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1 Basic

1.1 vimrc

```
set nocompatible
set t_Co=256
set nu
set ai
set tabstop=4
set shiftwidth=4
set softtabstop=4
colorscheme torte
syntax on
filetype plugin indent on
```

1.2 default

```
#include < bits / stdc++.h>
4
   using namespace std;
   #define FI freopen("in.txt", "r", stdin)
#define FO freopen("out.txt", "w", stdout)
   #define IOS ios_base::sync_with_stdio(0); cin.tie(0)
   #define pb push_back
   #define mp make_pair
   #define ff first
   #define ss second
   typedef long long LL;
   const int MOD = 1000000007;
   const double PI = acos(-1.0);
   int dx[] = \{-1,0,1,0\};
   int dy[] = \{0,1,0,-1\};
   int main(){
        IOS; // 測 試 中 文
        return 0;
```

2 Data Structure

2.1 Disjoint Set

```
struct DisjointSet{
   int p[N];
   void init(int n){for(int i=1;i<=n;i++)p[i] = i;}
   int Find(int x){return x == p[x] ? x : p[x] = Find(
        p[x]); }
   void Union(int x,int y){p[Find(x)] = Find(y);}
};</pre>
```

2.2 Segment Tree

```
struct Node{
   int value;
   Node *lc,*rc;
   Node(){value = 0; lc = rc = NULL;}
   void pull(){
      value = lc->value+rc->value;
   }
};
int v[N];
Node* build(int L, int R){
   Node * node = new Node();
   if(L == R){
      node->value = v[L];
      return node;
   }
   int mid = (L+R)>>1;
   node->lc = build(L,mid);
```

```
node->rc = build(mid+1,R);
     node->pull();
     return node;
void modify(Node *node, int L, int R, int i, int d){
     if(L = R)
          node->value += d;
          return;
     int mid = (L+R) >> 1;
     if (i<=mid) modify (node->lc, L, mid, i, d);
     else modify(node->rc, mid+1,R, i, d);
     node->pull();
int query(Node* node,int L,int R,int ql,int qr){
     if(ql > R \mid \mid qr < L)return 0;
     \label{eq:local_relation}  \mbox{if} (\, \mbox{ql} <= \, L \, \&\& \, R <= \, \mbox{qr}) \, \mbox{return node->value} \, ; 
     int mid = (L+R) >> 1;
     return query (node->lc, L, mid, ql, qr)+query (node->rc,
         mid+1,R,ql,qr);
```

2.3 Treap

```
struct Treap {
    int key, pri , val ,sz , lazy;
    Treap *1, *r;
    Treap(int _key, int _val): key(_key) , val(_val)
        pri(rand()), sz(1), lazy(0), l(NULL), r(NULL){
inline int Size (Treap* t)
{
    return t?t->sz:0;
inline void Pull(Treap* t)
{
    t->sz = Size(t->1) + Size(t->r) + 1;
void Push(Treap* t)
{
    t->val += t->lazy;
    if (t->l)t->l->lazy += t->lazy;
    if (t->r)t->r->lazy += t->lazy;
    t \rightarrow lazy = 0;
Treap* Merge(Treap* a, Treap* b)
    if (!a || !b) return a ? a : b;
    if (a->pri > b->pri) {
        a->r = Merge(a->r, b); Pull(a); return a;
     else {
        b->l = Merge(a, b->r); Pull(b); return b;
void Split (Treap* t, int k, Treap*& a, Treap*& b)
    if (!t) a = b = NULL;
      if (t->key <= k) {
            a = t; Split(t->r, k, a->r, b); Pull(a);
          else {
            b = t; Split(t->l, k, a, b->l); Pull(b);
    }
}
Treap* Del(Treap* t, int k) //delete all key=k
    if (t->key == k) {return Merge(t->l, t->r);
    else if (k < t->key) { t->l = Del(t->l, k);}
        return t;
      else { t->r = Del(t->r, k); return t;
Treap* insert (Treap* t, int key, int val)
{
    Treap *tl, *tr;
    Split(t, key, tl, tr);
    Treap tmp(key, val);
Treap *ans = &tmp;
```

```
3 Graph
```

return ans;

Merge(ans, tl); Merge(ans, tr);

3.1 BCC

```
int adj[9][9];
int visit [9], low [9], t = 0;
int stack[9], top = 0;
int contract[9];
void DFS(int i, int p)
{
     \label{eq:visit} visit [\,i\,] \,=\, low\,[\,i\,] \,=\, +\!\!\!+\!\!\!t\,;
     \operatorname{stack}[\operatorname{top}++] = i; // push i
     for (int j=0; j<9; ++j)
          if (adj[i][j]){
               if (!visit[j]) DFS(j, i);
                                                                 //
                     tree edge
                if \ (!(j =\!\!\!\!\!\!- p \;\&\&\; adj[\,i\,][\,j\,] =\!\!\!\!\!\!- 1))
                                   // tree edge + back edge
                     low[i] = min(low[i], low[j]);
     if (visit[i] == low[i])
                                        // 形成BCC i 點會是BCCE
           面, 最早拜訪的點。
          int j;
          do {
               j = \operatorname{stack}[--\operatorname{top}];
                                         // pop j
               contract[j] = i;
          } while (i != j);
     }
}
void tarjan()
     memset(visit, 0, sizeof(visit));
     t = 0;
     for (int i=0; i<9; ++i)
          if (! visit[i])
               DFS(i, i);
}
```

3.2 SCC

```
vector<int> e[10000]; int visit[10000], low[10000]; bool
     instack[10000]; int belong[10000]; stack<int> s;
int \ t;; int \ num; \ //number \ of \ SCC
void DFS(int u)
{
     visit[u] = low[u] = ++t; //進行標號
     s.push(u); instack[u] = true;
     for (int i = 0; i < e[i].size(); i++) {
          int v = e[u][i];
          if (!visit[v])
              DFS(v)\,;\,\,low\,[\,u\,]\,=\,min(\,low\,[\,u\,]\,,\,\,low\,[\,v\,]\,)\,;\,\,\,//\,\,\,\sharp
                     u 的最上層祖先
          if (instack[v]) low[u] = min(low[u], visit[v]);
                //還在stack中 用 visit的值
     if (visit[u] = low[u]) {//SCC}
         num++; int v = s.top(); s.pop();
          {\tt instack}\,[\,v\,] \;=\; {\tt false}\,; {\tt belong}\,[\,v\,] \;=\; {\tt num};
          while (v != u) {
               v = s.top(); s.pop();
              belong\left[\,v\,\right] \;=\; num;\;\; instack\left[\,v\,\right] \;=\; false\,;
     }
int Tarjan(int n) //n:number of vertex 0-based
     t = 0, num = 0;
```

```
memset(visit, 0, sizeof(visit));
for (int i = 0; i < n; i++) e[i].clear();
for (int i = 0; i < n; i++)
    if (!visit[i]) DFS(i);
return num;
}</pre>
```

