

Nodebots - Electronics Primer

#nodebotsau #nbd14

V = I * R



BEFORE WE PLUG IN THE ARDUINO, WE WILL REVIEW A FEW TERMS AND PRINCIPLES THAT HAVE TO DO WITH HOW ELECTRICITY (AND THEREFORE ELECTRONICS) WORKS.

VOLTAGE (V)

IS A MEASURE OF ELECTRICAL POTENTIAL. IT IS MEASURED IN VOLTS.

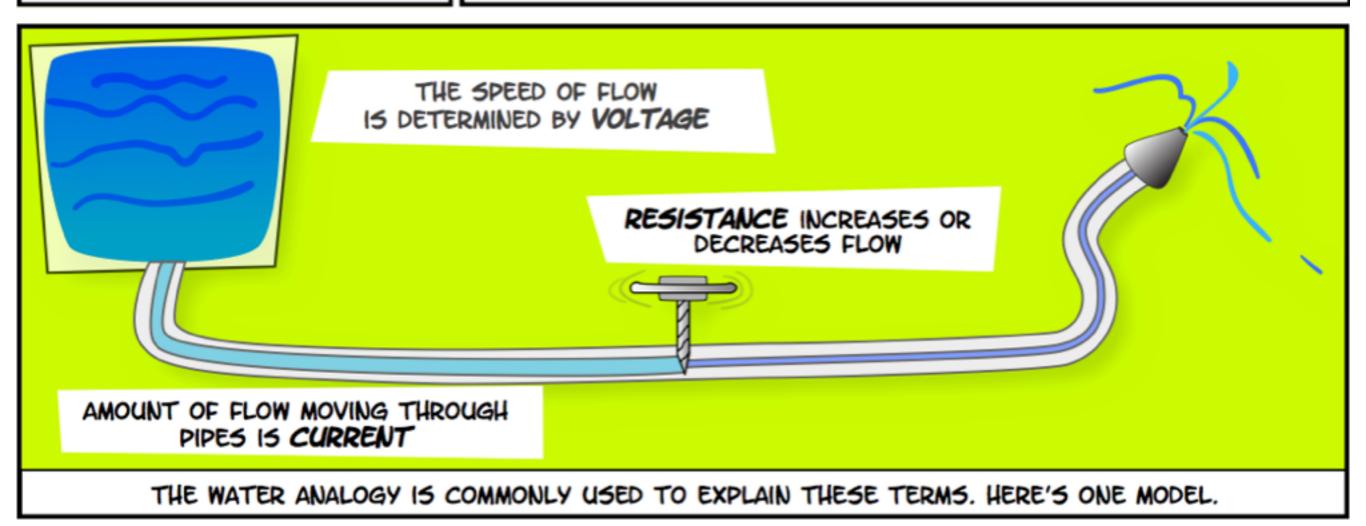
CURRENT (I)

OF FLOW
THROUGH A
CONDUCTIVE
MATERIAL.
IT IS MEASURED
IN AMPERES
OR AMPS.

