

# **Regularization & Bayesian Estimation**

**Mikio Aoi & Gal Mishne**

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# Combining information from different sources

## Many applications in neuroscience

- Want to make judgments about things we don't see from things we do see.
- Integration across sensory systems (eg. normative models)
- Adding data / features we didn't collect ourselves

Need a principled way to combine disparate pieces of information to a common purpose, vis a vis different levels of confidence in each piece.

# Joint probabilities

unobserved parts  
(model parameters, synaptic weights,  
gene expression)



$$P(Y, X)$$



observed parts  
(spikes, fluorescence, voltage, etc.)

# Conditional probabilities

$$\begin{aligned} P(Y, X) &= P(X|Y)P(Y) \\ &= P(Y|X)P(X) \end{aligned}$$

# Conditional probabilities

$$P(X|Y)P(Y) = P(Y|X)P(X)$$

# Bayes' rule

posterior

$$P(X|Y)$$

=

likelihood

prior

$$P(Y|X) P(X)$$

$$P(Y)$$

marginal likelihood /  
evidence / partition  
function

# Bayes' rule

**What are the chances you have covid if you tested negative?**

$$P(\text{have}|-) = ?$$

# Bayes' rule

What are the chances you have covid if you tested negative?

$$\begin{array}{c} \text{posterior} \\ \boxed{P(X|Y)} \end{array} = \frac{\begin{array}{c} \text{likelihood} \quad \text{prior} \\ \boxed{P(Y|X)} \boxed{P(X)} \end{array}}{\begin{array}{c} \boxed{P(Y)} \\ \text{marginal likelihood /} \\ \text{evidence / partition} \\ \text{function} \end{array}}$$



# Bayes' rule

What are the chances you have covid if you tested negative?

$$\begin{array}{c} \text{posterior} \\ \boxed{P(\text{have}|-)} \end{array} = \frac{\begin{array}{c} \text{likelihood} \quad \text{prior} \\ \boxed{P(Y|X)} \boxed{P(X)} \end{array}}{\begin{array}{c} \boxed{P(Y)} \\ \text{marginal likelihood /} \\ \text{evidence / partition} \\ \text{function} \end{array}}$$

# Bayes' rule

What are the chances you have covid if you tested negative?

$$\begin{array}{c} \text{posterior} \\ P(\text{have}|-) \end{array} = \frac{\begin{array}{c} \text{false} \\ \text{negative rate} \end{array} P(-|\text{have}) \begin{array}{c} \text{prior} \\ P(X) \end{array}}{\begin{array}{c} P(Y) \\ \text{marginal likelihood /} \\ \text{evidence / partition} \\ \text{function} \end{array}}$$

# Bayes' rule

What are the chances you have covid if you tested negative?

posterior

false  
negative rate    prevalence

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(Y)}$$

marginal likelihood /  
evidence / partition  
function

# Bayes' rule

What are the chances you have covid if you tested negative?

posterior

$$P(\text{have}|-) = \frac{\overset{\text{false}}{\underset{\text{negative rate}}{P(-|\text{have})}} \overset{\text{prevalence}}{P(\text{have})}}{\underset{\text{negativity rate}}{P(-)}}$$

# Bayes' rule

What are the chances you have covid if you tested negative?

90% CI:  
(.02,.54)      prevalence

posterior

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(-)}$$

negativity rate

# Bayes' rule

What are the chances you have covid if you tested negative?

90% CI:  
(.02,.54)

posterior

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(-)}$$

negativity rate

varies a lot by geographic location, occupation, etc.

Sampling and testing biases

# Bayes' rule

What are the chances you have covid if you tested negative?

90% CI:  
(.02,.54)

0.01 for closest studied  
region (San Francisco)

posterior

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(-)}$$

negativity rate

# Bayes' rule

What are the chances you have covid if you tested negative?

posterior

90% CI:  
(.02,.54)

0.01 for closest studied  
region (San Francisco)

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(-)}$$

$$P(-) = P(-|\text{have})P(\text{have}) + P(-|\text{don't have})P(\text{don't have})$$

false positive prevalence

true negative = 1 -  
false positive

1-prevalence

false positives < 0.05



# Bayes' rule

What are the chances you have covid if you tested negative?

posterior

90% CI: (.02,.54)

0.01 for closest studied region (San Francisco)

$$P(\text{have}|-) = \frac{P(-|\text{have})P(\text{have})}{P(-)}$$

$$P(-) = P(-|\text{have})P(\text{have}) + P(-|\text{don't have})P(\text{don't have})$$

(.2,.54)

0.01

true negative = 1 -  
false positive

.99

false positives < 0.05

# Bayes' rule

What are the chances you have covid if you tested negative?

posterior

$$\boxed{P(\text{have}|-)} = \frac{(.02,.54) * 0.01}{(.02,.54) * 0.01 + 0.95 * .99}$$
$$= (.0002, .0057)$$

# Bayes' rule

What are the chances you have covid if you tested negative?

$$\begin{aligned} \text{posterior} \\ \boxed{P(\text{have}|-)} &= \frac{(.02,.54) * 0.01}{.991 \text{ for UCSD students}} \\ &= (.0002, .0054) \end{aligned}$$

# Bayes' rule

What are the chances you have covid if you tested negative?