3.3 SPFA

```
struct Edge {
                 int v, cost;
                Edge(int \_v=0, int \_cost=0) : v(\_v), cost(\_cost)\{\}
};
vector<Edge> E[MAXN]; //MAXN:num of point
bool visited [MAXN]; int cnt [MAXN]; int dist [MAXN];
bool SPFA(int start , int n)
{
                memset(\,visited\,\,,0\,\,,\, \verb+sizeof(\,visited)\,)\,;
                 \begin{tabular}{ll} & \begin{tabular}{ll} 
                 visited [start]=true, dist[start]=0;
                queue<int> que;
                 while (!que.empty()) que.pop();
                que.push(start); cnt[start]=1;
                 while (!que.empty()) {
                                int u=que.front();
                                que.pop();
                                  visited [u]=false;
                                  for (int i=0; i < E[u]. size(); i++){
                                                  int v=E[u][i].v;
                                                   if(dist[u]!=INT\_MAX \&\& dist[v]>dist[u]+E[u]
                                                                    ][i].cost){
                                                                   dist[v]=dist[u]+E[u][i].cost;
                                                                   if (! visited [v]) {
                                                                                   {\tt visited} \; [\, v] {=} \, {\tt true} \, ;
                                                                                   que.push(v);
                                                                                    if(++cnt[v]>n) return false; //有負
                                                                  }
                                                 }
                                }
                 return true; //正常
```

3.4 Prim

```
const int MAXN=110;bool vis[MAXN];int lowc[MAXN];
int Prim(int cost[][MAXN], int n) //0-based
     int ans=0; memset(vis,0, sizeof(vis)); vis[0]=false;
     for (int i=1; i < n; i++)lowc[i] = cost[0][i];
     for (int i=1; i< n; i++){}
         int minc=NT MAX;
         int p=-1;
         for (int j=0; j< n; j++){
             if (!vis[j] && minc>lowc[j]) {
                  minc=lowc[j];
                  р=j ;
         if (minc=NT_MAX) return -1; //failed
         ans\!\!+\!\!=\!\!minc\,;
         vis[p]=true;
         for (int j=0; j< n; j++)
              if(!vis[j] && lowc[j]>cost[p][j])
                  lowc[j] = cost[p][j];
     return ans;
}
```

3.5 Dijkstra

```
 \begin{array}{lll} & \operatorname{int}^* \operatorname{Dijkstra}(\operatorname{vector} <\! \operatorname{VPII}\! > E, \operatorname{int}\ \operatorname{N}, \operatorname{int}\ \operatorname{S}) \{ \\ & \operatorname{bool}\ ^*\operatorname{visit} = \operatorname{new}\ \operatorname{bool}\left[\operatorname{N}+1\right]; \operatorname{for}\left(\operatorname{int}\ i=1; i <\! =\! \operatorname{N}; i+\! +\! \right) \\ & \operatorname{visit}\left[i\right] = \operatorname{false}; \\ & \operatorname{int}\ ^*\operatorname{D} = \operatorname{new}\ \operatorname{int}\left[\operatorname{N}+1\right]; \operatorname{for}\left(\operatorname{int}\ i=1; i <\! =\! \operatorname{N}; i+\! +\! \right) \operatorname{D}\left[i\right] = \operatorname{INF}; \\ \end{array}
```

```
priority_queue<PII, VPII, greater<PII>>> P;
P.push(MP(0,S));D[S]=0;
while(!P.empty()){
    int weight=P.top().ff,now=P.top().ss;P.pop();
    if(visit[now]) continue;
    visit [now]=true;
    for(auto i:E[now]){
        int potential=D[now]+i.ff;
        if(!visit[i.ss] && potential < D[i.ss]){
            P.push(MP(D[i.ss]=potential,i.ss));
        }
    }
}
return D;
</pre>
```

3.6 Bipartite Match

```
vector<int> g[10000]; bool check[10000]; int match
     [10000]; int num_left, num_right;
void init(int n)
{
     num\_left \, = \, num\_right \, = \, 0;
     for (int i = 0; i < n; i++)g[i].clear();}
bool DFS(int u)
     for (int i = 0; i < g[u].size(); i++) {
          \  \  \, int \  \, v \, = \, g\,[\,u\,]\,[\,\,i\,\,]\,;
          if (!check[v]) {
               check[v] = true;
                match[v] = u; match[u] = v; return true;
          }
     return false;
int Hungarian_DFS() //匈牙利算法
     int ans = 0;memset(match, -1, sizeof(match));
     for (int i = 0; i < num_left; i++) {//只要對二分圖
           的一邊即可
          memset(check, 0, sizeof(check));
          if (DFS(i)) ans++;
     return ans;
int Hungarian_BFS()
     _{\text{int prev}[10000]; \text{ int } ans=0;}
     memset(match, -1, sizeof(match));
     for (int i = 0; i < num_left; i++) {
          memset(check, 0, sizeof(check));
          if (match[i] == -1) {
               \label{eq:queue} queue < \hspace{-0.1cm} \begin{array}{ll} int > q; \hspace{0.1cm} q.\hspace{0.1cm} push \hspace{-0.1cm} (\hspace{0.1cm} i\hspace{0.1cm}) \hspace{0.1cm} ; \hspace{0.5cm} prev \hspace{-0.1cm} [\hspace{0.1cm} i\hspace{0.1cm}] \hspace{0.1cm} = \hspace{0.1cm} -1; \end{array}
                     bool flag = false;
                while (!q.empty() && !flag) {
                     int u = q.front(); q.pop();
                     for (int j = 0; j < g[u].size() && !
                          flag; j++) {
                          int v = g[u][j];
                          if (!check[v]) { check[v] = true;
    if (match[v] != -1) {
                                    q.push(match[v]); prev[
                                          \mathrm{match}\,[\,v\,]\,]\ =\ u\,;
                               } else {
                                    flag = true; int d = u, e =
                                     while (d != -1) {
                                          int t = match[d]; match
                                               [d] = e; match[e] =
                                                d;
                                          d = prev[d]; e = t;
                                    }
                               }
                          }
                     }
                if (match[i] != -1) ans++;
          }
```

```
return ans;
```

4 Stringology

4.1 KMP

```
int* predo(string pattern){
    \label{eq:int*} int* \ dp = new \ int[pattern.size()];
    dp[0] = 0;
    for(int i=1;i<pattern.size();i++){</pre>
        dp[i] = dp[i-1];
        while(dp[i] > 0 && pattern[dp[i]] != pattern[i
])dp[i] = dp[dp[i]-1];
         if(pattern[dp[i]] = pattern[i])dp[i]++;
    return dp;
}
void KMP(string text, string pattern){
    int* dp = predo(pattern);
    for(int i=0,match=0;i< text.size();i++){}
         while (match > 0 && pattern [match] != text[i])
             match = dp[match-1];
         if(pattern[match] == text[i]) match++;
         if (match == pattern.size()){
             cout \ll i - pattern.size()+1 \ll endl;
             match = dp[match-1];
    delete [] dp;
```

