


Quantum Physics II: Angular Momentum in Real Space

Lecture notes 2020-21



REVISÕES [~]MOMENTO ANGULAR NO ESPAÇO REAL

$$\hat{L}^2 = -\hbar^2 \left[\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\hbar^2 \sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right]$$

$$\hat{L}^2 |l, m\rangle = \hbar^2 l(l+1) |l, m\rangle$$

Fazendo o produto interno com $\langle\theta, \varphi|$

$$\begin{aligned} \langle\theta, \varphi| \hat{L}^2 |l, m\rangle &= \hat{L}^2 \langle\theta, \varphi| l, m\rangle \\ &= \hat{L}^2 Y_{l, m}(\theta, \varphi) = \hbar^2 l(l+1) Y_{l, m} \end{aligned}$$

↓ harmônicos esféricos

Qual a forma de $\hat{\vec{L}}$?

$$\vec{L} = \vec{r} \times \vec{p} ; \quad \vec{p} = -i\hbar \vec{\nabla}$$

$$\vec{r} = r \hat{u}_r \quad (\text{coordenadas esféricas})$$

$$\vec{p} = -i\hbar \left(\hat{u}_r \frac{\partial}{\partial r} + \hat{u}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{u}_\varphi \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} \right)$$

(coordenadas esféricas)

$\hat{u}_r, \hat{u}_\theta, \hat{u}_\varphi \rightarrow \text{senhores}$

$$\vec{L} = \vec{r} \times \vec{p} =$$

$$= -i\hbar \left(\hat{u}_\varphi \frac{\partial}{\partial \theta} - \hat{u}_\theta \frac{1}{\sin \theta} \frac{\partial}{\partial \varphi} \right)$$

$$\hat{L}_z = \hat{u}_z \cdot \hat{\vec{L}} = -i\hbar \frac{\partial}{\partial \varphi}$$

$$\hat{L}_x = -i\hbar \left(-\sin\varphi \frac{\partial}{\partial \theta} - \cot\theta \cos\varphi \frac{\partial}{\partial \varphi} \right)$$

$$\hat{L}_y = -i\hbar \left(\cos\varphi \frac{\partial}{\partial \theta} - \cot\theta \sin\varphi \frac{\partial}{\partial \varphi} \right)$$

Eg. valores próprios

$$\hat{L}_z Y_{lm}(\theta, \varphi) = -i\hbar \frac{\partial}{\partial \varphi} Y_{lm}(\theta, \varphi)$$

separação de variáveis:

$$Y_{lm} = \Theta_{lm}(\theta) \Phi_m(\varphi)$$

$$\begin{aligned} \hat{L}_z Y_{lm} &= \cancel{\Theta_{lm}(\theta)} (-i\hbar) \frac{\partial}{\partial \varphi} \Phi_m(\varphi) \\ &= \hbar m \cancel{\Theta_{lm}(\theta)} \Phi_m(\varphi) \end{aligned}$$

$$-i\hbar \frac{\partial}{\partial \varphi} \Phi_m(\varphi) = \hbar m \Phi_m(\varphi)$$

a solução é: $\Phi_m(\varphi) = e^{i\varphi m}$

$$\varphi \rightarrow \varphi + 2\pi : \Phi_m(\varphi) = \Phi_m(\varphi + 2\pi)$$

$$\Leftrightarrow e^{i\varphi m} = e^{i(\varphi + 2\pi)m}$$

$$\Rightarrow m = 0, \pm 1, \pm 2, \dots$$

$$\Rightarrow \ell = \text{inteiros.}$$

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Emcontrar $\Phi_{em}(\theta)$

$$L_+ = L_x + i L_y$$

$$= -i\hbar \left(i \frac{\partial}{\partial \theta} - \cot \theta \frac{\partial}{\partial \varphi} \right)$$

$$Y_{lm}(\theta, \varphi) = \Theta_{lm}(\theta) e^{im\varphi}$$

$$L_+ Y_{ll}(\theta, \varphi) = 0 \quad (L_+ |l, l\rangle = 0)$$

$$-i\hbar \left(i \frac{\partial}{\partial \theta} - \cot \theta \frac{\partial}{\partial \varphi} \right) \Theta_{ll}(\theta) e^{il\varphi} = 0$$