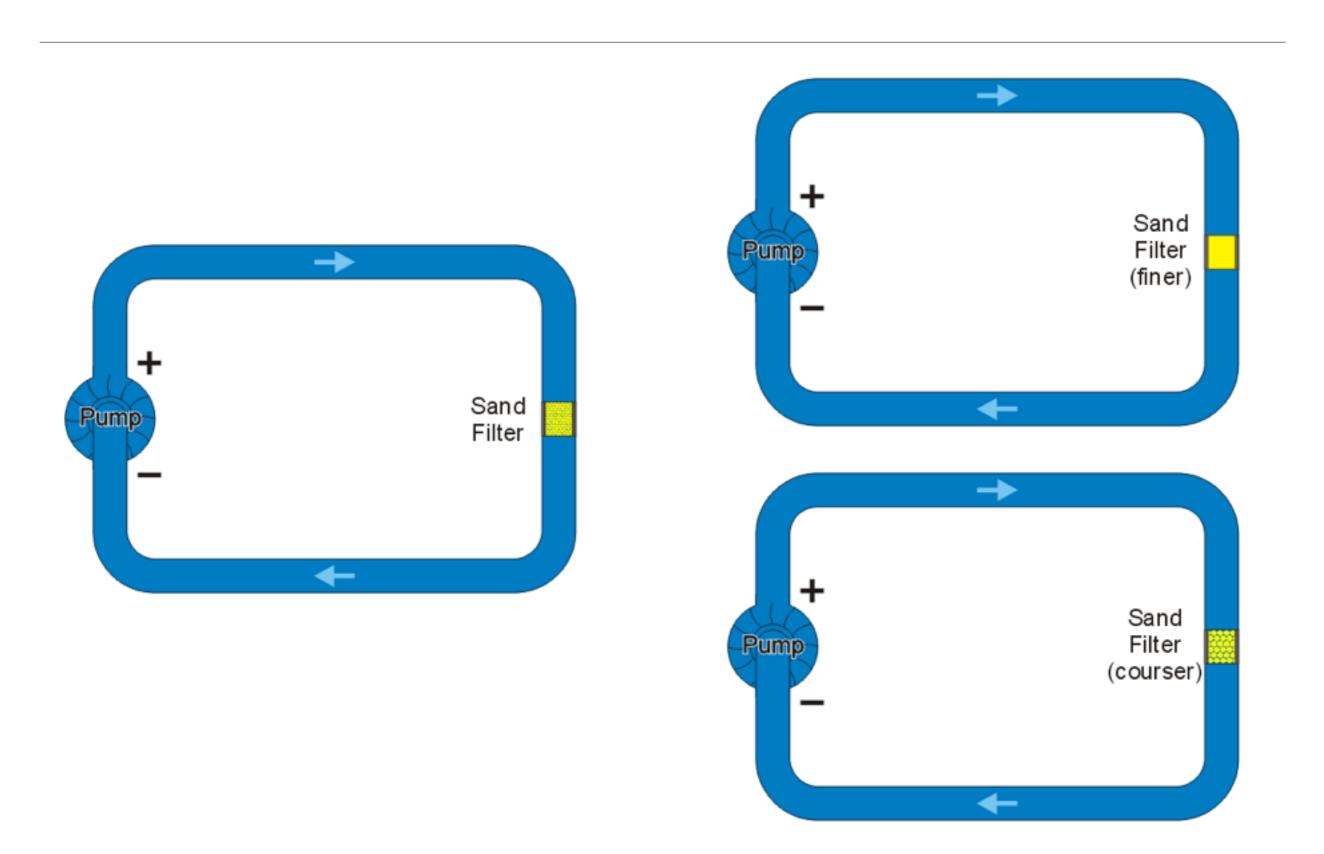
RESISTANCE (R)

IS A MATERIAL'S
OPPOSITION TO
THE FLOW OF
ELECTRIC
CURRENT.
IT IS MEASURED
IN OHMS.

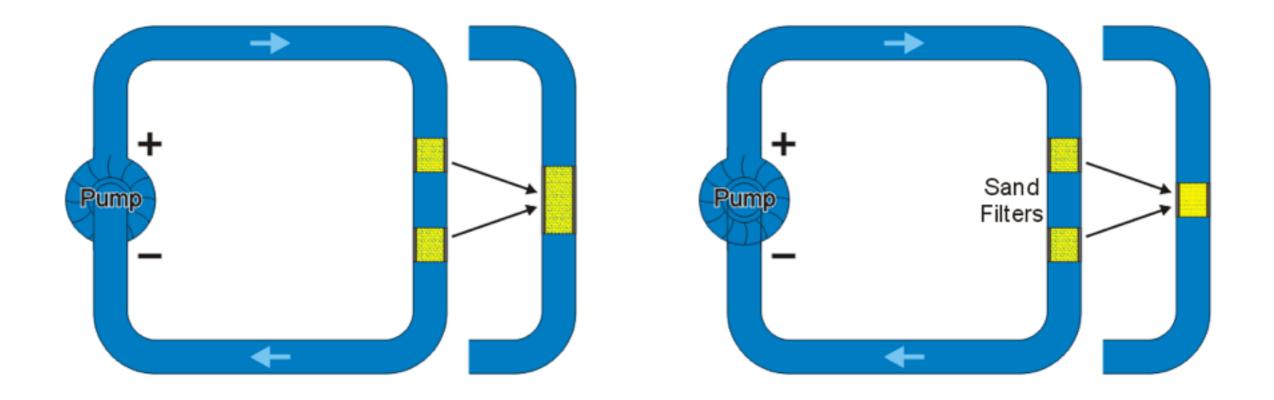
ELECTRICITY IS THE FLOW OF ENERGY THROUGH A CONDUCTIVE MATERIAL.