$4.2 \quad \mathbf{Z}$

```
void ZAlgorithm(string word, string pattern) {
    int Z[word.size()+pattern.size()];
    string S = pattern+word;
    Z[0] = 0;
    for(int i=1,best=0;i<S.size();i++) {
        if(best+Z[best] <= i)Z[i] = 0;
        else Z[i] = min(Z[i-best],best+Z[best]-i);
        while(S[i+Z[i]] = S[Z[i]])Z[i]++;
        if(i+Z[i] > best+Z[best]) best = i;
    }
    for(int i=pattern.size();i<S.size();i++) {
        if(Z[i] >= pattern.size())cout << i-pattern.size() << " ";
    }
}</pre>
```

4.3 Trie

```
const int MAXCHAR = 10;
const char CHAR = '0';
struct Node{
    Node* child [MAXCHAR];
    int N;
    Node():N(0)\{for(int i=0;i \le MAXCHAR;i++)child[i] =
        NULL; }
Node^* root = new Node;
void word(string s){
    Node^* now = root;
    for (int i=0; i < s. size(); i++){
         int c = s[i] - CHAR;
         if(now->child[c] == NULL(now->child[c] = new
             Node:
        now = now - > child[c];
    now->N++;
}
```

4.4 AC automaton

```
const int MAXCHAR = 26;
const char CHAR = 'a';
struct Node{
    Node*\ child\ [M\!A\!X\!C\!H\!A\!R]\,;
    Node* fail;
    int N;
    Node():N(-1), fail (NULL) { for (int i=0; i < MAXCHAR; i++)
          child[i] = NULL;
};
struct AC{
    Node* root;
    AC()\{root = new Node;\}
     void word(string s, int index){
         Node*\ now\ =\ root\ ;
         \begin{array}{ll} \mbox{for(int} & i\!=\!0; i\!<\!s.\,size(); i\!+\!+\!)\{\\ & \mbox{int} & c = s[\,i\,] & - \mbox{CHAR}; \end{array}
               if(now->child[c] == NULL(now->child[c] =
                   new Node;
              now = now - > child[c];
         if (now->N = -1)now->N = index;
     void predo(){
         root->fail = NULL;
Node* p;
         queue<Node*> Q;
         Q. push (root);
         while (!Q. empty()) {
              Node^* now = Q. front(); Q. pop();
               for (int i=0; i \le MAXCHAR; i++){
                   if (!now->child[i]) continue;
                   Q. push(now-> child[i]);
                   p = now -> fail;
                   while (p != NULL && p->child [i] == NULL)
                        p\,=\,p\text{-}\!>\!f\,a\,i\,l\;;
                    if (p == NULL)now->child[i]->fail = root
                   else now-> child[i]-> fail = p-> child[i];
              }
         }
     void match(string text){
         Node* now = root;
         for (int i=0; i < text. size(); i++){
              int c = text[i] - CHAR;
               while (now != root && now->child [c] == NULL)
                   now = now -> fail;
               if(now->child[c])now = now->child[c];
               if(now->N != -1)cout << "Got you" << endl;
     void release(Node* now = root){
         for (int i=0; i \leq MAXCHAR; i++)if (now-> child [i])
               release (now->child[i]);
         delete now;
```

4.5 Suffix Array

```
for(int i=N-1; i>=0;i--)SA[--radix[text[i]]] = i;
    for(int power=1;power<N;power<<=1){</pre>
         for (int i=0; i< A; i++)radix [i] = 0;
         for(int i=0;i<N;i++)radix[rank[i]]++;
         for (int i=0; i<A; i++) radix [i] += radix [i-1];
         int now = 0;
         for (int i=N-power; i < N; i++)SA2[now++] = i;
         for (int i=0; i< N; i++){
             if(SA[i] - power >= 0)SA2[now++] = SA[i] -
                  power;
         for (int i=N-1; i>=0;i--)SA[--radix[rank[SA2[i
              ]]]] = SA2[i];
         rank2[SA[0]] = now = 0;
         for (int i=1; i < N; i++){}
             if (!(rank[SA[i-1]] == rank[SA[i]] && SA[i
                  -1]+power < N && SA[i]+power < N &&
                  rank [SA[i-1]+power] = rank [SA[i]+power
                  ]))now++;
             rank2[SA[i]] = now;
         swap(rank, rank2);
         if (now = N-1) break;
         A = \text{now} + 1;
    for (int i=0; i \le N; i++) rank [SA[i]] = i;
    for (int i=0,k=0; i< N; i++,k?k--:0) {
         if(rank[i] == 0){H[rank[i]] = 0; continue;}
         int j = SA[rank[i]-1];
         while (i+k < N \&\& j+k < N \&\& text[i+k] = text[j]
             +k])k++;
         H[rank[i]] = k;
}
```