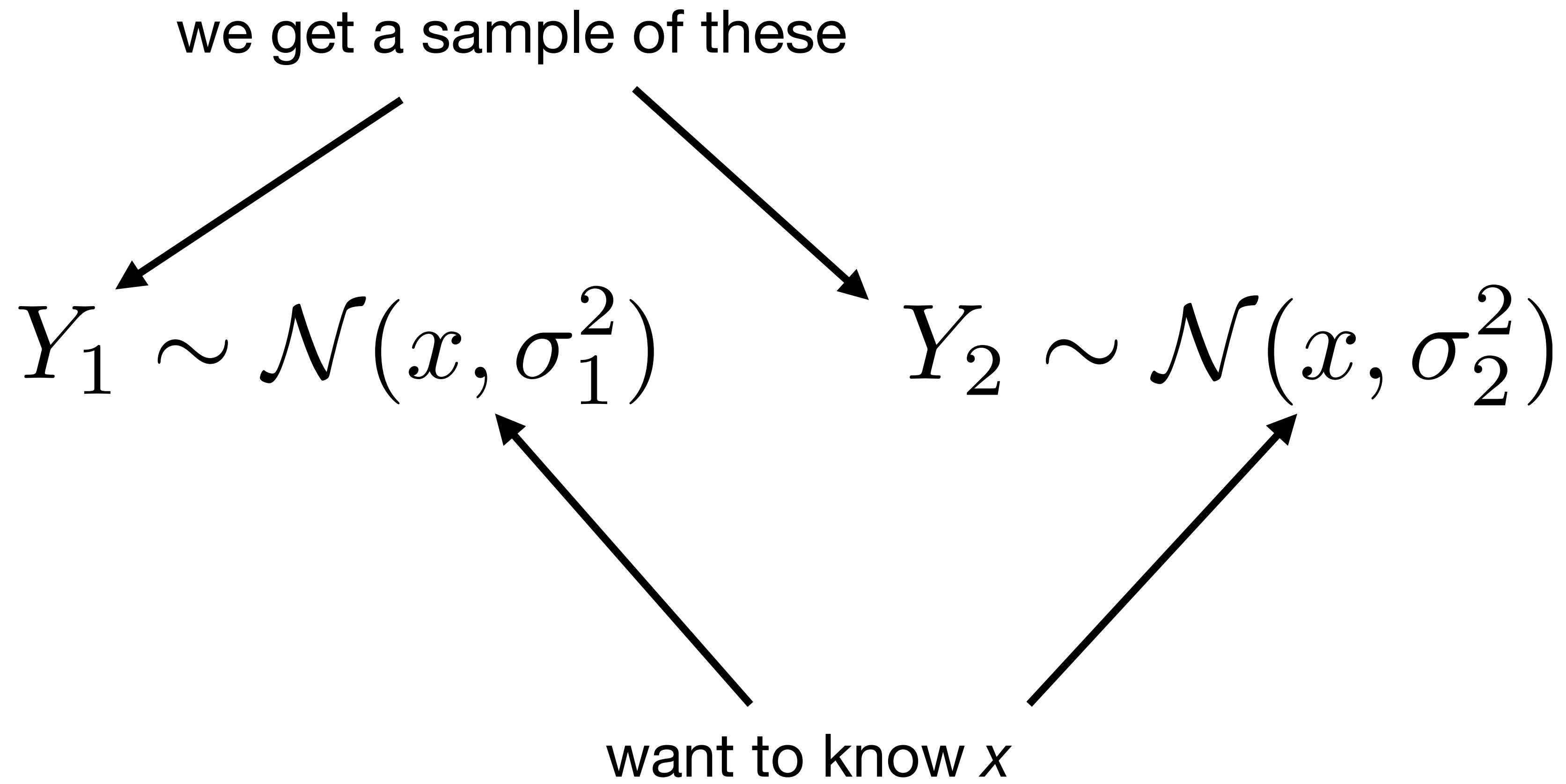
posterior

$$\boxed{P(\text{have}|-)} = \frac{(.02,.54) * .23}{(.02,.54) * .23 + 0.95 * .77}$$
$$= (.0062, .1451)$$