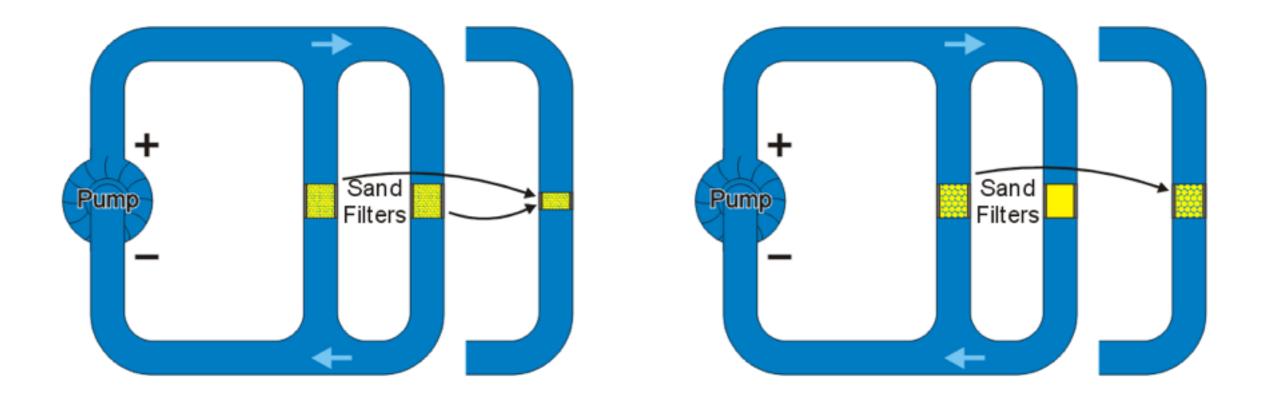
Resistors are like a sand filters



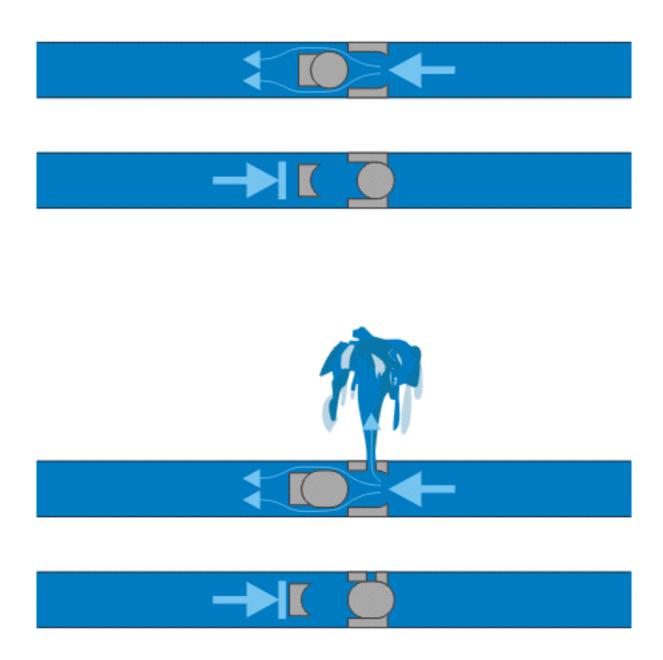
Resistors in series



