

Can we trust AI?

- A case for eXplainable AI (X-AI)**

Krishna Kumar, The University of Texas at Austin

Machine Learning Training for Natural Hazards Engineering 2022

What is DesignSafe?

- A web-based research platform that enables transformative research to protect human life and reduce damage during natural hazard events

DesignSafe Vision

- A cyberinfrastructure (CI) that is an integral part of research discovery
 - Provide a platform for data sharing/publishing
 - Enable research workflows and access to high performance computing (HPC)
 - Deliver cloud-based tools that support the analysis, visualization, and integration of diverse data types
- Amplify and link the capabilities of natural hazards researchers in the US and abroad



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The screenshot shows a search bar at the top with the placeholder "Find in Published Projects". Below it is a sidebar with options: "Add", "My Data", "My Projects", "Shared with Me", "Box.com", and "Dropbox.com". The main area displays a "Publication Type" section with checkboxes for "Experimental", "Simulation", "Hybrid Simulation", and "I". A "Project Title" section follows, containing the text: "Collaborative Research: Development, experimental validation and case studies for the next generation of landslide tsunami models for coastal hazard mitigation (Simulation)".

The screenshot shows a "Workspace" interface with a "Learning Center" tab. Below it are links to "Data Depot", "Tools & Applications", "Recon Portal", "SimCenter Research Tools", and "User Guides". A large blue arrow points from the "DATA DEPOT" screenshot to this interface.

The screenshot shows a "DesignSafe Tutorials" page with a "NEW" section for "Leveraging DesignSafe with TAPIS" (December 17, 2020) and a "Best Practices to Enhance the Quality, Discoverability and Re-Use Potential for Post-Event Reconnaissance Data" (November 11, 2020). Both sections include "Watch Tutorial" and "Presentation Slides" links. A blue arrow points from the "Workspace" screenshot to this page.

The screenshot shows a "TOOLS & APPLICATIONS" interface with a "Learn About the Workspace" section. It lists "Simulation [7]", "Visualization [8]", "Data Processing [2]", and "Farmer Data Apps [5]". Below this are icons for "ADCIRC", "clawpack", "Dakota", and "LS-DYNA". A "jupyter" logo is also present.

The screenshot shows a "Recon Portal" interface with a "Learn more about contributing" section. It lists "2021 M 6.2 Sulawesi Indonesia Earthquake Majene Sulawesi Indonesia" and "2020 M 6.4 Petrinja Croatia Earthquake Petrinja Croatia". To the right is a map of North America and the Caribbean showing numerous blue location pins.

QGIS



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DATA DEPOT

+ Add

My Data

My Projects

Shared with Me

Box.com

Dropbox.com

Google Drive

Published

Find in My Projects



Rename

Move

Copy

Preview

Download

Move to Trash

Project ID	Project Title	PI	Last Modified
PRJ-2440	Ridgecrest, CA earthquake, July 4, 2019	Scott Brandenberg	9/11/19 8:56 AM
PRJ-2531	TxDOT - Seismic Vulnerability and Post-Event Actions	Patricia Clayton	8/29/19 1:36 PM
PRJ-1716	NHERI TallWood Project_Task 4a	Shiling Pei	8/29/19 9:31 AM
PRJ-1437	Simulation Test Project	Ellen Rathje	8/28/19 2:31 PM
PRJ-2466	DesignSafe-QuakeCoRE Cyberinfrastructure Workshop	Ellen Rathje	8/27/19 2:53 AM
PRJ-1729	NHERI@UTexas Nonintrusive Sinkhole 3D-Imaging Workshop	Kenneth Stokoe	8/21/19 10:34 AM
PRJ-2504	Vorticity-Advection-RODSEX experiment	Steve Elgar	8/19/19 1:27 PM

My Projects: A space to share files/data/results with collaborators and to eventually publish for public use



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DATA DEPOT

Find in Data Depot

Rename Move Copy Preview Download Move to Trash



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Box.com

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Google Drive

Published

Community Data



PRJ-2363 | SOIL-FOUNDATION-STRUCTURE INTERACTION EFFECTS ON THE CYCLIC FAILURE POTENTIAL OF SILTS AND CLAYS

PI Brandenberg, Scott

CoPIs Stewart, Jonathan

Project Type Experimental

Keywords Cyclic Softening, Fine-Grained Soil, Soil-Foundation-Structure Interaction

Earthquake-induced ground failure has resulted in billions of dollars of damage during recent earthquakes, exhibiting either "sand-like" or "clay-like" behavior with respect to strength loss during earthquakes in soils, which are less well understood than "sand-like" soils. Cyclic failure of fine-grained soils are not in the free-field soils away from the structures, indicating that soil-foundation-structure interaction is important in centrifuge model testing to study cyclic failure of fine-grained soils beneath structures. This research contains all of the experimental measurements and metadata required for users to make sense of the data.

View Data Diagram

Experiment | Centrifuge Testing on Kaolinite Clay - Test UCLA JZB02

Experiment Type Centrifuge
Authors Buenker, Jason; Brandenberg, Scott; Stewart, Jonathan
Experimental Facility Center For Geotechnical Modeling, UC Davis
Equipment Type 9m Radius Dynamic Geotechnical Centrifuge
Date of Experiment 10-24-2018 — 01-26-2019
Date of Publication 01-09-2020
DOI [Citation](#) 10.17603/ds2-jpwh-nq72
License(s) Open Data Commons Attribution

This experiment tested three structures resting on fine-grained soil consisting of non-plastic sand. A sequence of earthquake ground motions was applied to the model container. Measurements include bending strain, and axial strain.

Report | Data Processing

Report | Data Processing

Report | Digital Data Report (JZB02)

Model Configuration | Centrifuge Model (JZB02)

Sensor Information | Centrifuge (JZB02)

Event | CPT (JZB02)

Event | Fast Data from Spin 2 (Dynamic Shaking Applied)

Data collected at 5000 Hz during shaking

01162019@082639@110817@77.0rpm.bin

01162019@082639@112208@77.0rpm.bin

01162019@082639@113803@76.8rpm.bin

01162019@082639@115034@76.9rpm.bin

01162019@082639@122026@77.0rpm.bin

01162019@082639@125704@77.0rpm.bin



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Curation Assistance

- Curation and publication guidelines under **User Guides**
 - <https://www.designsafe-ci.org/rw/user-guides/data-curation-publication/>
 - Managing protected/identifiable data – talk to Maria Esteva
- Data transfer methods
 - <https://www.designsafe-ci.org/rw/user-guides/data-transfer-guide/>
 - Web browser/Dropbox/etc (smaller uploads), Globus, Cyberduck
- Virtual Curation Office Hours
 - DesignSafe Data Curators: Maria Esteva and Craig Jansen
 - Tuesday and Thursday at 1 pm Central (or by appt)
 - <https://www.designsafe-ci.org/learning-center/training/>



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Reconnaissance Portal

Identifying Published Datasets from Recon Events



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Tools & Apps: Simulation

TOOLS & APPLICATIONS

Learn About Tools & Applications.

Simulation	SimCenter Tools	Visualization	Analysis	Hazard Apps	Utilities	My Apps
ADCIRC 	ANSYS 	clawpack 	Dakota 	LS-DYNA 		OpenFOAM 
OpenSees 	rWHALE 					

- HPC-enabled simulation codes (Stampede2, Frontera)
- Available through portal or at the Command Line, easy access to HPC allocation (CPUs, GPUs) through DesignSafe



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Tools & Apps: Data Analysis

Simulation [8]	Visualization [9]	Data Processing [2]	Partner Data Apps [5]	Utilities [2]	My Apps [8]
FigureGen 	HazMapper 	Kalpana 	Paraview 	Potree Converter 	Potree Viewer 
QGIS Desktop 3.8.1 	STKO 	VisIt 	Jupyter 	MATLAB 	

- Cloud-based tools for data analysis and visualization
- Access to files in Data Depot



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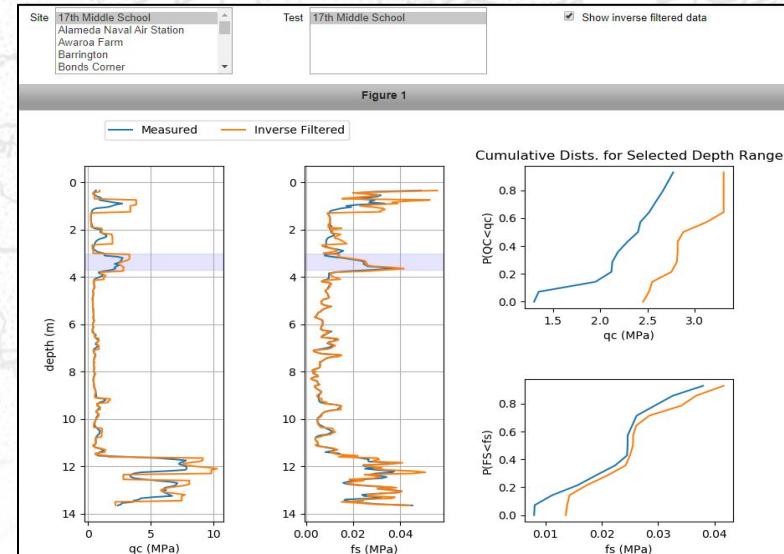
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Jupyter Notebooks

- Electronic notebooks in Python or R
- JupyterHub in DesignSafe
 - Access to Data Depot files
- Interactive data viewer
- Can write scripts for data processing, AI or machine learning
- Publish for use by others



Next Generation Liquefaction



From Scott Brandenberg (UCLA)



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HazMapper

- Easy access to images and point cloud data
 - Location and preview exposed
 - Link to Potree viewer provided
 - Links to Streetview imagery (Mapillary)

The figure shows the HazMapper application interface. On the left, there is a sidebar with various icons for 'Assets', 'Point Clouds', 'Layers', and 'Filters'. Below this is a preview window showing a photograph of a damaged building with debris. The main area is a map of the University of Washington campus, with a specific polygon highlighted in blue. To the right of the map is a 3D rendering of a building, labeled '96972'. Below the 3D rendering are sections for 'View' and 'Metadata'. The 'Metadata' section includes a 'Geometry: Polygon' section with an area of 161731.98772860041 square meters, and a 'Bounding Box' section with latitude and longitude coordinates for the polygon's vertices.

	Latitude	Longitude
Min	47.6501437109597	-122.308231325997
Max	47.6535931484506	-122.302614622767



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Learning Center



Workspace

Learning Center

Education & Training

Archived DesignSafe Webinars

<https://tinyurl.com/DesignSafe-Webinars>

DesignSafe Tutorials

NEW

Development and utilization of a relational database to support post-earthquake building damage and recovery assessment

March 12, 2021

- [Watch Tutorial](#)

Experimental Data Workflow for Real Time Decision Making Using Python and Jupyter Notebooks

February 3, 2021

- [Watch Tutorial](#)

Leveraging DesignSafe with TAPIS

December 17, 2020

- [Watch Tutorial](#)

Best Practices to Enhance the Quality, Discoverability and Re-Use Potential for Post-Event Reconnaissance Data

November 11, 2020

- [Watch Tutorial](#)
- [Presentation Slides](#)

SimCenter Webinars

NEW

Physical Modeling of Wave Attenuation & Wave Force Reduction by a Mangrove Forest

December 4, 2020

- [Watch Webinar](#)

Computational Frameworks for the Implementation of Performance-Based Wind Engineering

November 23, 2020

- [Watch Webinar](#)

Partial Turbulence Simulation for Predicting Peak Wind Loads on Buildings

October 16, 2020

- [Watch Webinar](#)

Hurricane Loss Analysis for Single-Family Houses Considering Current and Changing Climate Conditions

October 6, 2020

- [Watch Webinar](#)



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DesignSafe: We are here for you!

Available to the Global Natural Hazards Research Community

Analyze,
Simulate
& Share

Start Your
Experiments

Expand
Your Skills

Join the
Community



- Interact with us and the community using the DesignSafe Slack team
- Cite data using DOIs in your reference list!



Please share your feedback, ideas, experiences!



