

MCG 4322A

Optimization Tutorial

In advance of the tutorial session, do the following:

1. Set up the client software for uOttawa's RemoteLabs https://it.uottawa.ca/students/remote_labs .
2. It is strongly advised to use **the student network drive** for all files (H: or Z:) and follow the given file organization scheme.
3. Download the GUI template files from Brightspace, save it to the remote H: or Z: drive, then extract the zip file.
4. With RemoteLabs, start Solidworks app, new part file.
5. Also with RemoteLabs, start Matlab, open the folder containing the GUI template files.

Remote Apps state as of 2024

Seriously, carefully read the documentation for this!

<https://www.uottawa.ca/faculty-engineering/it-services/remote-apps>

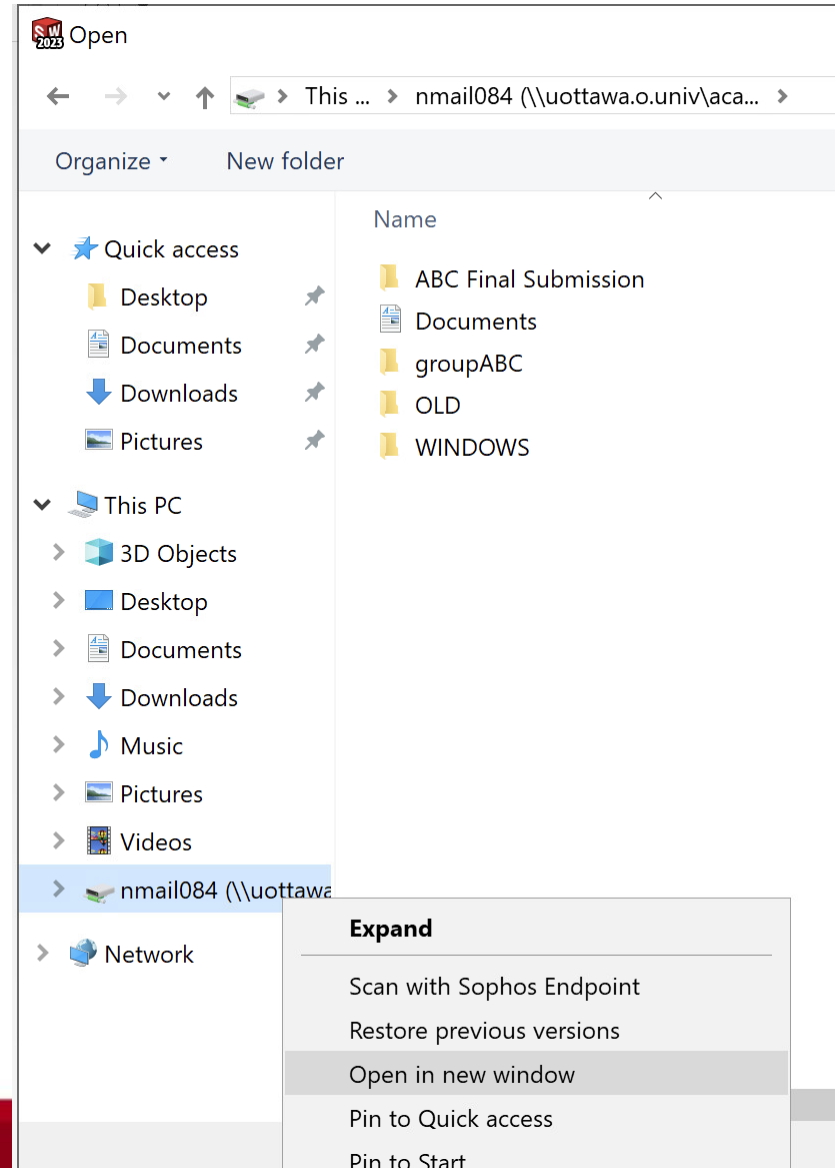
Most important points up front:

1. It is essential to set up a remote desktop client to enable the recommended file transfer between your local drive and remote drive.
2. Work with a good, stable internet connection.
3. Solidworks and Matlab is the most consistently functional when using files on your student network drive (H: or Z:) .
4. **Save OFTEN.** Historically, bad network connections and Solidworks being Solidworks have caused the most tears to be shed when students lose their work.

Remote Apps file system

To access the remote file explorer:

- Pick any "open file/folder" prompt in the software you have started,
- Right click your remote drive,
- Select "open in new window",
- A new windows file explorer window will open!





Open



H:\



Organize ▾

New



3D Objects



Desktop



Documents



Downloads



Music



Pictures



Videos



nmail084 (\\uott)

H:\ABC Final Submission

H:\ABC Final Submission.zip

H:\Documents

H:\groupABC

H:\OLD

H:\WINDOWS

groupABC

OLD

WINDOWS



uOttawa

Use YOUR uOttawa network drive!!!

Do use

uOttawa network drive (Network locations)

- **You should use this drive** for saving your work, because it is the fastest and because it is available to you across campus on all lab computers.
- In Remote Apps, the location of your network drive should start with **\\uottawa.o.univ\acadhomes\...** This is your uOttawa network drive, to which the Remote App server has high-speed access.
- This appears as under Network locations as your Z: drive if you are a student, or or H: drive if you are an employee.

Avoid using

Personal computer drives (Devices and drives)

These are drives on your personal computer. Although it is convenient to access files stored on your personal computer with Remote Apps, we recommend not using them directly with remote applications for performance reasons: When you use Remote Apps, the application displayed is running on a server within the University's network. Files on your computer will be accessed via network using the RDP protocol, which is not designed for fast file access. This considerably reduces the performance of your remote session. We recommend instead that you transfer your files to your uOttawa network drive (Z:), then open them from that location.

Remote App server folders (Folders)

You should never use these folders to store your files. Files saved in these folders will be destroyed at the end of your remote session.

To make the point clear

Saving files in the Network drive is better (Z: or H: drive). It's faster since it is on the same network as the remote apps tool itself. This will make a big difference in using Solidworks. Save your work here, as you go along.

Saving files on your local drive is worse (C: drive). Using this drive will affect performance especially with applications that frequently write to the file - like Solidworks, since all of the file information must traverse much slower networks to get to and from your local machine.

File transfer between local and remote drive

As simple as copy and pasting files between windows...

But only if you have set up permissions for the remote client app, client and system dependent!

