

## Machine Learning Worksheet 4

### Multivariate Normal

## 1 Basic Gaussian

**Problem 1:** We decomposed the covariance matrix  $\Sigma$  into  $U\Lambda U^T$  with the orthonormal matrix  $U$  and the diagonal matrix of eigenvalues  $\Lambda$ . Show that:

$$U\Lambda^{-1}U^T = \sum_{i=1}^d \frac{1}{\lambda_i} \mathbf{u}_i \mathbf{u}_i^T$$

We know that:

Index notation for outer product:

$$(\mathbf{A}\mathbf{B})_{ij} = \sum_k a_{ik} b_{kj}$$

Index notation for matrix product:

$$(\mathbf{u}\mathbf{v}^T)_{ij} = u_i v_j$$

Indexing of column vectors:

$$(\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k) = U$$

On the LHS we have:

$$(\mathbf{U}\Lambda)_{ij} = \sum_k u_{ik} \frac{1}{\lambda_{kj}} = u_{ij} \frac{1}{\lambda_j}$$

$$((\mathbf{U}\Lambda)\mathbf{U}^T)_{ij} = \sum_k u_{ik} \frac{1}{\lambda_k} u_{jk} = \sum_k \frac{1}{\lambda_k} u_{ik} u_{jk}$$

On the RHS we have:

$$\left( \sum_k \frac{1}{\lambda_k} \mathbf{u}_k \mathbf{u}_k^T \right)_{ij} = \sum_k \frac{1}{\lambda_k} (\mathbf{u}_k \mathbf{u}_k^T)_{ij} = \sum_k \frac{1}{\lambda_k} u_{ik} u_{jk}$$

**Problem 2:** Let  $L$  be an invertible  $n$  by  $n$  matrix over  $\mathbb{R}$ . Show that the linear transformation  $Y = LX$  of a Gaussian is again a Gaussian. Use the moment parametrisation and the change of variable theorem to get there.

Moment parametrisation of a Gaussian:

$$\propto e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})}$$

We apply the linear transformation  $\mathbf{y} = \mathbf{L}\mathbf{x}$ .  $\mathbf{x}(\mathbf{y})$  is therefore  $\mathbf{x} = \mathbf{L}^{-1}\mathbf{y}$

Together with the change of variable theorem we get:

$$\begin{aligned} f(\mathbf{x}) &= f(\mathbf{x}(\mathbf{y})) \left| \frac{d\mathbf{x}}{d\mathbf{y}} \right| = f(\mathbf{L}^{-1}) |\mathbf{L}| \propto e^{-\frac{1}{2}(\mathbf{L}^{-1}\mathbf{y}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{L}^{-1}\mathbf{y}-\boldsymbol{\mu})} \\ &= e^{-\frac{1}{2}(\mathbf{L}^{-1}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu}))^T \boldsymbol{\Sigma}^{-1} \mathbf{L}^{-1}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu})} = e^{-\frac{1}{2}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu})^T \mathbf{L}^{-T} \boldsymbol{\Sigma}^{-1} \mathbf{L}^{-1}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu})} \\ &= e^{-\frac{1}{2}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu})^T (\mathbf{L}\boldsymbol{\Sigma}\mathbf{L}^T)^{-1}(\mathbf{y}-\mathbf{L}\boldsymbol{\mu})} \end{aligned}$$

## 2 Conditioned Gaussian

You got a dataset with pairs  $\mathbf{x}$  and  $\mathbf{y}$ . You computed the covariance of the concatenated datapoints  $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix}$ . The covariance matrix looks like this:  $\begin{pmatrix} \boldsymbol{\Sigma}_{X,X} & \boldsymbol{\Sigma}_{X,Y} \\ \boldsymbol{\Sigma}_{Y,X} & \boldsymbol{\Sigma}_{Y,Y} \end{pmatrix}$ . For simplicity we assume that  $\boldsymbol{\mu}_X$  and  $\boldsymbol{\mu}_Y$  are  $\mathbf{0}$ .

**Problem 3:** The underlying process of the probability distribution  $p(\mathbf{y} | \mathbf{x})$  can be expressed as  $\mathbf{Y} = \mathbf{T}\mathbf{X} + \mathbf{Z}$  where  $\mathbf{Z} \sim \mathcal{N}(\mathbf{0}, \boldsymbol{\Sigma}_{Y|X})$ . What is the value of the matrix  $\mathbf{T}$ ?

From Bishop we know that

$$\begin{aligned} p(\mathbf{z}) &= \mathcal{N}(\boldsymbol{\mu}_Z, \boldsymbol{\Sigma}_Z) \\ \boldsymbol{\mu}_Z &= \begin{pmatrix} \boldsymbol{\mu}_X \\ \mathbf{A}\boldsymbol{\mu}_X + \mathbf{b} \end{pmatrix} \\ \boldsymbol{\Sigma}_Z &= \begin{pmatrix} \boldsymbol{\Sigma}_X & \boldsymbol{\Sigma}_X \mathbf{A}^T \\ \mathbf{A}\boldsymbol{\Sigma}_X & \boldsymbol{\Sigma}_{Y|X} + \mathbf{A}\boldsymbol{\Sigma}_X \mathbf{A}^T \end{pmatrix} = \begin{pmatrix} \boldsymbol{\Sigma}_{X,X} & \boldsymbol{\Sigma}_{X,Y} \\ \boldsymbol{\Sigma}_{Y,X} & \boldsymbol{\Sigma}_{Y,Y} \end{pmatrix} \end{aligned}$$

In our transformation  $\mathbf{T}$  corresponds to  $\mathbf{A}$ , so we need to solve:

$$\begin{aligned} \boldsymbol{\Sigma}_X \mathbf{T}^T &= \boldsymbol{\Sigma}_{X,Y} \\ \mathbf{T} &= (\boldsymbol{\Sigma}_X^{-1} \boldsymbol{\Sigma}_{X,Y})^T \end{aligned}$$

**Problem 4:** What is the covariance of  $\mathbf{Z}$ ?

From the last question we know that:

$$\Sigma_{Y|X} + T\Sigma_X T^T = \Sigma_{Y,Y}$$

$$\Sigma_{Y|X} = \Sigma_{Y,Y} - T\Sigma_X T^T$$