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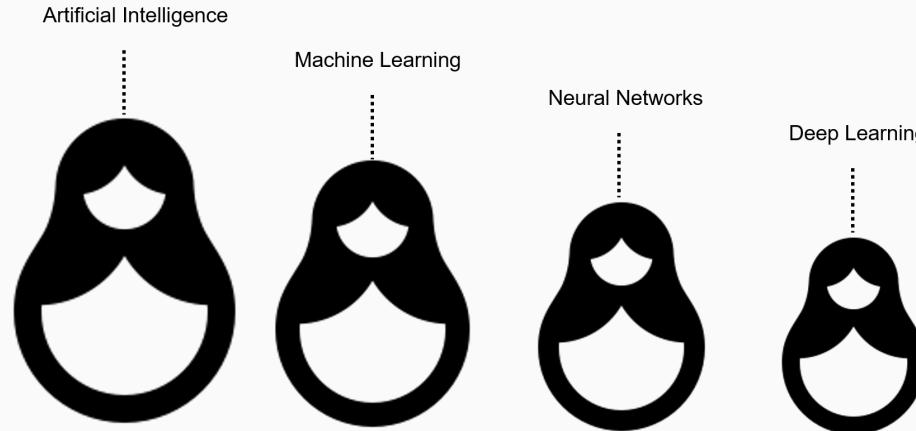
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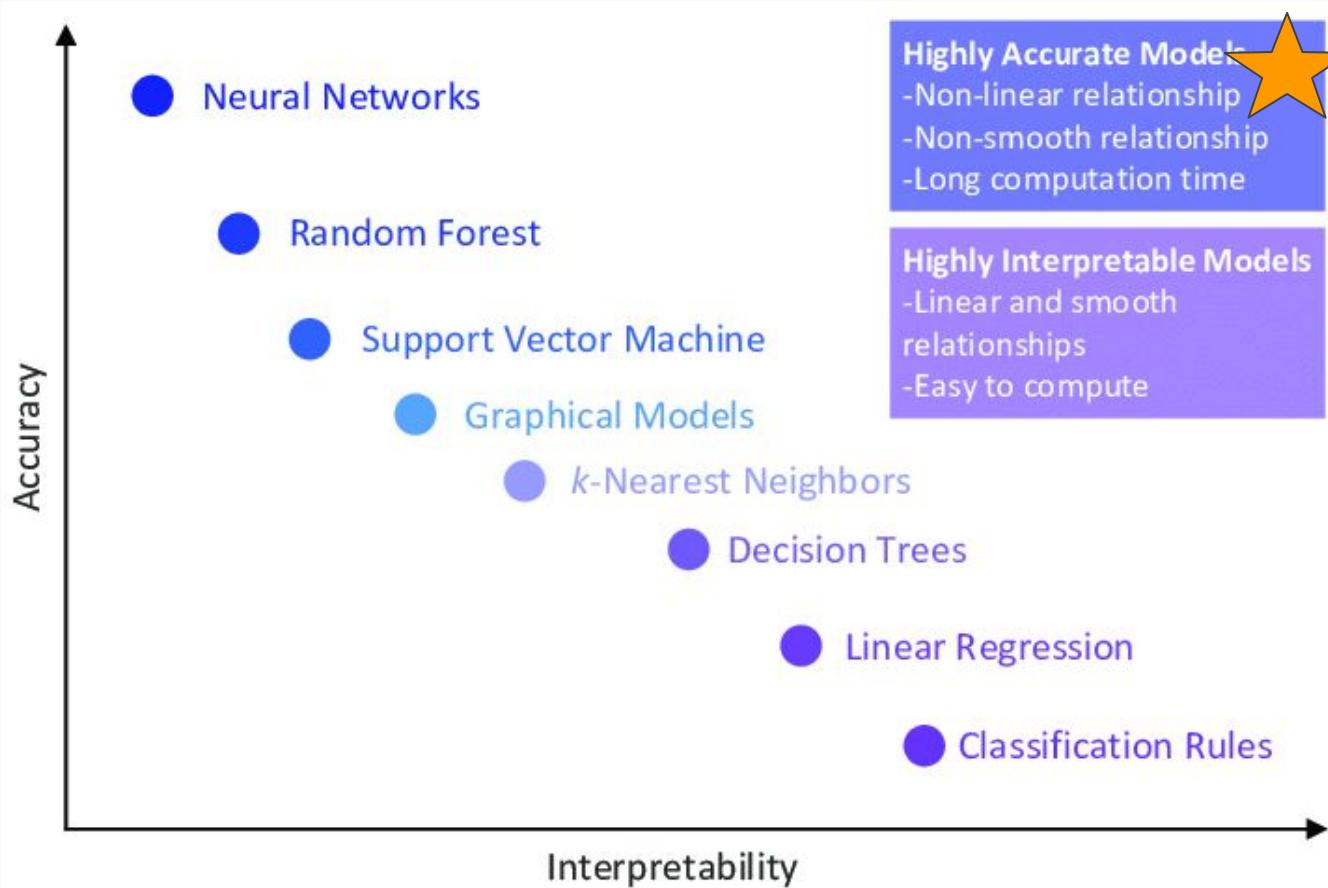
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AI vs Machine Learning vs Deep Learning

- **Artificial intelligence**: build intelligent programs and machines that can creatively solve problems, which has always been considered a human prerogative.
- **Machine learning** is a subset of artificial intelligence (AI) that provides systems the ability to automatically learn and improve from experience without being explicitly programmed. In ML, there are different algorithms (e.g. neural networks) that help to solve problems.
- **Deep learning** is a subset of machine learning, which uses the neural networks to analyze different factors with a structure that is similar to the human neural system.



Interpretability vs accuracy



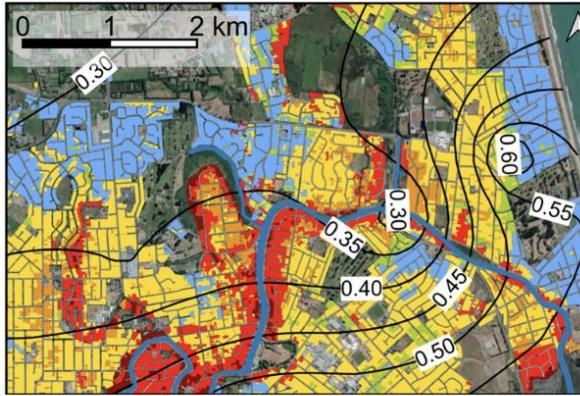
Lateral Spreading

Decision Trees
&
Random Forest

Liquefaction in NZ

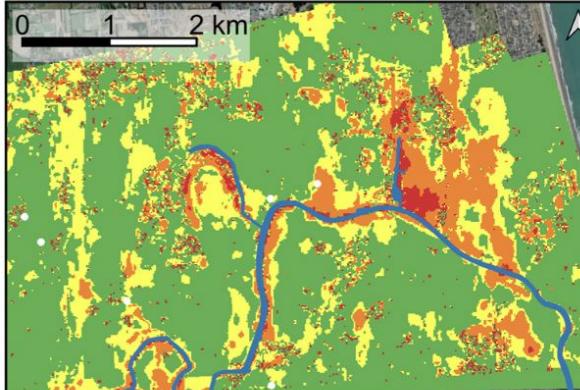
(a) Observed liquefaction related damage

- Conditional median PGA (g)
- No damage
- Minor cracks no ejecta
- No LS - minor to moderate ejecta
- No LS - large ejecta
- Moderate to major LS
- Severe LS



(b) Observed displacement (m)

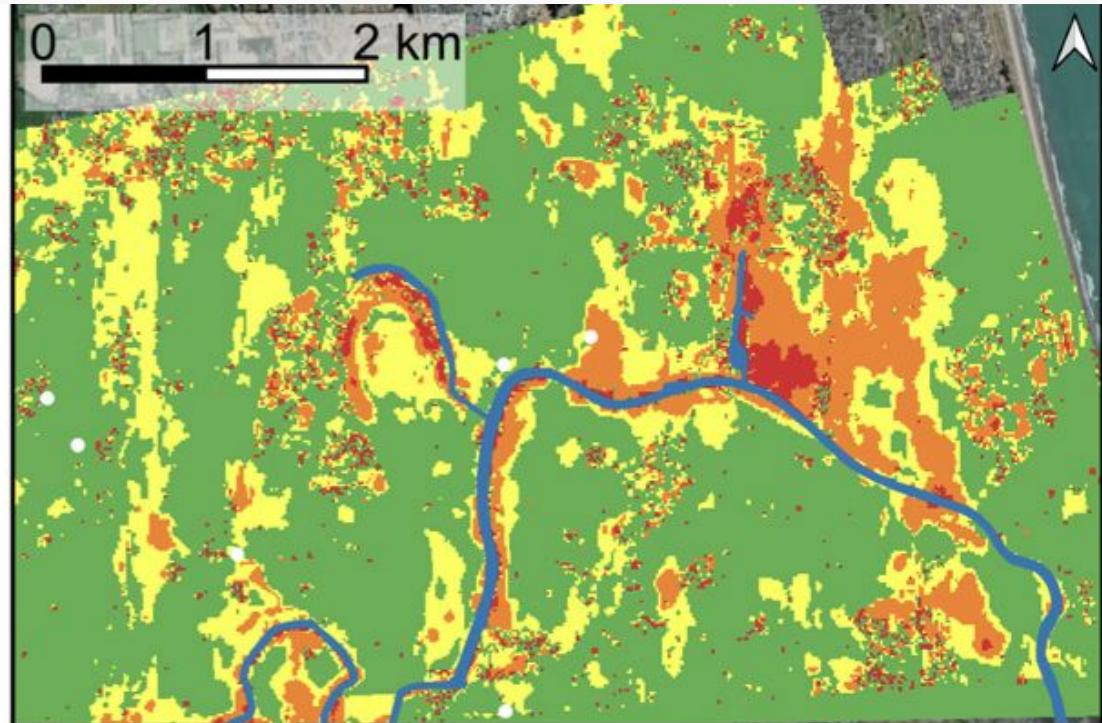
- None (< 0.30)
- 0.30 - 0.50
- 0.50 - 1.00
- > 1.00



Predicting lateral spreading in NZ

Observed
displacement (m)

- None (< 0.30)
- 0.30 - 0.50
- 0.50 - 1.00
- > 1.00



Durante and Rathje, 2021

Predicting lateral spreading in NZ

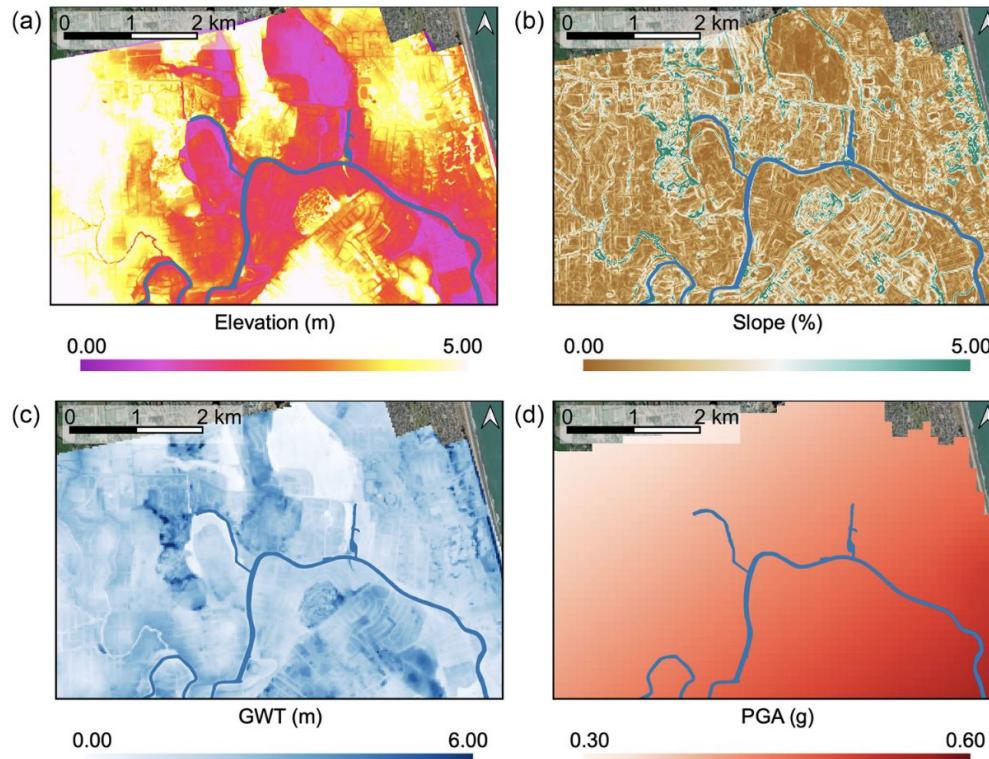
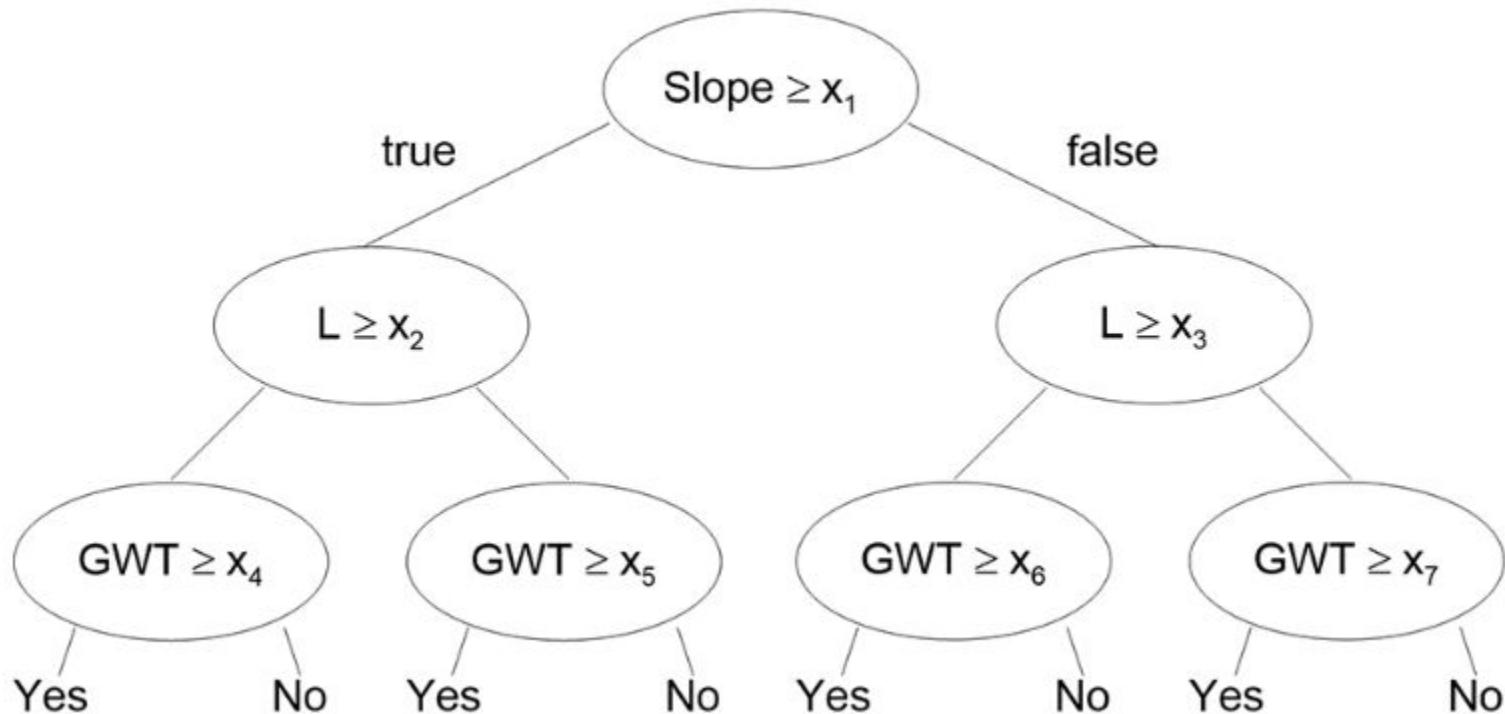