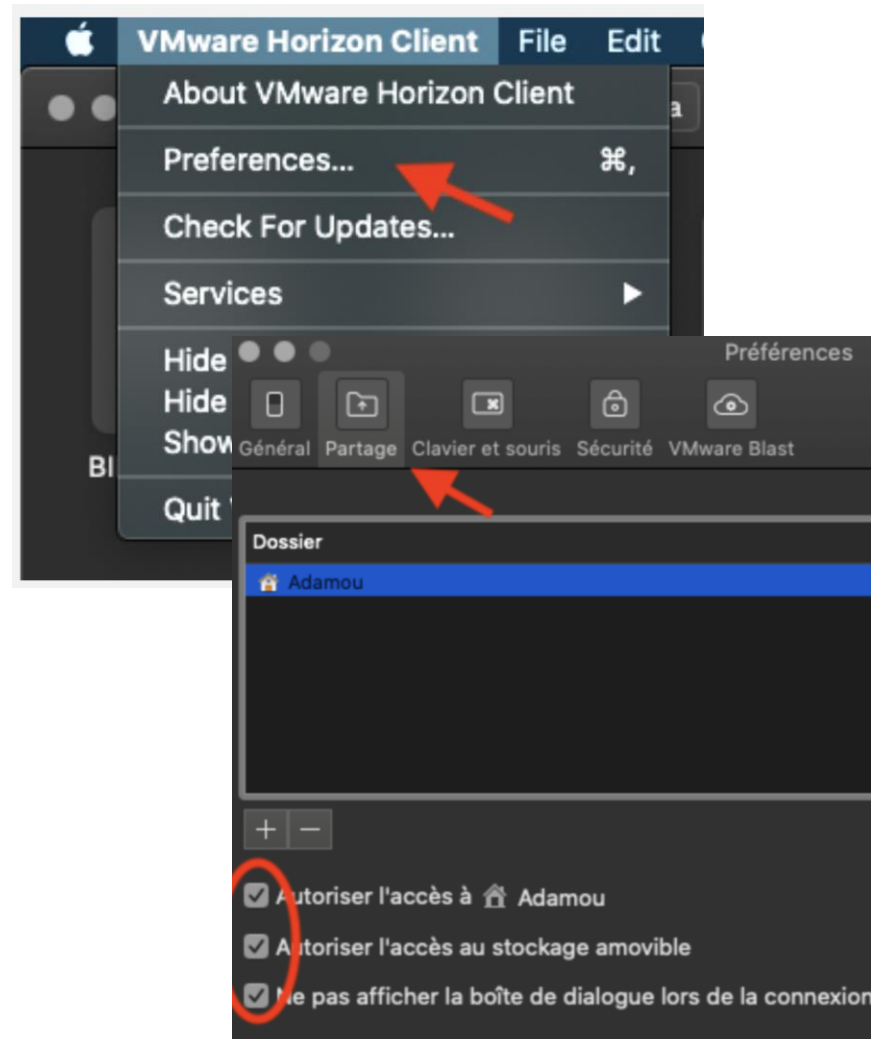
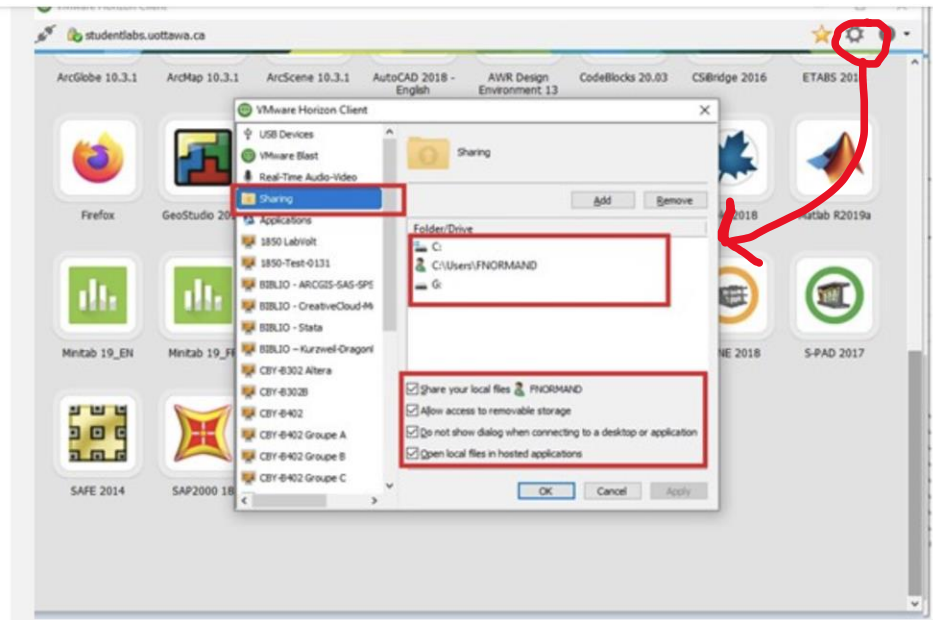
<https://www.uottawa.ca/about-us/information-technology/remote/lab>

Steps

On this page you will find how to connect to the portal from your personal devices and work efficiently with the University's licensed softwares and applications.

Before using uOlabsPlus: You will need to self-enrol your account for Multi-Factor Authentication (MFA).

File transfer between local and remote drive



Purpose of Algorithmic Design Optimization

Algorithmic design optimization allows us to automatically:

- Verify the entire analysis for operational criteria.
- Check if the design can be adapted for situations adjacent to nominal operation.
- Improve the robustness of your CAD model for changes from algorithmic process.

A critical tool for *efficient* mechanical design

Relationship between Parametric Design and Optimization

Parametrize

To express in terms of parameters.

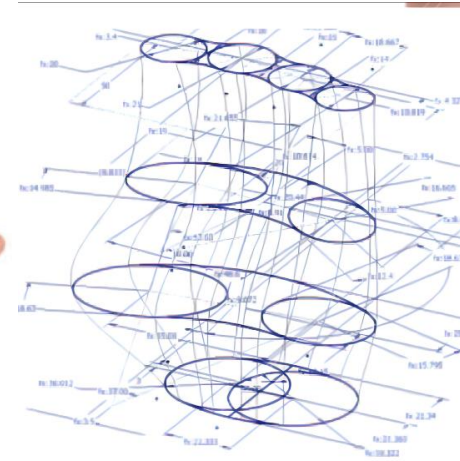
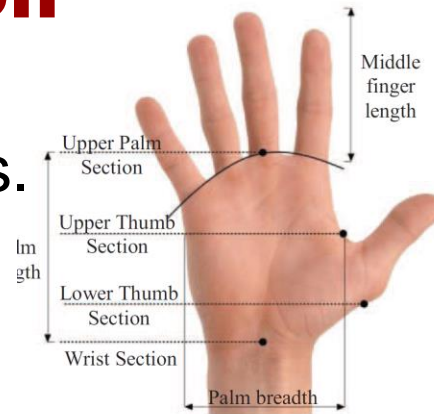
Parametrization

Process to express a model as a function of a set of independent quantities, i.e. the *parameters*.