5 Geometry

5.1 Point

```
int dcmp(double x)
     if (fabs(x) < EPS)
         return 0;
     else
         return x < 0 ? -1 : 1;
struct Point {
    \begin{array}{l} \text{double } x, \ y; \\ \text{Point()} \ \{ \ x = 0, \ y = 0; \ \} \end{array}
    Point(double _x, double _y)
    {
         x = \underline{x};
         y = \underline{y};
     Point operator+(const Point& b)
         return Point(x + b.x, y + b.y);
     Point operator - (const Point& b) const
          return Point(x - b.x, y - b.y);
     Point operator*(double p)
         return Point(x * p, y * p);
     Point operator/(double p)
         return Point(x / p, y / p);
     bool operator < (const Point& b)
     {
          return x < b.x || (x == b.x \&\& y < b.y);
```

```
bool operator==(const Point& b)
        return dcmp(x - b.x) == 0 \&\& dcmp(y - b.y) ==
};
typedef Point Vector;
double dot(Vector v1, Vector v2)
    return v1.x * v2.x + v1.y * v2.y;
double cross (Point& o, Point& a, Point& b) //OA X OB
{
    return (a.x - o.x) * (b.y - o.y) - (a.y - o.y) * (b
        .x - o.x);
double cross (Vector a, Vector b)
    return a.x * b.y - a.y * b.x;
double length (Vector v)
    return sqrt(v.x * v.x + v.y * v.y); //return sqrt(
        dot(v,v));
\begin{tabular}{lll} \bf double & angle(const \ Vector\& \ a, \ const \ Vector\& \ b)\{return \end{tabular}
    acos(dot(a, b) / length(a) / length(b));}
double Triarea (const Point pl, const Point p2, const
    Point& p3){
return fabs(cross(p2 - p1, p3 - p1)) / 2;
Vector Rotate(const Vector& a, double rad) //radian 0~2
    pi //counterclockwise{
    return Vector(a.x * cos(rad) - a.y * sin(rad), a.x
        * sin(rad) + a.y * cos(rad)); //旋轉矩陣
Vector Normal(const Vector& a) { // 向量的單位法臣
    double L = length(a);
    return Vector(-a.y / L, a.x / L);
struct Line {
   Point p1, p2;
typedef Line Segment;
Point GetLineIntersection(Point p, Vector v, Point q,
    Vector w) //點斜式交點 p+vt1 q+wt2
    Vector u = p - q;
    double t = cross(w, u) / cross(v, w); //t1
    Point GetLineProjection (Point p, Point a, Point b)
    Vector v = b - a;
    typedef Line Segment;
bool Onsegment(Point p, Point a1, Point a2) //點在匠上
                               //端點在兩側
    //平行
    return \ dcmp(cross(a1 - p, a2 - p)) == 0 \&\& dcmp(dot
        (a1 - p, a2 - p)) < 0;
bool SegmentProperIntersection(Point a1, Point a2,
    Point b1, Point b2)
    // 規範相交 :交點不能是图段的交點
    double c1 = cross(a2 - a1, b1 - a1), c2 = cross(a2)
       - a1, b2 - a1);
    double c3 = cross(b2 - b1, a1 - b1), c4 = cross(b2)
       - b1, a2 - b1);
    return dcmp(c1) * dcmp(c2) < 0 && dcmp(c3) * dcmp(
        c4) < 0;
```

```
bool SegmentProperIntersection(Segment s1, Segment s2)
    return SegmentProperIntersection(s1.p1, s1.p2, s2.
        p1, s2.p2);
bool SegmentInterSection(Point a1, Point a2, Point b1,
    Point b2) //非規範相交
    //端點相交
    if \ (Onsegment(a1\,,\ b1\,,\ b2)\ \mid\,\mid\ Onsegment(a2\,,\ b1\,,\ b2)
           Onsegment(b1, a1, a2) || Onsegment(b2, a1,
        a2))
         return true;
    if (SegmentProperIntersection(a1, a2, b1, b2))
         return true; //規範相交
    return false;
bool SegmentInterSection(Line& 11, Line& 12)
{
    return SegmentInterSection(l1.p1, l1.p2, l2.p1, l2.
double distance (Point& a, Point& b)
    return sqrt(length(b - a));
double distance (Point& p, Point& p1, Point& p2) //Line
    \Rightarrow p1, p2
    Vector v1 = p - p1, v2 = p2 - p1;
    return fabs(cross(v1, v2)) / length(v2); //面積/底=
double distance (Point& p, Segment& s) //Point to
    Segment
{
    Vector\ v=s.p2\ \text{-}\ s.p1\,;
    if (dcmp(length(v)) = 0)
        return length(p - s.p1); // E 段 退 化 成 點
    Vector v1 = p - s.p1;
    Vector v2 = p - s.p2;
    if (dcmp(dot(v1, v)) < 0)
         return length(v1); //
                                 點投影不在匠上
     \text{if } \left( \operatorname{dcmp} \left( \operatorname{dot} \left( \operatorname{v2} \,,\, \, \operatorname{v} \right) \right) \,>\, 0 \right) 
        return length(v2); // 點投影不在匠上
    return fabs(cross(v, v1)) / length(v);
double distance (Segment& s1, Segment& s2) // 图段到图段
    if (SegmentInterSection(s1, s2))
        return 0;
    double d = 1e9;
    d = min(d, distance(s1.p1, s2)); // 點到 图 段 距離 取 最
    d = min(d, distance(s1.p2, s2));
    d \, = \, \min(d \, , \ distance \, (\, s2 \, .p1 \, , \ s1 \, ) \, ) \, ;
    d = \min(d, distance(s2.p2, s1));
double ldistance (Line& l1, Line& l2) // F 段到F段距離
    Vector v1 = 11.p2 - 11.p1;
    Vector v2 = 12.p2 - 12.p1;
    if (cross(v1, v2) != 0)
        return 0;
    return distance(l1.p1, l2); //點到 F 段 距離
int ConvexHull(vector<Point>& P, Point* res)
{ // 凸包Andrew's Monotone Chain
    sort(P.begin(), P.end()); //先x 後 y
    auto last = unique(P.begin(), P.end()); //非重臣的
         點數量
    P.erase(last, P.end());
    int cnt = P.size();
    int m = 0;
    for (int i = 0; i < cnt; i++) {
         while (m > 1 \&\& cross(res[m - 1] - res[m - 2],
             P[i] - res[m - 2] <= 0
             m- -
         res\left[m\!\!+\!\!+\!\!\right] = P\left[\:i\:\right];
    int k = m;
```

```
for (int i = cnt - 2; i >= 0; i --)
        while (m > k \&\& cross(res[m - 1] - res[m - 2],
            P[i] - res[m - 2] <= 0
            m- -:
        res[m++] = P[i];
    if (cnt > 1) // 頭尾 1個點不用--
       m--;
    return m; //凸包點數
double PolygonArea(Point* p, int n)
    double area = 0;
    for (int i = 0; i < n; ++i)
        area += cross(p[i], p[(i + 1) \% n]);
    return fabs(area) / 2;
//半平面交
typedef vector<Point> Polygon;
Polygon \ halfplane\_intersection (Polygon\&\ p,\ Line\&\ line)
    Polygon q;
    Point \ p1 = \, line.p1 \, , \ p2 = \, line.p2 \, ;
    int n = p.size();
    for (int^{-}i = 0; i < n; i++) {
        double d = cross(p1, p2, p[(i + 1) \% n]);
        if (dcmp(c) >= 0)
            q.push_back(p[i]);
        if (dcmp(c * d) < 0)
            q.push\_back(\,GetLineIntersection\,(p1\,,\ p2\,,\ p\,[\,i
                ], p[(i + 1) \% n]);
    return q;
```