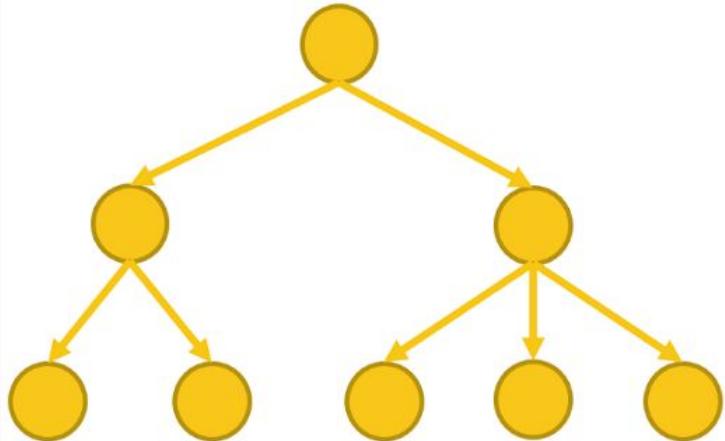
Figure 4. Spatial distribution of geometric and event-specific input features considered in ML models:
(a) ground elevation, (b) ground slope, (c) GWT depth, and (d) PGA.

Classification - Decision Tree

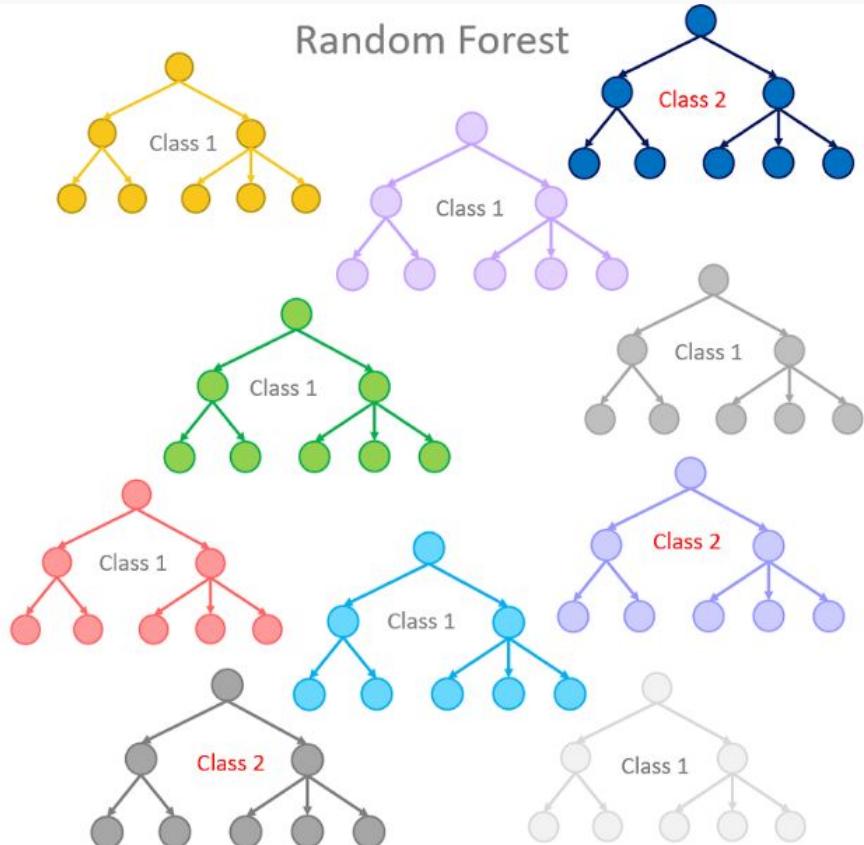


Random Forest

Single Decision Tree



Random Forest



Random Forest model

Table 3. Summary of features used in each RF model analyzed

		Feature					
		L (m)	GWT (m)	Slope (%)	PGA (g)	Elevation (m)	CPT data
No CPT data	Model 0	✓	✓	✓	○	○	○
	Model 1	✓	✓	✓	✓	○	○
	Model 2	✓	✓	✓	○	✓	○
	Model 3	✓	✓	✓	✓	✓	○
CPT data	Model 4	✓	✓	✓	✓	○	✓
	Model 5	✓	✓	✓	✓	✓	✓

GWT: ground water table; PGA: peak ground acceleration; CPT: cone penetration tests.

Durante and Rathje, 2021

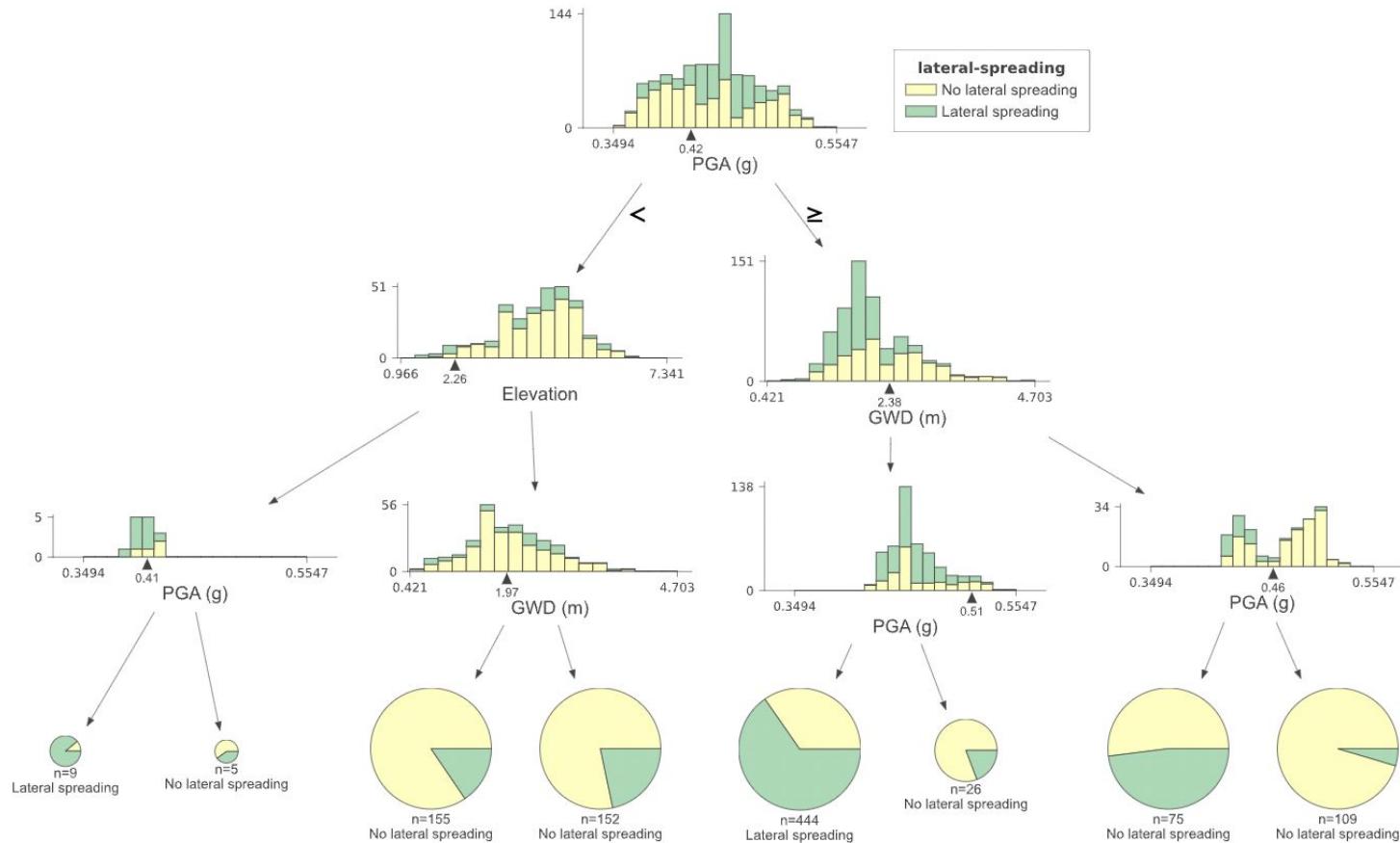
Random Forest - Performance

Table 4. Evaluation metrics for RF models for Yes/No and displacement classification problems