Resistors in parallel



Diodes and LEDs



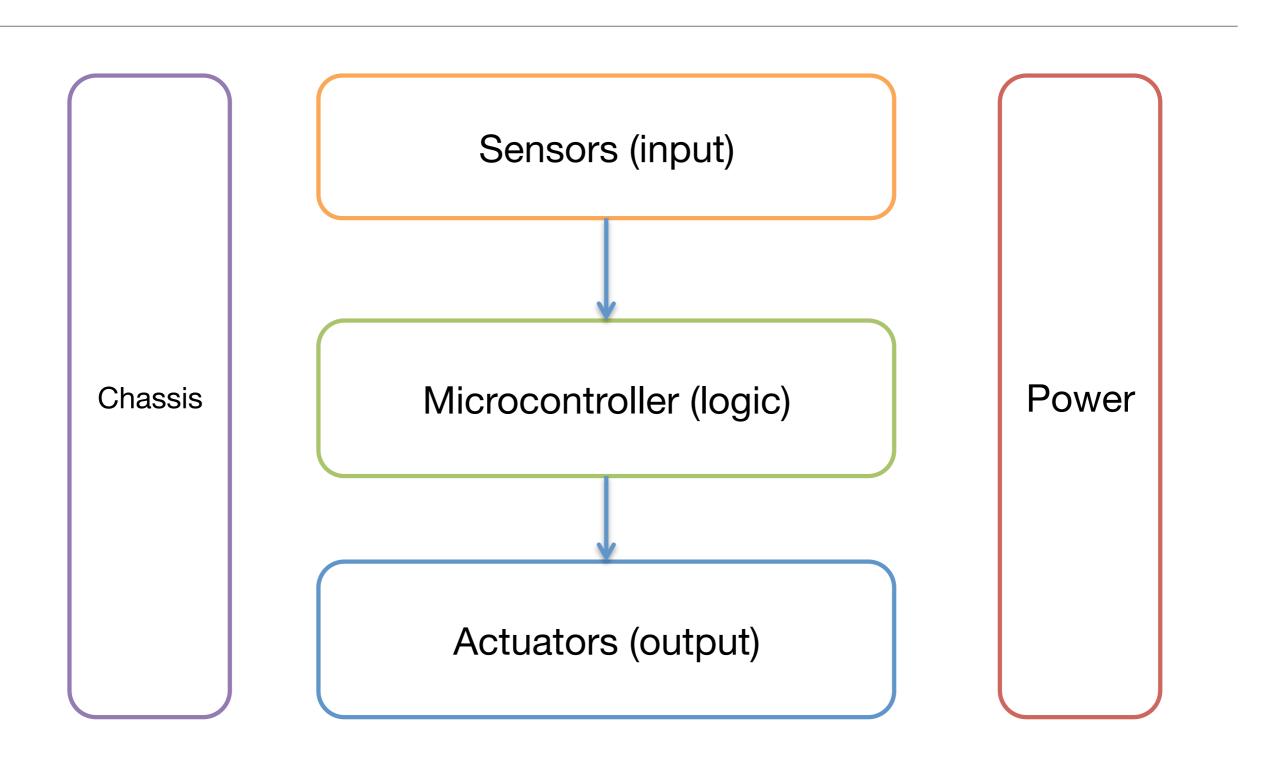
$$V = I * R$$

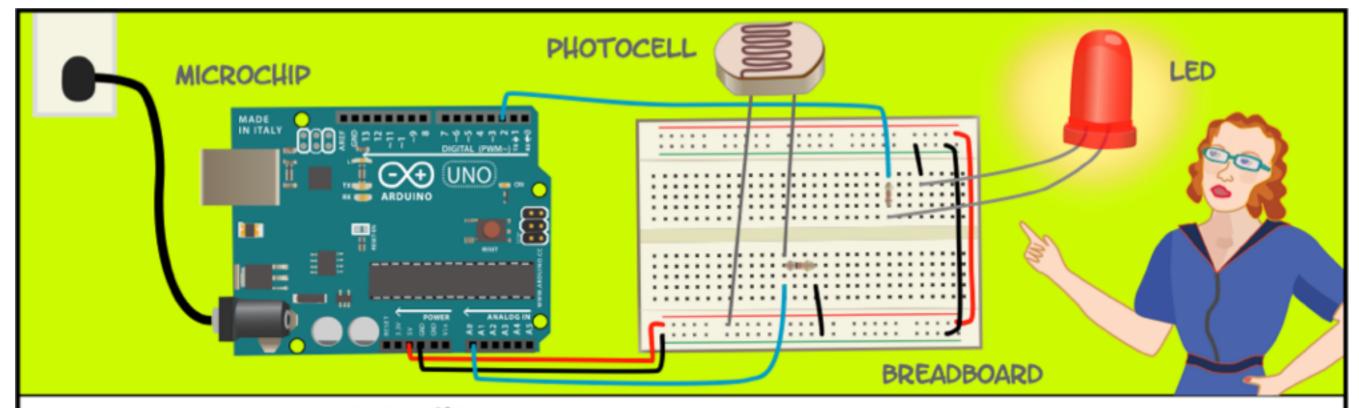
More info:

https://github.com/AnnaGerber/bits-n-bots (general intro material)
https://ece.uwaterloo.ca/~dwharder/Analogy/ (more water analogies)
https://www.khanacademy.org/science/physics/electricity-and-magnetism/v/circuits--part-1 (course on circuits)

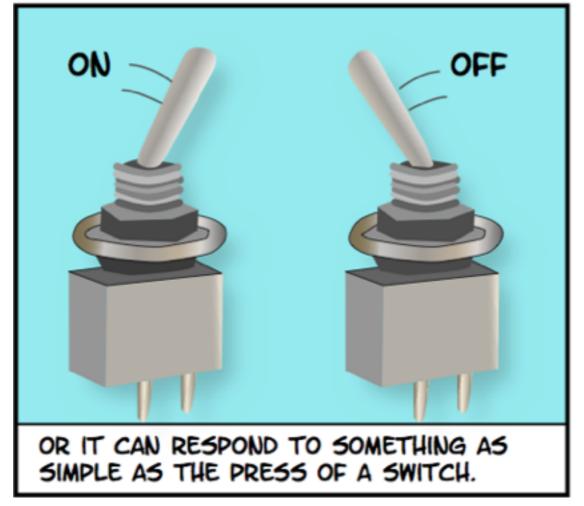
Physical computing is building interactive systems, using hardware and software, to sense and respond to the physical world.

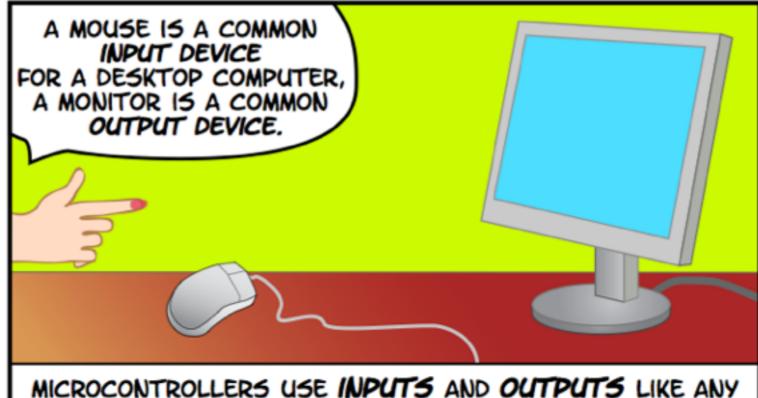
Our nodebots will have sensors and actuators, and they will use a microcontroller for decision making...





AN ARDUINO CONTAINS A **MICROCHIP**, WHICH IS A VERY SMALL COMPUTER THAT YOU CAN PROGRAM. YOU CAN ATTACH SENSORS TO IT THAT CAN MEASURE CONDITIONS (LIKE HOW MUCH LIGHT THERE IS IN THE ROOM). IT CAN CONTROL HOW OTHER OBJECTS REACT TO THOSE CONDITIONS (ROOM GETS DARK, LED TURNS ON).





COMPUTER. INPUTS CAPTURE INFORMATION FROM THE USER OR THE ENVIRONMENT WHILE OUTPUTS DO SOMETHING WITH

THE INFORMATION THAT HAS BEEN CAPTURED.

