An introduction to numerical methods using BLAS

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Overview

- What are numerical libraries and how to use them?
- Functionality and uses of BLAS
- How computer architecture (caches) affect implementation of computations

Not all evaluations are the same!

Consider a simple matrix multiplication

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}. \tag{1}$$

Can be evaluated in 2 ways, with a dot product or a scalar-matrix product:

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \begin{pmatrix} 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ \begin{pmatrix} 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} \end{pmatrix}, \qquad \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} + 2 \begin{pmatrix} 2 \\ 4 \end{pmatrix}.$$

Software libraries

- BLAS is a typical software library
- Libraries can be used in 2 forms:
 - Static
 - Dynamic

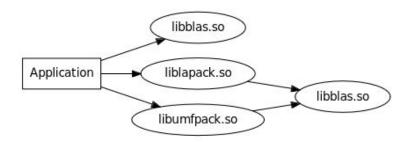
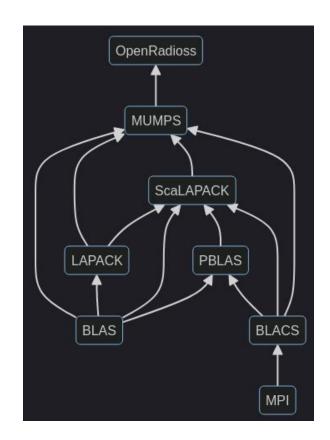
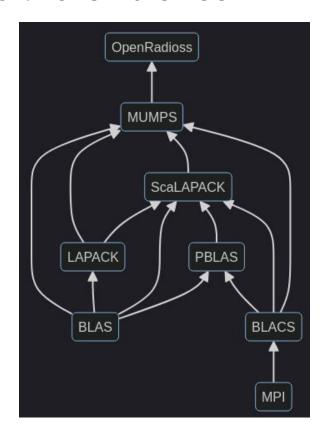
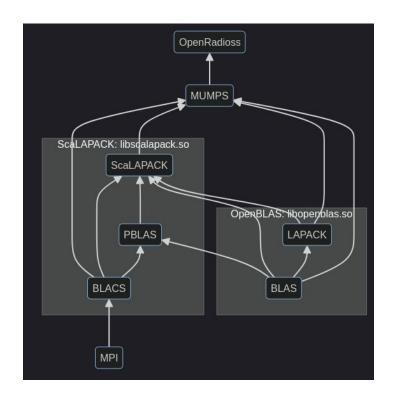


Figure 1: Shared library dependencies of an example application.



Software libraries





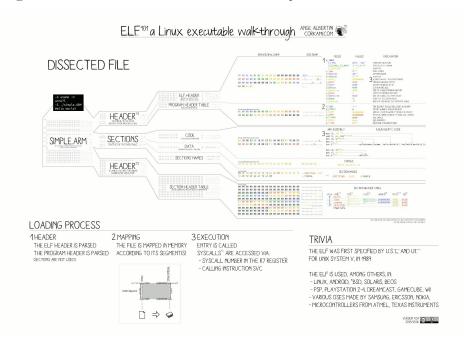
Practical session

Compile and install:

- BLAS: https://gitlab.com/greeklug/lapack/-/tree/greeklug-presentation
- Matrix-Market I/O library:
 https://gitlab.com/greeklug/matrix market exchange formats

Tools for inspecting libraries and executables

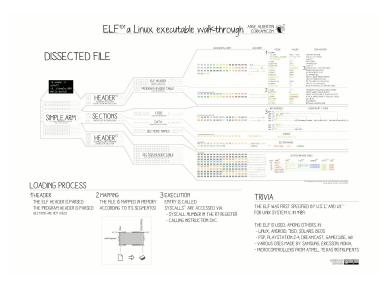
Does this `libopeblas.so` instance implement the CBLAS interface?