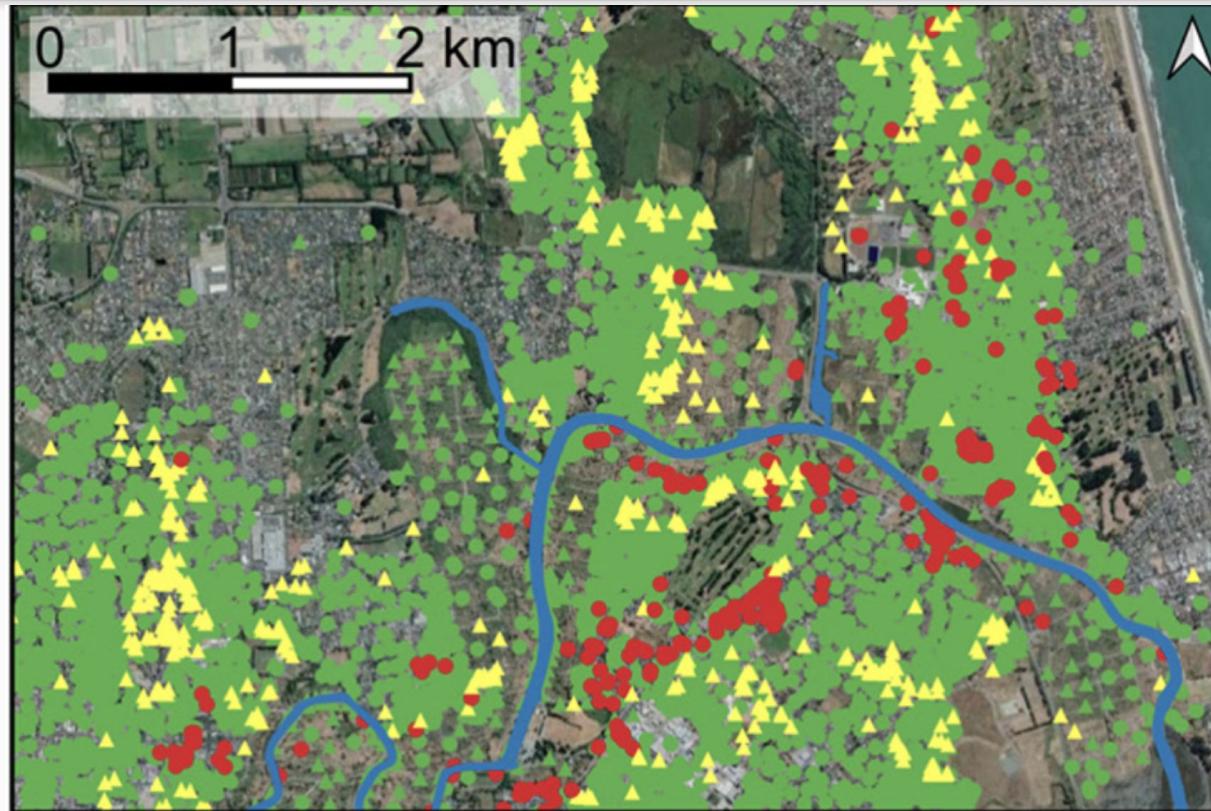
		No CPT data				CPT data	
		Model 0	Model 1	Model 2	Model 3	Model 4	Model 5
Y/N	Accuracy (Overall)	0.76	0.85	0.82	0.88	0.85	0.87
	Recall—Yes	0.58	0.75	0.74	0.82	0.76	0.78
	Recall—No	0.90	0.92	0.88	0.93	0.92	0.93
	Precision—Yes	0.80	0.88	0.82	0.89	0.87	0.89
	Precision—No	0.75	0.84	0.83	0.87	0.84	0.85
	ROC AUC	0.76	0.88	0.84	0.90	0.86	0.88
DISPL	Accuracy (Overall)	0.78	0.88	0.86	0.89	0.88	0.89
	Recall—Class 0	0.88	0.91	0.93	0.92	0.91	0.91
	Recall—Class 1	0.67	0.87	0.79	0.89	0.88	0.90
	Recall—Class 2	0.27	0.42	0.33	0.42	0.53	0.49
	Precision—Class 0	0.79	0.90	0.86	0.92	0.90	0.92
	Precision—Class 1	0.74	0.84	0.84	0.85	0.85	0.84
	Precision—Class 2	0.97	0.98	0.97	0.94	0.95	0.93
	ROC AUC	0.82	0.89	0.87	0.90	0.86	0.88

CPT: cone penetration tests; ROC: receiver operating characteristic; AUC: area under the ROC curve; Y/N: Yes/No Classification problem; DISPL: Class Displacement Classification problem.

Visualizing the first tree in RF



Random forest prediction of lateral spreading



Durante and Rathje, 2021

▲ True Positive (TP) ● True Negative (TN) ● False Positive (FP) ▲ False Negative (FN)

SHAP Value: Contribution of each variable



$$A: v(\{A\}) - v(\{\}) = 10 - 0 = 10$$

$$B: v(\{A, B\}) - v(\{A\}) = 60 - 10 = 50$$

$$C: v(\{A, B, C\}) - v(\{A, B\}) = 100 - 60 = 40$$

$$v(\{\}) = 0$$

$$v(\{A\}) = 10$$

$$v(\{B\}) = 20$$

$$v(\{C\}) = 30$$

$$v(\{A, B\}) = 60$$

$$v(\{B, C\}) = 70$$

$$v(\{A, C\}) = 90$$

$$v(\{A, B, C\}) = 100$$

$$\{\} \rightarrow \{A\} \rightarrow \{A, B\} \rightarrow \{A, B, C\} \parallel A = 10, B = 50, C = 40$$

$$\{\} \rightarrow \{A\} \rightarrow \{A, C\} \rightarrow \{A, B, C\} \parallel A = 10, B = 10, C = 80$$

$$\{\} \rightarrow \{B\} \rightarrow \{A, B\} \rightarrow \{A, B, C\} \parallel A = 40, B = 20, C = 40$$

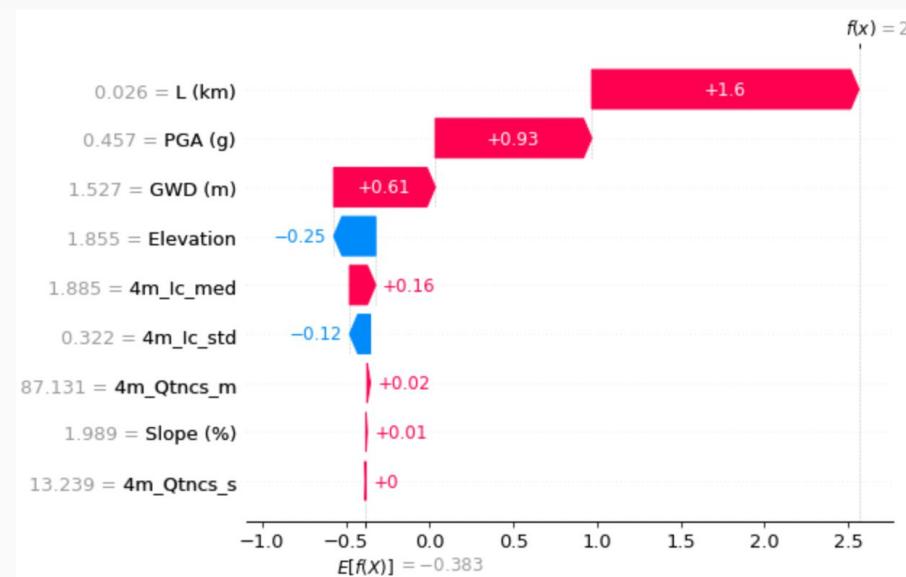
$$\{\} \rightarrow \{B\} \rightarrow \{B, C\} \rightarrow \{A, B, C\} \parallel A = 30, B = 20, C = 50$$

$$\{\} \rightarrow \{C\} \rightarrow \{B, C\} \rightarrow \{A, B, C\} \parallel A = 30, B = 40, C = 30$$

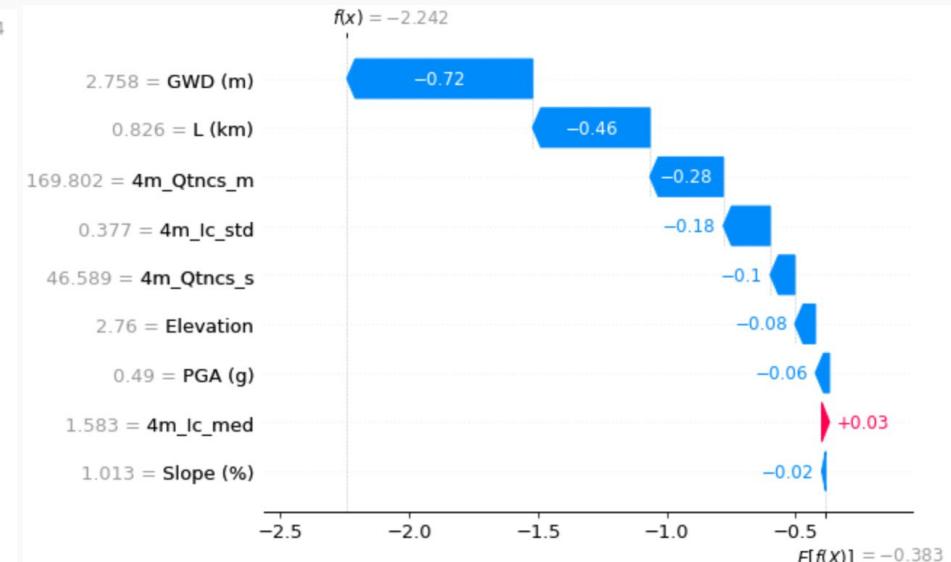
$$\{\} \rightarrow \{C\} \rightarrow \{A, C\} \rightarrow \{A, B, C\} \parallel A = 60, B = 10, C = 30$$