6 Sort

6.1 Heap Sort

```
void heap_sort(int* arr, int len)
      heapify(arr, len/2-1, len);
      max_heap(arr, len);
void heapify(int* ptr, int now, int last)
       if(now >= last/2 \mid \mid now < 0)
                                                        return:
      sub_heapify(ptr, now, last);
      heapify(ptr, now-1, last);
void sub_heapify(int* ptr, int now, int last)
{
       \label{eq:constraint}  \mbox{if} \ (\mbox{now*2+2} < \mbox{last \&\& !(ptr[now] >= ptr[now*2+1] \&\& } \\
             ptr[now] >= ptr[now*2+2])) {
              \begin{array}{ll} \operatorname{int} \ \operatorname{max} = \left( \operatorname{ptr} \left[ \operatorname{now}^* 2 {+} 1 \right] > \operatorname{ptr} \left[ \operatorname{now}^* 2 {+} 2 \right] \right) \ ? \ \operatorname{now} \end{array} 
                    *2+1 : now*2+2;
             swap(ptr, now, max, 1);

if(max < last/2) sub\_heapify(ptr, max, last);
       else if (now*2+1 < last && ptr[now] < ptr[now*2+1]){
             swap(ptr, now, now*2+1, 1);
             \begin{array}{l} \textbf{if} \left( \text{now*2+1} < \ \text{last/2} \right) \\ \textbf{sub\_heapify} \left( \ \text{ptr} \ , \ \ \text{now*2+1}, \right. \end{array}
                    last);
      }
void max_heap(int* ptr, int len)
       if(len <= 1) return;</pre>
      swap(ptr, 0, len-1, 2);
sub_heapify(ptr, 0, len-1);
      \max\_heap(\,ptr\,,\ len\,\text{-}1)\,;
```

6.2 Merge Sort

```
 \begin{array}{l} \mbox{void Merge(int* N, int L, int M)} \{ \\ \mbox{int } \mbox{tmp}[L], \mbox{p=0; int a,b;} \\ \mbox{for } (a=0,b=M; a<M \&\& b<L;) \{ \\ \mbox{if } (N[a] < N[b]) \{ \mbox{tmp}[p++]=N[a]; a++; \} \\ \mbox{else} \{ \mbox{tmp}[p++]=N[b]; b++; \} \\ \mbox{if } (a=M) \mbox{for } (\mbox{int } i=b; i<L; i++) \mbox{tmp}[p++]=N[i]; \\ \mbox{else for } (\mbox{int } i=a; i<M; i++) \mbox{tmp}[p++]=N[i]; \\ \mbox{for } (\mbox{int } i=0; i<L; i++) \mbox{N}[i] = \mbox{tmp}[i]; \\ \mbox{yoid MergeSort(int* N, int L)} \{ \\ \mbox{int } M=L/2; \\ \mbox{if } (L=1) \mbox{return}; \\ \mbox{MergeSort(N,M)}; \\ \mbox{MergeSort(N+M,L-M)}; \\ \mbox{Merge}(N,L,M); \\ \mbox{Merge}(N,L,M); \\ \mbox{} \} \\ \end{array}
```

6.3 Radix Sort

```
int maxbit(int data[], int n) //輔助函数, 求數据的最大
    位數
{
    int maxData = data[0];
                                   ///< 最大數
    /// 先求出最大數, 再求其位數, 这样有原先依次每个數
         判斷其位數,稍微優化點。
    for (int i = 1; i < n; ++i) {
         if (maxData < data[i]) maxData = data[i];</pre>
    int d = 1; int p = 10;
    while (maxData >= p){
 p *= 10;
        +\!\!+\!\!d;
    }
    return d;
           int d = 1; //保存最大的位數
           int p = 10;
           for (int i = 0; i < n; ++i){
           while (data [ i ] >= p) {
            p *= 10;
            ++d;
           return d; */
void radixsort(int data[], int n) //基數排序
{
    int d = maxbit(data, n);
    int *tmp = new int[n];
    int *count = new int[10]; //計數器
    int i, j, k;
    int radix = 1;
    for(i = 1; i <= d; i++) { //進行d次排序
         for(j = 0; j < 10; j++) count[j] = 0; //每次分
             配前清空计數器
         for (j = 0; j < n; j++){
             k = (data[j] / radix) % 10; //統计每個桶中
                 的記下數
             count[k]++;
         for(j = 1; j < 10; j++) count[j] = count[j - 1]
              + count [j]; //將tmp中的位置依次分配给每個
         for(j = n - 1; j >= 0; j--) { //將所有桶中記匠
             依次收集到tmp中
             \begin{array}{l} k = (\, data \, [\, j \,] \ / \ radix ) \ \% \ 10; \\ tmp[count \, [\, k] \ - \ 1] = data \, [\, j \,]; \end{array}
             count[k]--;
         for(j = 0; j < n; j++) // 將 臨 時 數 组 的 内 容 <math>\mathbb{F} \mathbb{F} 到
             data 🕈
             data[j] = tmp[j];
         radix = radix * 10;
    delete []tmp;
delete []count;
}
```

6.4 Shell Sort

7 Math

7.1 Extended Euclidean

```
 \begin{array}{ll} & \text{int ExGCD(int A, int B, int\& X, int\& Y, int } s0 = 1, int \ s1 = \\ & 0, int \ t0 = 0, int \ t1 = 1) \{ \\ & \text{if (A\%B == 0)} \{ \\ & X = s1; \\ & Y = t1; \\ & \text{return B;} \\ \} \\ & \text{s0-=s1*(A/B)}; \\ & \text{t0-=t1*(A/B)}; \\ & \text{return ExGCD(B,A\%B,X,Y,s1,s0,t1,t0)}; \\ \} \end{array}
```

7.2 Prime

```
void BuildPrime(bool prime[], int N){
  for (int i=2; i \le N; i++) prime [i] = true;
  for(int i=2; i< N; i++){
     if(prime[i]) \{for(int j=i*i; j \le N; j+=i) prime[j] =
           false;}
  }
}
void ExBuildPrime(int first[], bool prime[], int N){
  for (int i=2; i < N; i++){
     prime[i] = true;
      first[i] = 1;
  for (int i=2; i \le N; i++){
      \begin{array}{ll} if(prime[i]) \{for(int j=i*i;j<\!\!N;j+\!\!=\!\!i) \{\\ prime[j] = false; \end{array} 
        if(first[j] == 1)first[j] = i;
     }}
  }
```

7.3 Factor Decomposition

```
\label{eq:vector_pair} $$ \begin{array}{l} \operatorname{vector_pair_int}, \operatorname{int} & \operatorname{Factor_Decomposition_int} \ x) \{ \\ \operatorname{vector_pair_int}, \operatorname{int} & \operatorname{Ans}; \\ \operatorname{while}(x > 1) \{ \\ \operatorname{int} \ p, e = 0; \\ \operatorname{if}(\operatorname{prime}[x] & = \operatorname{true}) p = x; \operatorname{else} \ p = \operatorname{first}[x]; \\ \operatorname{while}(x\%p & = 0) \{x/=p; e++; \} \\ \operatorname{Ans.push_back_(make_pair_p, e))}; \\ \} \\ \operatorname{return} \ \operatorname{Ans}; \\ \} \\ \end{aligned}
```

7.4 Module Inverse

```
int inverse(int A, int M, int X = 1, int Y = 0) {
    if (AM == 0) {
        if (Y < 0)Y+=M;
        return Y;
    }
    X-=Y*(A/M);
    return inverse(M,AM,Y,X);
}

int inverse(int A, int M) {
    return A == 1?1:inverse(MM)*(M-M/A)M;
}

inline int inverse(int A, int M) {
    return ExPower(A,M-2,M);
}</pre>
```