$$\left(i \frac{\partial}{\partial \theta} - \cot \theta \frac{\partial}{\partial \varphi} \right) \Theta_{ll}(\theta) e^{il\varphi}$$

$$= \left(\frac{\partial}{\partial \theta} - l \frac{\cot \theta}{\tan \theta} \right) \Theta_{ll}(\theta) = 0$$

solução é $\Theta_{l,l}(\theta) = \sin^l \theta$

$$Y_{ll}(\theta, \varphi) = A \sin^l \theta \cdot e^{il\varphi}$$

O próximo estado da torre:

$$Y_{l, l-1}(\theta, \varphi) = \Theta_{l, l-1}(\theta) e^{i(l-1)\varphi}$$

$$Y_{l, l-1}(\theta, \varphi) = L_- Y_{l, l}(\theta, \varphi)$$

$$L_- = L_x - i L_y$$

$$= -i\hbar \left(-\sin\varphi \frac{\partial}{\partial\theta} - \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \right)$$

$$-i(-i\hbar) \left(\cos\varphi \frac{\partial}{\partial\theta} - \cot\theta \sin\varphi \frac{\partial}{\partial\varphi} \right)$$

$$= -i\hbar \left(-i(\cos\varphi - i\sin\varphi) \frac{\partial}{\partial\theta} \right. \\ \left. - (\cos\varphi - i\sin\varphi) \cot\theta \frac{\partial}{\partial\varphi} \right)$$

$$L_- = -i\hbar \left(-i e^{-i\varphi} \frac{\partial}{\partial \theta} - \cot \varphi e^{-i\varphi} \frac{\partial}{\partial \varphi} \right)$$

$$= -i\hbar e^{-i\varphi} \left(-i \frac{\partial}{\partial \theta} - \cot \varphi \frac{\partial}{\partial \varphi} \right)$$

$$L_- \Psi_{l, l}(\theta, \varphi) = L_- \lim_{\theta \rightarrow 0} e^{il\varphi}$$

$$= -i\hbar e^{i(l-1)\varphi} \left(-il \lim_{\theta \rightarrow 0} e^{i\varphi} \right.$$

$$\left. - \cot \varphi \cdot \lim_{\theta \rightarrow 0} e^{i\varphi} \cdot il \right)$$

$$= -i\hbar e^{i(l-1)\varphi} (-il) \times$$

$$\left(\lim_{\theta \rightarrow 0} e^{i\varphi} - \cot \varphi \lim_{\theta \rightarrow 0} e^{i\varphi} \right)$$

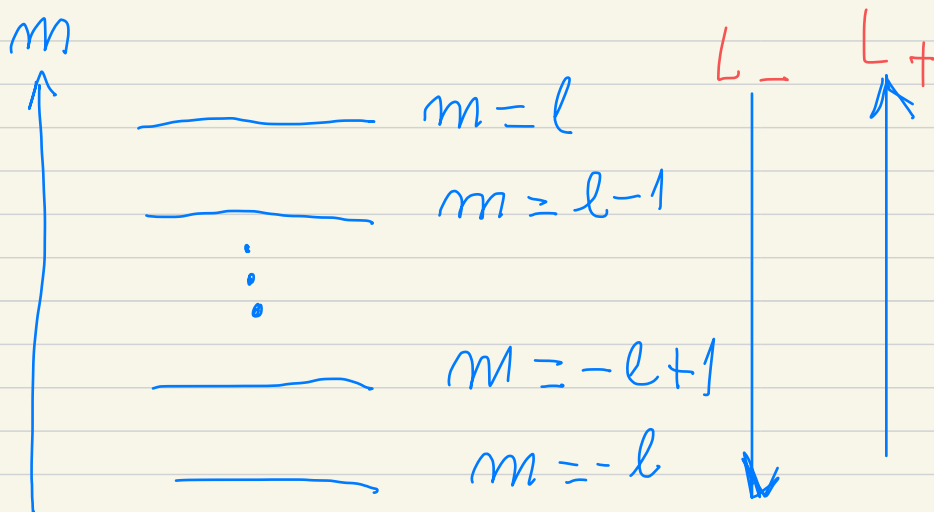
$$= \hbar \lim_{\theta \rightarrow 0} e^{i(l-1)\varphi} (1 - \cot \varphi) e^{i\varphi} \quad (*)$$