$$A_{avg} = 30, B_{avg} = 25, C_{avg} = 45$$

Random Forest post-hoc explanation

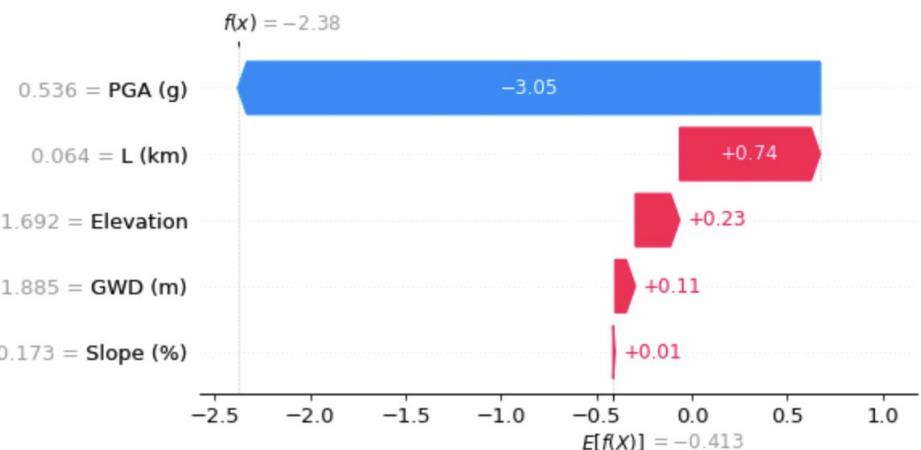


Lateral spreading - Prob (Lat spread) = 90%

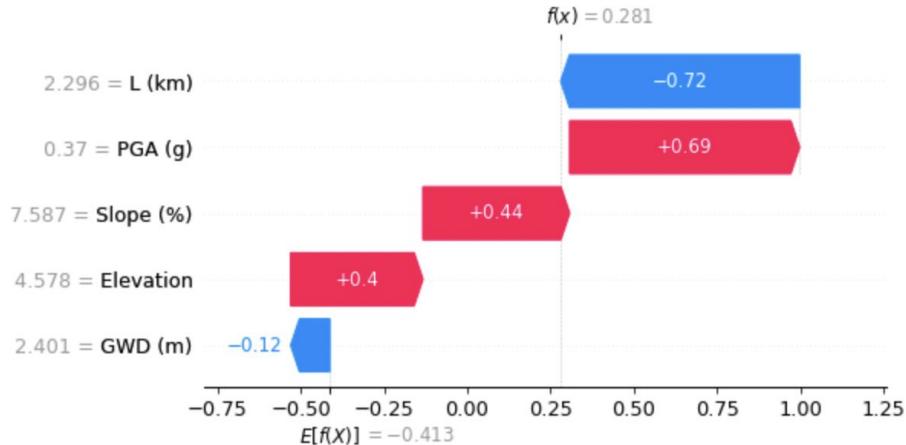


No lateral spreading - Prob (Lat spread) = 7%

Incorrect learning

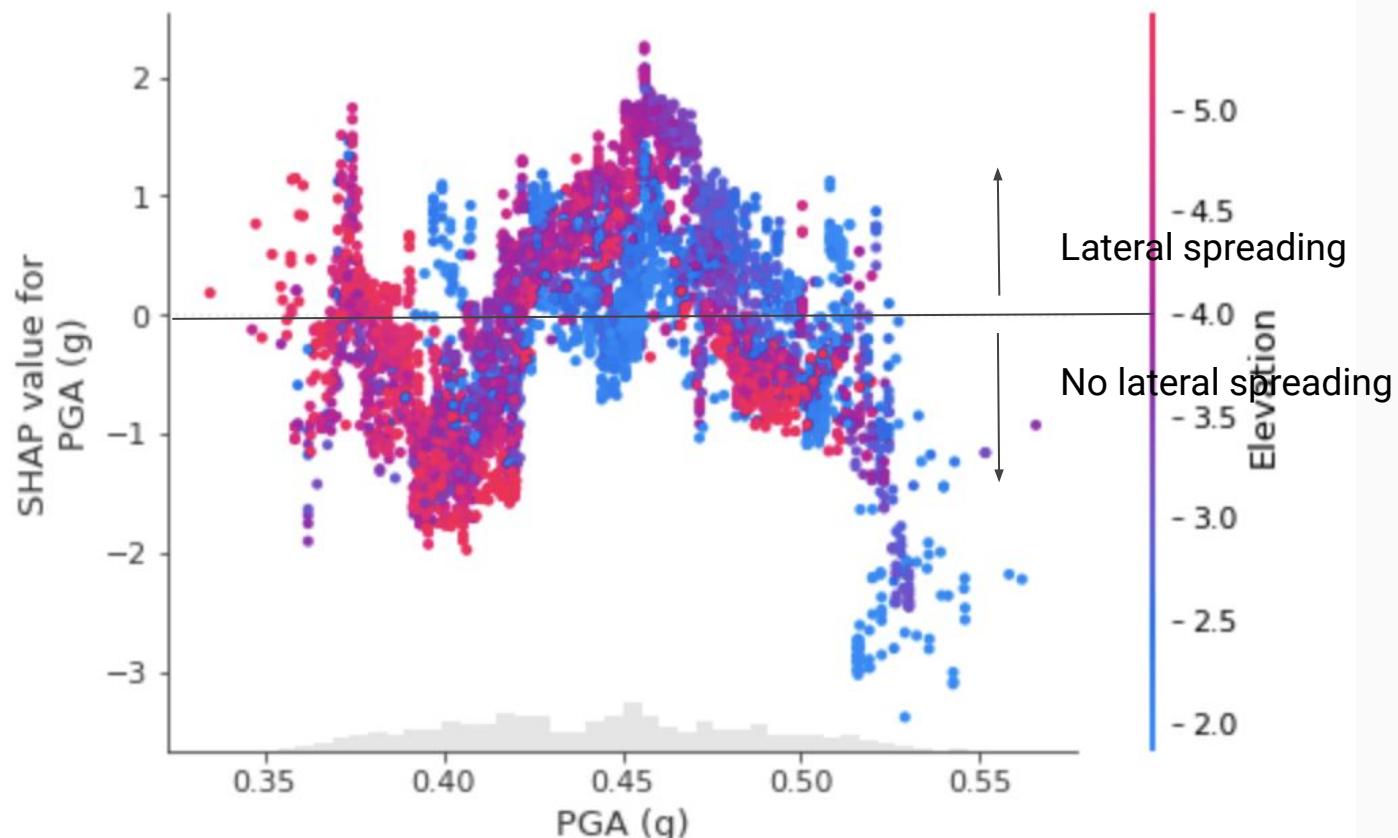


Incorrectly predicting no lateral spreading
Prob (Lat spread) = 8%

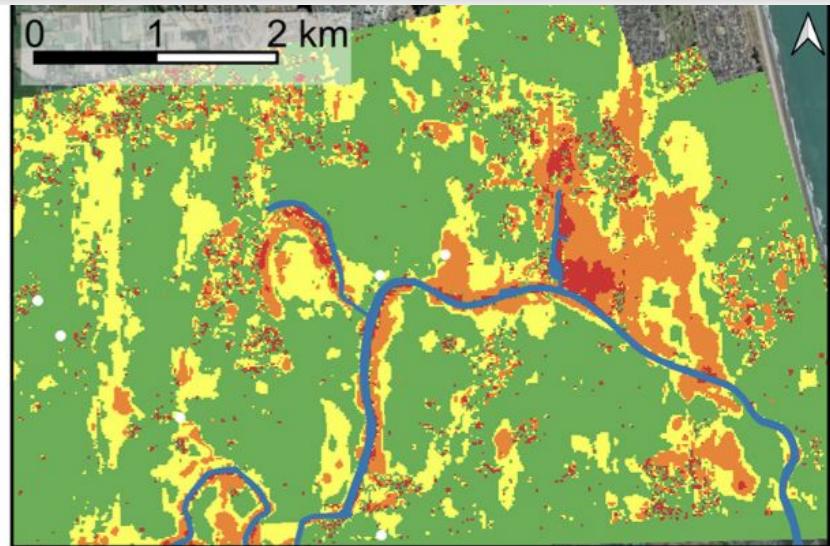
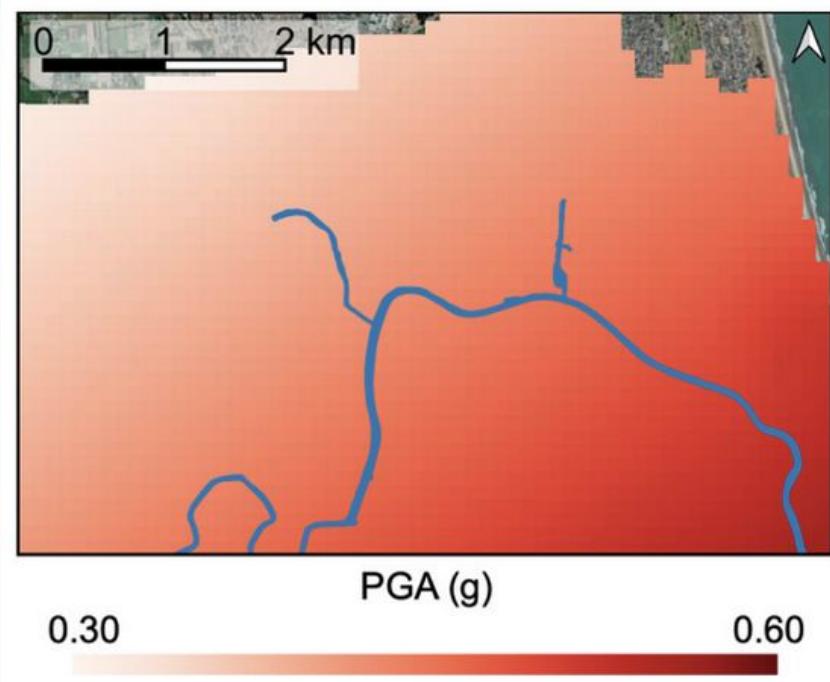


Incorrectly predicting lateral spreading
Prob (Lat spread) = 53%

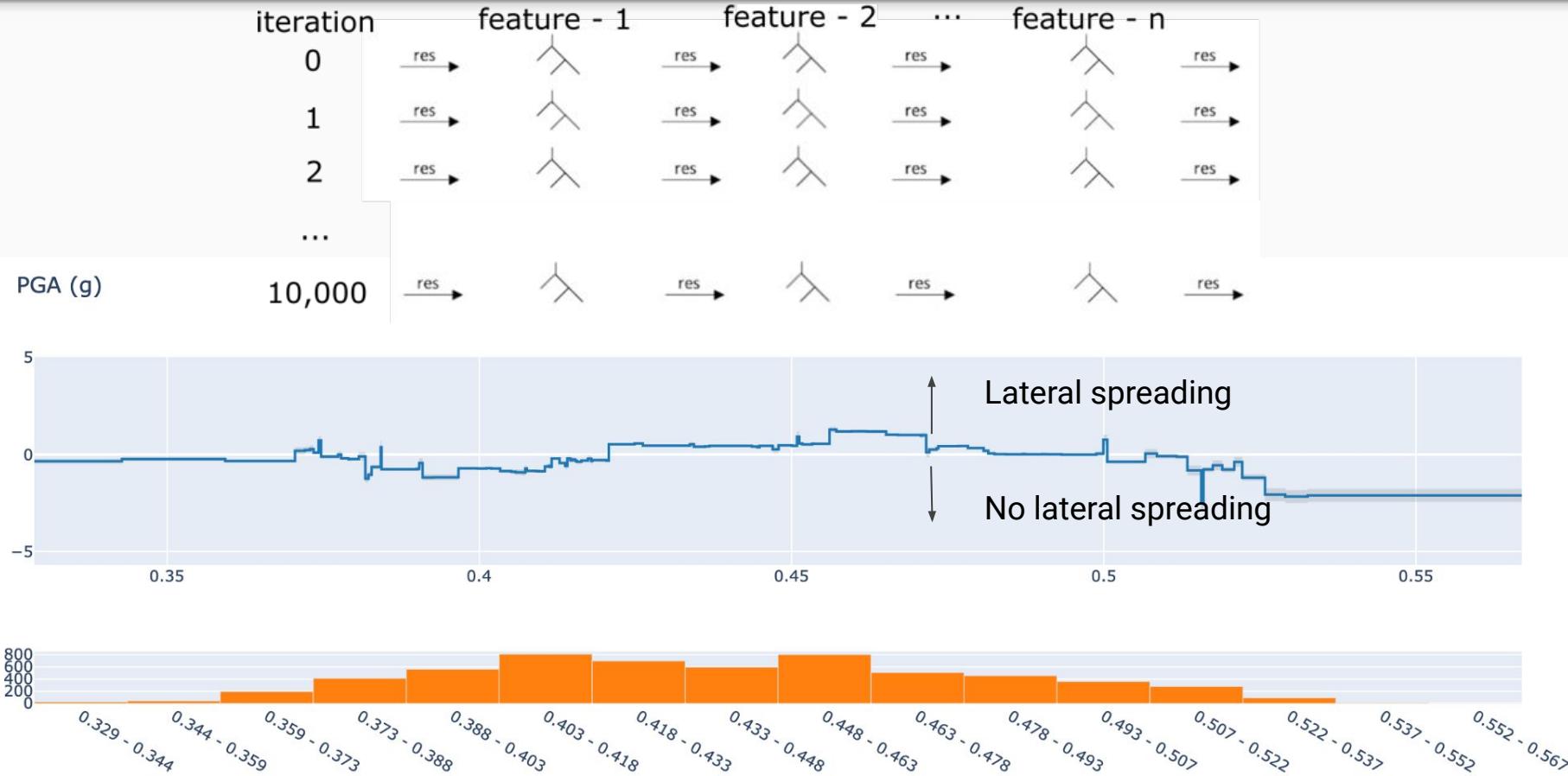
Why PGA has a bad influence?