7.5 Miller Rabin

```
bool MillerRabin(int a, int n){
     if(a = n) return true;
     if(\underline{\underline{\hspace{1cm}}}gcd(a,n) != 1)return false;
     int s = 0, d = n-1;
     int power_of_a;
     while (d\%2 = 0) \{d/=2; s++;\}
     power\_of\_a\!\!=\!\!ExPower(a\,,d\,,n\,)\,;
     if(power_of_a == 1)return true;
     for(int i=0; i < s; i++){
          if (power_of_a == n-1) return true;
         power_of_a=power_of_a*power_of_a%n;
     return false;
}
bool PrimeMillerRabin(int n){
     int a_{set}[3] = \{2,7,61\};
     //LL a_set
          [7] = \{2,325,9375,28178,450775,9780504,1795265022\}
     if (n = 2 \mid \mid n = 3) return true;
     if (n \le 1 \mid | n\%2 = 0 \mid | n\%3 = 0) return false;
     for (int i=0; i<3; i++){
          if (! MillerRabin(a_set[i],n))return false;
     return true;
}
```

7.6 Fraction

```
struct fraction_positive{
    int p,q;
    fraction_positive(){}
    fraction\_positive(\underbrace{int}\ p, \underbrace{int}\ q) : p(p)\,, q(q)\,\{\}
    void reduction(){
         int G = \underline{gcd}(p,q);
        p\ /\!=\,G;
         q /= G;
    bool operator == (const fraction_positive& B) const {
         return (p = B.p \&\& q = B.q);
    bool operator!=(const fraction_positive& B) const {
         return (p != B.p || q != B.q);
    bool operator > (const fraction_positive& B) const {
         return (p*B.q > B.p*q);
    bool operator>=(const fraction_positive& B) const {
          return (p*B.q >= B.p*q); 
    bool operator < (const fraction_positive& B) const {
         return (p*B.q < B.p*q);
    bool operator <= (const fraction_positive& B) const {
         return (p*B.q \ll B.p*q);
    fraction\_positive \hspace{0.2cm} operator + (const \hspace{0.2cm} fraction\_positive
         & B) const {
```

```
fraction_positive F;
        F.p = p*B.q+B.p*q;
        F.q = q*B.q;
        F. reduction();
        return F;
    fraction\_positive \hspace{0.2cm} operator \hbox{-} (const \hspace{0.2cm} fraction\_positive
        & B) const {
        fraction_positive F;
        F.p = p*B.q-B.p*q;
        F.q = q*B.q;
        F. reduction();
        return F;
    fraction\_positive \hspace{0.2cm} operator*(const \hspace{0.2cm} fraction\_positive
        & B) const {
        fraction_positive F;
        F.p = p*B.p;
        F.q = q*B.q;
        F. reduction();
        return F;
    fraction_positive operator/(const fraction_positive
        & B) const {
        fraction_positive F;
        F.p = p*B.q;
        F.q = q*B.p;
        F. reduction();
        return F;
    fraction_positive operator*(int x) const {
        fraction\_positive F = *this;
        F.p *= x;
        F.reduction();
        return F;
    fraction_positive operator/(int x) const {
        fraction\_positive F = *this;
        F.q = x;
        F. reduction();
        return F;
};
struct fraction {
    fraction_positive N;
    bool sign, broken; //O positive 1 negative
    fraction():broken(false){}
    fraction(int p, int q, bool sign): sign(sign){
        if(q == 0){broken = true; cout << "==divide by
             zero===" << endl;}
        else\{N.p = p; N.q = q; N. reduction(); \}
    bool operator == (const fraction & B) const {
        return (N == B.N && sign == B. sign);
    bool operator!=(const fraction& B) const {
        return (N != B.N || sign != B.sign);
    bool operator > (const fraction & B) const {
        return (!sign && B.sign) || (!sign && N > B.N)
             | | (sign \&\& N < B.N);
    bool operator>=(const fraction& B) const {
        return (!sign && B.sign) || (!sign && N >= B.N
             ) || (sign \&\& N \le B.N);
    bool operator < (const fraction & B) const {
        return !(*this >= B);
    bool operator <= (const fraction & B) const {
        return !(*this > B);
    fraction operator+(const fraction& B) const {
        fraction F;
        if (broken | B. broken) {F. broken = true; return F
             ;}
        if(sign^B.sign){
            const fraction_positive& big = (N > B.N ? N
                  : B.N);
             const fraction_positive& small = (N <= B.N
                 ? N : B.N);
```

```
F.N = big - small;
             F.sign = (N > B.N ? sign : B.sign);
        }
         else{
             F.N = N + B.N;
             F.sign = sign;
         return F;
    fraction operator - (const fraction& B) const {
         fraction F = B;
         if (broken | B. broken) {F. broken = true; return F
        F. sign = !F. sign;
        return (*this+F);
    fraction operator*(const fraction& B) const {
         fraction F;
         if (broken | B. broken) {F. broken = true; return F
             ;}
        F.N = N*B.N;
        F. sign = sign^B. sign;
        return F;
    fraction operator/(const fraction& B) const {
         fraction F;
         if (broken | B. broken | B.N.p = 0) (F. broken =
              true; return F;}
        F.N = N/B.N;
        F. sign = sign^B. sign;
        return F;
    fraction operator*(int x) const {
        fraction F = *this;
         if (broken) {F. broken = true; return F;}
        F.N = F.N*abs(x);
        if(x < 0)F.sign = !F.sign;
        return F;
    fraction operator/(int x) const {
        fraction F = *this;
         if(x == 0) \{F. broken = true; return F; \}
        F.N = F.N/abs(x);
        if(x < 0)F.sign = !F.sign;
        return F;
    friend istream& operator>>(istream& in, fraction& B)
        {
        int x;
        char c;
        B. sign = false;
        in >> x; if (x < 0)\{B. sign = true; x = -x;\}
        B.N.p = x;
        in \gg c \gg x; if (x == 0){B. broken = true; return
             in;
        B.N.q = x;
        B.N. reduction();
        return in;
    friend ostream& operator << (ostream& out, const
         fraction& B) {
         if (B. broken) { return out << "NaN"; }</pre>
         if(B.sign)out << '-';
        return out << B.N.p << '/' << B.N.q;
    }
};
```