(**)

$$L_- Y_{l,l}(\theta, \varphi) = \hbar \sqrt{l(l+1) - l(l-1)} \times Y_{l,l-1}(\theta, \varphi)$$

(*) = (**)

$$Y_{l,l-1} = \frac{l}{\sqrt{2l}} \cdot \sin^{l-1} \theta (1 - \cos \theta) e^{i(l-1)\varphi}$$



$$L_+ Y_{l,l} = 0 \quad \text{and} \quad L_- Y_{l,-l} = 0.$$

Dado um harmônico esférico

$$Y_{lm}(\theta, \varphi)$$

A condição de normalização

$$\int d\Omega \, Y_{lm}^*(\theta, \varphi) Y_{lm}(\theta, \varphi)$$

$$= \int_0^{2\pi} d\varphi \cdot \int_0^\pi \sin\theta \, d\theta \cdot |Y_{lm}(\theta, \varphi)|^2 = 1.$$

Outro harmônico esférico $Y_{l0}(\theta, \varphi)$

$$\hat{L}^2 Y_{l0}(\theta, \varphi) = \hbar^2 l(l+1) Y_{l0}(\theta, \varphi)$$

$$\Rightarrow \hat{L}^2 \Theta_{l0}(\theta) = \hbar^2 l(l+1) \Theta_{l0}(\theta)$$

$$\cos\theta \frac{\partial \Theta_{l0}(\theta)}{\partial \theta} + \sin\theta \frac{\partial^2 \Theta_{l0}(\theta)}{\partial \theta^2} + \sin\theta \ell(\ell+1) \Theta_{l0}(\theta) = 0$$

↳ Eq. Legendre

Soluções: funções Legendre
se $\ell = \text{inteiros}$

funções Legendre = polinômios

$$P_{\ell 0}(\cos\theta)$$

$$Y_{\ell 0} = \sqrt{\frac{2\ell+1}{4\pi}} \cdot P_{\ell}(\cos\theta)$$

6.1 4 primeiros $Y_{\ell,0}(\theta)$

$$Y_{00} = \sqrt{\frac{1}{4\pi}}.$$

$$Y_{10} = \sqrt{\frac{3}{4\pi}} \cdot \cos\theta.$$

usando o $L+$ em $Y_{1,0}$

$$Y_{1,1} = -\sqrt{\frac{3}{8\pi}} \cdot e^{+i\varphi} \cdot \sin\theta.$$

usando o $L-$ em $Y_{1,0}$

$$Y_{1,-1} = +\sqrt{\frac{3}{8\pi}} \cdot e^{-i\varphi} \sin\theta.$$

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1. ADIÇÃO DE MOMENTOS ANGULARES

1.1) Lista de resultados importantes:

exemplo prático: átomo He
que tem 2 elétrons: $s_1 = 1/2$ e

$s_2 = 1/2$
para o momento angular de spin.

$$[L^2, L_z] = 0, [S_i^2, S_{zi}] = 0$$

$$[L_x, L_y] = i\hbar L_z, [S_x, S_y] = i\hbar S_z$$

$$L^2 |l, m\rangle = \hbar^2 l(l+1) |l, m\rangle$$

$$L_z |l, m\rangle = \hbar m |l, m\rangle$$

$$S_i^2 |s_i, s_{zi}\rangle = \hbar^2 s_i(s_i+1) |s_i, s_{zi}\rangle$$

$$S_{zi} |s_i, s_{zi}\rangle = \hbar s_{zi} |s_i, s_{zi}\rangle$$

$$L_+ |l, m\rangle = \hbar \sqrt{l(l+1) - m(m+1)} |l, m+1\rangle$$

$$L_- |l, m\rangle = \hbar \sqrt{l(l+1) - m(m-1)} |l, m-1\rangle$$

$$S_{+i} |\Delta_i, \Delta_{zi}\rangle = \hbar \sqrt{\Delta_i(\Delta_i+1) - \Delta_{zi}(\Delta_{zi}+1)} \times | \Delta_i, \Delta_{zi}+1 \rangle$$

