Basic of Stochastic Finance

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Martingales

Definition

A process X is called *martingale* (relative to $\{F_N\}$) if

- 1. *X* is adopted,
- $2. E|Xn| < \infty$,
- 3. $E(X_n | \mathcal{F}_{n-1}) = X_{n-1}$ a. s. $(n \ge 1)$.
- *Supermartingale* is defined similarly, except that (3) is replaced by

$$E(X_n|\mathcal{F}_{n-1}) \le X_{n-1}$$
 a.s. $(n \ge 1)$

• *Submartingale* is defined with (3) replaced by

$$E(X_n | \mathcal{F}_{n-1}) \ge X_{n-1} \text{ a. s. } (n \ge 1)$$

• A supermartingale decreases on average, a submartingale increases on average in time.

Martingales: examples

One reason martingales are so powerful is that they model a situation where one gains progressively more information over time. Suppose that \mathcal{U} is a set of objects, and $f: \mathcal{U} \to \mathbb{R}$. Let X be a random variable taking values in \mathcal{U} , and let $\{Y_i\}$ be another sequence of random variables. The associated *Doob martingale* is given by

$$X_i = \mathbb{E}[f(X) \mid Y_0, Y_1, \dots, Y_i].$$

In words, this is our "estimate" for the value of f(X) given the information contained in $\{Y_0, \ldots, Y_i\}$. To see that this is always a martingale with respect to $\{Y_i\}$, observe that

$$\mathbb{E}[X_{i+1} \mid Y_0, \dots, Y_i] = \mathbb{E}[\mathbb{E}[f(X) \mid Y_0, \dots, Y_{i+1}] \mid Y_0, \dots, Y_i] = \mathbb{E}[f(X) \mid Y_0, \dots, Y_i] = X_i,$$

where we have used the tower rule of conditional expectations.

Martingales: examples

Balls in bins. Suppose we throw m balls into n bins one at a time. At step i, we place ball i in a uniformly random bin. Let C_1, C_2, \ldots, C_m be the sequence of (random) choices, and let C denote the final configuration of the system, i.e. exactly which balls end up in which bins.

Now we can consider a functional like f(C) = # of empty bins. If $X_i = \mathbb{E}[f(C) \mid C_1, \dots, C_i]$, then $\{X_i\}$ is a (Doob) martingale. It is straightforward to calculate that

$$\mathbb{E}[X_m] = \mathbb{E}[X_0] = \mathbb{E}[f(C)] = n \cdot \left(1 - \frac{1}{n}\right)^m.$$

Suppose we are interested the concentration of $X_m = f(C)$ around its mean value. Of course, we can write $X_m = Z_1 + \cdots + Z_m$ where Z_i is the indicator of whether the ith been is empty after all the balls have been thrown. But note that the $\{Z_i\}$ variables are not independent—in particular, if I tell you that $Z_1 = 1$ (bin 1 is empty), it decreases slightly the likelihood that other bins are empty.

Martingales: examples

The Hoeffding-Azuma inequality

Say that a martingale $\{X_i\}$ has *L*-bounded increments if

$$|X_{i+1} - X_i| \le L$$

for all $i \ge 0$. (The preceding inequality is meant to hold with probability 1

Theorem 2.1. For every L > 0, if $\{X_i\}$ is a martingale with L-bounded increments, then for every $\lambda > 0$ and $n \ge 0$, we have $-\frac{1}{2}\cdot\left(\frac{\lambda}{L}\right)^2\cdot \frac{1}{2}$

$$\mathbb{P}[X_n \ge X_0 + \lambda] \le e^{-\frac{\lambda^2}{2L^2n}} = \mathbb{P}[X_n \le X_0 - \lambda] \le e^{-\frac{\lambda^2}{2L^2n}}$$

We will prove this in Section 3. It's useful to note the following special case of the theorem.

