

# 2021 Programming Bootcamp

## Machine Learning in Natural Hazard Engineering

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NSF award: CMMI 1612843

## Slides:

[https://github.com/NHERI-SimCenter/SimCenterAI\\_Workshop2021/blob/master/presentations/day1/Part1-2.pdf](https://github.com/NHERI-SimCenter/SimCenterAI_Workshop2021/blob/master/presentations/day1/Part1-2.pdf)

## Demos:

[https://github.com/charlesxwang/SimCenterAI\\_Workshop2021/tree/master/notebooks/day1](https://github.com/charlesxwang/SimCenterAI_Workshop2021/tree/master/notebooks/day1)

## Outline

### **Part 1 Conventional Machine Learning**

Introduction to machine learning

Applications in Natural Hazard Engineering

Algorithms in Conventional Machine Learning

Software and Platforms

Demos & Exercises

### **Part 2 Deep Learning**

Deep neural networks

CNN and Image Classification

Demos & Exercises

# **Part 1**

# **Conventional Machine Learning**

## Supervised Learning

- Classification
- Regression

## Unsupervised Learning

- Clustering
- Dimension reduction

## Reinforcement Learning

- Decisions
- Robotics
- ...

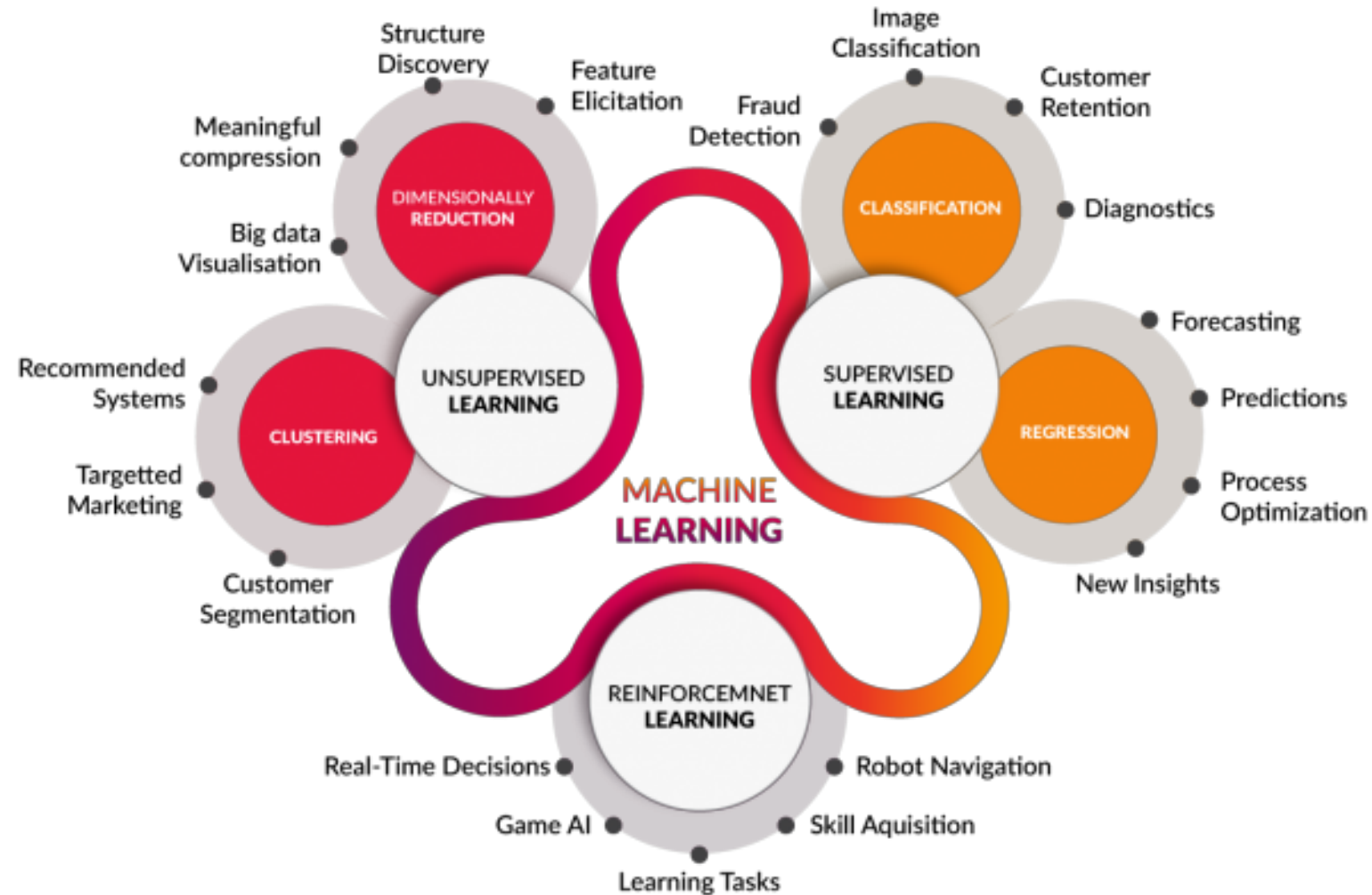


Image from ironhack

## Supervised Learning:

- Classification
- Regression

## Algorithms:

Regressions

Decision trees

Support Vector Machines

Linear discriminant analysis

K-nearest neighbor algorithm

Multilayer perceptron

...