Parametric design

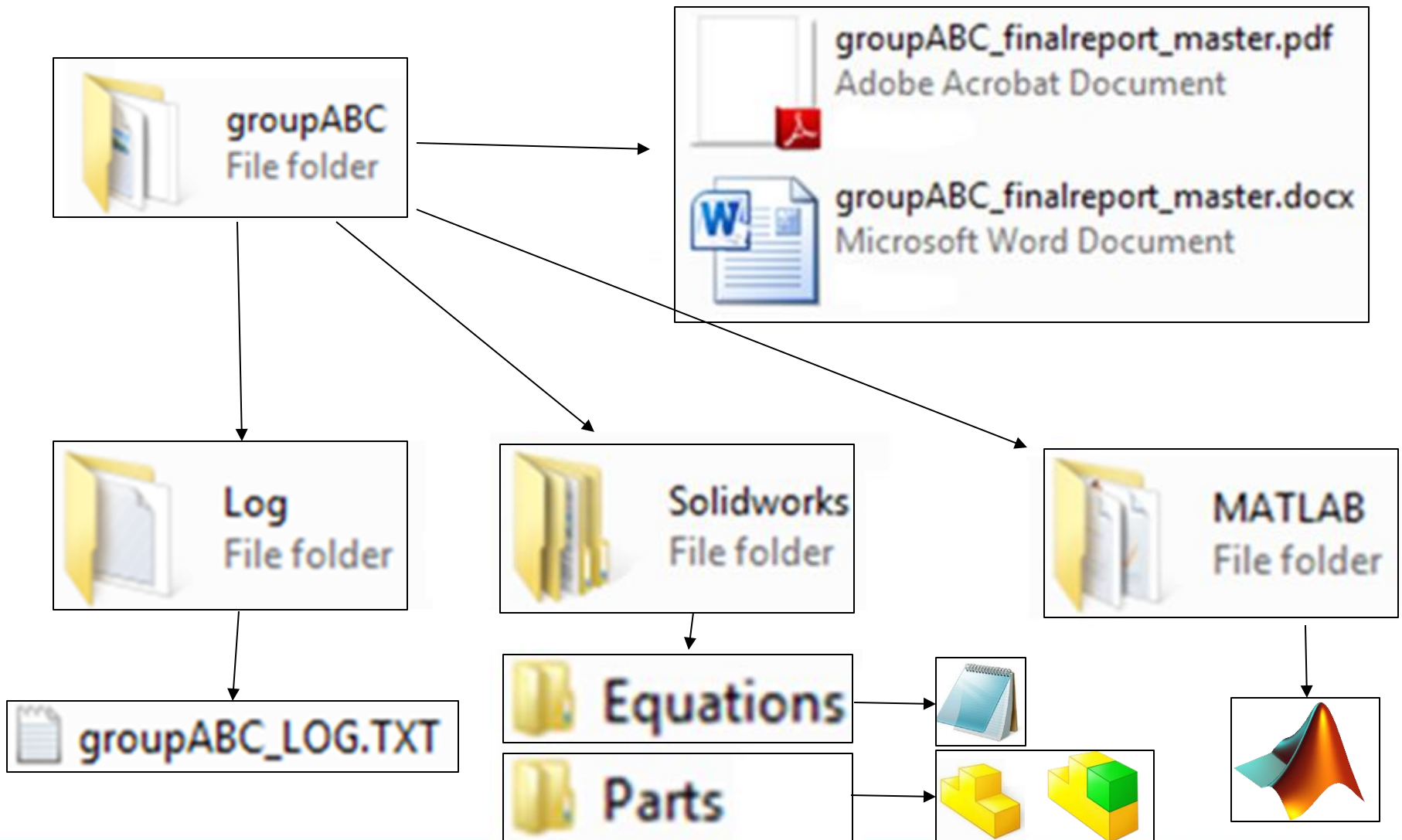
A set of parameters defines an optimal candidate via algorithmic procedure,

e.g. hand prosthesis design



M. Bustamante et al., "A Parametric 3D-Printed Body-Powered Hand Prosthesis Based on the Four-Bar Linkage Mechanism," *2018 IEEE 18th International Conference on Bioinformatics and Bioengineering (BIBE)*, 2018, pp. 79-85.

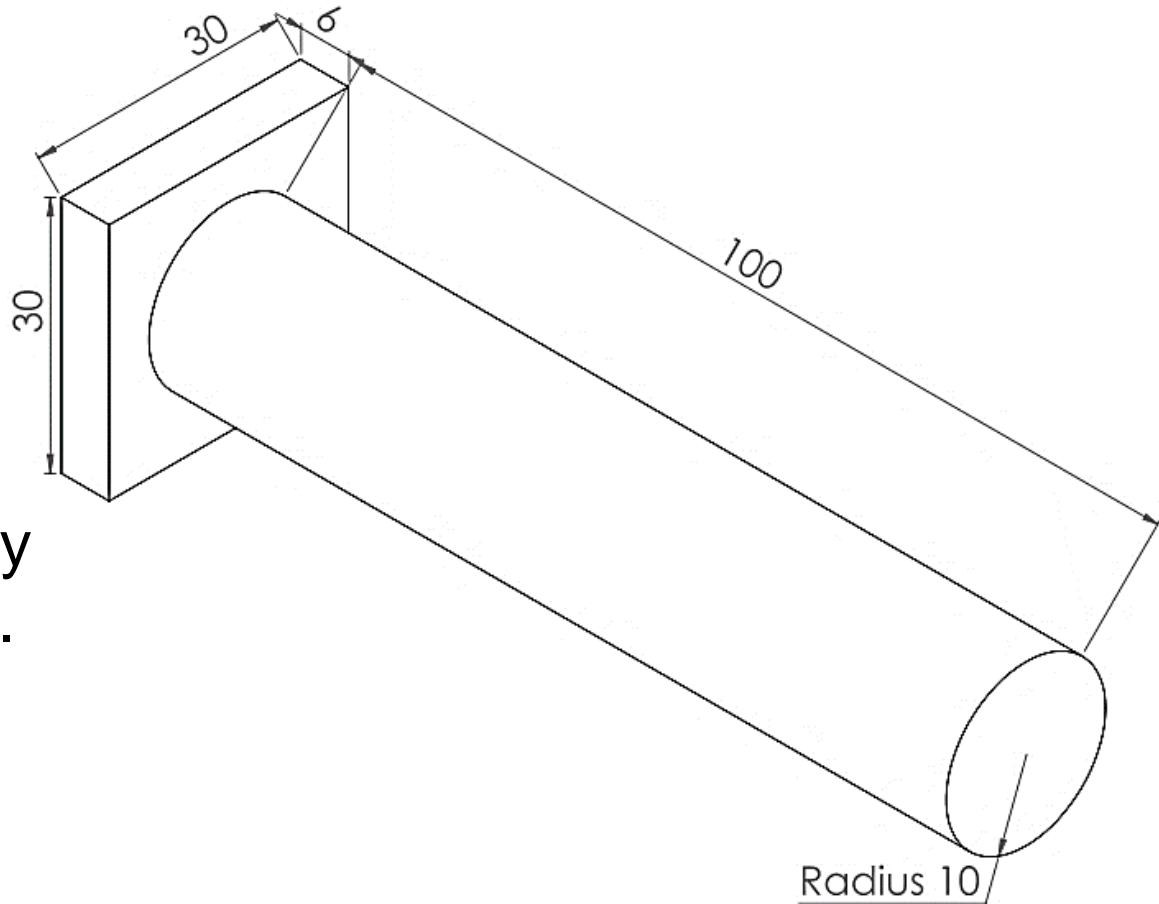
Required Final Submission File Organization



Step 1: Draft a cantilever beam

In Solidworks, model a beam with the following:

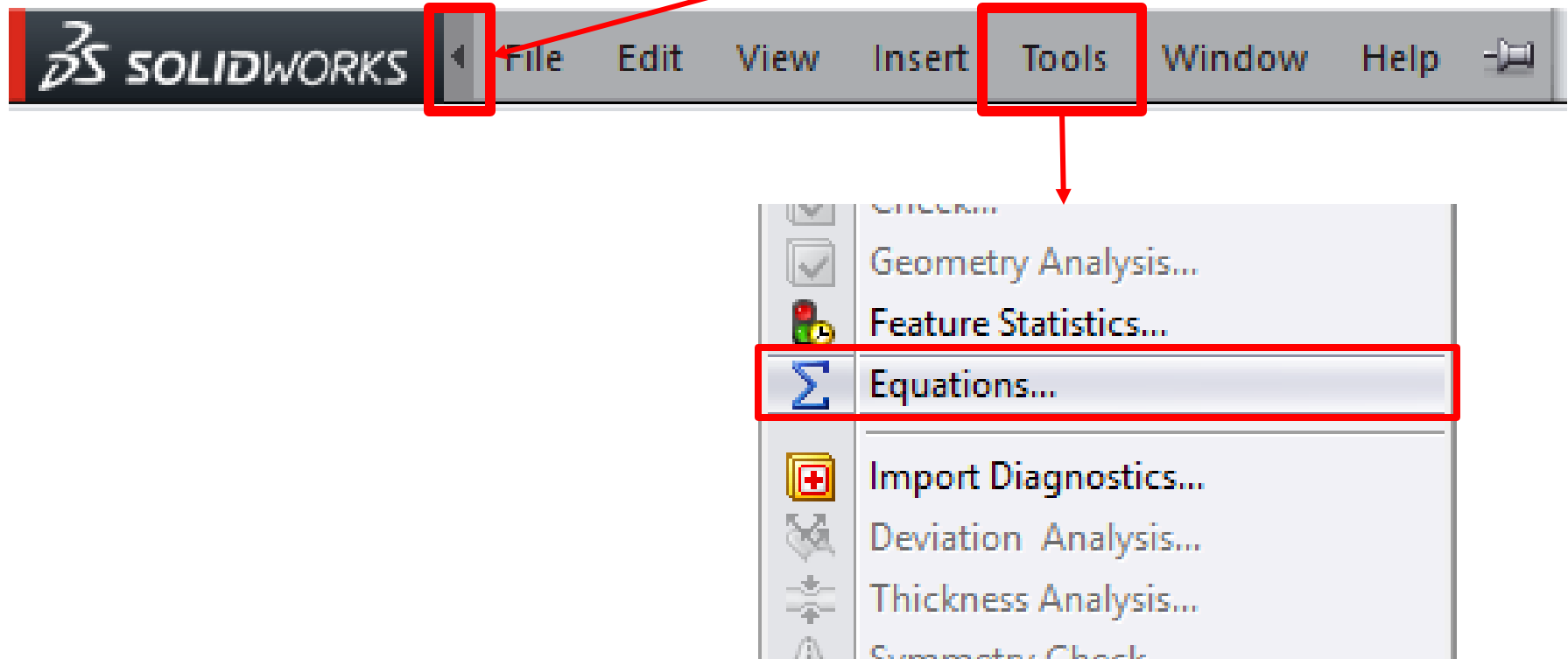
- Round cross section with 20mm diameter and 100mm length,
- Square base 30mm by 30 mm by 6 mm thick.



Save as: *shaft.sldprt*
in H:/groupABC/Solidworks/Parts

Step 2: Declaring global variables

In top toolbar, hover over the arrow and navigate to Tools → Equations









Step 2: Declaring global variables




Add two variables with exactly these names/values:


“Diameter” = 20 mm

“Length” = 100 mm

Equations, Global Variables, and Dimensions

    Filter All Fields  

Name	Value / Equation	Evaluates to	Comments
 Global Variables			
 Features			
Add feature suppression			
 Equations			
Add equation			

☐ Automatically rebuild  Angular equation units: Degrees ☒ Automatic solve order

☐ Link to external file:

OK
Cancel
Import...
Export...
Help

Step 2: Declaring global variables

Add two variables with exactly these names/values:

“Diameter”







= 20 mm

“Length”


= 100 mm

When done, hit
‘OK’

Equations, Global Variables, and Dimensions

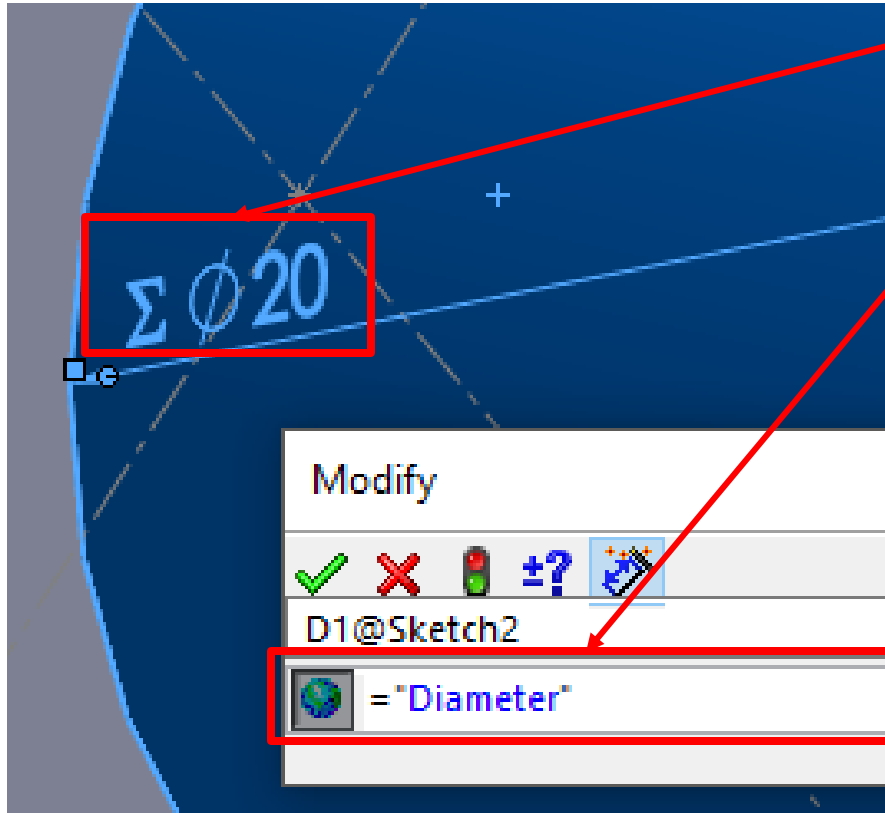
Name	Value / Equation	Evaluates to	Comments
Global Variables			
"Diameter"	= 20	20	
"Length"	= 100	100	
<i>Add global variable</i>			
Features			
<i>Add feature suppression</i>			
Equations			
<i>Add equation</i>			

☐ Automatically rebuild  Angular equation units: ☒ Automatic solve order

☐ Link to external file:

OK
Cancel
Import...
Export...
Help

Step 3: Link dimension to a variable



- Double click beam diameter dimension,
- Click on input value field, type exactly:
= "Diameter"
- Assign beam length dimension, exactly:
= "Length"


Variables are now linked to dimensions!

