



Posturometre

Masse.cpp

Masse.hpp

Posturometre.cpp

Posturometre.hpp

Stockage.cpp

Stockage.hpp

liaisonEthernet.cpp

liaisonE

```

#include "Posturometre.hpp"
#include "string.h"
#include <Arduino.h>

int reponse = 0;

Posturometre o_Posturometre;

void setup(){
    Serial.begin(115200);

    Serial.println("1.Récupération de donnees. ou 2.Transfert.");

    while(reponse == 0){
        if(Serial.available() > 0){
            reponse = Serial.read();
        }
        if(reponse == 49){
            o_Posturometre.viderMemoire();
            o_Posturometre.stockerDonnees();
        }else if (reponse == 50){
            delay(1000);
            o_Posturometre.connexionServeur();
        }else{
            reponse = 0;
        }
    }
}

void loop(){
}
    
```

