

SORTING

QuickSort

- A Divide-and-Conquer Algorithm
- Best and Worst cases
- Analysis

SORTING – DIVIDE AND CONQUER

- The two sorting algorithms seen so far:
 - Insertion Sort and Merge Sort
- Both were designed by using:
 - divide-and-conquer as the design technique
 - an order-preserving combination operation (*insert* or *merge*)
- Question:
 - Are there other ways to divide-and-conquer?
 - Are there other ways of dividing problems / combining solutions ?

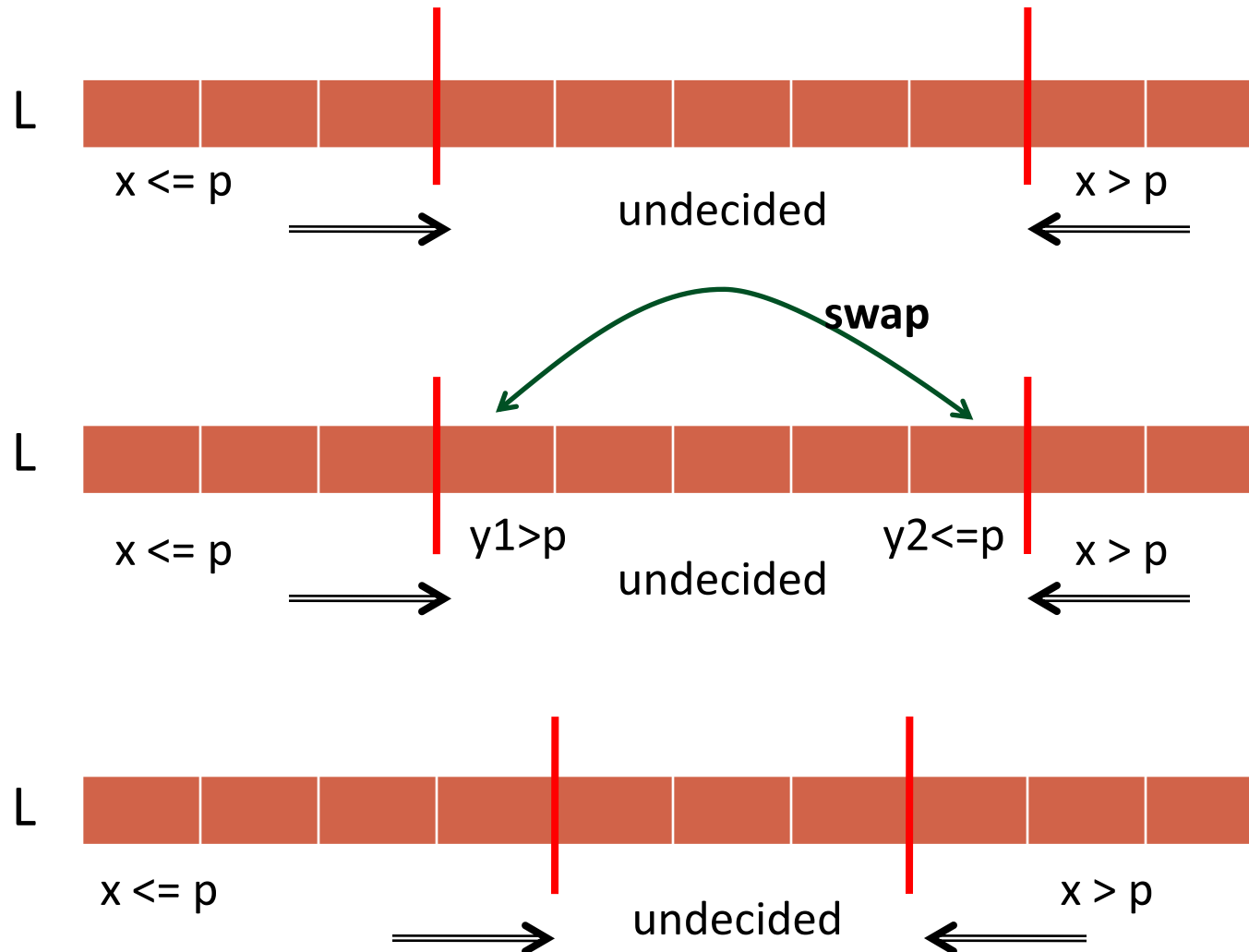
QUICKSORT

- Input: List of **N** elements **L[0], L[1], ... L[N-1]**
- Divide and Conquer:
 - Partition **L** into **LL** and **LG** based on a pivot **p** in **L** s.t. :
 - **LL = { x in L | x ≤ p }**
 - **LG = { x in L | x > p }**
 - Combine sorted versions of **LL** and **LG** and **{p}**:
 - Append: **LL, { p }, LG**
 - Append is trivial if **LL** & **LG** were sorted in place and **p** is in position
 - Sorting in place requires partitioning in place:
 - Question: How do you keep **p** in between?



QUICKSORT

- (Hoare's) Partitioning : (pivot p in L)



QUICKSORT

Input: List of elements $Ls[lo], \dots L[hi]$

$qs(Ls, lo, hi)$

{

 if ($lo < hi$) {

$p = \text{pivot}(Ls, lo, hi);$ // $Ls[p]$ is the pivot

$p = \text{part}(Ls, lo, hi, p);$ // $Ls[p]$ is the pivot

 /* ($Ls[j] \leq Ls[p]$ for j in $lo..pPos-1$) and
 ($Ls[j] > Ls[p]$ for j in $pPos+1..hi$)

 */

$qs(Ls, lo, p-1);$

$qs(Ls, p+1, hi);$

 }

}

QUICKSORT – TIME COMPLEXITY

○ Time Complexity of Partition:

- $\Theta(N)$ - /* # comparisons? # swaps? */

○ Quick Sort – Time - Worst case (recurrence relation):

- $T(N) = T(N-1) + \Theta(N)$ for $N > 1$