NYC is a different story

# Bayes' rule with Gaussians

## Tutorial scenario



# Bayes' rule with Gaussians

## Point estimation

we get a sample of this

$$Y_1 \sim \mathcal{N}(x, \sigma_1^2)$$

$$p(Y|X)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

want to know  $x$

# Bayes' rule with Gaussians

## Point estimation

likelihood  
 $p(Y|X)$

prior  
 $p(X)$

$$Y_1 \sim \mathcal{N}(x, \sigma_1^2)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

want to know  $x$

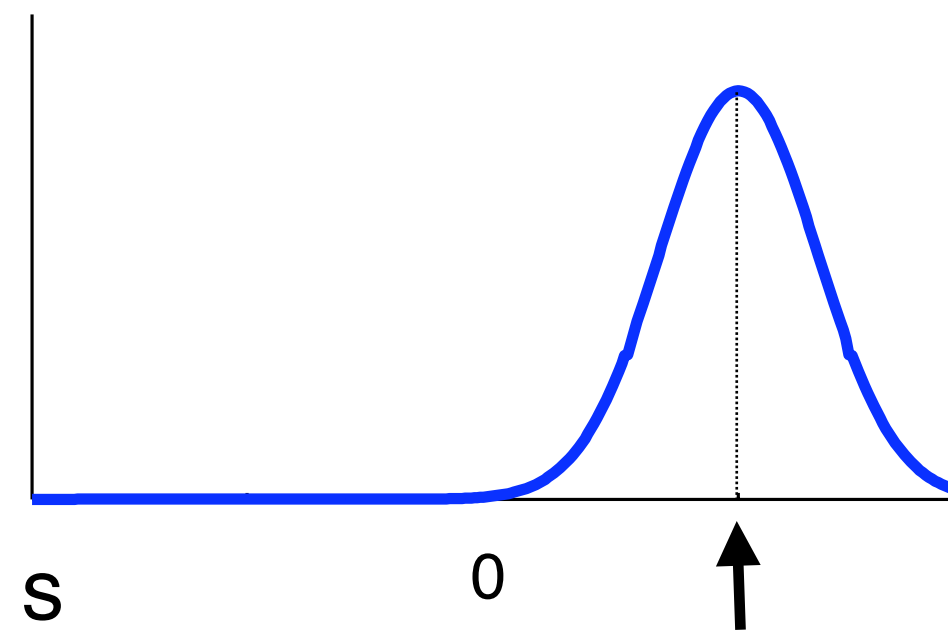


# Bayes' rule with Gaussians

Bayesian estimates are biased

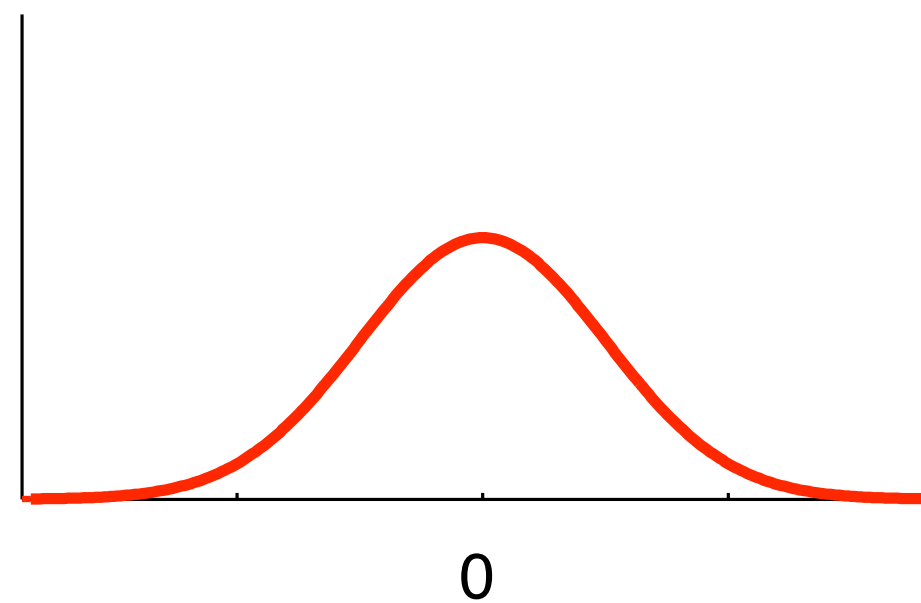
likelihood

$$p(Y|X)$$



prior

$$p(X)$$



$$\hat{X}_{MLE}$$

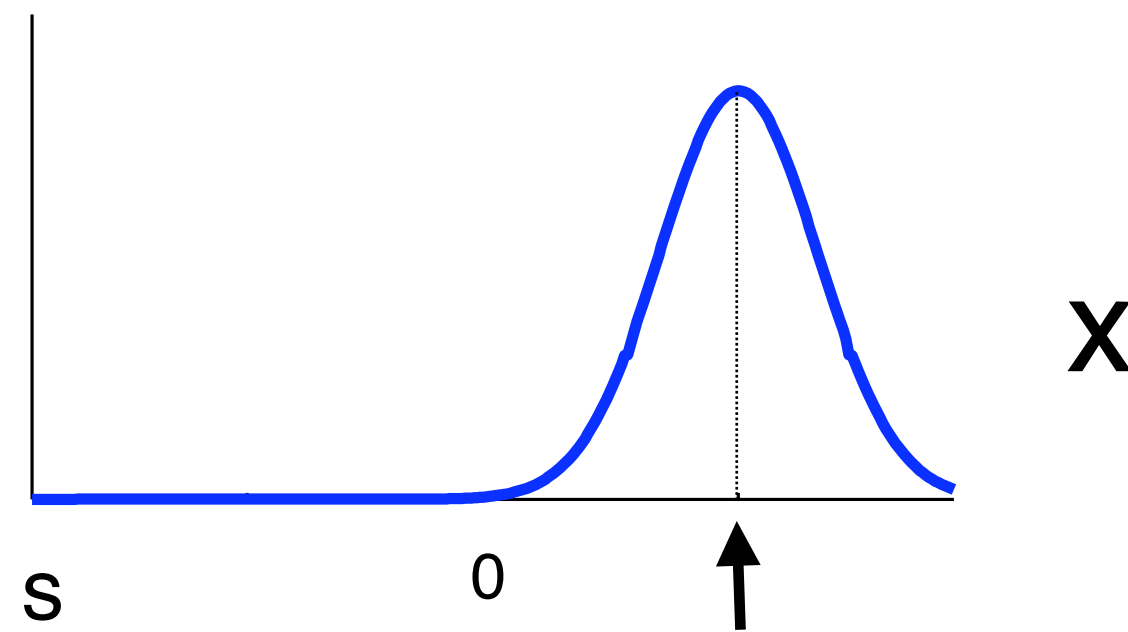