Indicated by the sigma Σ , next to the dimension.

Step 4: Linking variables to text file

- Go back to the Equations menu,
(Tools → Equations)
- Bottom left, click “Link to external file:”
- The “Link Equations” pop-up menu will open.

	"Diameter"	= 20
	"Length"	= 100
	Add global variable	
<input type="checkbox"/>	Features	
	Add feature suppression	
<input type="checkbox"/>	Equations	
	Add equation	

☐ Automatically rebuild  Angular equation units: Degree

☐ Link to external file:

Link Equations

☐ Link to existing file
☒ Create new file

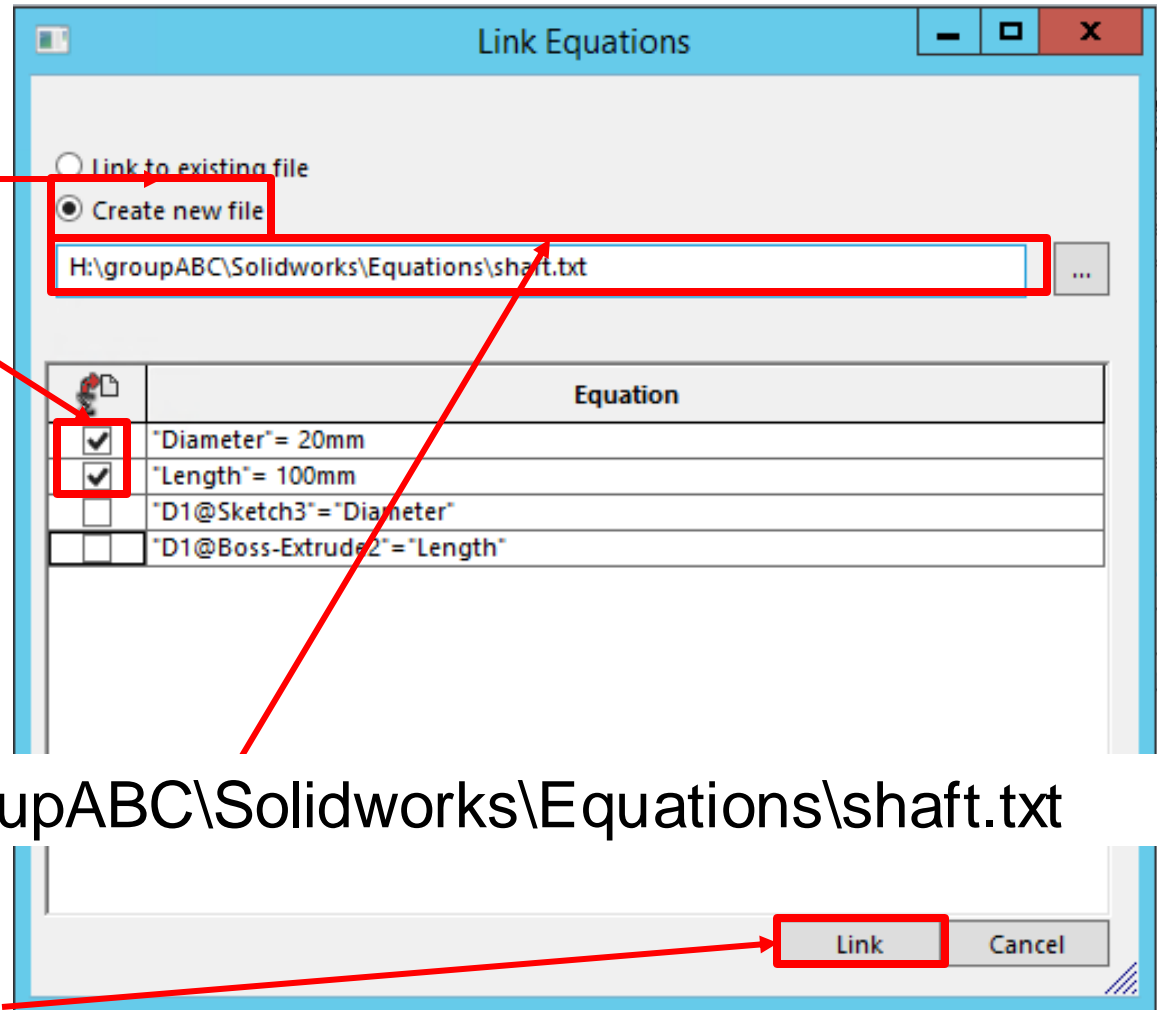
H:\groupABC\Solidworks\Equations\shaft.txt

	Equation
<input checked="" type="checkbox"/>	"Diameter" = 20mm
<input checked="" type="checkbox"/>	"Length" = 100mm
<input type="checkbox"/>	"D1@Sketch3" = "Diameter"
<input type="checkbox"/>	"D1@Boss-Extrude2" = "Length"