Bad learning of PGA relation

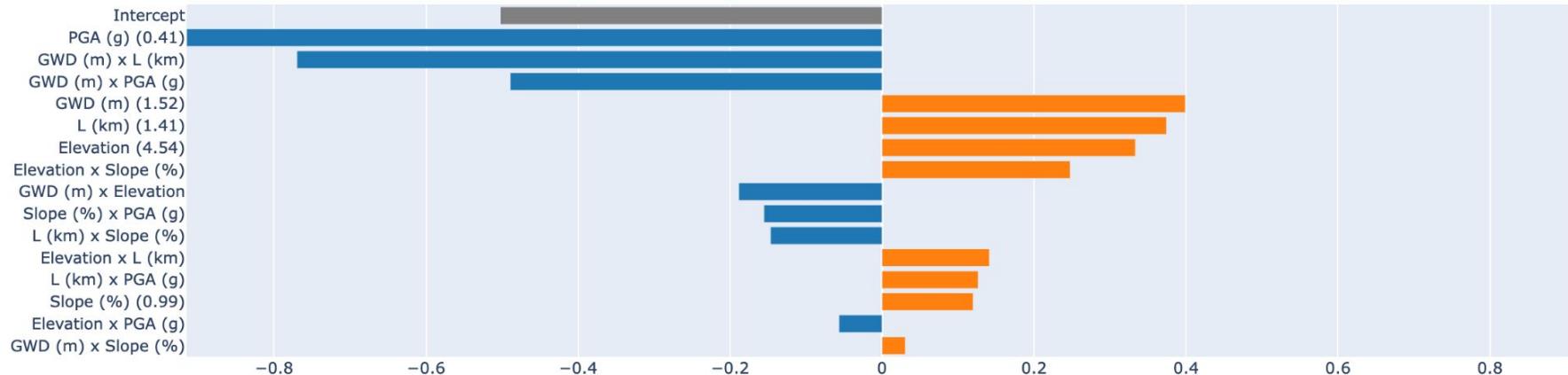


GlassBox models - Physics Informed (PIX) Trees



GlassBox models - PIX Trees

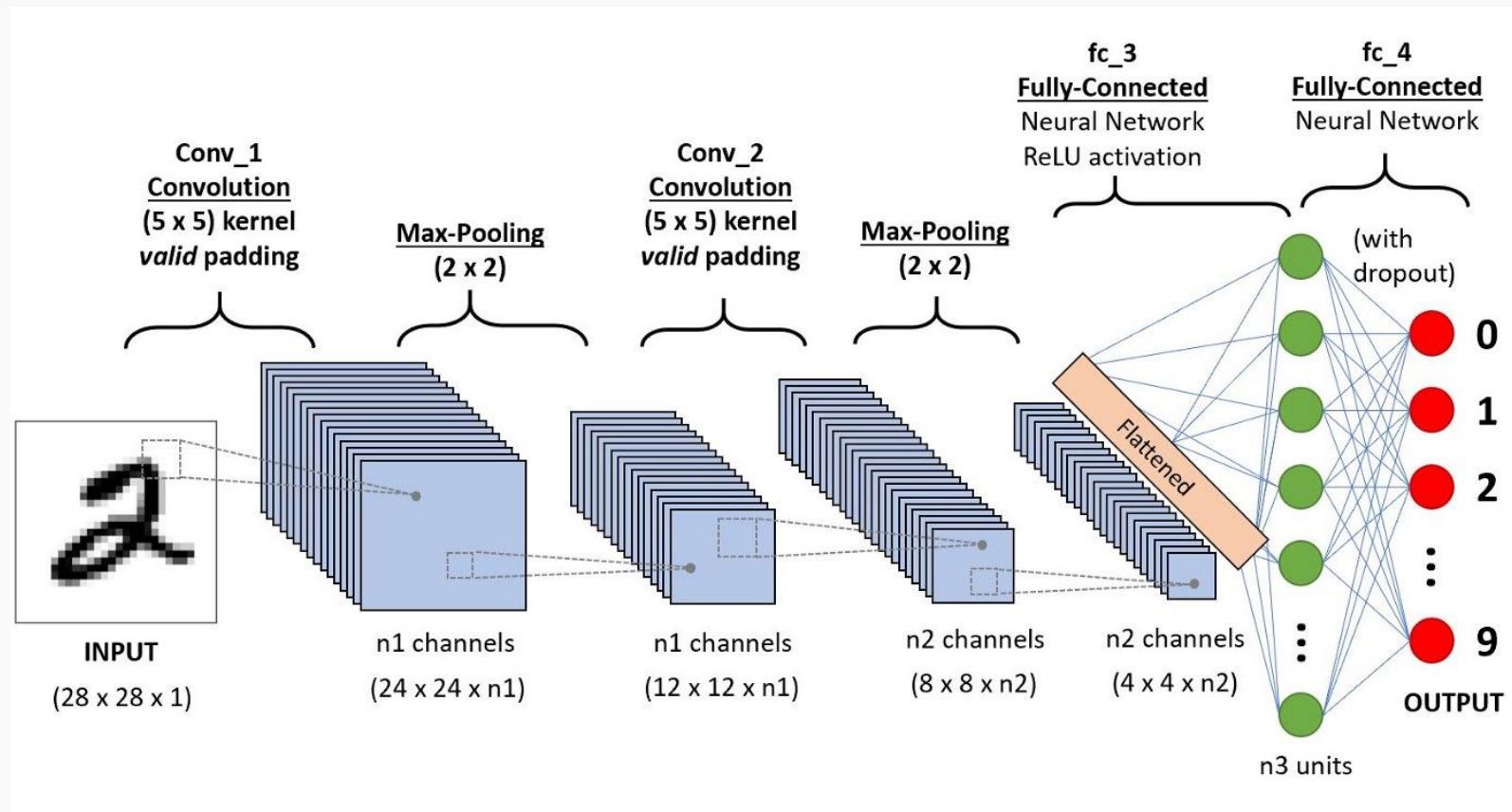
Predicted (0): 0.810 | Actual (0): 0.810



Convolutional Neural Network (CNN)

Full-Waveform Inversion

Convolutional Neural Network



CNN: Kernel

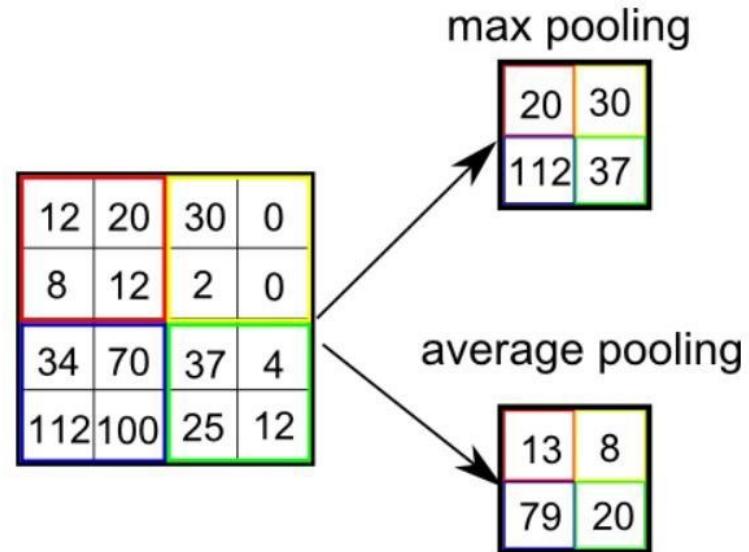
1 <small>x1</small>	1 <small>x0</small>	1 <small>x1</small>	0	0
0 <small>x0</small>	1 <small>x1</small>	1 <small>x0</small>	1	0
0 <small>x1</small>	0 <small>x0</small>	1 <small>x1</small>	1	1
0	0	1	1	0
0	1	1	0	0

Image



Convolved
Feature

Convolutional Layer



Pooling Layer

Building damage classifier - an explanation



Undamaged



Partially-damaged



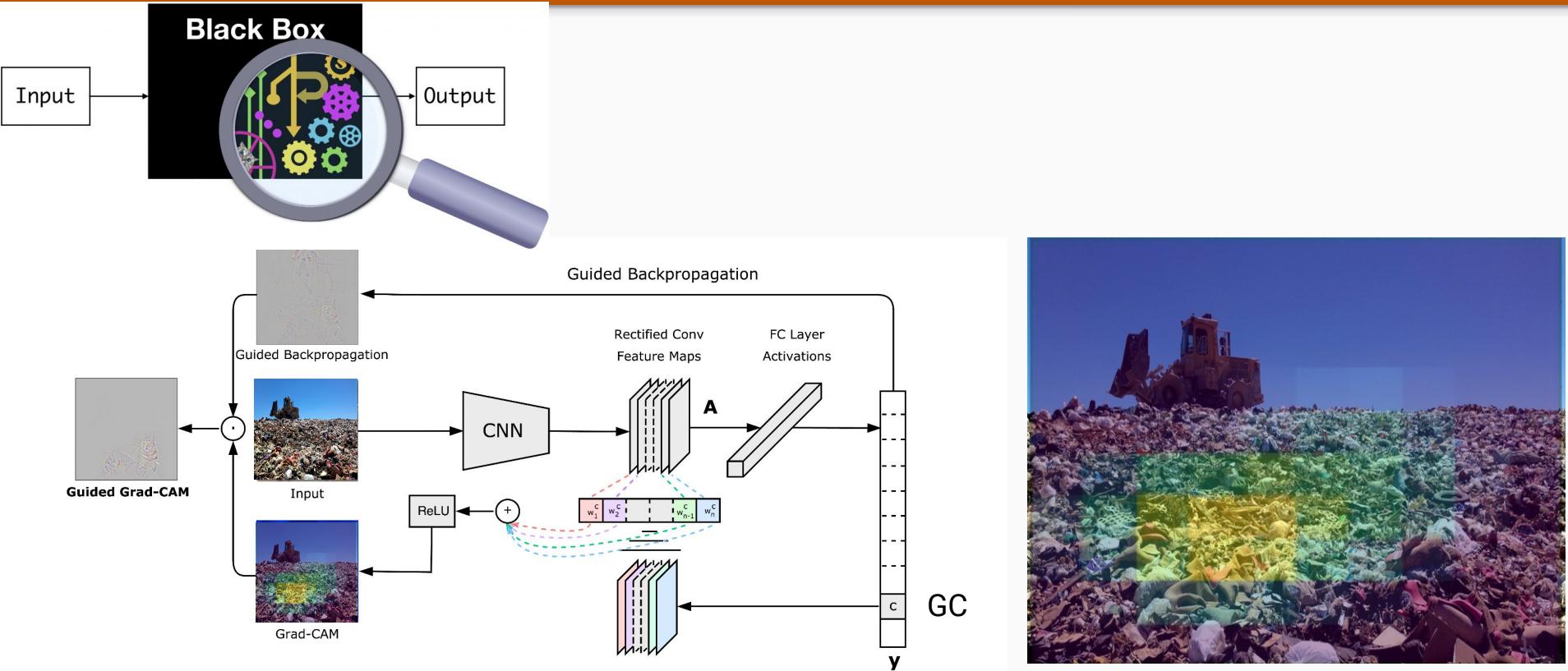
Completely-destroyed

Explaining a building image classifier

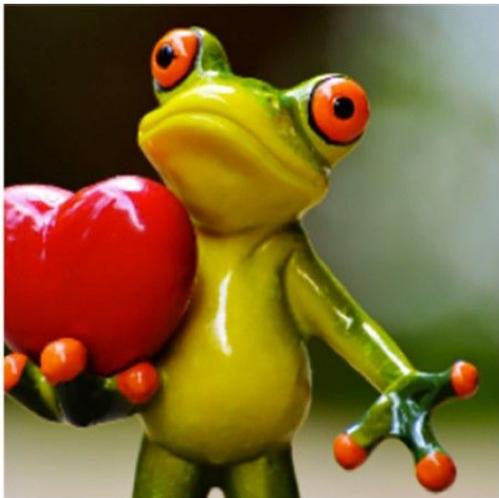


Predicted class: General Collapse
Transfer learning prediction: Ants

GradCAM Explanation



Post-hoc explanations - LIME Explainer

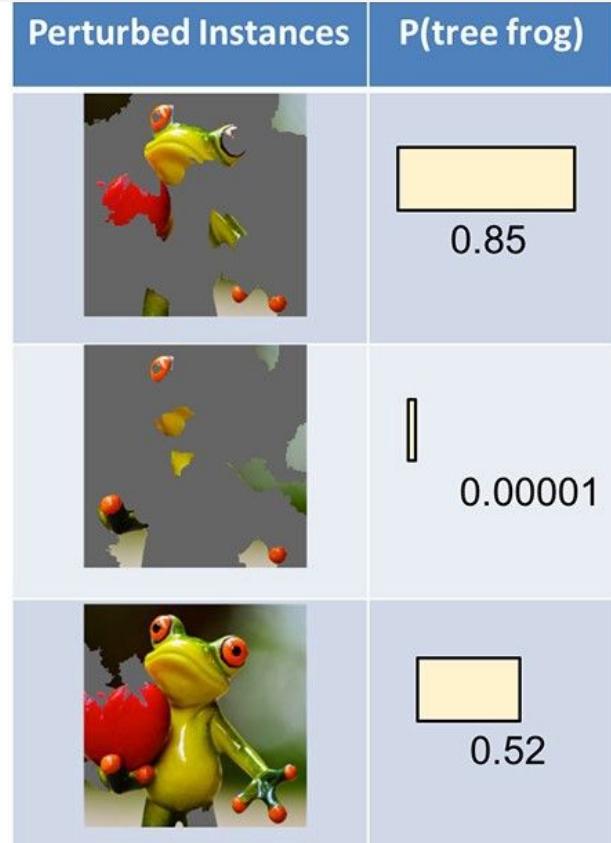


Original Image

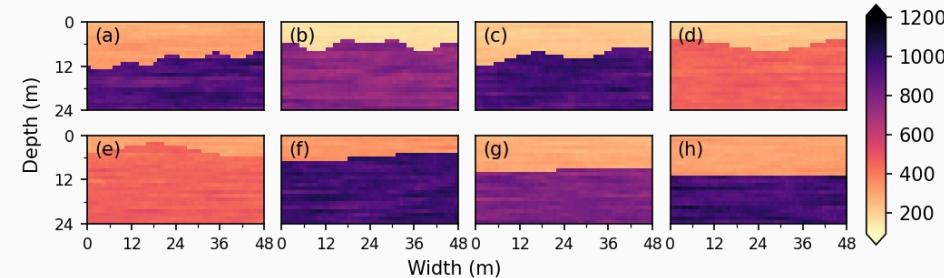
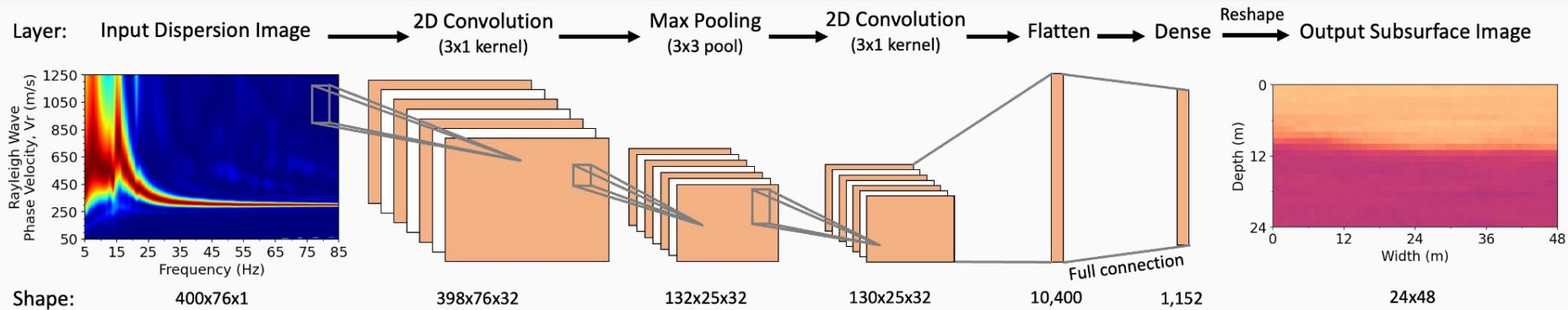
Tree Frog ($P = 0.54$)