$$S_{-i} |\Delta_i, \Delta_{zi}\rangle = \hbar \sqrt{\Delta_i(\Delta_i+1) - \Delta_{zi}(\Delta_{zi}-1)} \times | \Delta_i, \Delta_{zi}-1 \rangle$$

$$\Delta_i = 1/2, \quad \Delta_{zi} = \pm \frac{1}{2}.$$

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1.2 Adição de spins 1/2

$$\vec{S}_1 \quad \text{e} \quad \vec{S}_2$$

$$\vec{S}_1 = \frac{\hbar}{2} \vec{\sigma}_1, \quad \vec{S}_2 = \frac{\hbar}{2} \vec{\sigma}_2$$

Momento angular total :

$$\vec{S} = \vec{S}_1 + \vec{S}_2, \quad S_z = S_{1z} + S_{2z}$$

$$\vec{S}^2 = (\vec{S}_1 + \vec{S}_2)^2$$

$$= \vec{S}_1^2 + \vec{S}_2^2 + 2\vec{S}_1 \cdot \vec{S}_2$$

conjunto de resultados:

$$[\vec{S}^2, S_z] = 0, [\vec{S}^2, \vec{S}_1^2] = 0,$$

$$[S_z, \vec{S}_1^2] = 0$$

Existe uma base de estados:

$$|\Lambda_1, \Lambda_2; \Lambda_1, \Lambda_2\rangle \quad (2)$$

Existe uma base de estados:

$$|\Lambda_1, \Lambda_2; \Lambda_{z1}, \Lambda_{z2}\rangle \quad (1)$$

O número de estados nas duas bases tem o mesmo:

Exemplo: base (1)

$$\Lambda_1 = 1/2 \Rightarrow \Lambda_{z1} = -1/2 \text{ ou } +1/2$$

$$\Lambda_2 = 1/2 \Rightarrow \Lambda_{z2} = -1/2 \text{ ou } +1/2$$

$$\begin{aligned} \#_{\text{estados}} &= 2 \times 2 = 4 \\ &= (2\Lambda_1 + 1)(2\Lambda_2 + 1). \end{aligned}$$

Expressar a base (2) à custa da base (1)

$$|l_1, l_{z1}; l_2, l_{z2}\rangle =$$

$$\sum_{l_{z1}, l_{z2}} |l_1, l_2; l_{z1}, l_{z2}\rangle \cdot$$

$$\cdot \underbrace{\langle l_1, l_2; l_{z1}, l_{z2} | l_1, l_{z1}; l_2, l_{z2} \rangle}$$

coeficientes de Clebsch-Gordan
Objectivo: encontrar os C.G.

$$S_z |l_1, l_2; l_{z1}, l_{z2}\rangle = (S_{z1} + S_{z2}) \times |l_1, l_2; l_{z1}, l_{z2}\rangle$$

$$= S_z |l_1, l_2; l_{z1}, l_{z2}\rangle = (l_{z1} + l_{z2}) \times |l_1, l_2; l_{z1}, l_{z2}\rangle$$

$$\langle \Lambda_1, \Lambda_z; \Lambda_1, \Lambda_z | S_z | \Lambda_1, \Lambda_z; \Lambda_{z1}, \Lambda_{z2} \rangle$$

$$= \langle \Lambda_1, \Lambda_z; \Lambda_1, \Lambda_z | S_z | \Lambda_1, \Lambda_z; \Lambda_{z1}, \Lambda_{z2} \rangle$$

$$= S_z \langle \Lambda_1, \Lambda_z; \Lambda_1, \Lambda_z | \Lambda_1, \Lambda_z; \Lambda_{z1}, \Lambda_{z2} \rangle$$