Corollary 2.2. Suppose that $Z_1, Z_2, ..., Z_n$ are independent random variables taking values in the interval [-L, L]. Put $Z = Z_1 + \cdots + Z_n$ and $\mu = \mathbb{E}[Z]$. Then for every $\lambda > 0$, we have

$$\mathbb{P}\big[Z \geq \mu + \lambda\big] \leq e^{-\lambda^2/(2L^2n)}$$

$$\mathbb{P}\big[Z \geqslant \mu - \lambda\big] \leqslant e^{-\lambda^2/(2L^2n)}$$

Continuous time. Brownian Motion

- By choosing the relationship between Δx and Δt such that $\frac{(\Delta x)^2}{\Delta t} = const =: C^2$ we get, on the limit, that $X_t \sim N(0, C\sqrt{t})$. The limiting process X_t , preserves some important features of SRW:
- (i) The increments of X; are independent i.e. for $0 \le s \le t \le u \le v$ the increments $X_t X_s$ and $X_v X_u$ are independent r.v. (the same is valid for any n time intervals).
- (ii) The increments of X_t are stationary i.e. the distribution of $X_{s+t} X_s$, only depends on t (and not on s).

Definition 6

The random process $\{W_t, t \ge 0\}$ is called Brownian motion (Wiener process), if

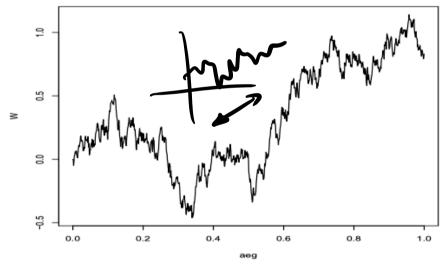
- (i) W(0) = 0,
- (ii) for all t > 0 the r.v. $W_t \sim N(0, C\sqrt{t})$, where C > 0 is a constant.

Continuous time. Brownian Motion

 From the definition of BM it follows that also the increments of BM are normally distributed: by the stationarity of increments

$$W_t - W_s \stackrel{\text{D}}{=} W_{t-s} - W_0 = W_{t-s} \sim N(0, C\sqrt{t-s}),$$

where $\stackrel{D}{=}$ is to be read as "has same distribution as".



A trajectory of standard Brownian motion

- Note that, in fact, the property (iv) can be deduced from properties (i)-(iii).
- BM is a mathematical model widely used in physics (diffusions), economics (price models) e.t.c.

Finite-dimensional distributions of SBM

- The joint distribution of $(W_{t_1}, W_{t_2}, ..., W_{t_n})$ where $0 < t_1 < t_2 < \cdots < t_n$ can easily be calculated.
- For each t_i , the density of W_{t_i} is

$$f_{W_{t_i}}(x) = \frac{1}{\sqrt{2\pi t_i}} e^{-\frac{x^2}{2t_i}}$$

From each t_i , the density of w_{t_i} is $f_{W_{t_i}}(x) = \frac{1}{\sqrt{2\pi t_i}} e^{\frac{x^2}{2t_i}}$ $f_{W_{t_i}}(x) = \frac{1}{\sqrt{2\pi t_i}} e^{\frac{x^2}{2t_i}} e$

$$W_{t_1} = x_1 \quad \text{fersion} \quad$$

And since the increments ate independent, we have

$$f_{W_{t_1,\dots,W_{t_n}}}(x_1,\dots,x_n) = f_{W_{t_1},W_{t_2}-W_{t_1},\dots,W_{t_n}-W_{t_{n-1}}}(x_1,x_2-x_1,\dots,x_n-x_{n-1}) = f_{W_{t_1}}(x_1) \cdot f_{W_{t_2}-W_{t_1}}(x_2-x_1) \cdot \dots \cdot f_{W_{t_n}-W_{t_{n-1}}}(x_n-x_{n-1}) = \frac{1}{\sqrt{2\pi t_1}} e^{\frac{x_1^2}{2t_1}} \frac{1}{\sqrt{2\pi (t_2-t_1)}} e^{\frac{(x_2-x_1)^2}{2(t_2-t_1)}} \cdot \dots \cdot \frac{1}{\sqrt{2\pi (t_n-t_{n-1})}} e^{\frac{(x_n-x_{n-1})^2}{2(t_n-t_{n-1})}}$$

• The formula obtained can be used for many purposes.