Tools for inspecting libraries and executables

To investigate the shared object:

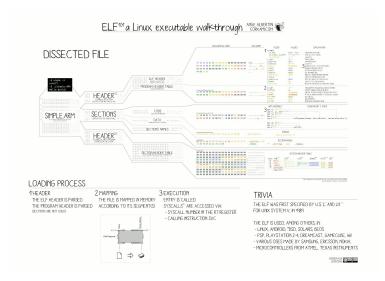
- readelf: display information about ELF files
 - --all: all sections
 - --file-header: information about interoperability
 - --dynamic: dynamically linked libraries and other information
- objdump: display information about objects
 - --syms: information for symbols (functions and variables)
 - --demangle: restore human readable names for objects generated from C++
- nm: list symbols
 - --dynamic: list only export symbols (only for dynamic libraries)



Tools for inspecting libraries and executables

Even extract information about function signatures (needs debug info, -g):

- Read debug info with readelf
 - O --debug-dump=info
- Partially disassemble with objdump
 - o --disassemble
 - o --disassemble-all



Practical session

- Compile the tutorial example code: https://gitlab.com/greeklug/blas-tutorial
- Call some function Matrix Market I/O
- Can you break the linking? Try removing the linker option: --no-as-needed

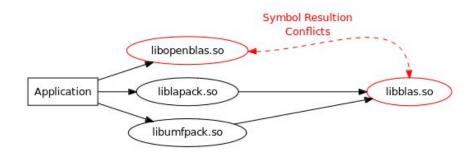


Figure 2: Wrong symbol resolution after relinking the example application.

Data representation

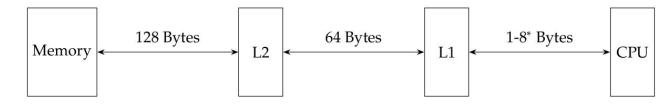
- Computer memory is linear
- Matrices are linearized:

$$\left(\begin{array}{ccc} 1 & 3 & 5 \\ 2 & 4 & 6 \end{array}\right) \longrightarrow 1 2 3 4 5 6$$

```
typedef struct _dense_matrix {
   /* Data structure storing matrix A */
   double* a; // Pointer to the C array with the entries of A
   int m; // Number of rows in A
   int n; // Number of columns in A
} dense_matrix;
```

- Direct linearization is not sufficient for good performance!
- Caches affect the speed of memory access

```
for ( int i = 0; i < n; ++i ) {
  a[i] = 0;
}</pre>
```



*up to 64 for some special SIMD instructions sets such as AVX-512

- Direct linearization is not sufficient for good performance!
- Caches affect the speed of memory access

```
for ( int i = 0; i < n; ++i )
{
    a[i] = 0;
}</pre>
Non-vectorizable:
```

- Direct linearization is not sufficient for good performance!
- Caches affect the speed of memory access

```
#pragma omp simd aligned(a:32)
for ( int i = 0; i < 4*n; i+=1 ) {
    a[i] = 0;
}</pre>
Non-vectorizable:
```

- Direct linearization is not sufficient for good performance!
- Caches affect the speed of memory access

```
for ( int i = 0; i < n; i+=1 ) {
    a[4*i] = 0;
    a[4*i+1] = 0;
    a[4*i+2] = 0;
    a[4*i+3] = 0;
```

Not all evaluations are the same!

Revisiting the simple matrix-vector product:

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}. \tag{1}$$

The dot product evaluation jumps across cache lines!

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \begin{pmatrix} 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ \begin{pmatrix} 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} \end{pmatrix}, \qquad \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} + 2 \begin{pmatrix} 2 \\ 4 \end{pmatrix}.$$

- Direct linearization is not sufficient for good performance!
- Caches affect the speed of memory access

```
typedef struct _dense_matrix {
   /* Data structure storing matrix A */
   double* a; // Pointer to the C array with the entries of A
   int m; // Number of rows in A
   int n; // Number of columns in A
   int nzmax; // Maximum number of entries that can be stored in array a
   int lda; // Leading dimension of the array A
} dense_matrix;
```

Practical session

- Call some function (DGEMV) of BLAS
- Try the code with aligned memory allocation!

- Operations organized by computational complexity
 - Level 1: O(n)
 - Level 2: O(n^2)
 - Level 3: O(n^3)
- BLAS supports various number types and numerical precision (first part of function names):
 - single precision (S) with 32-bits,
 - double precision (**D**) with 64-bits,
 - single precision complex (C) with 64-bits, and
 - double precision complex (**Z**) with 128-bits.