Types of sensors

- · Acoustic, sound, vibration: microphone, lace sensor (guitar pickup)
- · Chemical: CO2, CO, pH, smoke detector, breathalyser
- Electric current, electric potential, magnetic, radio: magnetometer, hall-effect sensor, electron multipliers
- Environment, weather, moisture, humidity: soil moisture, water sensor
- Flow, fluid velocity: flow meter
- Ionizing radiation, subatomic particles: geiger counter, particle detector
- Position, angle, displacement, distance, speed, acceleration:
 capacitive sensing, gyroscope, accelerometer, LIDAR, tachometer, tilt
- Optical, light, imaging, photon: infra-red, LED as light sensor, photoresistor, camera
- · Pressure: barometer, tactile sensor, piezometer
- Thermal, heat, temperature: thermistor
- Proximity, presence: ultra-sonic sensor

Examples of sensors and input devices

- Ultrasonic sensor: used to detect distance from objects.
- Photo resistor: used to detect light.
- Push button: used to capture discrete input or collision
- Camera: used to capture visual information







Types and examples of actuators

Light and display: LED, LCD

Sound: piezo buzzer







Motion and switching: DC motor, servo motor, solenoid relay







Others, such as: hydraulic, pneumatic, mechanical

Digital vs Analog signals

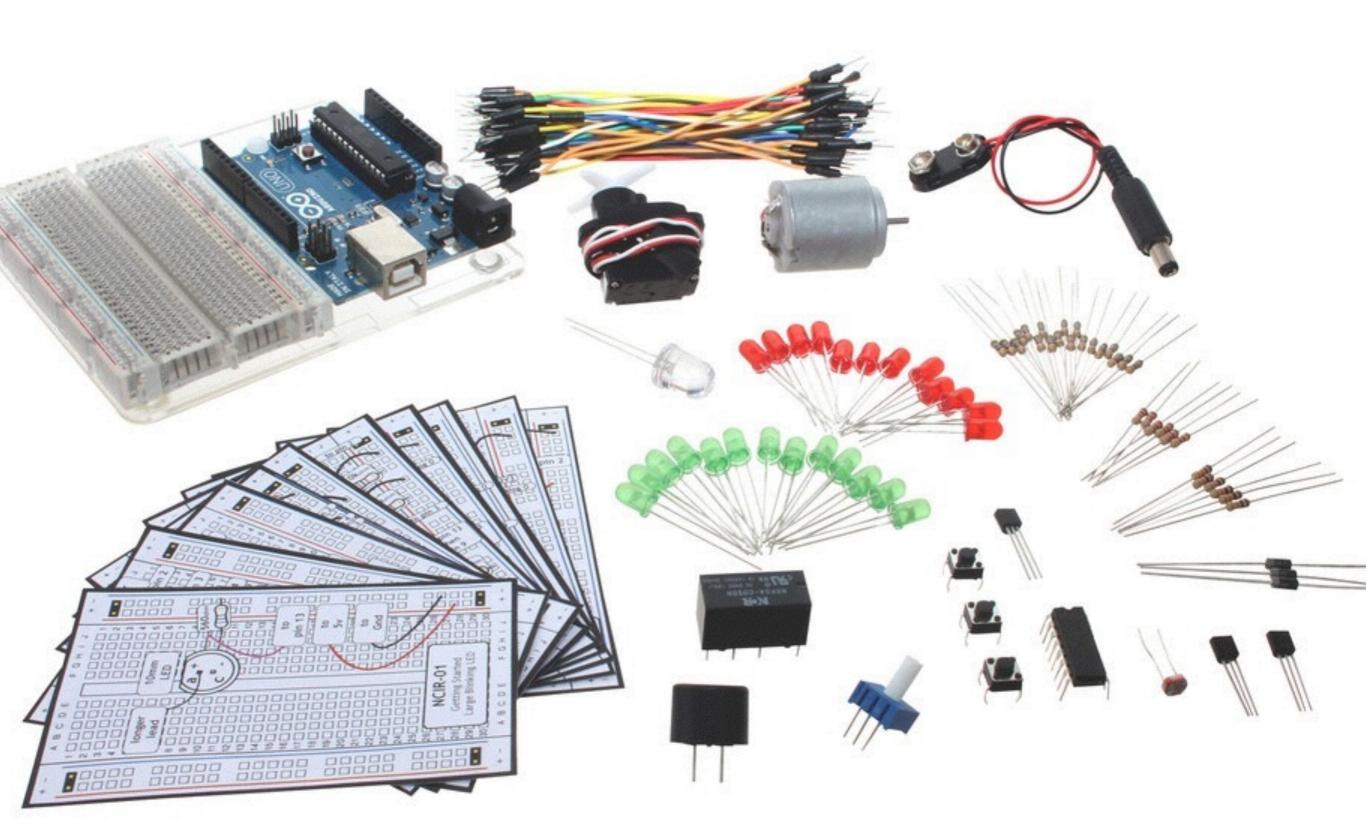
Digital components rely on discrete values, typically indicated by high and low voltages