Conditional Distribution

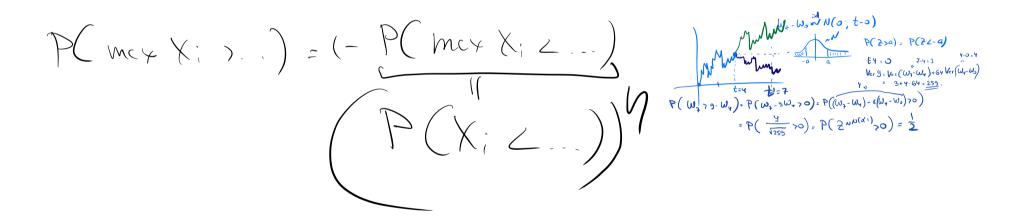
- Let's use the formula above to solve one particular problem. Suppose we know that at time t BM has taken value $W_t = B$. Let s be an earlier time, s < t.
- What is the conditional distribution of W_s given the event $W_t = B$? It is known that the conditional density is the ratio of joint density and the density of the condition, we can calculate

$$f_{W_s|W_t}(x|B) = \frac{f_{W_s,W_t}(x,B)}{f_{W_t(B)}} = \frac{\frac{1}{\sqrt{2\pi s}} e^{\frac{x^2}{2s}} \cdot \frac{1}{\sqrt{2\pi(t-s)}} e^{\frac{(B-x)^2}{2(t-s)}}}{\frac{1}{\sqrt{2\pi t}} e^{\frac{B^2}{2t}}} = \dots = \frac{1}{\sqrt{2\pi \frac{t}{s}} (t-s)} e^{\frac{t(x-B_t^S)^2}{2s(t-s)}}$$

• Hence, the conditional distribution of W_s is normal distribution with mean and variance $\frac{s(t-s)}{t}$.

Maxima of Brownian Motion

- If a > 0, then $P\left\{\max_{0 \le s \le t} W_s \ge a\right\} = P\{T_a \le t\} = 2[1 \Phi\left(\frac{|a|}{\sqrt{t}}\right)]$
- If a < 0, then $P\left\{\max_{0 \le s \le t} W_s \ge a\right\} = 1$



Brownian Motion between Two Boundaries

Let A > 0, B > 0. Let us find the probability that, starting from 0, BM reaches level A before -B. Recall that in the case of SRW the answer to the same question is $\frac{B}{A+B}$. As the same answer remains true for any time and space steps sizes, we have

$$P\{W_t reaches \ A \ before \ -B\} = P\{T_A < T_B\} = \frac{B}{A+B}$$

Exercise

Let W_t be a standard Brownian motion. Assume that W_1 = 2. Find the probability that $W_5 < 0$.

- Without any given condition we would have $P\{W_5 < 0\} = 3$, since $W_t \sim N(0, \sqrt{t})$.
- However, under the condition W_1 = 2the increment $W_5 W_1 \sim N(0, \sqrt{4})$ this distribution only depends on the length of the time interval and not on its location. Therefore we have

$$P\{W_5 < 0 | W_1 = 2\} = P\{W_5 - W_1 < -2 | W_1 = 2\} =$$

$$= P\{W_5 - W_1 < -2\} = P\{W_4 < -2\} =$$

$$= P\{N(0, \sqrt{4}) < -2\} = \Phi\left(\frac{-2}{2}\right) = \Phi(-1) = 0.16$$

Continuous time. Filtration

- Many important concepts and results that are known for martingales with discrete time can be transferred to continuous time without any major change.
- Let $(\Omega, \mathcal{F}, \mathbf{P})$ be a probability space and let t be a real-valued parameter interpreted as time. Most often, t takes values from the half-line R^+ or finite interval (0, T).

Definition 7

A family of σ -algebras $\{\mathcal{F}_t, t \geq 0\}$ is called a *filtration*, if

- 1) all its members \mathcal{F}_t are sub- σ -algebras of \mathcal{F} and,
- 2) for s < t one has $\mathcal{F}_s \subseteq \mathcal{F}_t$.