Fit a function:  $y=f(x)$



x1	x2	x3	x4	x5	y
0.21	0.20	0.65	0.87	0.29	0.22
0.83	0.47	0.14	0.77	0.43	0.63
0.42	0.31	0.41	0.43	0.11	0.92
0.83	0.49	0.52	0.01	0.94	0.17
0.99	0.05	0.47	0.72	0.01	0.60
0.31	0.31	0.74	0.41	0.93	0.13
0.29	0.03	0.32	0.16	0.24	0.35
0.91	0.91	0.24	0.23	0.51	0.23
0.47	0.04	0.17	0.77	0.34	0.08
0.10	0.10	0.73	0.82	0.32	0.23
0.09	0.66	0.10	0.98	0.21	0.66
0.00	0.35	0.38	0.18	0.89	0.02

## Unsupervised Learning

- Clustering
- Dimension reduction

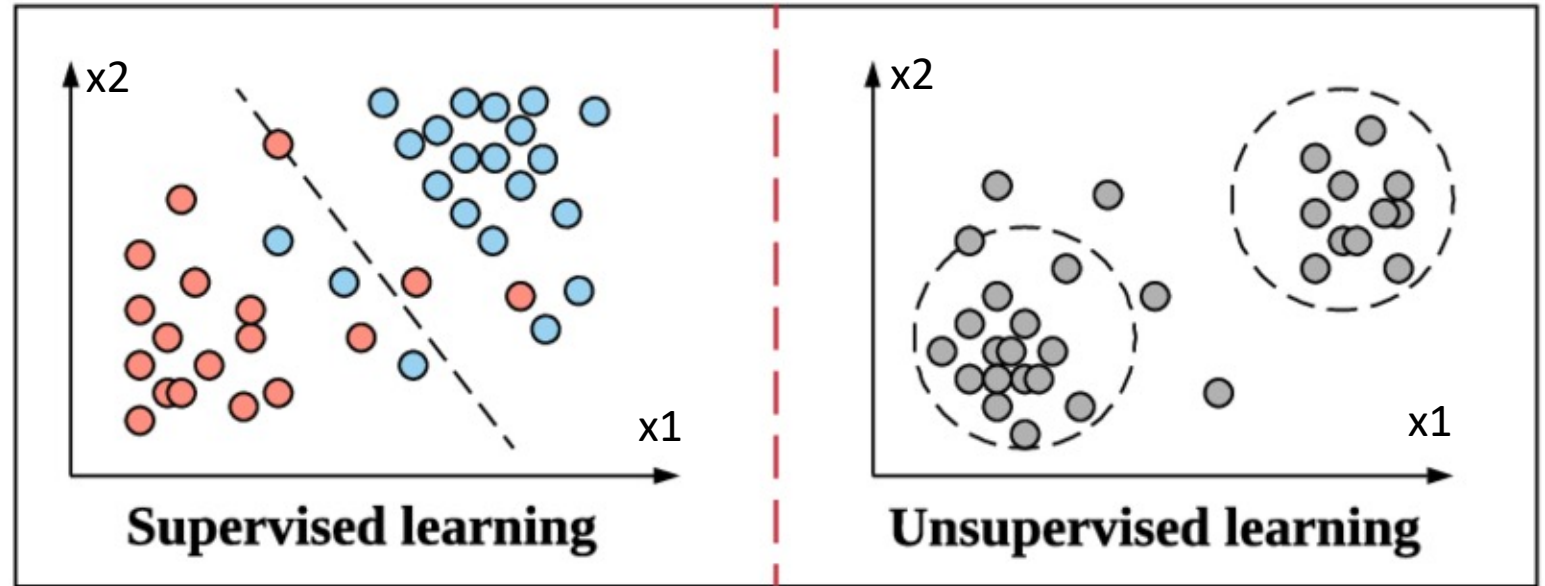
### Algorithms:

K-means

Principal component analysis

Autoencoder

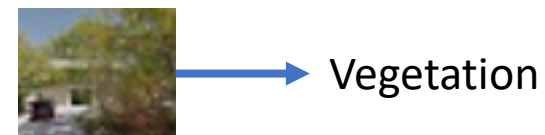
Generative adversarial networks



### Classification

Trained with **labeled data**

Can predict the class name



### Clustering

Trained with **unlabeled data**

Similar data points are grouped together



Group A

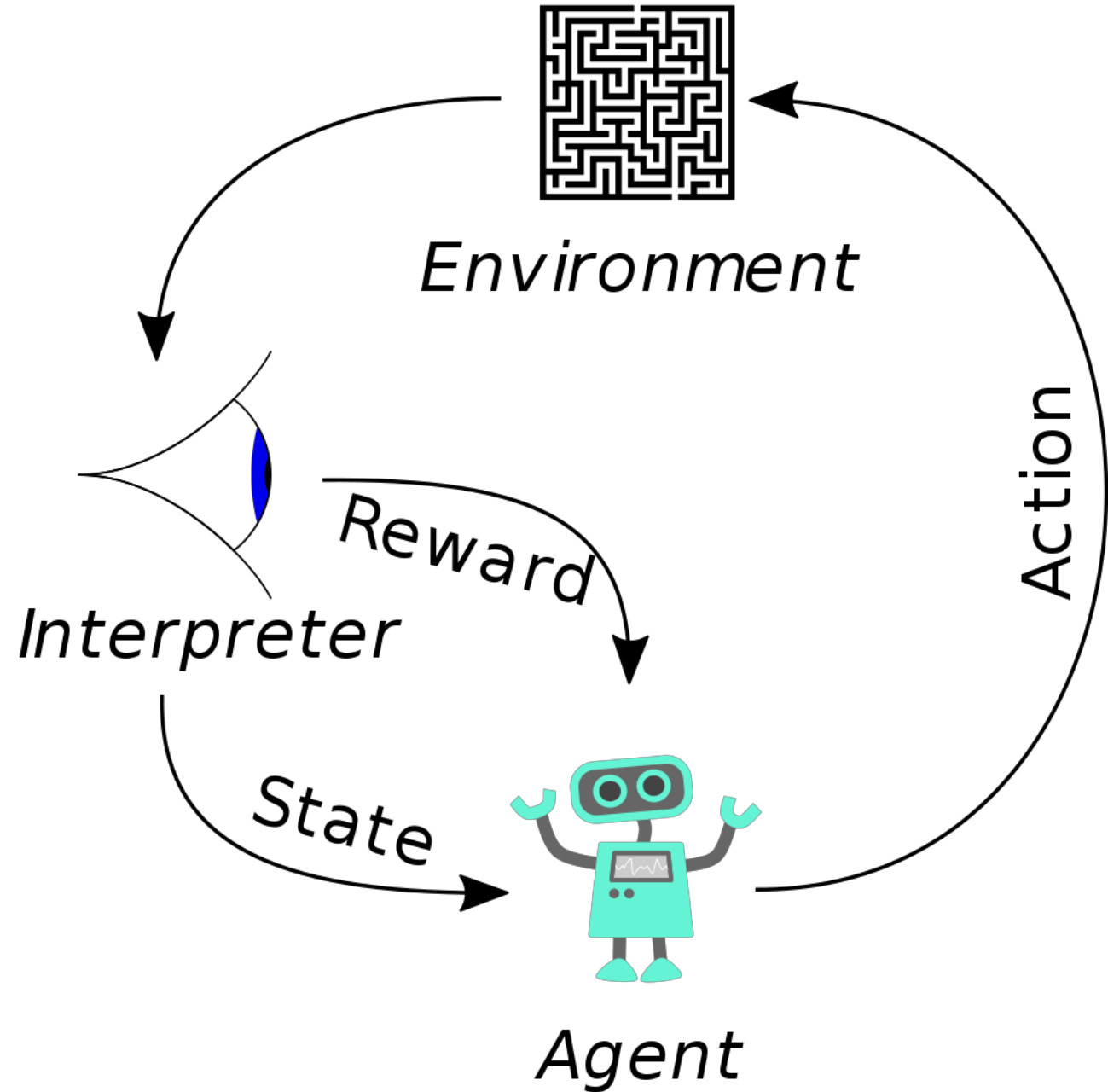
Group B

## Reinforcement Learning

- Decisions
- Robotics
- ...

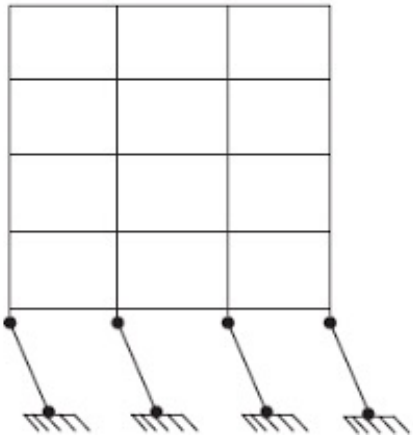
## Algorithms:

Q-learning  
SARSA  
DQN  
...

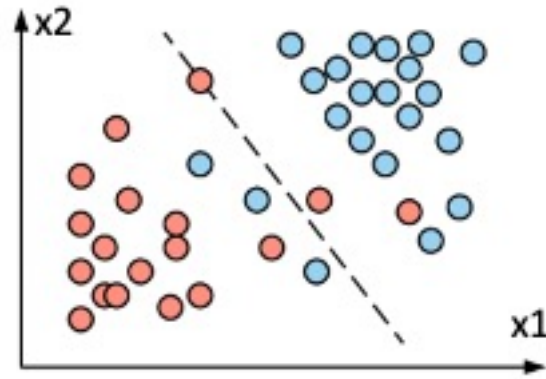




# Applications in Natural Hazard Engineering



Physics-based simulation



Statistical method (ML)