# Bayes' rule with Gaussians

Bayesian estimates are biased

likelihood

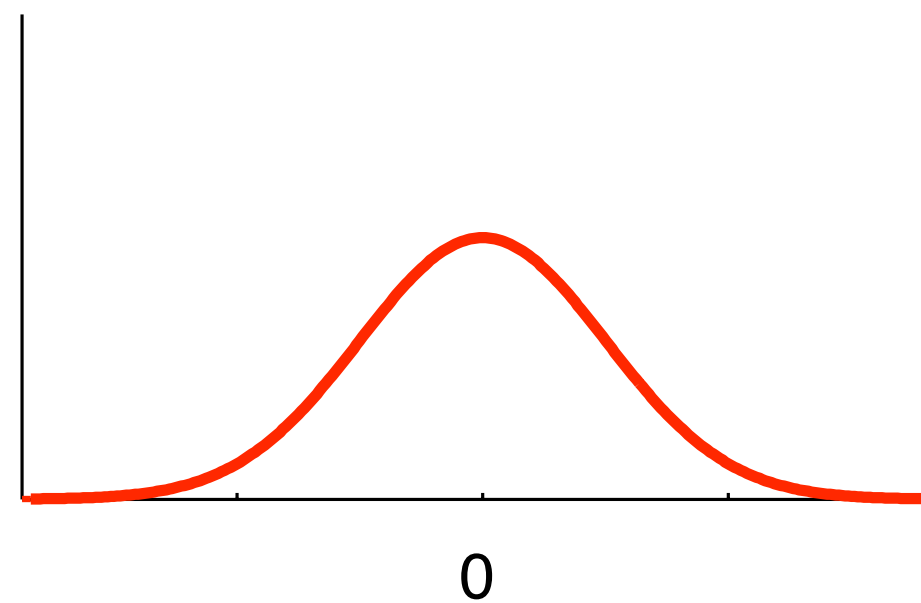
$$p(Y|X)$$



$$\hat{X}_{MLE}$$

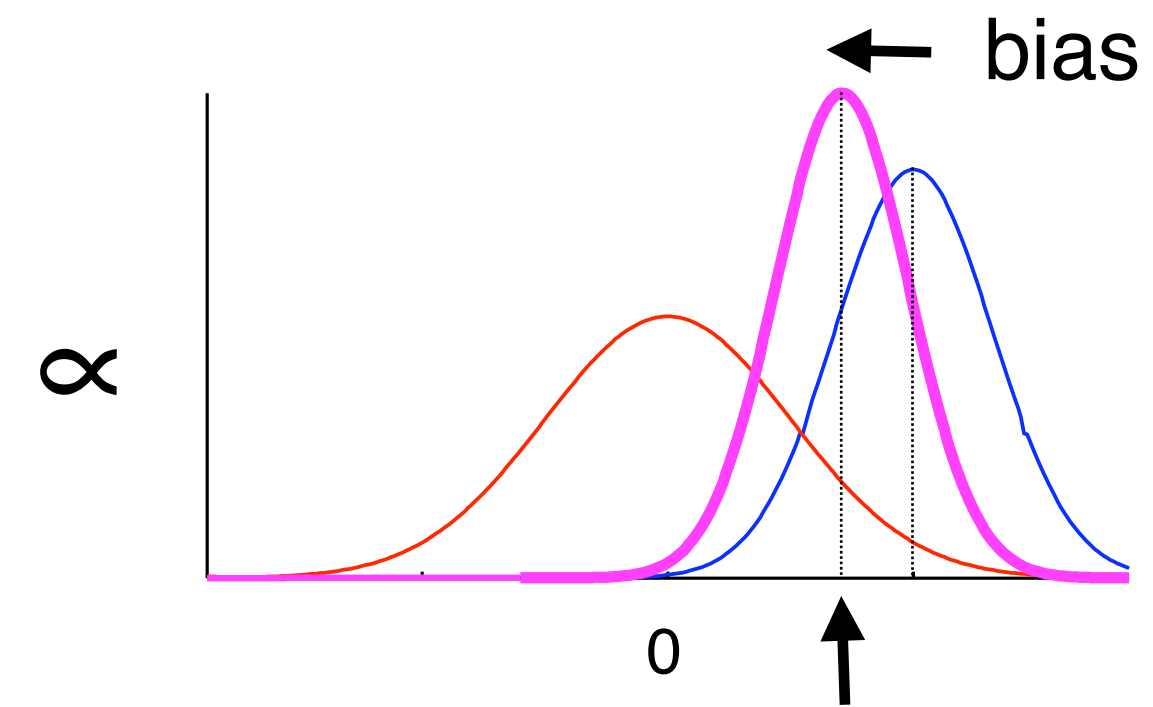
prior

$$p(X)$$



posterior

$$p(X|Y)$$



$$\hat{X}_{MAP}$$

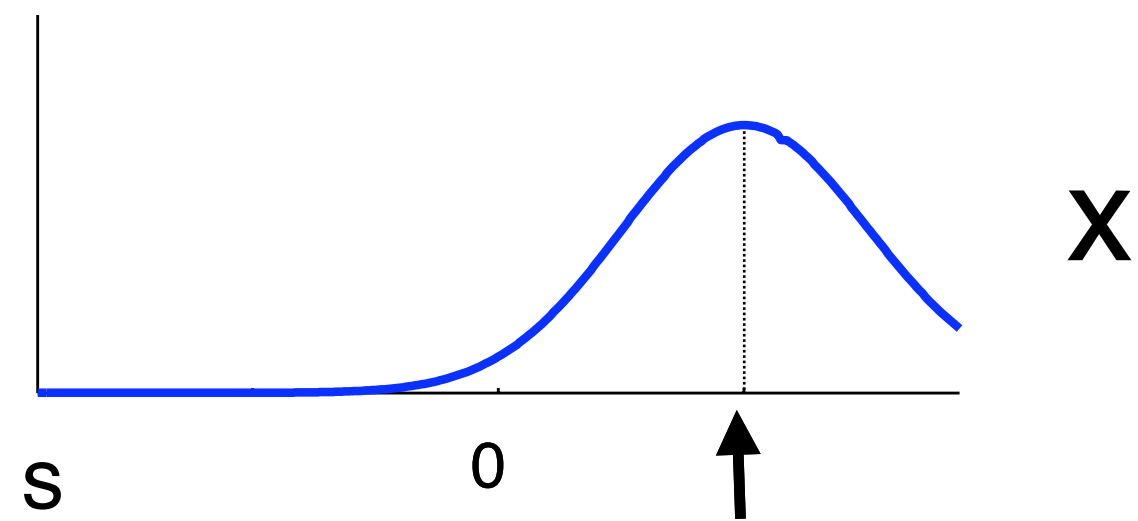
- MAP estimate lives between ML estimate & prior

