

Class Method

Task

→ Supports timing control

@ (posedge clk);
#10;

→ Multiple output port

Function

→ Do not support timing control

→ Do not support output port

Task

```
task sys_rst();  
rst <= 1;  
#30;  
rst <= 0;  
endtask
```

→ Supports timing control

@ (posedge clk);
#10;

→ Multiple output port

Function

→ Do not support timing (new)

```
task sys_rst();  
rst <= 1'b1;  
#30;  
rst <= 1'b0;  
endtask
```