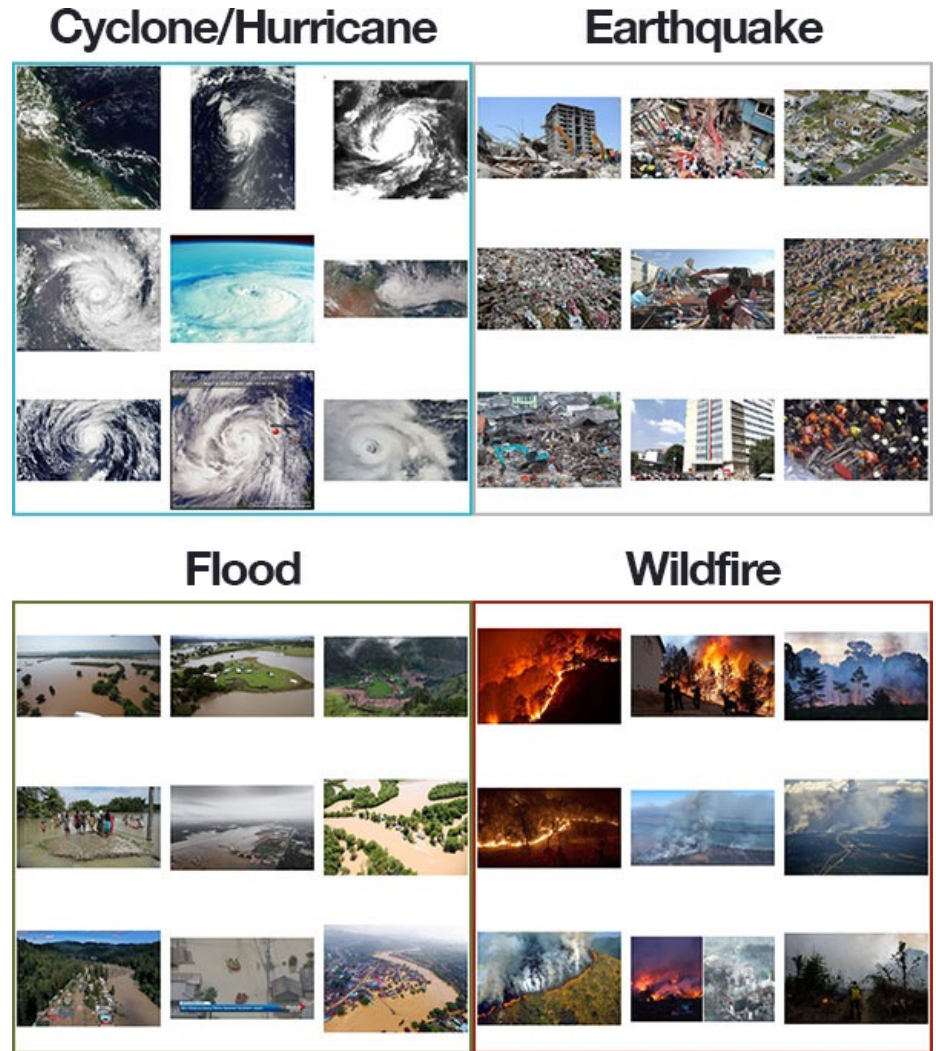


Image from Gautam Kumar

## Popular Algorithms in **Supervised Machine Learning** that are used in natural hazard engineering

Regression

Decision tree / Random forest

K-nearest neighbor

Support vector machines

Multilayer perceptron (Neural network)

...

**Keywords:**

**Data    Model    Training**

**Basic frame:**

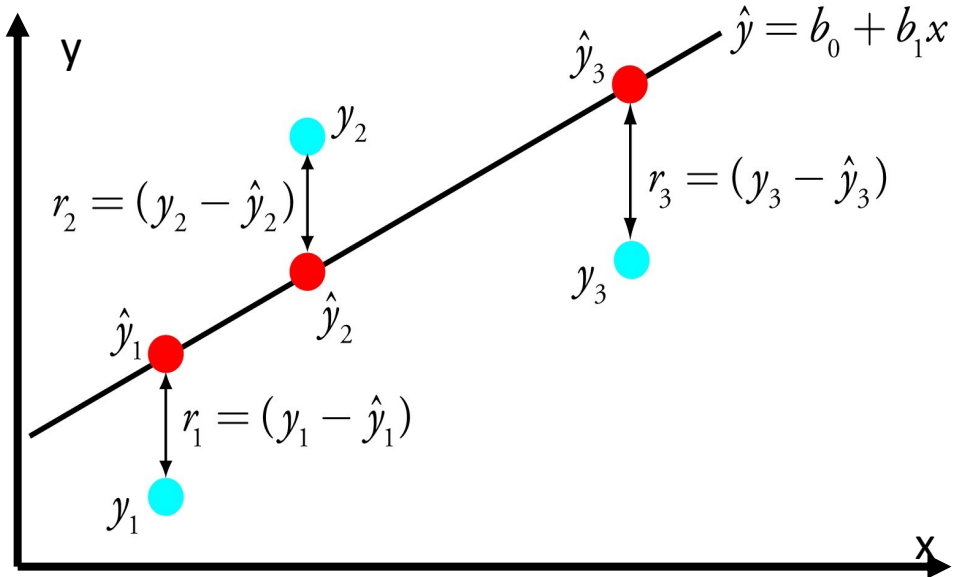
**Use data to set the parameters of a model to fit the labels.**

# Linear Regression

x	y
0.1	0.05
0.2	0.3
0.4	0.2
$x_i$	?

Fit the relation by  
a **linear function**:

$$y = X\beta + \epsilon$$



Math:  
Find **coefficient  $\beta$  and error  $\epsilon$**  for  
 $y = X\beta + \epsilon$   
that minimize the **residual**:

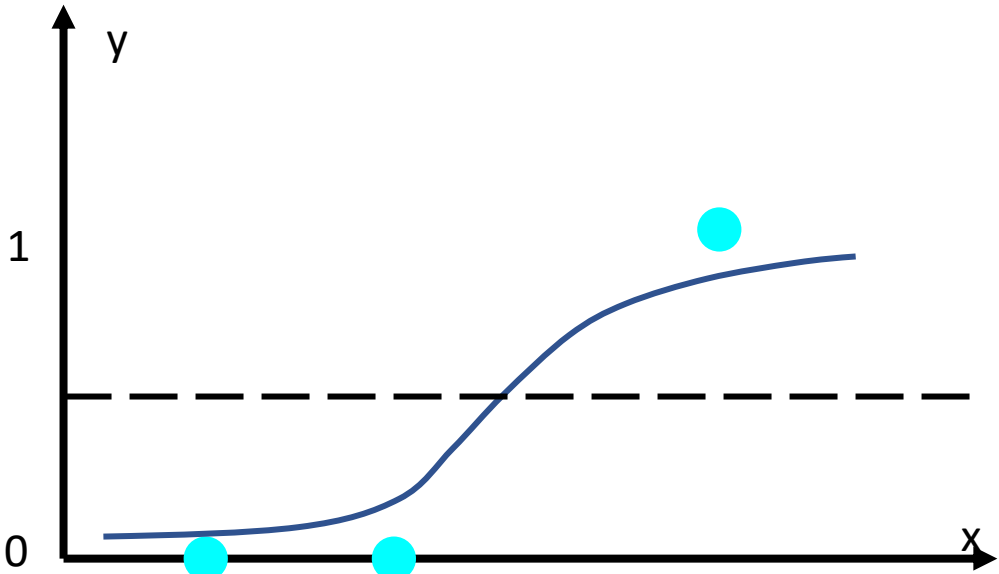
$$\mathcal{R} = \sum_1^n r_i^2$$

# Logistic Regression

x	y
0.1	0
0.2	0
0.4	1
$x_i$	?