- $= \Theta(1)$ for $N = 1$

○ $T(N) = ?$

○ When does the worst case occur?

○ Quick Sort – Time - Best case (recurrence relation):

- $T(N) = 2 * T(N/2) + \Theta(N)$ for $N > 1$
- $= \Theta(1)$ for $N = 1$

○ $T(N) = ?$

○ When does the best case occur?

QUICKSORT – TIME COMPLEXITY

○ Average Case:

- By assuming input distributions to be random *one can compute the average case complexity.*
- Verify that $O(N*\log N)$ is a solution to recurrence relation:

$$\begin{aligned} \circ T(N) &= \Theta(N) + (1/N) * (\sum_{k=1 \text{ to } N} (T(k-1) + T(N-k))) \\ &\quad \text{for } N > 1 \end{aligned}$$

$$\circ T(N) = 1 \quad \text{for } N \leq 1$$

- But the time taken for a specific input depends heavily on the pivot(s) chosen for partitioning.

QUICKSORT : SPACE COMPLEXITY

- What is the depth of recursion?
 - Worst Case: $N-1$
 - Why?
 - Best Case: $\log_2 N$
 - Why?

QUICKSORT - CALL STACK OVERHEAD

Recursive version

```
void qs(Element ls[],
        int lo, int hi)
{
    if (lo < hi) {
        p = pivot(ls, lo, hi);
        p = part(ls, lo, hi, p);
        qs(ls, lo, p-1);
        qSort(ls, p+1, hi);
    }
}
```

Tail call elimination

```
void qs(Element ls[],
        int lo, int hi)
{
    while (lo < hi) {
        p = pivot(ls, lo, hi);
        p = part(ls, lo, hi, p);
        qs(ls, lo, p-1);
        lo = p+1;
    }
}
```

QUICKSORT - CALL STACK OVERHEAD

Recursive version (w/o tail calls)

```
void qs(Element ls[],
        int lo, int hi)
{
    while (lo < hi) {
        p = pivot(ls, lo, hi);
        p = part(ls, lo, hi, p);
        qs(ls, lo, p-1);
        lo = p+1;
    }
}
```