$$= (\Lambda_{z1} + \Lambda_{z2}) \langle \Lambda_1, \Lambda_z; \Lambda_1, \Lambda_z | \Lambda_1, \Lambda_z; \Lambda_{z1}, \Lambda_{z2} \rangle$$

$$\Leftrightarrow (\Lambda_z - \Lambda_{z1} - \Lambda_{z2}) \cdot$$

$$\underbrace{\langle \Lambda_1, \Lambda_z; \Lambda_1, \Lambda_z | \Lambda_1, \Lambda_z; \Lambda_{z1}, \Lambda_{z2} \rangle}_{\text{coeficiente de C.G.}} = 0$$

Para que o coeficiente de C.G. seja diferente de zero:

$$\Lambda_{z1} + \Lambda_{z2} = \Lambda_z$$

$$| \lambda_1, \lambda_z; \lambda_1, \lambda_2 \rangle =$$

$$\sum_{\lambda_{z1}} \sum_{\lambda_{z2}} | \lambda_1, \lambda_2; \lambda_{z1}, \lambda_{z2} \rangle \cdot$$

$$\cdot \underbrace{\langle \lambda_1, \lambda_2; \lambda_{z1}, \lambda_{z2} | \lambda_1, \lambda_z; \lambda_1, \lambda_2 \rangle}_{\text{coeficientes de Clebsch-Gordan}}$$

coeficientes de Clebsch-Gordan

A nome na eq. atrás:

$$\sum_{\lambda_{z1}} \sum_{\lambda_{z2}} = \sum_{\substack{\lambda_{z1}, \lambda_{z2} \\ \lambda_z = \lambda_{z1} + \lambda_{z2}}}$$

Valores esperados para λ_z

$$\lambda_z = 0, \quad \lambda_z = 0, \pm 1$$

Podemos mostrar que os valores possíveis de J estão compreendidos entre:

$$J = |J_1 - J_2| \cdots (J_1 + J_2)$$

$$J_1 = J_2 = 1/2$$

$$J = 0, 1$$

$$J_z = 0$$

$$J_z = 0, \pm 1$$

$$\#_{\text{estados}} = 1 + 3 = 4$$

As duas bases são:

base de partícula

$$\left\{ \begin{array}{l} |1/2, 1/2; 1/2, 1/2\rangle = |\uparrow, \uparrow\rangle \\ |1/2, 1/2; 1/2, -1/2\rangle = |\uparrow, \downarrow\rangle \\ |1/2, 1/2; -1/2, 1/2\rangle = |\downarrow, \uparrow\rangle \\ |1/2, 1/2; -1/2, -1/2\rangle = |\downarrow, \downarrow\rangle \end{array} \right.$$

na base $\Lambda, \Lambda_z, \Lambda_1, \Lambda_2$

$$|0, 0; 1/2, 1/2\rangle = |0, 0\rangle$$

$$|1, 1; 1/2, 1/2\rangle = |1, 1\rangle$$

$$|1, 0; 1/2, 1/2\rangle = |1, 0\rangle$$

$$|1, -1; 1/2, 1/2\rangle = |1, -1\rangle$$

O estado mais alto da torre

$$|1, 1\rangle = |\uparrow, \uparrow\rangle$$

$$S_- = S_{1-} + S_{2-}$$

$$S_- |1,1\rangle = (S_{1-} + S_{2-}) |\uparrow, \uparrow\rangle$$

$$\begin{aligned} &\rightarrow \hbar \sqrt{1(1+1) - 1(1-1)} |1,0\rangle = \\ &= \hbar |\downarrow, \uparrow\rangle + \hbar |\uparrow, \downarrow\rangle \end{aligned}$$

$$\Leftrightarrow |1,0\rangle = \frac{1}{\sqrt{2}} (|\downarrow, \uparrow\rangle + |\uparrow, \downarrow\rangle)$$