Fit the relation by  
a **logistic function**:

$$P(y = 1|x) = \frac{1}{1+e^{-(\beta_0+\beta_1x)}}$$



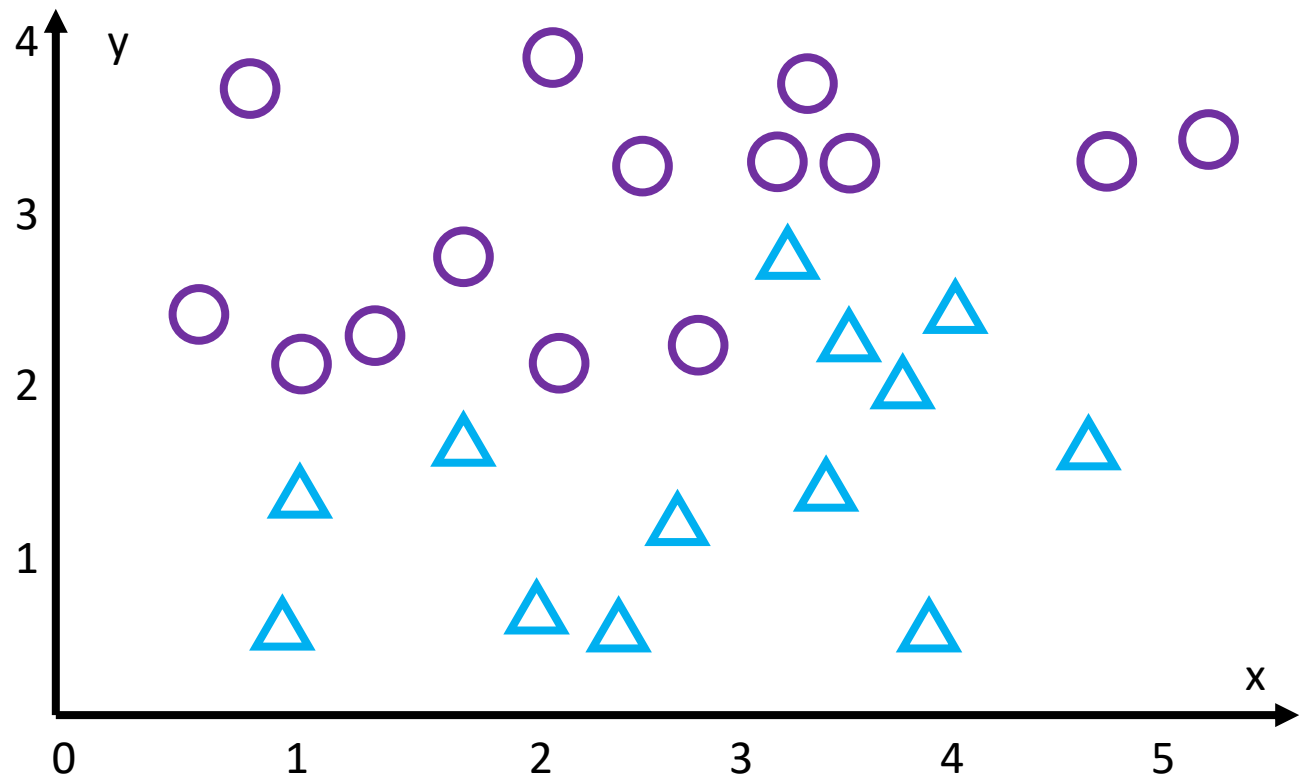
Math:

Find **coefficient  $\beta$**  for

$$P(y = 1|x) = \frac{1}{1 + e^{-(\beta_0+\beta_1x)}}$$

that minimize the residual between the  
prediction and the ground truth

# Decision Tree

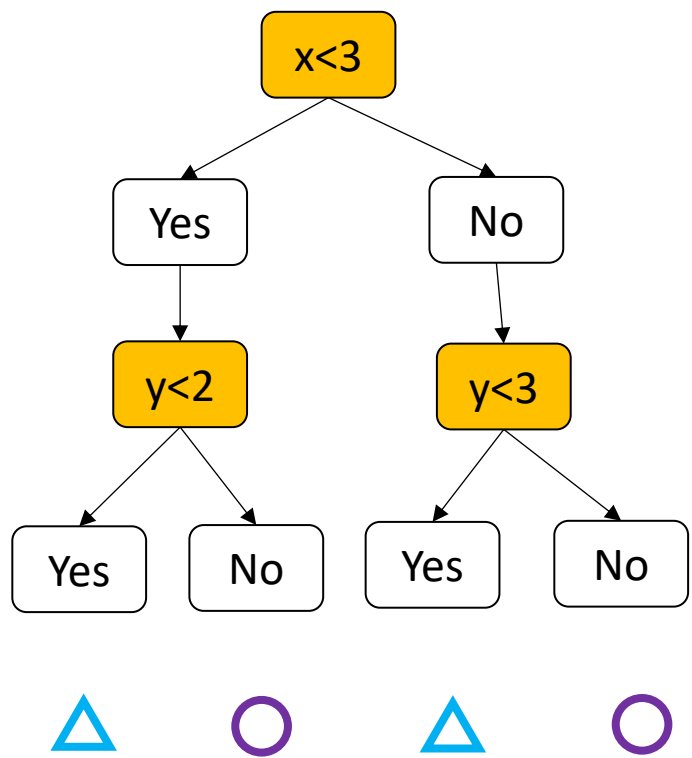
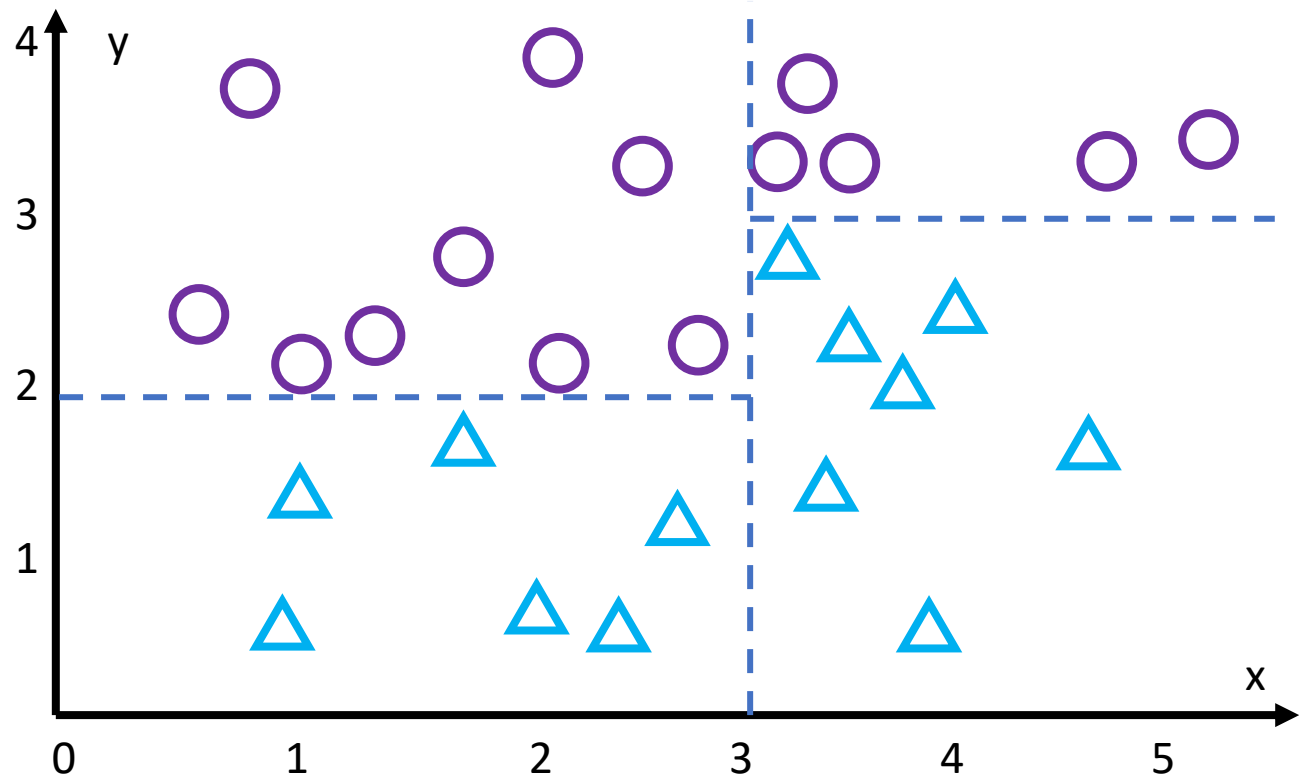


x and y are called features, each data point can be represented by features:

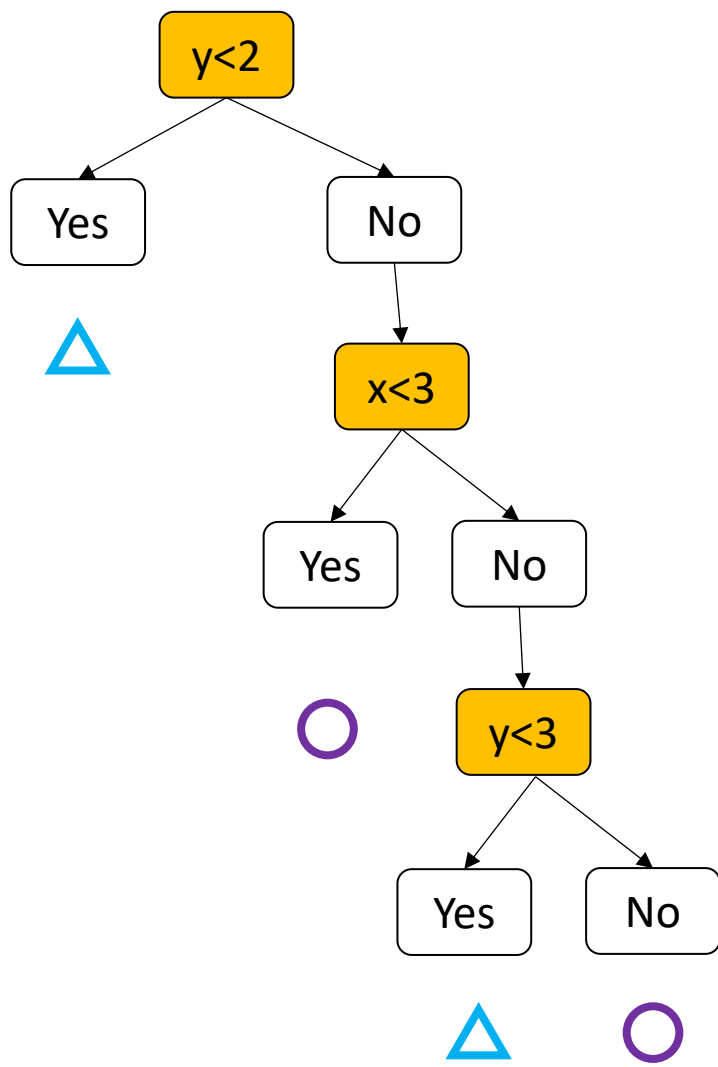
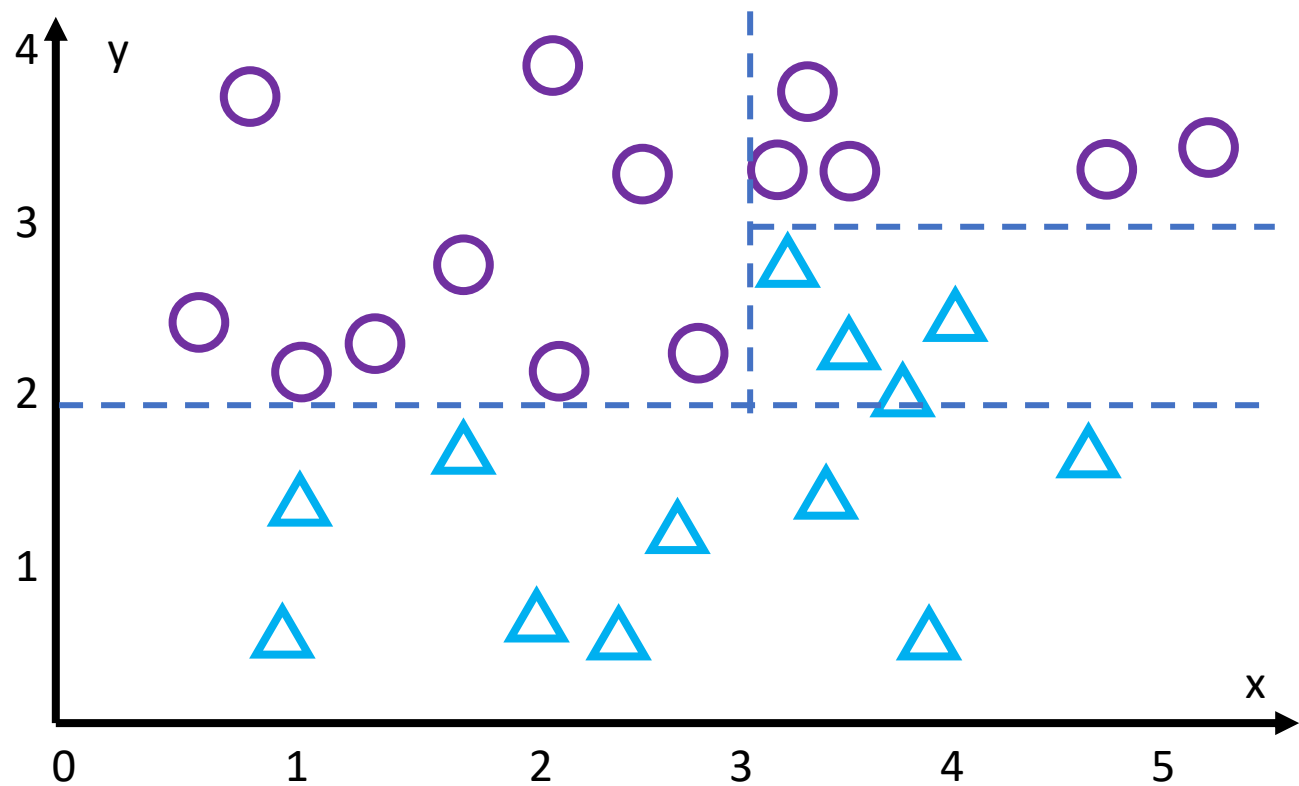
○ (x, y)

△ (x, y)