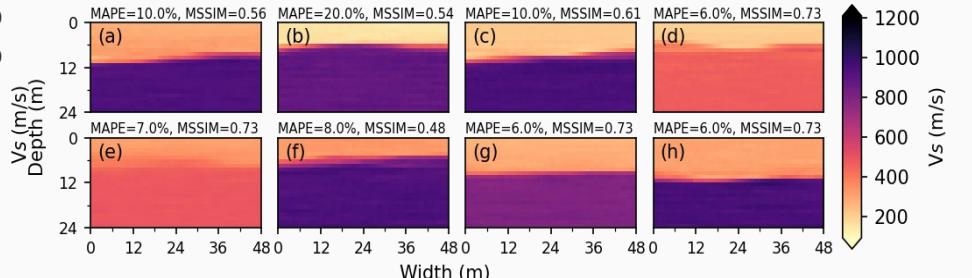
Interpretable Components



Convolutional Neural Network for inverse problem

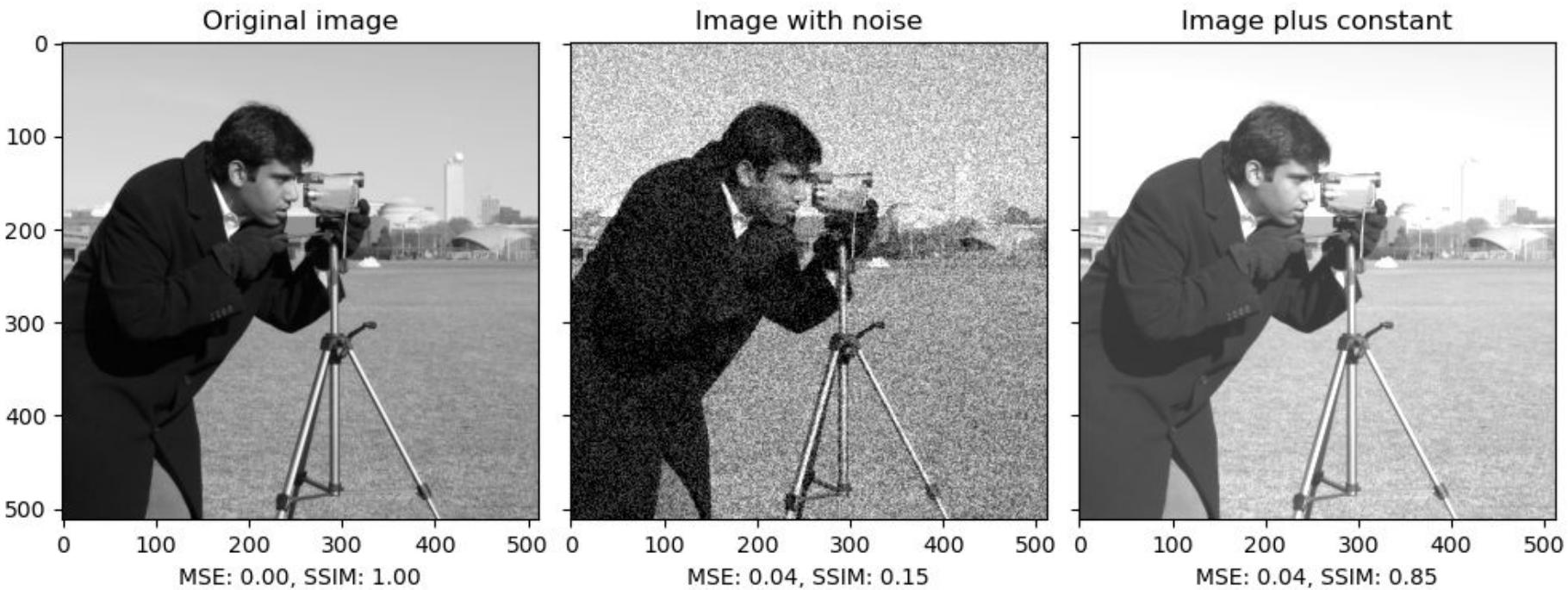


True Model



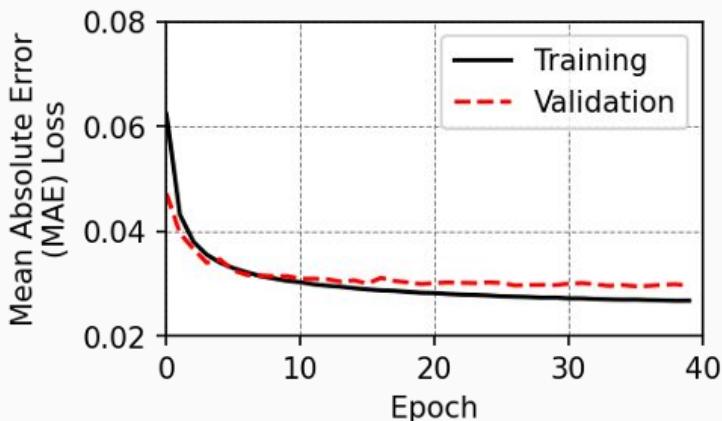
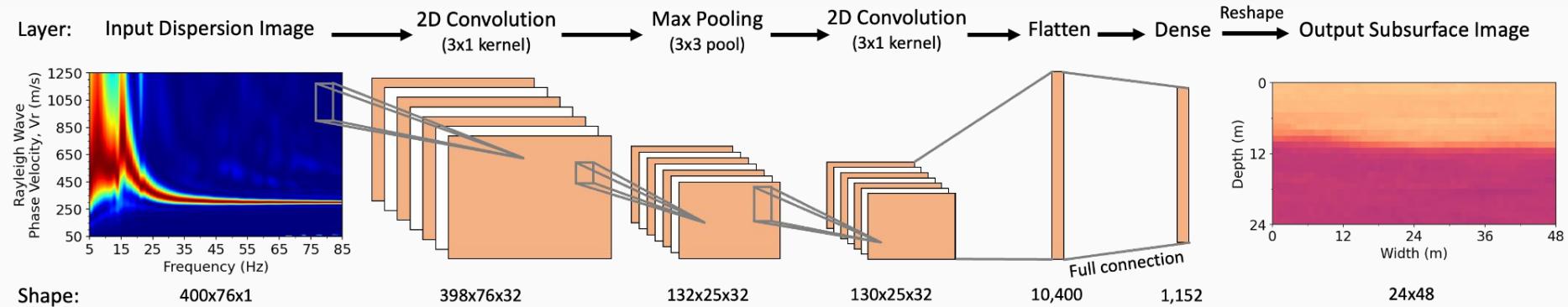
Predictions

Structural Similarity Index



https://scikit-image.org/docs/stable/auto_examples/transform/plot_ssim.html

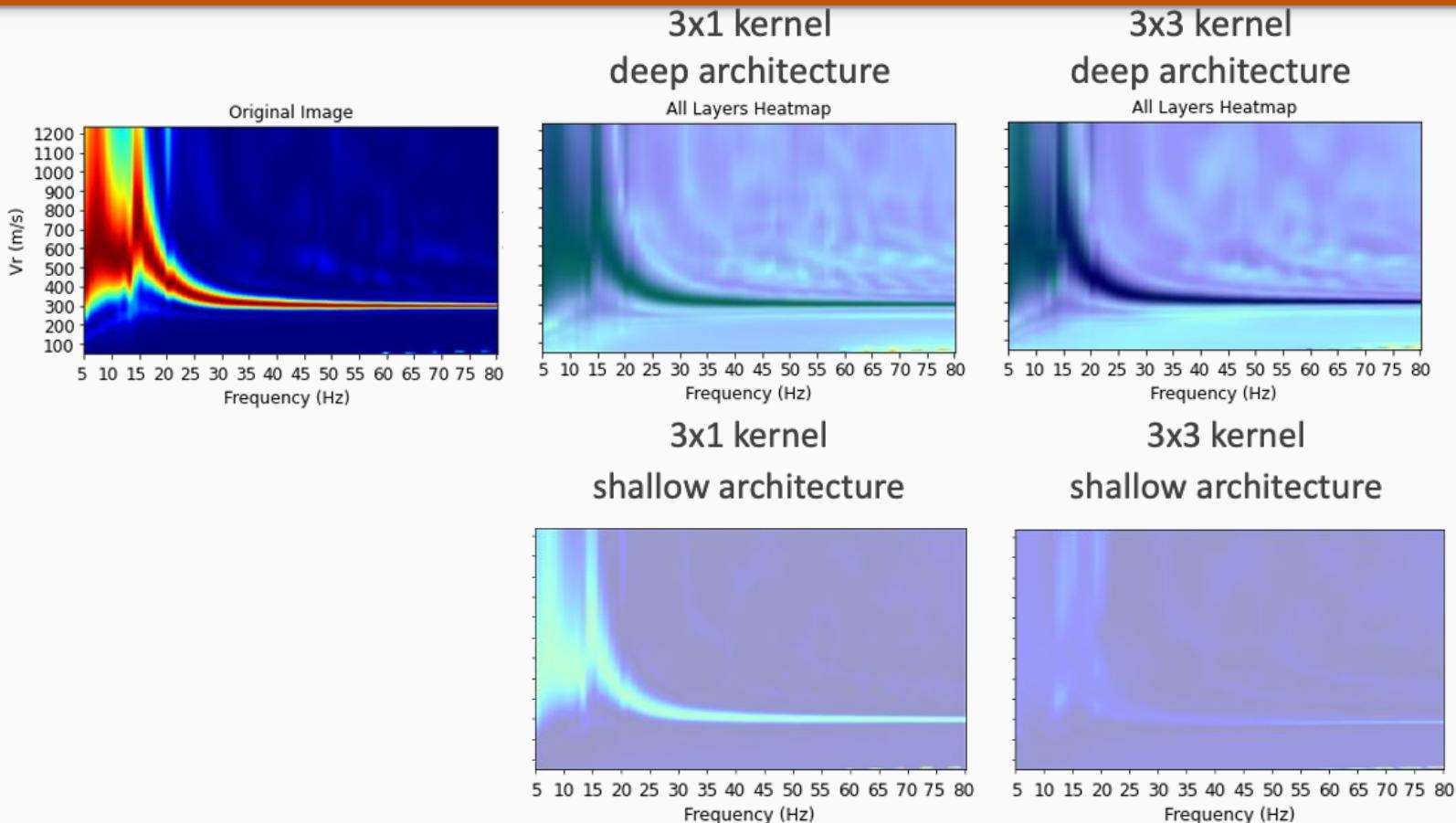
How to design a CNN



MAPE	Kernel Size: 3x1	Kernel Size: 3x3
Deep (5)	11.3 %	8.5 %
Shallow (3)	12.1 %	11.2 %

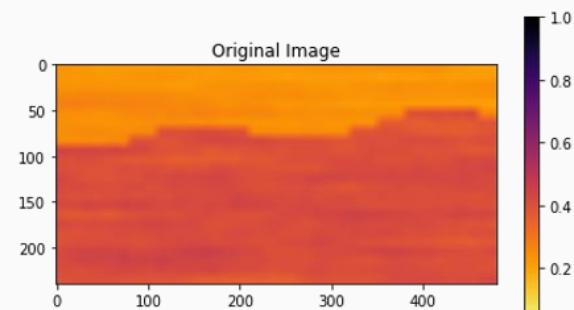
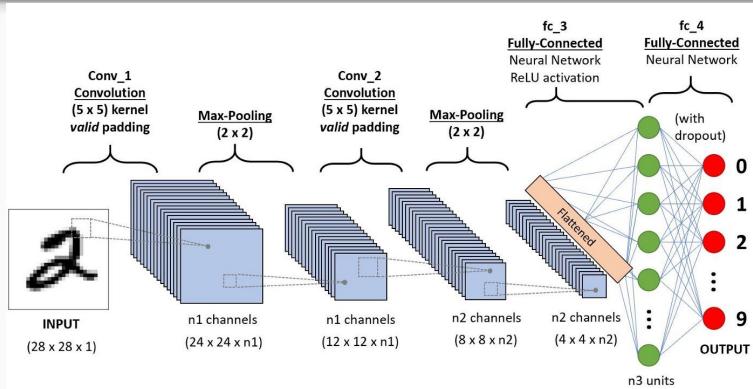
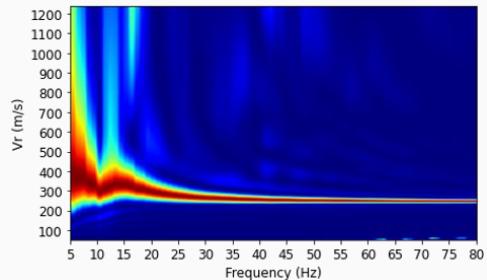
8.5 %