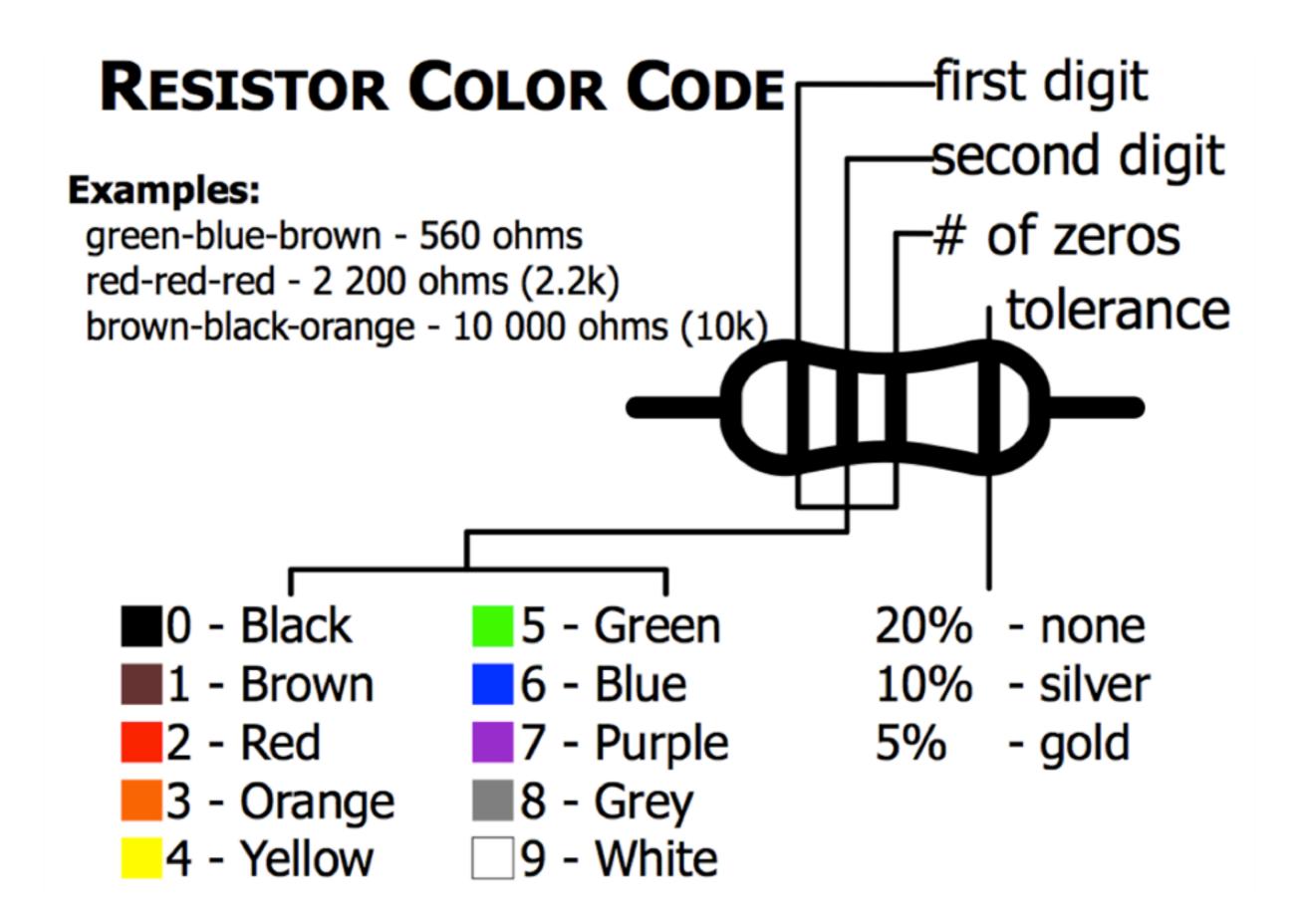
- 5V (or 3.3V) => high => 1 => ON
- 0V => low => 0 => OFF
 - Examples of digital sensors: tilt sensor, push button
 - Examples of digital actuators: relay, LCD display, servo motor