6º passo remove estado

$$S_- |1,0\rangle = (S_{1-} + S_{2-}) \frac{1}{\sqrt{2}} (|\downarrow, \uparrow\rangle + |\uparrow, \downarrow\rangle)$$

$$\begin{aligned} \Leftrightarrow &\hbar \sqrt{1(1+1) - 0} |1,-1\rangle = \\ &= \frac{1}{\sqrt{2}} \hbar (|\downarrow, \downarrow\rangle + |\downarrow, \downarrow\rangle) = \hbar \sqrt{2} |\downarrow, \downarrow\rangle \end{aligned}$$

$$|1, -1\rangle = |\downarrow, \downarrow\rangle$$

$J=1$ três estados

$$\text{Tripletto} \left\{ \begin{array}{l} |1, 1\rangle = |\uparrow, \uparrow\rangle \\ |1, 0\rangle = \frac{1}{\sqrt{2}} (|\uparrow, \downarrow\rangle + |\downarrow, \uparrow\rangle) \\ |1, -1\rangle = |\downarrow, \downarrow\rangle \end{array} \right.$$

orthogonais

$$J=0, J_z=0$$

$$|0, 0\rangle = \frac{1}{\sqrt{2}} (|\uparrow, \downarrow\rangle - |\downarrow, \uparrow\rangle)$$

TABELA DOS coeficientes de C.-G.

	$ \uparrow\uparrow\rangle$	$ \uparrow\downarrow\rangle$	$ \downarrow\uparrow\rangle$	$ \downarrow\downarrow\rangle$
$ 0,0\rangle$	0	$1/\sqrt{2}$	$-1/\sqrt{2}$	0
$ 1,1\rangle$	1	0	0	0
$ 1,0\rangle$	0	$1/\sqrt{2}$	$1/\sqrt{2}$	0
$ 1,-1\rangle$	0	0	0	1

As linhas e as colunas são ortogonais entre si:

A tabela do C.-G. define uma transformação unitária.

1.3 ADIÇÃO MOMENTO ANGULAR ORBITAL $l=1$ $s = 1/2$

original basis: $|l, m; s, s_z\rangle$

$$\#_S = (2l+1)(2s+1) = (2+1)(1+1) = 6 \text{ estados}$$

New basis: $|j, j_z, l, s\rangle$

$$\begin{aligned} \#_S &= (2j_1+1) + (2j_2+1) ; \begin{cases} j_2 = 1 - 1/2 = 1/2 & \text{tome 2} \\ j_1 = 1 + 1/2 = 3/2 & \text{tome 1} \end{cases} \\ &= (2 \cdot \frac{1}{2} + 1) + (2 \cdot \frac{3}{2} + 1) \\ &= 2 + 4 = 6 \text{ estados} \end{aligned}$$

$$|j, j_z; l, s\rangle = \sum_{\substack{m, s_z \\ m+s_z=j_z}} C_{m, s_z}^{j, l, s} |l, m; s, s_z\rangle$$

Tome 1:

$$|j, j_z; l, s\rangle = \begin{cases} |3/2, 3/2; 1, 1/2\rangle \equiv |3/2, 3/2\rangle \\ |3/2, 1/2; 1, 1/2\rangle \equiv |3/2, 1/2\rangle \\ |3/2, -1/2; 1, 1/2\rangle \equiv |3/2, -1/2\rangle \\ |3/2, -3/2; 1, 1/2\rangle \equiv |3/2, -3/2\rangle \end{cases}$$

$$|j, j_z\rangle = \sum_{m, \Delta_z} C_{m, \Delta_z}^{j, j_z} |1, m; 1/2, \Delta_z\rangle \quad (*)$$

$m + \Delta_z = 3/2$

$$m = 0, \pm 1; \Delta_z = \pm 1/2 : \quad \frac{3}{2} = \underset{m}{1} + \underset{\Delta_z}{1/2}$$

$$(*) \Rightarrow | \frac{3}{2}, \frac{3}{2} \rangle = C_{1, 1/2}^{3/2, 1, 1/2} |1, 1; 1/2, 1/2\rangle$$

\downarrow
1 (por normalização)

$$\text{logo: } |3/2, 3/2\rangle = |1, 1; 1/2, 1/2\rangle \equiv |1, \uparrow\rangle$$

