal.
23           reset:    IN std_logic;      -- Reset the module.
24           req:      IN std_logic;      -- Start computation.
25           AB:       IN unsigned(7 downto 0); -- The two operands.
26           ack:      OUT std_logic;     -- Computation is
27               complete.
27           C:        OUT unsigned(7 downto 0)); -- The result.
28 END gcd;
29
```



```
30 architecture FSMD_res_sharing of gcd is
31   -- FSMD States
32   type state_type is ( InputA, LoadA, RegAdone, InputB, LoadB, CmpAB,
       UpdateA, UpdateB, DoneC );
33   -- Declare signals
34   signal state, next_state : state_type;
35   signal reg_a, next_reg_a, next_reg_b, reg_b : unsigned(7 downto 0);
36   signal op1, op2, Y : signed(8 downto 0); -- One extra bit to hold
       the sign-bit.
37   signal C_int : unsigned (7 downto 0);
38   signal ABorALU : std_logic;
39
40   begin
41     -- Share the subtraction
42     Y <= op1 - op2;
43     -- Share the multiplexer (AB input or result from subtraction)
44     C_int <= unsigned(Y(7 downto 0)) when ABorALU = '0' else AB ;
45
46     -- Combinatorial logic
47     CL: process (req, AB, state, reg_a, reg_b, C_int, Y, reset)
48     begin
49       -- Default values.
50       C <= (others => 'Z');
51       ABorALU <= '0';
52       next_reg_a <= reg_a;
53       next_reg_b <= reg_b;
54       ack <= '0';
55       op1 <= signed('0' & std_logic_vector(reg_a));
56       op2 <= signed('0' & std_logic_vector(reg_b));
57
58       case (state) is
59
60         When InputA =>
61           if req = '1' then
62             next_state <= LoadA;
63           else
64             next_state <= InputA;
65           end if;
66
67         When LoadA =>
68           next_state <= RegAdone;
69           next_reg_a <= C_int;
70           ABorALU <= '1';
71
72         When RegAdone =>
73           ack <= '1';
74           if req = '0' then
75             next_state <= InputB;
76           else
```

```
77         next_state <= RegAdone;
78     end if;
79
80     When InputB =>
81         if req = '1' then
82             next_state <= LoadB;
83         else
84             next_state <= InputB;
85         end if;
86
87     When LoadB=>
88         next_state <= CmpAB;
89         next_reg_b <= C_int;
90         ABorALU <= '1';
91
92     When CmpAB =>
93         if Y(8) = '1' then -- If sign bit is set op2 > op1
94             next_state <= UpdateB;
95         elsif Y(7 downto 0) = 0 then
96             next_state <= DoneC;
97         else
98             next_state <= UpdateA;
99         end if;
100
101     When UpdateA =>
102         op1 <= signed('0' & std_logic_vector(reg_a));
103         op2 <= signed('0' & std_logic_vector(reg_b));
104         next_reg_a <= C_int;
105         next_state <= CmpAB;
106
107     When UpdateB =>
108         op1 <= signed('0' & std_logic_vector(reg_b));
109         op2 <= signed('0' & std_logic_vector(reg_a));
110         next_reg_b <= C_int;
111         next_state <= CmpAB;
112
113     When DoneC =>
114         ack <= '1';
115         C <= reg_a;
116         if req = '0' then
117             next_state <= InputA;
118         else
119             next_state <= DoneC;
120         end if;
121
122     end case;
123 end process CL;
124
125 -- Registers
```

```
126     seq: process (clk, reset)
127     begin
128         if reset = '1' then
129             state <= InputA;           -- Reset to initial state
130         elsif rising_edge(clk) then
131             state <= next_state;
132             reg_a <= next_reg_a;
133             reg_b <= next_reg_b;
134         end if;
135     end process seq;
136
137 end FSMD_res_sharing;
```