Iterative version (. explicit stack)

```
void qs(Element ls[], int lo, int hi)
{
    s = push(newStack(), (lo, hi));
    while (!isEmpty(s)) {
        (lo, hi) = top(s); s = pop(s);
        while (lo < hi) {
            p = pivot(ls, lo, hi, p);
            p = part(ls, lo, hi, p);
            s = push(s, (lo, p-1));
            lo = p+1;
        }
    }
}
```

QUICKSORT – SPACE COMPLEXITY

- 1. Avoid putting trivial lists on stack:
 - i.e. push only if $start < end$
- 2. Put the smaller of the two sub-lists on stack after each partitioning:
 - Every list is above a list that is (at least) twice as large
 - i.e. at most $\log_2 N$ items on stack at any point in time
 - where N is initial size.
- Exercise: Implement this version!

PARTITIONING

// Ls[lo..hi] is the input array; Ls[pInd] is the pivot

int partition(Ls, lo, hi, pInd)

{

 swap(Ls, pInd, lo);

 lt=lo+1; rt=hi; pv=Ls[lo];

 while (lt<rt) {

 for(; lt<=hi && Ls[lt]<=pv; lt++) ; // Ls[j]<=pv for j in lo..lt-1

 for(; Ls[rt]>pv; rt--) ; // Ls[j]>pv for j in rt+1..hi

 if (lt<rt) { swap(Ls, lt, rt); lt++; rt--; }

 }

 if (lt==rt) pPos=lt; else pPos=lt-1; // Do we need this? Is lt==rt possible?

 swap(Ls, lo, pPos);

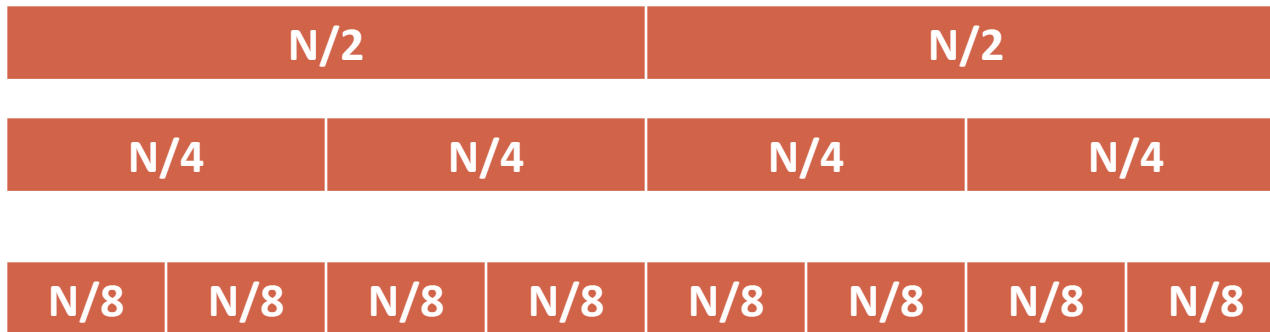
 //Postcond.: (Ls[j]<=pv for j in lo..pPos-1) and (Ls[j]>pv for j in pPos+1..hi)

 return pPos;

}

CASE ANALYSIS

- Best case Partitioning:



...

$\log N$ steps

Partitioning work in each step is $O(N)$

Time Complexity: $O(N \log N)$

CASE ANALYSIS

- Worst case Partitioning:



- ...

N-1 steps

Partitioning work in each step is $O(N)$

Time Complexity: $O(N*N)$

BALANCED PARTITIONING

- Better time complexity with balanced partitioning
- Consider the following example scenario:

.1N	0.9N		
	.09N	0.09N	0.81N

...