7.7 Matrix

```
rows = \_rows;
  cols = \_cols
  data = new T^*[rows]; for (int i = 0; i < rows; i++)
      data[i] = new T[cols];
  for (int i = 0; i < rows; i++)for (int j = 0; j <
      cols; j++)data[i][j] = _data[i][j];
Matrix (const Matrix& N) {
  wrong = N. wrong;
  rows = N.rows;
  cols = N. cols;
  data = new T^*[rows]; for (int i = 0; i < rows; i++)
      data[i] = new T[cols];
  for (int i = 0; i < rows; i++)for (int j = 0; j < rows)
      cols; j++)data[i][j] = N. data[i][j];
~Matrix(){
  delete data;
Matrix operator+(const Matrix& N){
  cout << (*this) << endl << N << endl;
  Matrix tmp = Matrix(*this);
  if (rows != N.rows || cols != N.cols)tmp.wrong =
  else for (int i = 0; i < rows; i++)for (int j = 0;
      j < cols; j++)tmp.data[i][j] += N.data[i][j];
  return tmp;
Matrix operator - (const Matrix& N) {
  Matrix tmp = Matrix(*this);
  if (rows != N.rows || cols != N.cols)tmp.wrong =
      true;
  else for (int i = 0; i < rows; i++)for (int j = 0;
      j < cols; j++)tmp.data[i][j] -= N.data[i][j];
  return tmp;
Matrix operator*(const Matrix& N){
  Matrix tmp = Matrix (rows, N. cols);
  if (cols != N.rows)tmp.wrong = true;
  else for (int i = 0; i < tmp.rows; i++)for (int j =
       0; j < tmp.cols; j++){
    tmp.data[i][j] = 0;
    for (int k = 0; k < cols; k++)tmp.data[i][j] +=
    data[i][k] * N.data[k][j];</pre>
  return tmp;
Matrix operator*(int c){
  Matrix tmp = Matrix(*this);
  for (int i = 0; i < rows; i++)for (int j = 0; j <
      cols; j++)tmp.data[i][j] *= c;
  return tmp;
Matrix operator=(const Matrix& N){
  wrong = N. wrong;
  rows = N.rows;
  cols = N. cols;
  data = new T^*[rows]; for (int i = 0; i < rows; i++)
      data[i] = new T[cols];
  for (int i = 0; i < rows; i++)for (int j = 0; j <
      cols; j++)data[i][j] = N. data[i][j];
  return (*this);
Matrix transpose(void) {
  Matrix tmp = Matrix(*this);
  //int fuck = tmp.rows; tmp.rows = tmp.cols; tmp.cols
       = fuck;
  swap(tmp.rows, tmp.cols);
  delete tmp.data; tmp.data = new T*[tmp.rows]; for (
      int i = 0; i < tmp.rows; i++)tmp.data[i] = new
      T[tmp.cols];
  for (int i = 0; i < rows; i++)for (int j = 0; j <
      cols; j++)tmp.data[j][i] = data[i][j];
  return tmp;
T **data;
int rows, cols;
bool wrong;
```

```
ostream& operator << (ostream& o, const Matrix <T>& N) {
  if (N. wrong) { o << "Error: Wrong Matrix Dimension" <<
        endl; return o; }
  for (int i = 0; i < N.rows; i++)for (int j = 0; j < N
       . cols; j++){}
     if (j = 0){
       if (i == 0)o << '[';
       else o << ' ';
    o << N. data[i][j];
    if (j = N. cols - 1){
       if (i == N.rows - 1)o << ']';
       else o << ';' << endl;
    else o << ' ';
  }
  return o;
}
template <typename T>
T det(Matrix<T> N) {
  if (N. cols = 2) return N. data[0][0]*N. data[1][1] - N.
       data[0][1]*N. data[1][0];
  T sum = 0;
  for (int i = 0; i < N. cols; i++){}
    Matrix<T> tmp(N. cols -1, N. cols -1);
     for (int j = 0; j < N. cols - 1; j++)for (int k = 0;
          k < N. cols - 1; k++){
        \  \, \text{int} \  \, r \, = \, j + 1, \, \, c \, ; \, \, \, \text{if} \  \, (k \, < \, i \,) \, c \, = \, k \, ; \, \, \, \text{else} \  \, c \, = \, k \, + \, 1; 
       tmp.data[j][k] = N.data[r][c];
    int Ans; if (i \% 2)Ans = -1; else Ans = 1;
    sum += Ans*N. data [0][i]*det(tmp);
  return sum;
}
```