Analog components use continuous values, produced as a signal over time

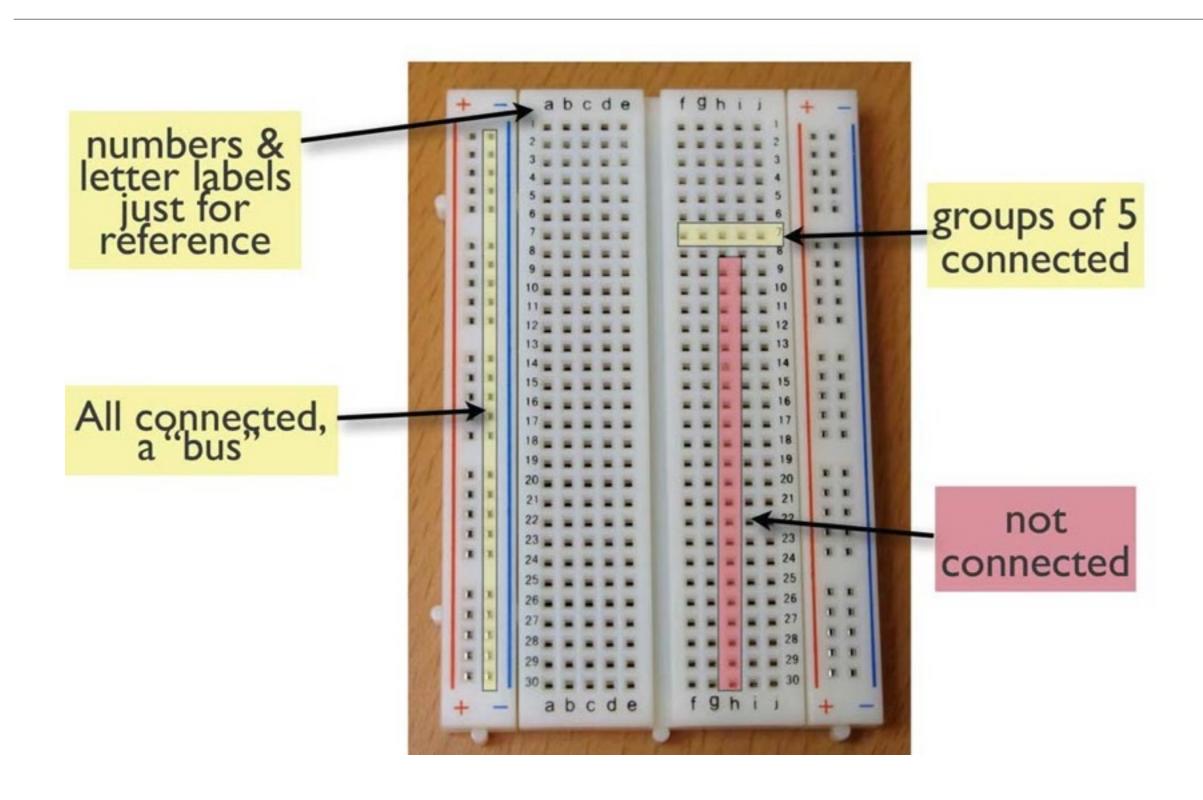
- Values are usually constrained, e.g. 0-100mA or 0-100k
 - Examples of analog sensors: accelerometer, thermistor, photoresistor
 - Examples of analog actuators: DC motor

Note: Some sensors support both Analog and Digital outputs.





Breadboard



Good luck!

#nodebotsau