$m \quad \Delta_z$

Aplicando J_- construí-lo a torre de momentos angulares:

$$J_- |3/2, 3/2\rangle = J_- |1, \uparrow\rangle = (L_- + S_-) |1, \uparrow\rangle$$

$$J_- |j, j_z\rangle = \hbar \sqrt{j(j+1) - j_z(j_z-1)} |j, j_z-1\rangle$$

$$\begin{aligned} & \hbar \sqrt{3/2(3/2+1) - \frac{3}{2}(\frac{3}{2}-1)} |3/2, 1/2\rangle \\ &= \hbar \sqrt{\frac{15}{4} - \frac{3}{4}} |3/2, 1/2\rangle = \hbar \sqrt{3} |3/2, 1/2\rangle \quad (co) \end{aligned}$$

Lado direito:

$$(L_- + S_-) |1, \uparrow\rangle = L_- |1, \uparrow\rangle + S_- |1, \uparrow\rangle =$$

$$\hbar \sqrt{1(1+1) - 1(1-1)} |0, \uparrow\rangle + \hbar |1, \downarrow\rangle =$$

$$= \hbar \sqrt{2} |0, \uparrow\rangle + \hbar |1, \downarrow\rangle \quad (00)$$

$$(0) = (00)$$

$$\cancel{\hbar} \sqrt{3} |3/2, 1/2\rangle = \cancel{\hbar} \sqrt{2} |0, \uparrow\rangle + \cancel{\hbar} |1, \downarrow\rangle$$

$$|3/2, 1/2\rangle = \sqrt{\frac{2}{3}} |0, \uparrow\rangle + \frac{1}{\sqrt{3}} |1, \downarrow\rangle$$

Proximo estado:

$$J_- |3/2, 1/2\rangle = (L_- + S_-) \left[\sqrt{\frac{2}{3}} |0, \uparrow\rangle + \frac{1}{\sqrt{3}} |1, \downarrow\rangle \right]$$

$$\Leftrightarrow \hbar \sqrt{\frac{3}{2} \left(\frac{3}{2} + 1 \right) - \frac{1}{2} \left(\frac{1}{2} - 1 \right)} |3/2, -1/2\rangle =$$

$$= \sqrt{\frac{2}{3}} L_- |0, \uparrow\rangle + \frac{1}{\sqrt{3}} L_- |1, \downarrow\rangle$$

$$\sqrt{\frac{2}{3}} S_- |0, \uparrow\rangle + \frac{1}{\sqrt{3}} S_- |1, \downarrow\rangle \quad \Leftrightarrow$$

$$\Leftrightarrow \hbar \sqrt{\frac{15}{4} + \frac{1}{4}} |3/2, -1/2\rangle = \hbar \sqrt{\frac{2}{3}} \sqrt{1(1+1) - 0} |-1, \uparrow\rangle$$

$$\hbar \frac{1}{\sqrt{3}} \sqrt{1(1+1) - 0} |0, \downarrow\rangle + \hbar \sqrt{\frac{2}{3}} |0, \downarrow\rangle + 0$$

$$\hbar 2 |3/2, -1/2\rangle = \hbar \sqrt{\frac{2}{3}} \sqrt{2} |-1, \uparrow\rangle + \hbar \sqrt{\frac{2}{3}} |0, \downarrow\rangle + \hbar \sqrt{\frac{2}{3}} |0, \downarrow\rangle$$

$$\Leftrightarrow |3/2, -1/2\rangle = \frac{1}{\sqrt{3}} |-1, \uparrow\rangle + \sqrt{\frac{2}{3}} |0, \downarrow\rangle$$

6º próximo estado :

$$J_- |3/2, -1/2\rangle = \frac{1}{\sqrt{3}} (L_- + S_-) |-1, \uparrow\rangle + \sqrt{\frac{2}{3}} (L_- + S_-) |0, \downarrow\rangle$$

$$\Leftrightarrow \hbar \sqrt{\frac{15}{4} + \frac{1}{2}(-\frac{1}{2} - 1)} |3/2, -3/2\rangle = \frac{1}{\sqrt{3}} \hbar |-1, \downarrow\rangle + \hbar \sqrt{\frac{2}{3}} \sqrt{2} |-1, \downarrow\rangle$$

$$\Leftrightarrow \hbar \sqrt{\frac{12}{4}} |3/2, -3/2\rangle = \frac{3}{\sqrt{3}} \hbar |-1, \downarrow\rangle$$

$$\Leftrightarrow |3/2, -3/2\rangle = |-1, \downarrow\rangle$$

estado mais
baixo da
tunel.