Link Cancel

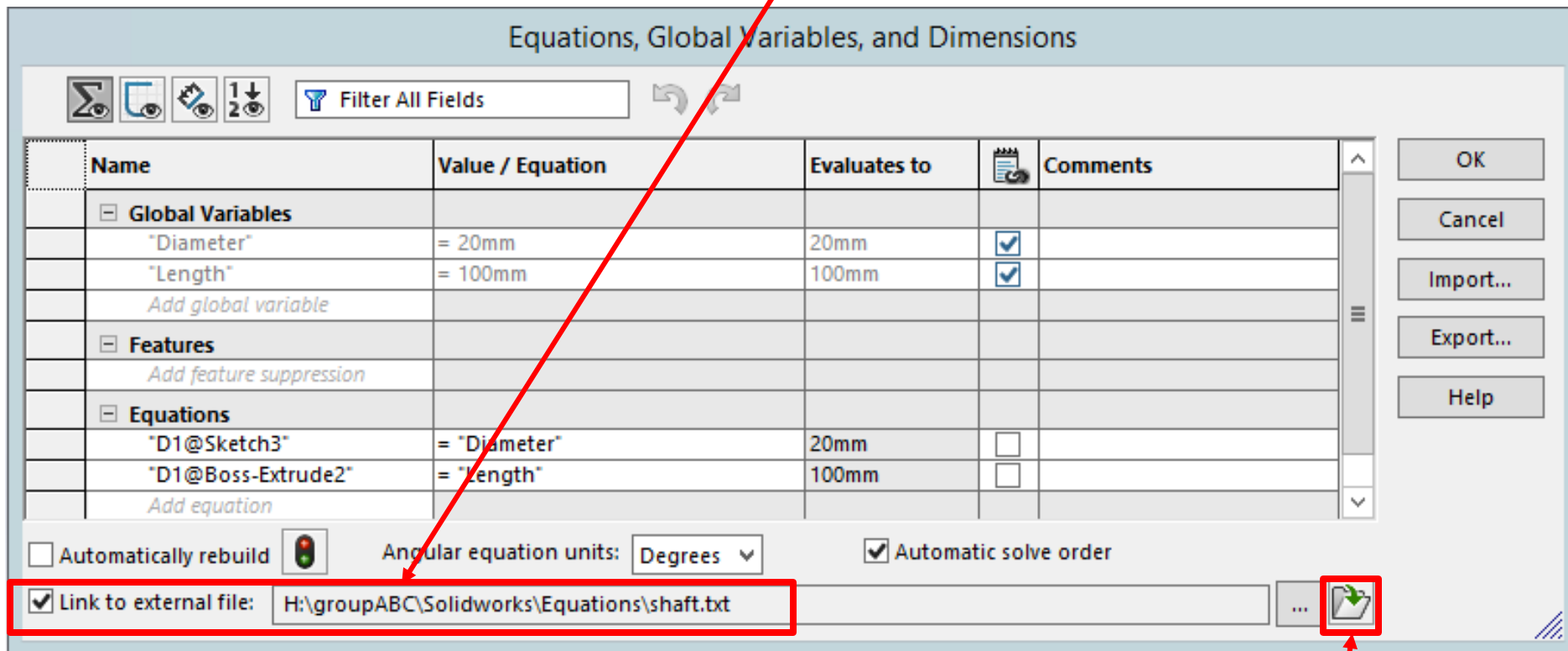
Step 4: Linking variables to text file

- Select 'Create new file',
- **Only** select variable entries,
- Define new text file, with the **correct** filepath:
<DIRECT-PREFIX>\groupABC\Solidworks\Equations\shaft.txt
- Hit 'Link' Button. Should now have new file in folder.



Step 4: Linking variables to text file

Checkbox filled and the file path included if all is good.



Next, click this to open linked text file, or open it directly from shared local drive.

Step 5: Change text file, rebuild part

- Change dimension values,
- Keep identical format, change **only** numerical values.
- Save the text file,
- Rebuild Solidworks part...



...hopefully...

...it has changed!

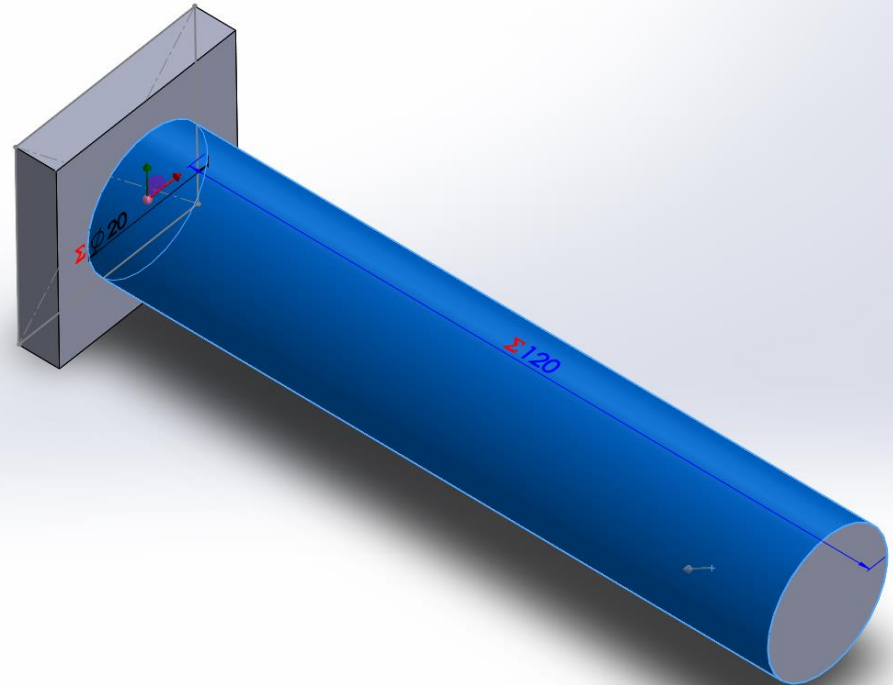


shaft - Notepad

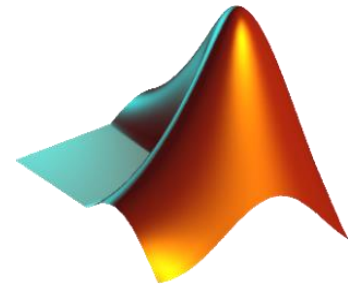
File Edit Format View

"Diameter"=20

"Length"= 120



Code expectations

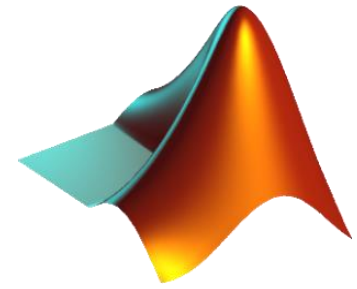


IMPORTANT: Include Code comments with MATLAB code

In MCG4322A:

- All code has to be done with MATLAB, no Octave, Python, etc.
- Code comments are required, keep clear and concise.
- Informs reviewers (e.g. the course instructor, T.A.s) on the purpose of the code.
- Assist with the debugging process, by clearly describing the intended purpose of code.

MATLAB GUI Template



The template's MATLAB folder consist of two files:

1. MAIN.mlapp

- Graphic User Interface (GUI) template,
- uses MATLAB's built-in 'App Designer' tool,
- passes user selected parameters to Design_code.m,
- displays log file generated by Design_code.m ,

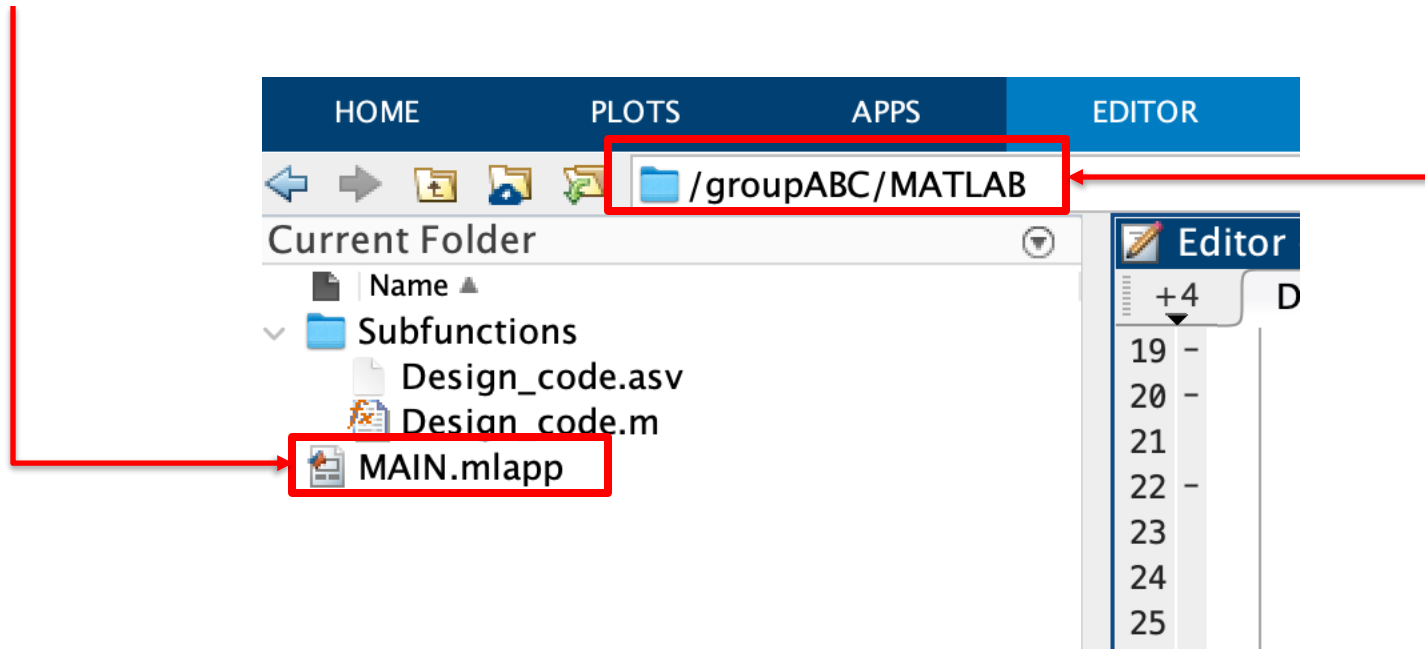
<https://www.mathworks.com/help/matlab/app-designer.html>