# Bayes' rule with Gaussians

Bayesian estimates are biased

likelihood

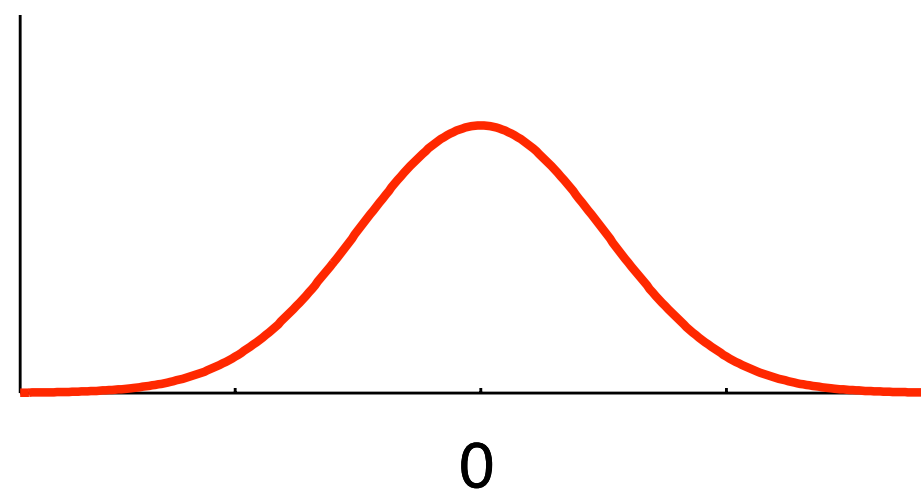
$$p(Y|X)$$



$$\hat{X}_{MLE}$$

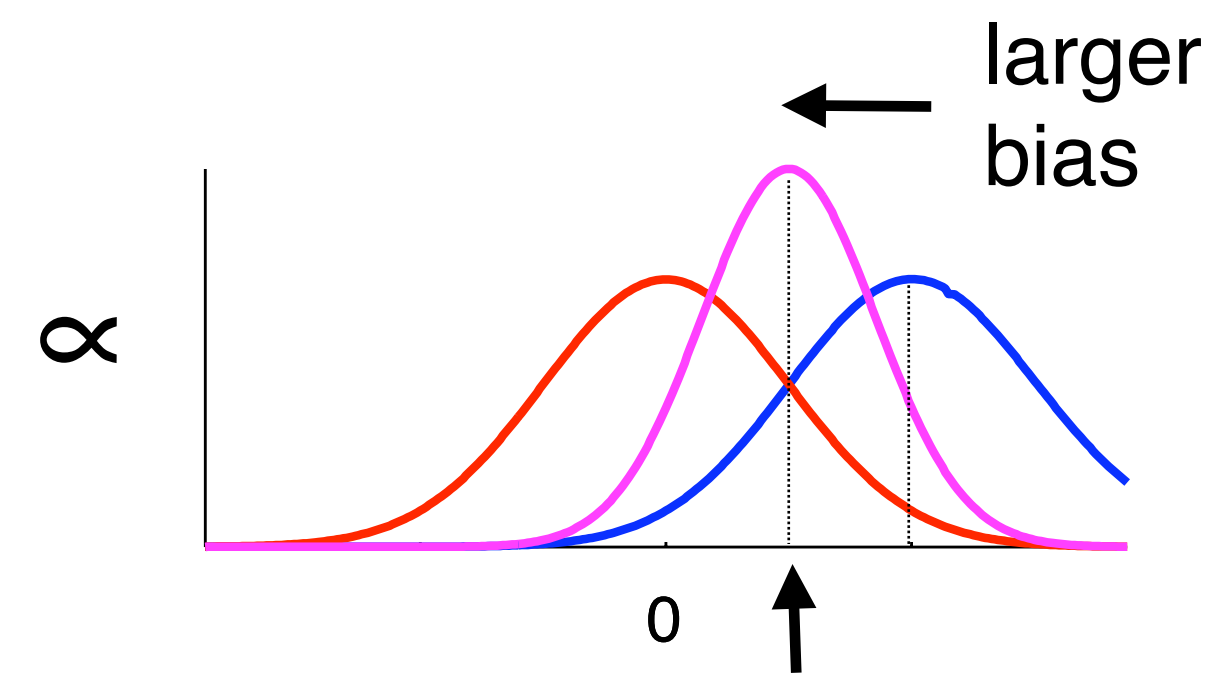
prior

$$p(X)$$



posterior

$$p(X|Y)$$



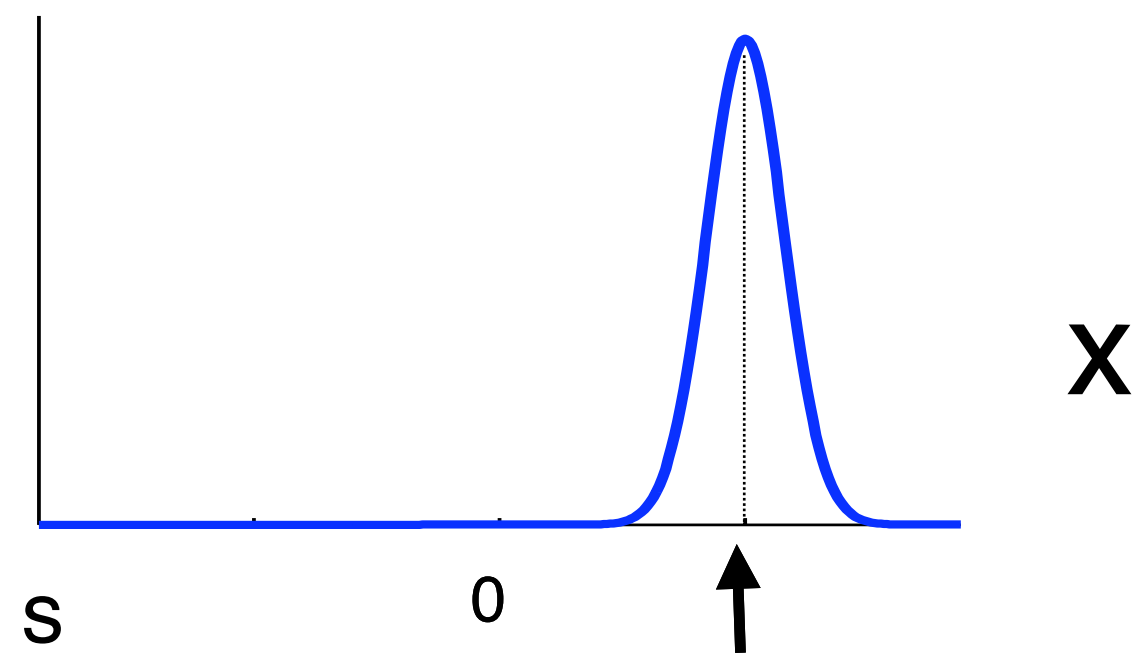
$$\hat{X}_{MAP}$$

# Bayes' rule with Gaussians

Bayesian estimates are biased

likelihood

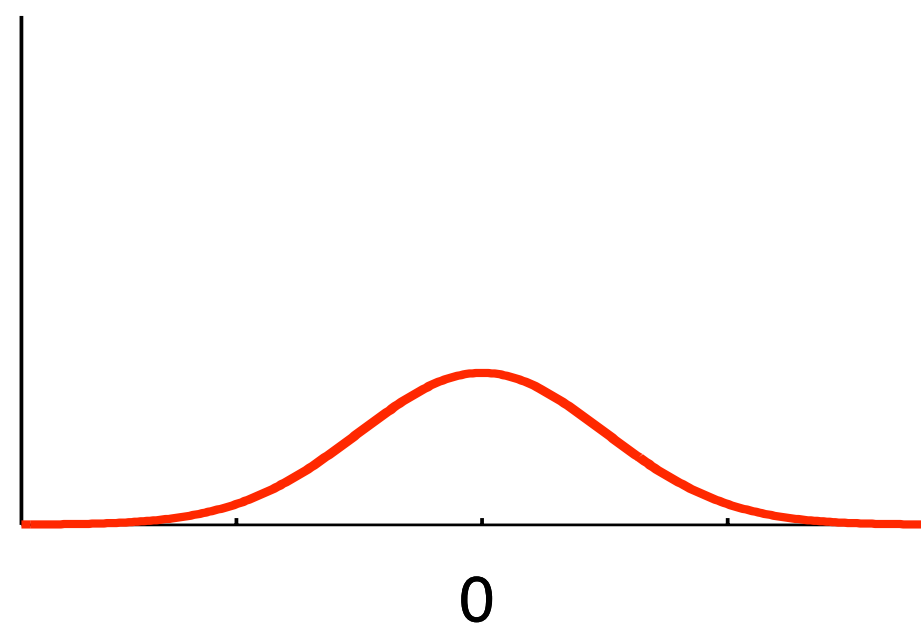
$$p(Y|X)$$



$$\hat{X}_{MLE}$$

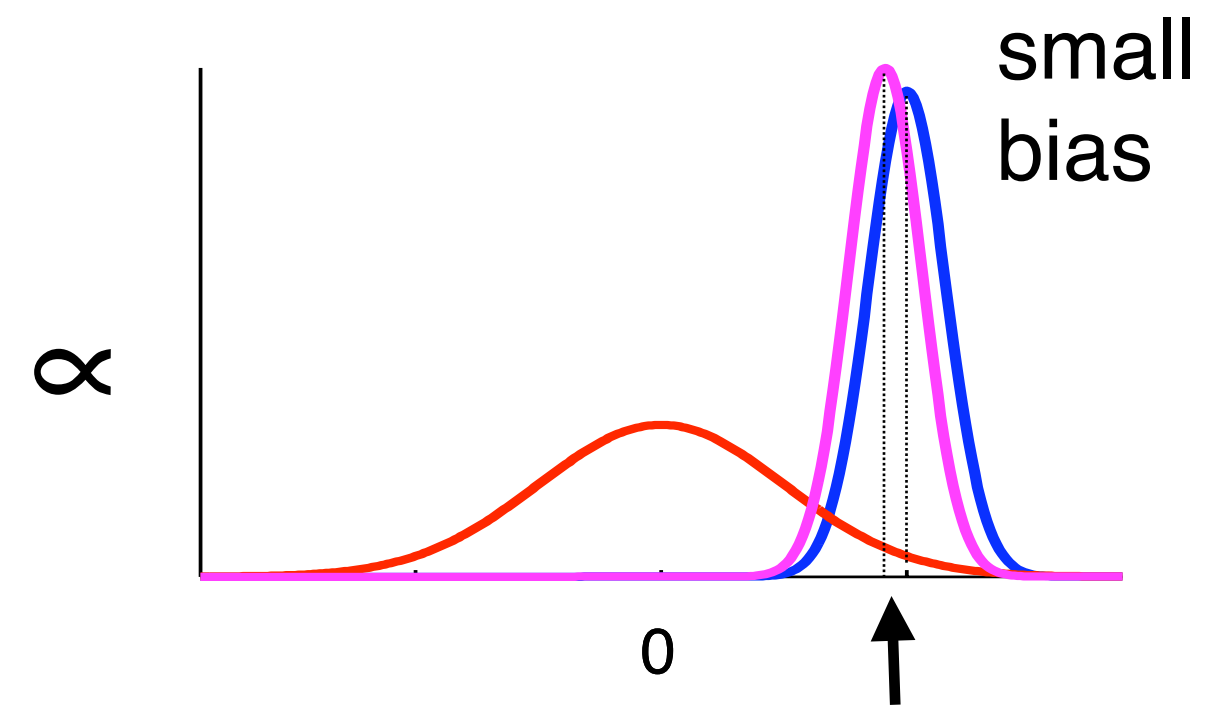
prior

$$p(X)$$



posterior

$$p(X|Y)$$



$$\hat{X}_{MAP}$$

# Bayes' rule with Gaussians

## Point estimation

likelihood  
 $p(Y|X)$

prior  
 $p(X)$

$$Y_1 \sim \mathcal{N}(x, \sigma_1^2)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

want to know  $x$



# Bayes' rule with Gaussians

## Point estimation

likelihood  