As in the case of dicsrete time, we are mainly interested in the natural filtration $\{\mathcal{F}_t^X, t \geq 0\}$, generated by a random process X. As before, \mathcal{F}_t^X contains the information induced by the random process X within the time interval [0,t]. It means that an event $A \in \mathcal{F}_t^X$ if and only if one can decide whether A occurred or not on the basis of the trajectory $\{X_s, 0 \leq s \leq t\}$ that the process X generates by time t.

Definition 8

If $\{Y_t, t \geq 0\}$ is a random process such that for each t the random variable Y is \mathcal{F}_t -measurable, then it is said that the process Y is *adopted to filtration* $\{\mathcal{F}_t, t \geq 0\}$.

Examples

- 1. The random process $Z_t = \int_0^t X_s ds$ is adopted to the filtration $\{\mathcal{F}_t^X, t \geq 0\}$, since knowing the path of X within time interval [0, t] is sufficient to determine Z_t .
- 2. The process $M_t = \max_{0 \le s \le t} W_s$ is adopted to the filtration $\{\mathcal{F}_t^W, t \ge 0\}$.
- 3. The process $Z_t = W_{t+1}^2 W_t^2$ is not adopted to the filtration $\{\mathcal{F}_t^W, t \geq 0\}$.

$$\int_{N} = \sum_{i=1}^{N} (y_{i} - y_{i-1})^{2} \\
+ E[J_{n}] \cdot E[\sum_{i=1}^{N} (y_{i} - y_{i-1})^{2}] = \sum_{i=1}^{N} E[(y_{i} - y_{i-1})^{2}] = \sum_{i=1}^{N} V_{or} (y_{i} - y_{i-1}) + E[y_{i} - y_{i-1}] = \\
= \sum_{i=1}^{N} \frac{1}{N} \cdot N \cdot \frac{1}{N} = t.$$

$$Ver(U_{i,1} - U_{i-1,1})^{2} = \sum_{i=1}^{N} V_{or} ((y_{i} - y_{i-1})^{2}) = \sum_{i=1}^{N} V_{or} ((y_{i} - y_{i-1})^{2}) + E[y_{i} - y_{i-1}] = \\
= \sum_{i=1}^{N} \frac{1}{N} \cdot N \cdot \frac{1}{N} = t.$$

$$Ver(U_{i,1} - U_{i-1,1})^{2} = \sum_{i=1}^{N} V_{or} ((y_{i} - y_{i-1})^{2}) = \sum_{i=1}^{N} V_{or} ((y_{i} - y_{i-1})^{2}) + \frac{1}{N} = \\
= \sum_{i=1}^{N} \frac{1}{N} \cdot N \cdot N(0, \frac{1}{N}) = \frac{1}{N} \cdot \sum_{i=1}^{N} V_{or} ((y_{i} - y_{i-1})^{2}) + \frac{1}{$$

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Continuous time. Martingales

$$\frac{dw_{+}}{dw_{+}} = \frac{dw_{+}}{dw_{+}} = \frac{dw_{+}}{dw_$$

Definition 9

Let $(\Omega, \mathcal{F}, \mathbf{P})$ be a probability space endowed with a filtration $\{\mathcal{F}_t, t \geq 0\}$. A random process $\{M_t, t \geq 0\}$ is called a martingale, if

- *1. M* is adopted to the filtration $\{\mathcal{F}_t, t \geq 0\}$,
- 2. $E|M_t| < \infty, \forall t$
- 3. For any $s \le t$ we have $E(M_t | \mathcal{F}_s) = M_s$ a.s.
- If the equality in (3) is replaced by the inequality $\leq (or \geq)$, then we speak about a supermartingale (respectively submartingale).

Remark: Similarly, a martingale can be defined on a finite time interval [0, T]. In the following mostly the filtration $\{\mathcal{F}_t^W, t \geq 0\}$, generated by a standard Brownian motion W, is used.