Torre 1:

$$|3/2, 3/2\rangle = |1, \uparrow\rangle$$

$$|3/2, 1/2\rangle = \sqrt{\frac{2}{3}} |0, \uparrow\rangle + \frac{1}{\sqrt{3}} |1, \downarrow\rangle$$

$$|3/2, -1/2\rangle = \frac{1}{\sqrt{3}} |-1, \uparrow\rangle + \sqrt{\frac{2}{3}} |0, \downarrow\rangle$$

$$|3/2, -1/2\rangle = |-1, \downarrow\rangle$$

Torre 2:

$$|j, j_z\rangle = \sum_{\substack{m, m_z \\ m+m_z=j_z}} C_{m, m_z}^{j, j_z} |m, m_z\rangle$$

torre 1: $j = \frac{3}{2}, j_z = \frac{3}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{3}{2}$

torre 2: $j = \frac{1}{2}, j_z = \frac{1}{2}, -\frac{1}{2}$

A soma é satisfeita para estados das duas torres:

$$|\frac{3}{2}, \frac{1}{2}\rangle = C_{0, 1/2}^{\frac{3}{2}, 1, 1/2} |0, 1/2\rangle + C_{1, -1/2}^{\frac{3}{2}, 1, 1/2} |1, -1/2\rangle$$

$$|\frac{1}{2}, \frac{1}{2}\rangle = C_{0, 1/2}^{1/2, 1, 1/2} |0, 1/2\rangle + C_{1, -1/2}^{1/2, 1, 1/2} |1, -1/2\rangle$$

$$|3/2, 1/2\rangle = \sqrt{\frac{2}{3}} |0, 1/2\rangle + \frac{1}{\sqrt{3}} |1, -1/2\rangle$$

$$|1/2, 1/2\rangle = \frac{1}{\sqrt{3}} |0, 1/2\rangle - \sqrt{\frac{2}{3}} |1, -1/2\rangle$$

$$\langle 3/2, 1/2 | 1/2, 1/2 \rangle = 0$$

↓ 1º estado da torre 2

2º estado da torre 2:

$$|1/2, -1/2\rangle = \sqrt{\frac{2}{3}} |-1, \uparrow\rangle - \frac{1}{\sqrt{3}} |0, \downarrow\rangle$$

$$\langle 3/2, -1/2 | 1/2, -1/2 \rangle$$

	$ \frac{3}{2}, \frac{3}{2}\rangle$	$ \frac{3}{2}, \frac{1}{2}\rangle$	$ \frac{3}{2}, -\frac{1}{2}\rangle$	$ \frac{3}{2}, -\frac{3}{2}\rangle$	$ \frac{1}{2}, \frac{1}{2}\rangle$	$ \frac{1}{2}, -\frac{1}{2}\rangle$
$ 1, 1/2\rangle$	1	0	0	0	0	0
$ 0, 1/2\rangle$	0	$\sqrt{2/3}$	0	0	$\sqrt{1/3}$	0
$ -1, 1/2\rangle$	0	0	$\sqrt{1/3}$	0	0	$\sqrt{2/3}$
$ 1, -1/2\rangle$	0	$\sqrt{1/3}$	0	0	$-\sqrt{2/3}$	0
$ 0, -1/2\rangle$	0	0	$\sqrt{2/3}$	0	0	$-1/\sqrt{3}$
$ -1, -1/2\rangle$	0	0	0	1	0	0

- Notar que as linhas e as colunas são ortogonais
- A tabela pode ser lida nos dois sentidos