



## Sonia Massa

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### WORK EXPERIENCE

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🏢 **Politecnico di Milano (NEARLab) - Rehab Tech Lab (IIT)**

#### PhD Student

[ 05/2025 – Current ]

🏢 **Istituto Italiano di Tecnologia - IIT**

#### Research Fellow

[ 10/2024 – 05/2025 ]

*Research title:* "Development of control algorithms for upper limb prosthesis with integrated systems."

🏢 **Università degli studi di Cagliari**

#### Research assistant

[ 05/2022 – 09/2022 ]

*Research Grant Title:* "Study of eye movements during motor tasks administered in a virtual environment with visual feedback perturbations."

*Project Title:* "RiPARTO – Tele-rehabilitation through visual feedback perturbations for the upper limb."

### EDUCATION AND TRAINING

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#### Master's degree in Bioengineering (Neuroengineering – Rehabilitation engineering and interaction technologies)

**Università degli studi di Genova** [ 09/2022 – 10/2024 ]

Field(s) of study: Biomedical Prosthetics and Robotic Rehabilitation | **Thesis:** From grasping to manipulation: synergy analysis and musculoskeletal modeling (carried out at: Rehab Technologies Lab (IIT))

#### Bachelor's degree in Biomedical Engineering

**Università degli studi di Cagliari** [ 09/2018 – 04/2022 ]

Field(s) of study: Neuroengineering and Neurorehabilitation | **Thesis:** Study and Implementation of MATLAB Software Modules for the Study of Ocular Motility

### LANGUAGE SKILLS

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**Mother tongue(s):** Italian

**Other language(s):**

**English**

**LISTENING** C1 **READING** C2 **WRITING** C1

**SPOKEN PRODUCTION** C1 **SPOKEN INTERACTION** C1

*Levels: A1 and A2: Basic user - B1 and B2: Independent user - C1 and C2: Proficient user*

## PUBLICATIONS

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### **From grasping to manipulation: Kinematic synergy analysis for advanced prosthetics.**

Massa, S., Marinelli, A., Laffranchi, M., Boccardo, N., & Sanguineti, V. (2025). ***From grasping to manipulation: Kinematic synergy analysis for advanced prosthetics***, 47th Annual International Conference of the IEEE Engineering in Medicine and Biology Society EMBC2025.

47th Annual International Conference of the IEEE Engineering in Medicine and Biology Society

### **EyeLab: a user friendly Matlab graphical user interface for real-time eye movements studies**

Sedda G., Olla G., Massa S., Raffo L., Traccis S., & Pani D. (2022, December). ***EyeLab: a user-friendly Matlab graphical user interface for real-time eye movements studies***. In *PERCEPTION* (Vol. 51, pp. 95-95). 1 OLIVERS YARD, 55 CITY ROAD, LONDON EC1Y 1SP, ENGLAND: SAGE PUBLICATIONS LTD.

ECVP 2022 - European Conference on Visual Perception 2022