

PSO Optimization System for COPs

Development a PSO optimization system for continuous optimization problems (COPs). Conduct necessary system requirement analysis before implementing your system, to figure out the requirements of data structured and user interfaces for solving COP benchmarks. You are given a library (.dll) and a set of COP benchmarks to import a formatted COP to your code. The class lab will instruct you the use of the library to take advantages of accessing a COP benchmark. Notice that C# code snippet is specified in the formatted file to define the objective function. The library provides run-time C# compiling capability to generate a dynamic dll file., The compiled dll interacts with your application by providing the objective evaluation function of the problem.

The system should have basic yet friendly user interfaces for benchmark problem selections, PSO parameter settings, and stopping condition settings, etc. It is very helpful for knowing the solutions evolution of a 2D COP, which can be visualized in a 3D objective surface.

Continuous Optimization Problems:

CALab collects near half a hundred of real number optimization benchmarks. They are expressed in RTF files and .cop files. A general format of the optimization problem is the following:

n : dimension

A possible PSO or GA real number encoding:

$\mathbf{x} = [x_0 x_1 \cdots x_{n-1}]; l_i \leq x_i \leq u_i; i = 0, 1, \dots, n-1$

x_i : the real value of the i th component

l_i : the lower bound of x_i

u_i : the upper bound of $x_i, l_i \leq u_i, \forall i$

$\min f(\mathbf{x})$

Example:

Peak.rtf

Title: Peak function

Source: MATLAB peak.m

Problem:

$$\min f(x, y) = 3(1-x)^2 e^{-x^2-(y+1)^2} - 10\left(\frac{x}{5} - x^3 - y^5\right) e^{-x^2-y^2} - \frac{1}{3} e^{-(x+1)^2-y^2}$$

s.t.

$$-4 \leq x, y \leq 4$$

$$\nabla f = \begin{bmatrix} (-6+12x^2-6x^3)e^{-x^2-(y+1)^2} + (-2+34x^2-20x^4-20xy^5)e^{-x^2-y^2} + \frac{2}{3}(x+1)e^{-(x+1)^2-y^2} \\ -6(1+y)(1-x)^2 e^{-x^2-(y+1)^2} + (4xy-20x^3y+50y^4-20y^6)e^{-x^2-y^2} + \frac{2}{3}ye^{-(x+1)^2-y^2} \end{bmatrix}$$

Optimal Value: -6.5511

Optimal Solution(s): $(x, y) = (0.2283, -1.6255)$

Peak.cop

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Title: Peak (2)
Type: Minimization
Dimension: 2
LowerBoundsUpperBounds: Enumerate
-4 4
-4 4
NumberOfOptimalSolution: 1
0.2283 -1.6255
BestObjectiveValue: -6.5511
NumberOfLinkedAssemblies: 0
CodingLanguage: CSharp
GlobalDefinition:

InitiationFunction:

ObjectiveFunction:
double x2 = x[0] * x[0];
double yp12 = x[1] + 1;
yp12 = yp12 * yp12;
double xp12 = x[0] + 1;
xp12 = xp12 * xp12;

double x3 = x[0] * x2;
double y2 = x[1] * x[1];