 $p(Y|X)$

prior  
 $p(X)$

$$Y_n \sim \mathcal{N}(x, \sigma^2)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

want to know  $x$



# Bayes' rule with Gaussians

## Point estimation

likelihood

$$p(Y|X)$$

prior

$$p(X)$$

$$Y_n \sim \mathcal{N}(x, \sigma^2)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

maximum likelihood

$$\log(p(Y_1, Y_2, \dots | X))$$

$$\hat{X}_{\text{MLE}} = \arg \max_X \log(p(Y_1, Y_2, \dots | X))$$

# Bayes' rule with Gaussians

## Point estimation

likelihood  
 $p(Y|X)$

prior  
 $p(X)$

$$Y_n \sim \mathcal{N}(x, \sigma^2)$$

$$X \sim \mathcal{N}(\theta, \tau^2)$$

maximum likelihood  $\log(p(Y_1, Y_2, \dots | X))$

$$\hat{X}_{\text{MLE}} = \arg \min_X \frac{1}{N} \sum_n (X - Y_n)^2 \quad \text{MSE}$$

# Bayes' rule with Gaussians

Regularized point estimation is Bayesian point estimation

likelihood

$$Y_n \sim \mathcal{N}(x, \sigma^2)$$

prior

$$X \sim \mathcal{N}(0, \tau^2)$$

$$\log(p(x|Y_1, Y_2, \dots)) \propto \underbrace{\frac{1}{N} \sum_n (X - Y_n)^2}_{\text{MSE}} + \underbrace{\beta X^2}_{\text{regularizer}}$$

log posterior

penalty  $\beta = \frac{\sigma^2}{\tau^2}$

“ridge”, “ $\ell_2$ ”



# NMA Tutorials

- Tutorial 1 - Regularization
  - Pick up where we left off with logistic regression
  - Regularizer is an expression of prior beliefs (in the Bayesian sense)
- Tutorial 2 - 4 - Combining information from 2 sources and manipulating the probabilities
- Tutorial 2 errata
  - typos in the instructional text - formula for mean of a distribution
  - url for videos are not all working. Will post correct url's in Slack.