Designing a neural network with explainability



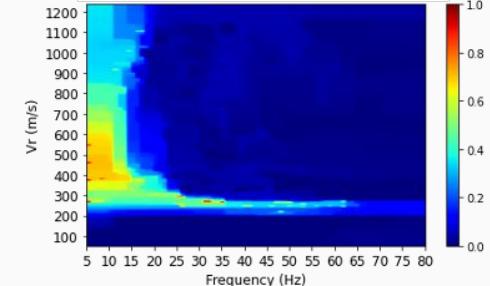
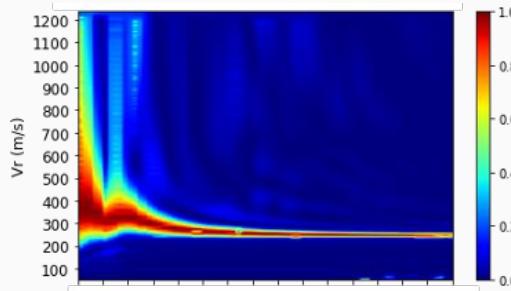
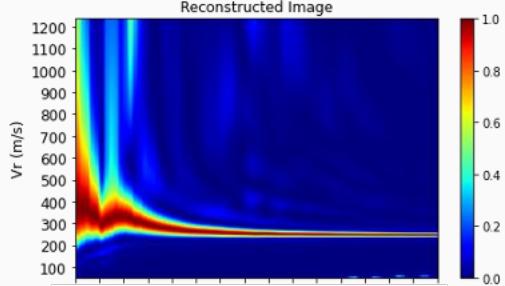
Inverting a neural network - Iteratively

Original image:

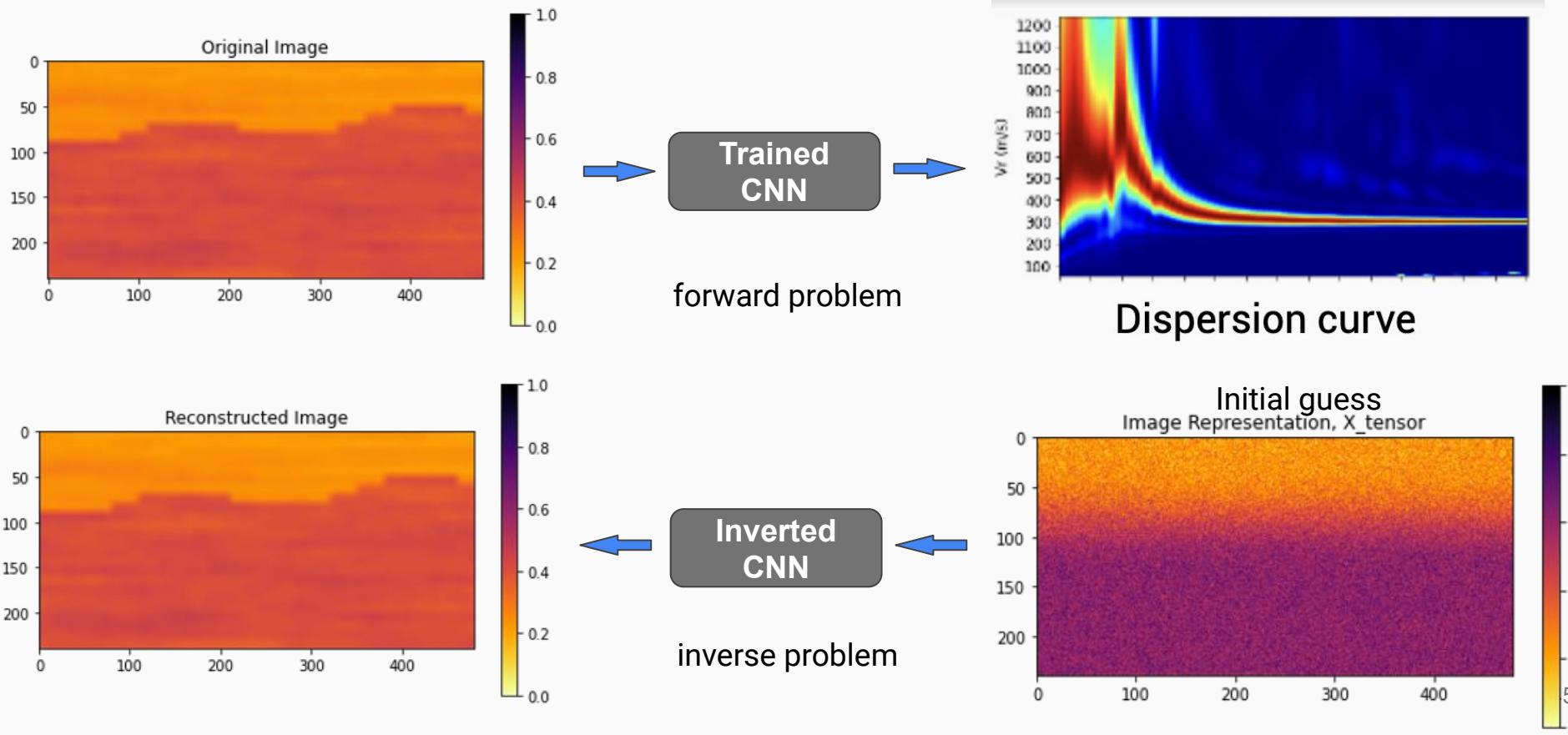


Deeper layers

Reconstructed Image



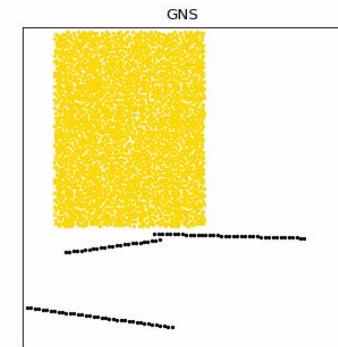
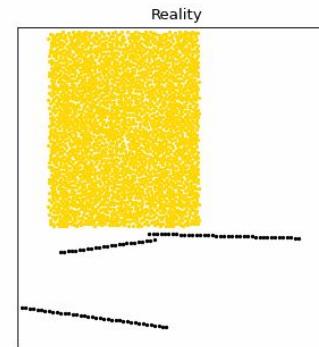
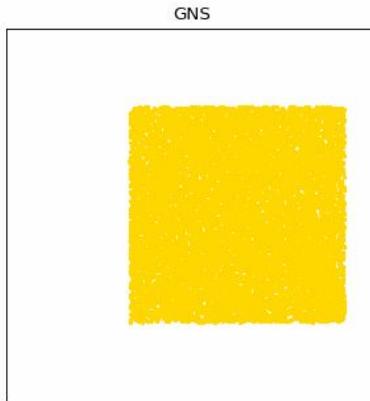
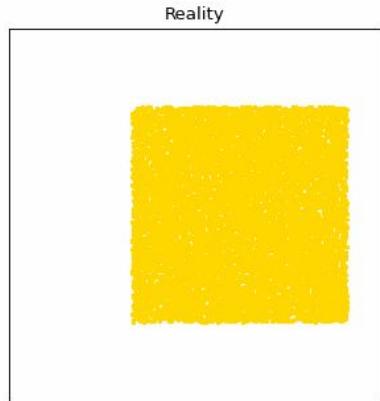
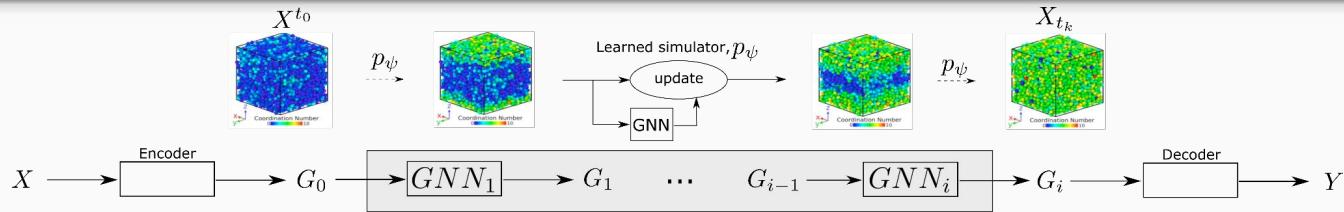
Using inversion to solve the inverse problem



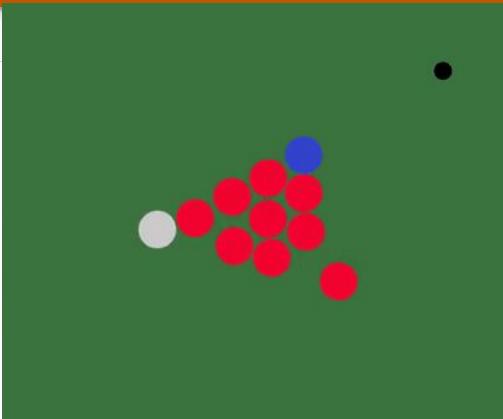
Future of Physics simulations

Knowledge Discovery and GNS

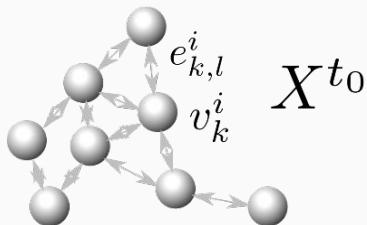
ML prediction of granular flows



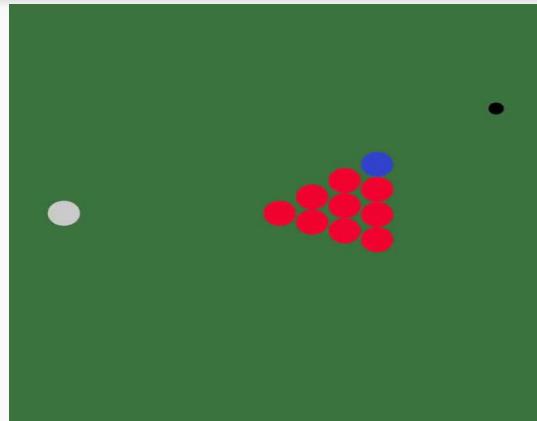
Knowledge discovery with AI



initial state



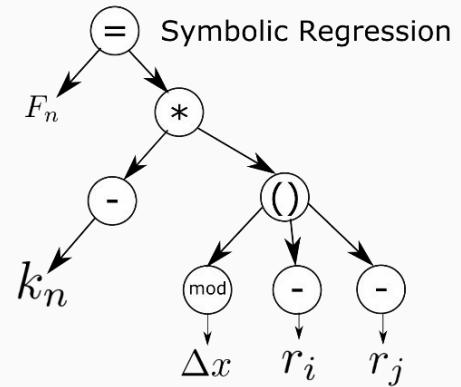
p_ψ
GNS



predicted dynamics



$$F_n = -k_n * (|\Delta x| - r_i - r_j)$$



Deriving analytical eq. linear spring with AI

Eq.	Derived equation	MSE	C_x	D_a
1	-198.72363	64747.52	1	Y
2	$(\Delta x + -198.92792)$	63938.996	3	N
3	$(-203.1408 + \exp(\Delta x))$	60907.68	4	N
4	$((\Delta x + -2.3484528) * 92.79602)$	27031.744	5	Y
5	$((\Delta x * (\mathbf{X}_1 + 92.75565)) + -218.16481)$	26830.58	7	N
6	$((\Delta x + (abs(r_1) * -1.1491286)) * 100.23312)$	21227.312	8	Y
7	$((\Delta x + ((abs(r_1) + 1.1013538) * -0.8038518)) * 98.86028)$	18721.219	10	Y
8*	$((\Delta x + (abs((\mathbf{r}_2 * -1.0) + \mathbf{r}_1) * -1.0)) * 100.0)$	3.76E-10	12	Y
9	$((\Delta x + (abs((r_2 * inv(-1.0)) + r_1) * -1.0)) * 99.9998)$	3.01E-10	15	N

C_x is the complexity and D_a represents if the expression passes dimensional analysis.
 * denotes the chosen solution.

$$F_n = k_n * abs(\Delta x - r_i - r_j)$$

Hook 'em Horns!

<https://geoelements.org>

This work was partially funded by NSF OAC: #2103937