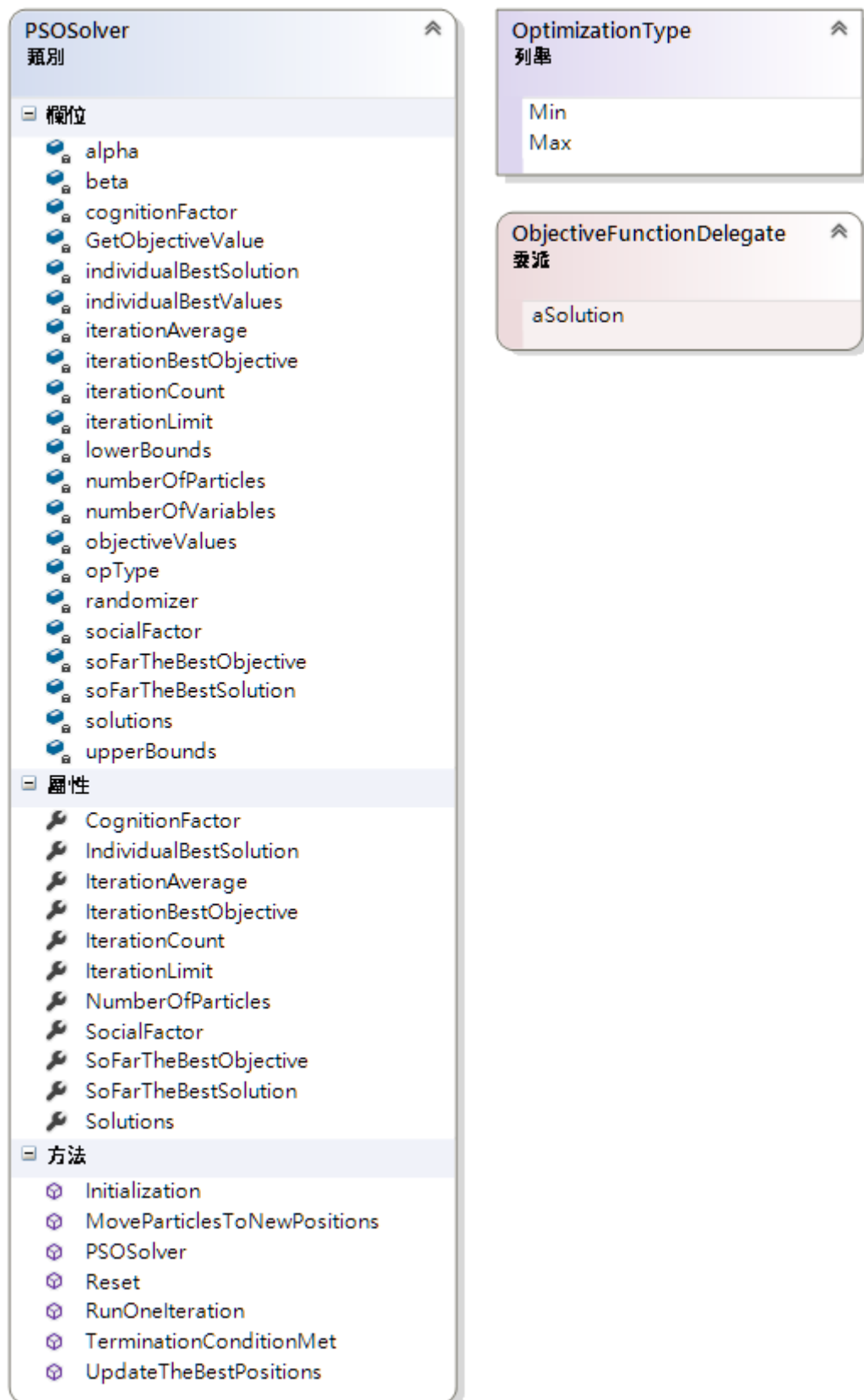
double y5 = y2 * y2 * x[1];

objective = 3 * ( 1 - x[0] ) * ( 1-x[0]) * Math.Exp( -x2 -
yp12) - 10 * ( x[0] * 0.2 -x3-y5) * Math.Exp( -x2-y2) -
Math.Exp( -xp12 - y2 ) / 3.0;

GradientFunction:
double xp1 = x[0] + 1;
double yp1 = x[1] + 1;
double x2 = x[0] * x[0];
double y2 = x[1] * x[1];

double t1 = Math.Exp( -x2 -yp1*yp1);
double t2 = Math.Exp( -x2 -y2 );
double t3 = Math.Exp( -xp1 * xp1 -y2 );

g[0] = -6 * t1 * ( x2 * x[0] - x2 - x2 + 1 ) + t2 * ( -2 + 34 *
x2 - 20 * x2 * x2 - 20 * x[0] * y2 * y2 * x[1]) + t3 * 2 *
xp1 / 3.0;
g[1] = -6 * t1 * ( 1-x[0] ) * ( 1-x[0]) * yp1 + t2 * ( 4.0 *
x[0] * x[1] - 20 * x2 * x[0] * x[1] - 20 * y2 * y2 * y2+ 50
* y2 * y2 ) + t3 * 2 * x[1] / 3.0;
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Sample Class Design of PSOSolver