2. Subfunctions folder

- Contains Design_code.m, (and other files you may add),
- Design code is where ALL the analysis equations, functions, and optimization algorithms are programmed.

Step 6: MATLAB file navigation

1. In current directory field, input project MATLAB folder directory, ... \groupABC\MATLAB,
2. Current folder pane shows file structure.
3. Open MAIN.mlapp

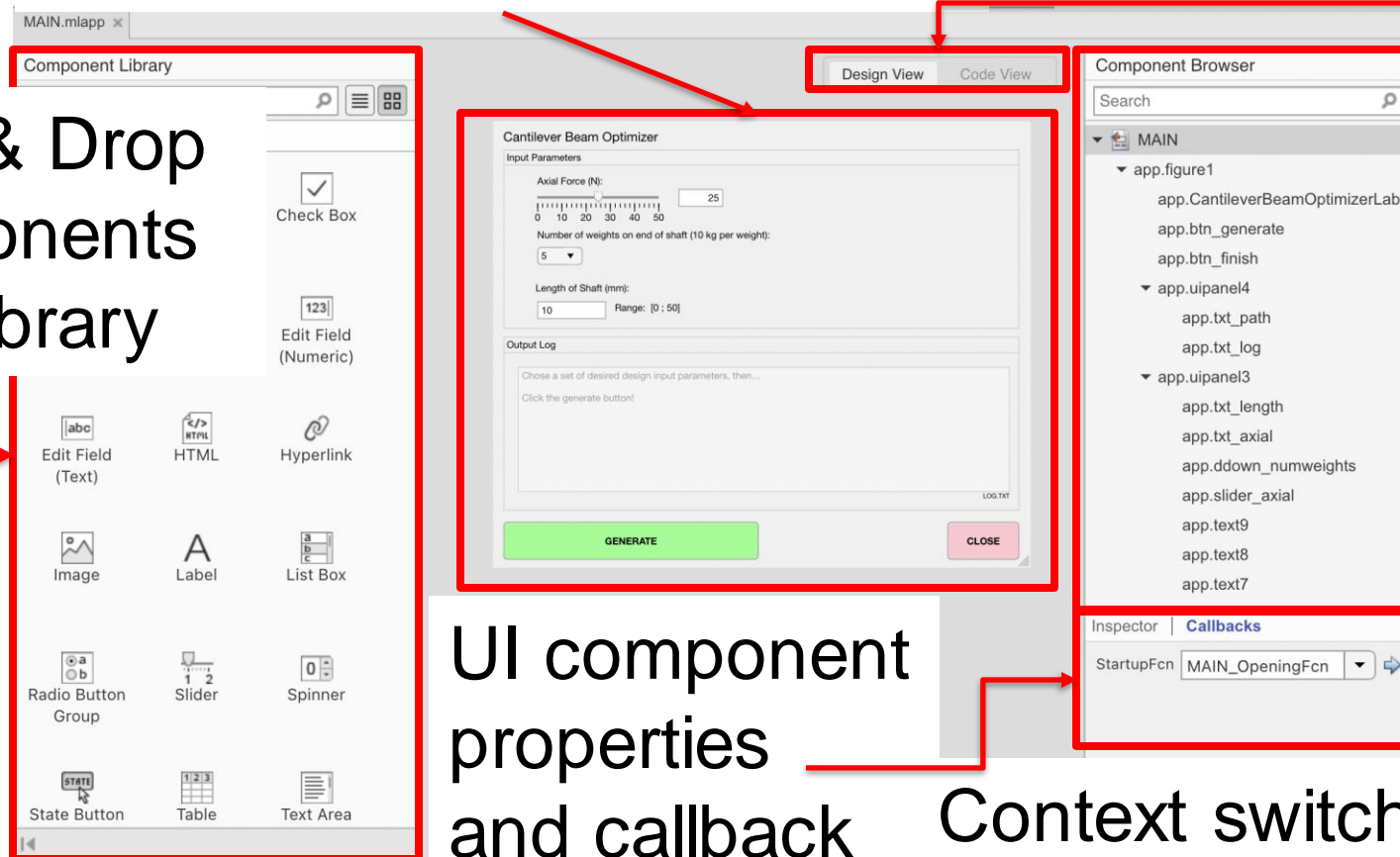


Step 7: App Designer – design interface

Dynamic selection of UI elements to be modified

UI component browser tree

Drag & Drop components from library



UI component properties and callback functions

Context switcher ... select 'Code View'

Step 8: App Designer – code interface

Code that
GUI uses

The screenshot displays the MATLAB App Designer interface. On the left, the 'Code Browser' is visible, listing various callback functions such as 'MAIN_OpeningFcn', 'btn_finish_Callback', and 'btn_generate_Callback'. Below it, the 'App Layout' shows a graphical representation of the app's UI, including input parameters and output logs. The central 'Code View' displays the MATLAB code for the app, starting with a class definition for 'MAIN' that inherits from 'matlab.apps.AppBase'. The code includes properties for various UI components and methods for handling callbacks. On the right, the 'Component Browser' lists the components used in the app, such as 'app.figure1', 'app.CantileverBeamOptimizerLabel', and 'app.btn_generate'. The 'Inspector' panel at the bottom right shows the 'Callbacks' tab, indicating the 'StartupFcn' is 'MAIN_OpeningFcn'.

```
1 classdef MAIN < matlab.apps.AppBase
2
3     % Properties that correspond to app components
4     properties (Access = public)
5         figure1          matlab.ui.Figure
6         CantileverBeamOptimizerLabel matlab.ui.control.Label
7         btn_generate      matlab.ui.control.Button
8         btn_finish        matlab.ui.control.Button
9         uipanel4          matlab.ui.container.Panel
10        txt_path           matlab.ui.control.Label
11        txt_log            matlab.ui.control.TextArea
12        uipanel3          matlab.ui.container.Panel
13        txt_length         matlab.ui.control.NumericEditField
14        txt_axial          matlab.ui.control.NumericEditField
15        ddown_numweights  matlab.ui.control.DropDown
16        slider_axial       matlab.ui.control.Slider
17        text9              matlab.ui.control.Label
18        text8              matlab.ui.control.Label
19        text7              matlab.ui.control.Label
20        text6              matlab.ui.control.Label
21    end
22
23    methods (Access = private)
24        % =====
25        % =====
26        % =====
27        % =====
28        % =====
29        % =====
30        % =====
31        % =====
32        % =====
33        % =====
34        % =====
35        % =====
36        % =====
37        % =====
38    end
```