 Matrix properties are exploited to save space and reduce memory accesses:

GE:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} a_{32} a_{13} a_{23} a_{33}$$

SY:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} * a_{13} * *$$

TR:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} * a_{13} * *$$

SP:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} a_{13}$$

TP:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} a_{13}$$

TP:
$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{pmatrix} \longrightarrow a_{11} a_{21} a_{31} a_{12} a_{22} a_{13}$$

- Matrix properties are exploited to save space and reduce memory accesses.
- This forms the second part of the name:

	Storage type		
Algebraic properties	Standard (-)	Banded (B)	Packed (P)
General (G)	GE	GB	
Symmetric (S)	SY	SB	SP
Hermitian (H)	HE	HB	HP
Triangular (T)	TR	TB	TP

- Last part is the type of the operants:
 - V: vector
 - M: matrix
- For instance:

DGEMV:

- D: double precision
- GE: general matrix
- o MV: matrix-vector multiplication

DGEMM:

- o D: double precision
- GE: general matrix
- MM: matrix-matrix multiplication
- The convention does not work always, especially for Level 1 operations
 - DAXPY: y ← ax+y

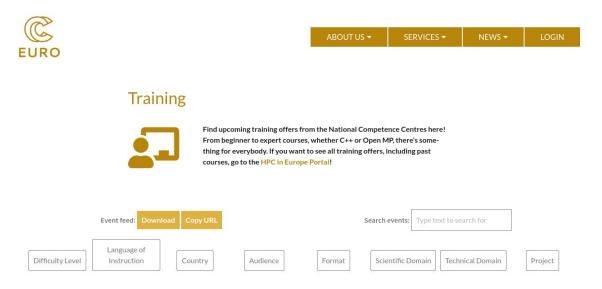
Course notes and resources

Will appear in the tutorial directory: https://gitlab.com/greeklug/blas-tutorial

Official BLAS webpage: https://www.netlib.org/blas/

- Quick reference (function list): https://www.netlib.org/blas/
- Reference BLAS implementation:
 https://www.netlib.org/lapack/explore-html/d1/df9/group blas.html

Seminar on numerical methods coming soon in EurroCC: https://www.eurocc-access.eu/services/training/

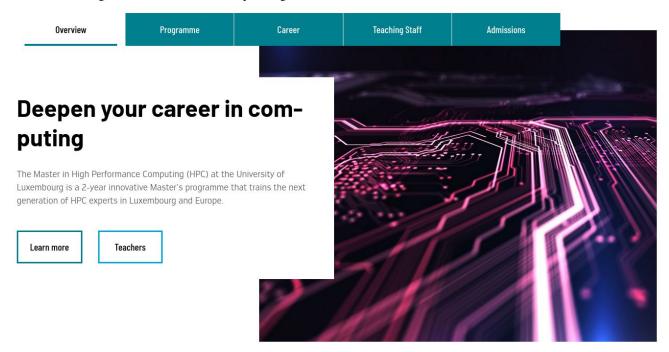






Thank you!

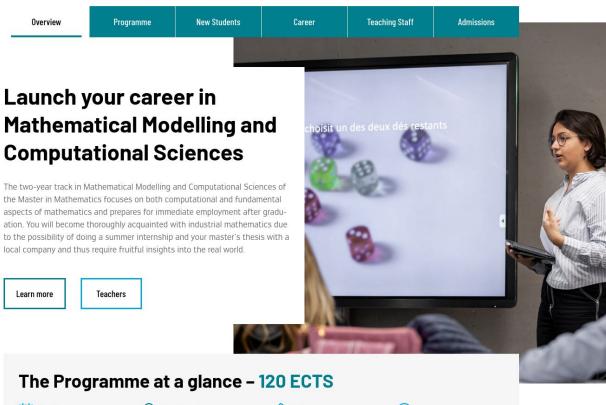
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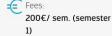






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- Master in High Performance Computing: https://www.uni.lu/fstm-en/study-programs/master-in-high-performance-computing/
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