- Time Complexity:

$$\begin{aligned}T(N) &= T(N/10) + T(9N/10) + \Theta(N) \\&\leq 2 * T(9N/10) + \Theta(N) \\&= O(N * \log_{10/9} (N))\end{aligned}$$

PIVOT SELECTION

- Biased pivots result in unbalanced partition
 - Pivot p such that $p < x$ for most x in L
 - Symmetrically, $p > x$ for most x in L
- Static/Fixed techniques for pivot selection repeat the bias at every level
 - E.g. First element of the list as a pivot in a (mostly) sorted list
- De-biasing Solution:
 - Adaptive selection of pivots
 - Typically done by sampling the input

PIVOT SELECTION TECHNIQUES

○ Several Options

- Median of 3
 - This is still a fixed partitioning technique but it is a better sample than one location!
- Median of Medians
- QuickSelect (selecting Kth smallest element)
- Random

○ Cost of *partition* and cost of *pivot selection*

- Pivot selection should not take more time than partition
 - i.e. pivot selection should be done in $\theta(N)$

PIVOT SELECTION TECHNIQUES

○ Median of 3:

- Median of first, middle, and last element in the (sub)list
- Exclude these elements from partitioning process

○ Questions:

- Will this improve the time complexity of QuickSort?
- What is the minimum number of comparisons required for finding median of 3 values?

PIVOT SELECTION TECHNIQUES

○ Median of Medians:

- For every 5 contiguous elements find the median by direct comparison ==> $N/5$ medians
- Obtain the median of these $N/5$ medians

○ How?

- Sort? Why is this a bad idea?
- QuickSelect(Ls, N, N/2)?

○ Assume

- QuickSelect (Ls, N, K)
 - selects (and returns) the Kth smallest of N elements in Ls
- We will revisit this.

○ Impact of MoM:

- Will this reduce the complexity of QuickSort?

PIVOT SELECTION - QUICKSELECT

- QuickSelect(Ls,lo,hi,K) // selecting Kth smallest element
 1. $p = \text{pivot}(Ls, lo, hi);$ // $Ls[p]$ is the pivot
 2. $p = \text{partition}(Ls, lo, hi, p)$ // pivot is in its correct position p
 3. if $K == p$ done,
 if $K < p$ QuickSelect(Ls,lo,p-1,K);
 else QuickSelect(Ls,p+1,hi,K-p);

Q: What is the time complexity of QuickSelect?

Q: How do you ensure QuickSelect is done in optimal time?
i.e. How do you ensure the partition called in QuickSelect is balanced?

PIVOT SELECTION

○ Randomized QuickSort

- Select pivot index **uniformly randomly** between first and last (indices).
- Need a (good) random number generator

○ Is there a random number?

- Random sources
- Bit Selection
 - **Repeated coin toss**
- Cost of random number generation
- Pseudo-random number generators

○ Exercise:

- Assuming random pivot selection (in each call to partition):
 - Estimate the probability of the worst case behavior of QuickSort.
 - Estimate the probability of the best case behavior of QuickSort.

PARTITIONING

// Ls[lo..hi] is the input array; Ls[pInd] is the pivot

int partition(Ls, lo, hi, pInd)

{

 swap(Ls, pInd, lo);

 lt=lo+1; rt=hi; pv=Ls[lo];

 while (lt<rt) {

 for(; lt<=hi && Ls[lt]<=pv; lt++) ; // Ls[j]<=pv for j in lo..lt-1

 for(; Ls[rt]>pv; rt--) ; // Ls[j]>pv for j in rt+1..hi

 if (lt<rt) { swap(Ls, lt, rt); lt++; rt--; }

 }

 if (lt==rt) pPos=lt; else pPos=lt-1;

 swap(Ls, lo, pPos);

 //Postcond.: (Ls[j]<=pv for j in lo..pPos-1) and (Ls[j]>pv for j in pPos+1..hi)

 return pPos;

}

SMALL LISTS

- Insertion Sort performs better than QuickSort on small lists.
 - Why?
 - So, what?
- Combine the two!
 - Invoke Insertion Sort inside QuickSort when size of the list is small.
 - Time Complexity (expected):
 - $O(k * k * (N/k) + N * \log(N))$
 - where k is the threshold (below which InsertionSort performs better than QuickSort)
- Alternatively, ignore, small sized lists inside QuickSort, and do an insertion Sort (on the full list)
 - Question: Why does this work (efficiently)?
 - Question: What is the time complexity?

EQUAL VALUES

- QuickSort performs badly when the same key occurs multiple times
- Solution: 3-way partition
 - Maintain an additional partition for elements equal to the pivot
 - Exercise: Implement this!