Left side now shows 'Code Browser',

- auto generated by added UI callbacks,
- right click -> delete to remove callback functions

Step 9: Translate GUI inputs to code

Template GUI has 3 input elements corresponding to three parameters.

1. *Slider*

Takes the axial force acting on cantilever beam.

2. *Drop down list*

Selection from a range of possible number of weights hanging on the end of beam.

3. *Edit text field*

Reads the value input into the text box for shaft length.

The screenshot shows a GUI titled "Cantilever Beam Optimizer" with an "Input Parameters" section. It contains three input elements: a slider for "Axial Force (N)" with a range from 0 to 50 and a value of 25; a drop-down list for "Number of weights on end of shaft (10 kg per weight)" with a value of 5; and a text field for "Length of Shaft (mm)" with a value of 10 and a range of [0 ; 50]. Red boxes and arrows highlight these elements, mapping them to the text descriptions on the left. Below the input parameters is an "Output Log" section with the text: "Chose a set of desired design input parameters, then..." and "Click the generate button!".

Step 9: Translate GUI inputs to code

Specific examples of code in MAIN.mlapp

- Lines 109-113, we define variables for each input by reading values from GUI

```
axial_force = app.slider_axial.Value;
```

- Line 117, we call the Design_code subfunction, passing our inputs as *arguments*.

```
Design_code(axial_force, num_weights,  
shaft_length)
```

- Lines 122-130, we display output of log file.

```
log_contents = char(fread(fid)') ;
```

Step 10: Analysis and design code

1. Open the **Design_code.m** file,
2. Line 1, function definition. Arguments: only sequence and data types matter.

```
function Design_code(axial_force,  
    number_of_weights, shaft_length)
```
3. Line 16, call the shaft optimization subfunction
4. This function *returns* an output, the optimized shaft diameter,

Study the optimization algorithm example at the end of the file in the subfunction definition.

Step 10: Analysis and design code

Design_code.m represents an example for a **single** analysis calculation set.

You will use **many separate files**, with each corresponding to each set of analysis calculations from your analysis report.

In other words, many design code subfunctions.

This approach ensures that your analysis calculations are easy to review independently.

Step 11: Modify text files with MATLAB

We use MATLAB built-in text editing functions to write to the equation and log text files.

- Directories are hard-coded, so if you change them you need to update code accordingly,
- Text output from MATLAB code **must have the same format** as the original SW's equation file,
- Common errors: Changing character spacing, incorrect variable names, changing line order/spacing, missing variables,

Verify! When MATLAB changes equation file, check that Solidworks rebuilds properly for all scenarios.

Step 11: Modify text files with MATLAB

How to access text files with MATLAB code:

1. Save directory prefix (Required only once per function)

```
directory_prefix_string = extractBefore(pwd,  
                                         "groupABC");
```

2. Define the filepath of text file to be modified, save into string variable:

```
your_file =  
    strcat(directory_prefix_string, '\groupABC\  
FOLDER\YOURFILE.TXT');
```

3. Use string variable to open text file for writing:

```
fid = fopen(your_file, 'w+t');
```


Step 11: Modify text files with MATLAB

How to write to text files with MATLAB code:

4. Use `fprintf()` to write to the text file:

```
fprintf(fid, strcat('Your text goes here', ...  
                    num2str(x), '\n'));
```

- `strcat` combine multiple strings and variables into a single string
- <https://www.mathworks.com/help/matlab/ref/fprintf.html>

5. When done writing to file, terminate the filestream:

```
fclose(fid);
```

Step 12: Log text file for results output


The output log file is where you display all results. The log text file is your responsibility to format. Make sure that it is:

- clear and human-readable,
- input parameters selected by user are displayed first,
- displays full set of calculated outputs, including values that do not reflect as Solidworks model changes.

Be creative and optimize for at-a-glance information!

Example of Completed Optimization GUI

Group RE1 // CAD/CAM 2015



uOttawa

Team Research and Development

Software by: Nathaniel Mailhot, Ali Sayed, Ibrahim El Wattar, Kirsten Campbell
December 10 2015

Input parameters for design:

Select maximum altitude of airship (m):	[10:1000]
<input type="text"/>	<input type="text" value="10"/>
Select atmospheric temperature (deg C):	[-15:50]
<input type="text"/>	<input type="text" value="-15"/>
Select continuous runtime (hours):	[2,4,6,8,10,12]
<input type="text"/>	<input type="text" value="2"/>
Enter desired operational speed of airship in calm winds (m/s):	[3:10]
<input type="text"/>	<input type="text" value="3"/>
Enter maximum payload length within cargo bay (cm):	[12:50]
<input type="text"/>	<input type="text" value="12"/>
Enter payload mass (g):	[500:1000]
<input type="text"/>	<input type="text" value="500"/>

Output log:

```
***Mass, volume, lift and pitch***  
Total mass of airship: 5.7601 kg.  
Total volume of envelope: 4.7393 m3.  
Volume estimation accuracy: 114.042 Total lift of airship= 5.7601 kgf  
Pitch range: [-10.8671: 7.145] deg.  
Number of AA batteries: 6.  
  
***Envelope, frame and fin size***  
Cylinder and sphere radius= 713.1118 mm.  
Cylinder length= 2039.4997 mm.
```

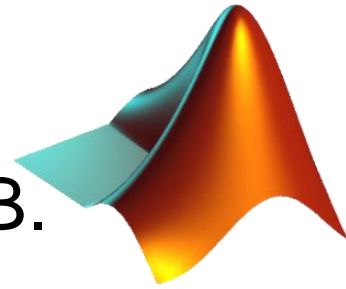
C:\groupRE1\Log\groupRE1_LOG.TXT

GENERATE DESIGN

FINISH AND CLOSE INTERFACE

Minimum number of significant design parameters is three, more is good.

Debugging MATLAB



Brief, live example of debugging with MATLAB.

- Play
- Console input, output and workspace context
- Step
- Continue
- End

Documentation (extremely useful to save you time!)

https://www.mathworks.com/help/matlab/matlab_prog/debugging-process-and-features.html

https://www.mathworks.com/help/matlab/matlab_prog/set-breakpoints.html

https://www.mathworks.com/help/matlab/matlab_prog/examine-values.html