7.8 BigInt

```
const int MAX_DIGIT = 1000;
const int POSTIONAL = 4;
const int POSTIONAL_NOTATION = 10000;
struct PositiveBigInt{
    int N[MAX_DIGIT],L;
    PositiveBigInt():L(0){}
    PositiveBigInt(string S){
        set_value(S);
    PositiveBigInt(int* N, int L){
        set\_value(N,L);
    void set_value(string S){
        L=(S. size()-1)/POSTIONAL+1;
        for (int i=0; i< L; i++)N[i]=0;
        for (int i=0; i*POSTIONAL < S.size(); i++){
            int pow10=1;
            for(int j=i*POSTIONAL; j<S.size() && j<i*
                POSTIONAL+POSTIONAL; j++){
                N[i]+=(S[S.size()-1-j]-48)*pow10;
                 pow10*=10;
            }
        }
    void set_value(int* N, int L){
        this -> L=L;
        for (int i=0; i< L; i++)this->N[i]=N[i];
    bool equal_zero() const {
        if(L = 1 \&\& N[0] = 0) return true;
        return false;
    void kill_zero(){
        while (L > 1 \&\& N[L-1] == 0)L--;
    int magic(int *Num, int Length, const PositiveBigInt&
         A) const {
        PositiveBigInt B(Num, Length);
        B. kill_zero();
        int Ans=0;
```

```
while(B >= A){
        B=B-A;
        Ans++:
    for(int i=0; i < Length; i++){
        if(i < B.L)Num[i]=B.N[i];
        else Num[i]=0;
    return Ans:
PositiveBigInt operator+(const PositiveBigInt& A)
    const -
    const PositiveBigInt &X=(*this > A ? *this : A)
    const PositiveBigInt &Y=(*this <= A ? *this : A
    PositiveBigInt tmp=X;
    for (int i=0; i<Y.L; i++)tmp.N[i]+=Y.N[i];
    tmp.N[tmp.L]=0;
    for (int i=0; i < tmp.L; i++)
        tmp.N[\ i+1] + = tmp.N[\ i\ ] / POSTIONAL\_NOTATION;
        tmp.N[i]%=POSTIONAL_NOTATION;
    if(tmp.N[tmp.L] > 0)tmp.L++;
    return tmp;
PositiveBigInt operator - (const PositiveBigInt& A)
    const +
    const PositiveBigInt &X=(*this > A ? *this : A)
    const PositiveBigInt &Y=(*this <= A ? *this : A
    PositiveBigInt tmp=X;
    for (int i=0; i<Y.L; i++)tmp.N[i]-=Y.N[i];
    for (int i=0; i < tmp.L; i++){}
        _{\displaystyle i\,f\,(\mathrm{tmp.N}[\;i\;]\;<\;0)\{}
             tmp.N[i+1]--
             tmp.N[i]+=POSTIONAL_NOTATION;
    tmp.kill zero();
    return tmp;
PositiveBigInt operator*(const PositiveBigInt& A)
    const {
    PositiveBigInt tmp;
    tmp.L=L+A.L;
    for (int i=0; i < tmp.L; i++)tmp.N[i]=0;
    for (int i=0; i< L; i++){
        for (int j=0; j<A.L; j++)tmp.N[i+j]+=N[i]*A.N[
             j];
        for (int j=0; j< tmp.L; j++){
            \operatorname{tmp.N[j+1]+=tmp.N[j]/POSTIONAL\_NOTATION}
             tmp.N[j]%=POSTIONAL_NOTATION;
    tmp.kill_zero();
    return tmp;
PositiveBigInt operator/(const PositiveBigInt& A)
    if(*this < A)return PositiveBigInt("0");</pre>
    PositiveBigInt Div, Mod=*this;
    Div.L=L;
    for (int i=L-1; i>=0; i--) Div.N[i]=magic (Mod.N+i,
        Mod.L-i,A);
    Div.kill_zero();
    return Div;
PositiveBigInt operator%(const PositiveBigInt& A)
    const {
    if (*this < A) return *this;
    PositiveBigInt Mod=*this;
    for (int i=L-1; i>=0; i--) magic (Mod.N+i, Mod.L-i, A)
    Mod.kill_zero();
    return Mod;
bool operator > (const Positive BigInt& A) const {
    if (L > A.L) return true;
    else if (L < A.L) return false;
```

```
for(int i=L-1;i>=0;i--){
             if (N[i] > A.N[i]) return true;
             else if (N[i] < A.N[i]) return false;
        return false;
    bool operator>=(const PositiveBigInt& A) const {
        if(L > A.L) return true;
        else if (L < A.L) return false;
        for(int i=L-1; i>=0; i--){
             if(N[i] > A.N[i]) return true;
            else if (N[i] < A.N[i]) return false;
        return true;
    bool operator < (const Positive BigInt& A) const {
        return !(*this >= A);
    bool operator <= (const Positive BigInt& A) const {
        return !(*this > A);
    bool operator==(const PositiveBigInt& A) const {
        if(L != A.L)return false;
        for (int i=0; i< L; i++){
            if(N[i] != A.N[i]) return false;
        return true;
    bool operator!=(const PositiveBigInt& A) const {
        return !(*this == A);
    PositiveBigInt operator=(const PositiveBigInt& A) {
        L=A.L:
        for (int i=0; i< L; i++)N[i]=A.N[i];
        return (*this);
    }
};
ostream& operator << (ostream& o, const PositiveBigInt& A)
    o << A.N[A.L-1];
    for (int i=A.L-2; i>=0; i--) {
        for (int c=1,tmp=A.N[i]; c < POSTIONAL && tmp*10
            < POSTIONAL_NOTATION; c++,tmp*=10)o << "0";
        o << A.N[i];
    return o;
}
struct BigInt{
    PositiveBigInt N;
    bool sign;
    BigInt()\{\}
    BigInt(string S){
        set_value(S);
    void set_value(string S){
        if(S[0] = ',-'){
            sign=false;
            N. set_value(S. substr(1, S. size()-1));
        else{
            sign=true;
            N. set_value(S);
    BigInt operator+(const BigInt& A) const {
        BigInt tmp;
        if (sign^A.sign){
            tmp.N=N-A.N;
            if(N > A.N)tmp.sign=sign;
            else if (N < A.N)tmp.sign=A.sign;
            else tmp.sign=true;
            tmp.N=N+A.N;
            tmp.sign=sign;
        return tmp;
    BigInt operator - (const BigInt& A) const {
        BigInt tmp=A;
```

```
tmp.sign = !tmp.sign;
    return (*this + tmp);
BigInt operator*(const BigInt& A) const {
    BigInt tmp;
    if (N. equal_zero() | A.N. equal_zero())tmp. sign=
    else tmp.sign=!(sign^A.sign);
    tmp.N=N*A.N;
    return tmp;
BigInt operator/(const BigInt& A) const {
    if(A.N.equal_zero()){printf("divided by 0 error
        !!\n"); return BigInt("0");}
    BigInt tmp;
    if (N. equal_zero())tmp. sign=true;
    else tmp.sign=!(sign^A.sign);
    tmp.N=N/A.N;
    return tmp;
BigInt operator%(const BigInt& A) const {
    if(A.N.equal_zero()){printf("divided by 0 error
        !!\n"); return BigInt("0");}
    BigInt tmp;
    tmp.sign=true;
    tmp.N\!\!=\!\!N\!\!/\!\!A.N;
    return tmp;
bool operator > (const BigInt& A) const {
    if (sign = true && A.sign = true) return (N > A
        .N);
    if (sign = true && A. sign = false) return true;
    if (sign = false && A. sign = true) return false
    if (sign == false && A.sign == false)return (N <
         A.N);
bool operator>=(const BigInt& A) const {
    if (sign = true && A. sign = true) return (N >=
        A.N);
    if (sign = true && A. sign = false) return true;
    if (sign = false && A. sign = true)return false
    if(sign == false && A.sign == false)return (N
        \langle = A.N \rangle;
bool operator < (const BigInt& A) const {
    return !(*this >= A);
bool operator <= (const BigInt& A) const {
    return !(*this > A);
bool operator == (const BigInt& A) const {
    if(sign != A.sign)return false;
    \mathbf{return} \ (\mathbf{N} = \mathbf{A}.\mathbf{N}) \,;
bool operator!=(const BigInt& A) const {
    return !(*this == A);
BigInt operator=(const BigInt &A){
    N=A.N;
    sign=A.sign;
    return (*this);
BigInt operator+=(const BigInt &A) {
    return (*this)=(*this)+A;
BigInt operator -= (const BigInt &A) {
    return (*this)=(*this)-A;
BigInt operator*=(const BigInt &A){
    return (*this)=(*this)*A;
BigInt operator/=(const BigInt &A){
    return (*this)=(*this)/A;
BigInt operator%=(const BigInt &A){
    return (*this)=(*this)%A;
BigInt operator++(){
    (*this)=(*this)+BigInt("1");
    return (*this);
```

```
}
BigInt operator++(int useless){
    BigInt tmp=(*this);
    (*this)=(*this)+BigInt("1");
    return tmp;
}
BigInt operator--(){
    (*this)=(*this)-BigInt("1");
    return (*this);
}
BigInt operator--(int useless){
    BigInt tmp=(*this);
    (*this)=(*this)-BigInt("1");
    return tmp;
}
};
ostream& operator<<(ostream& o,const BigInt& A){
    if (!A.sign)o << '-';
    return o << A.N;
}</pre>
```