# Decision Tree

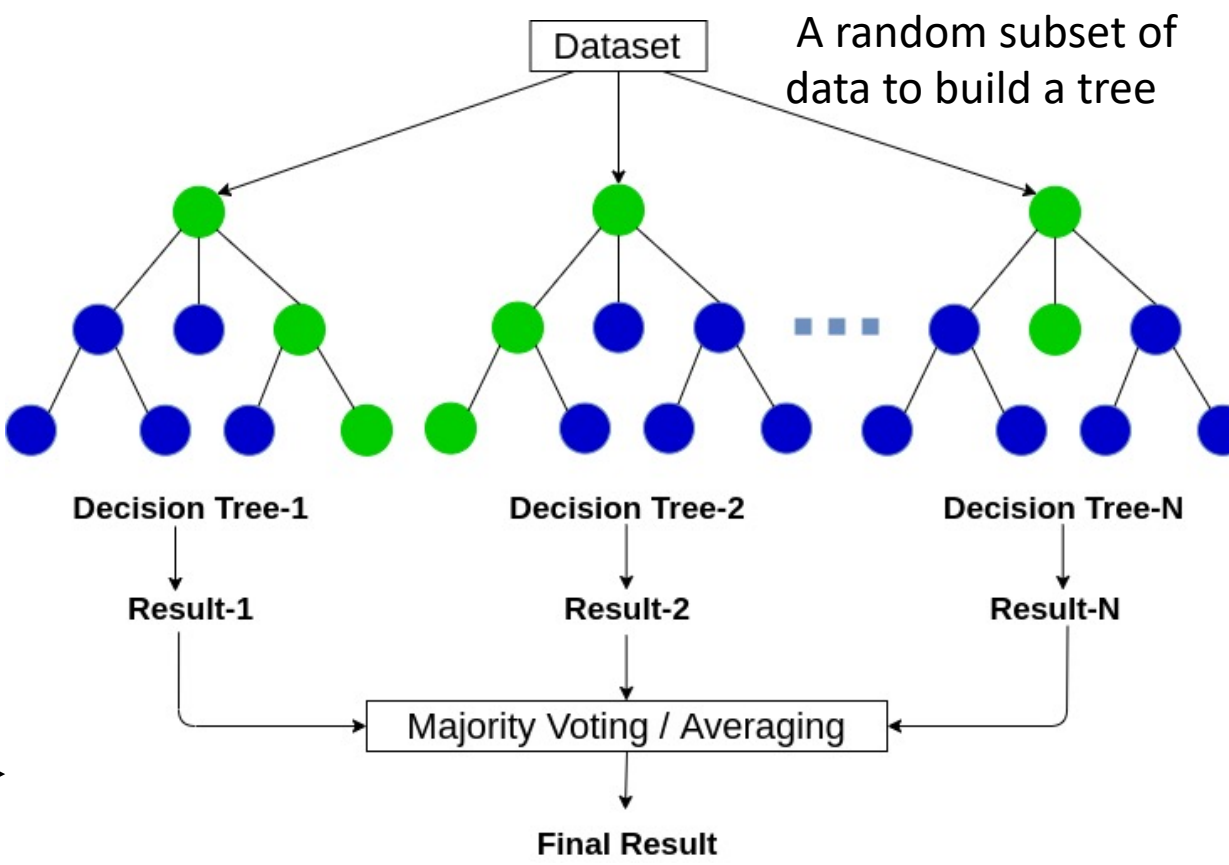
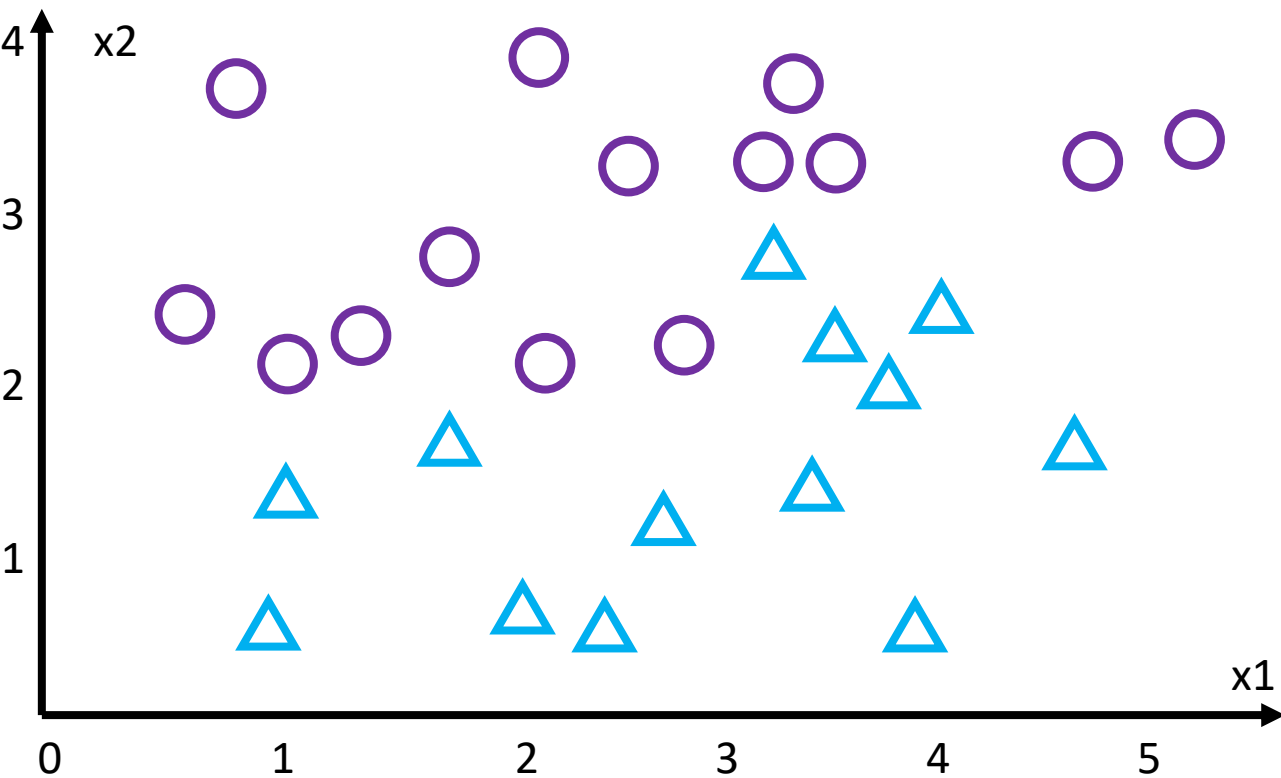


# Decision Tree



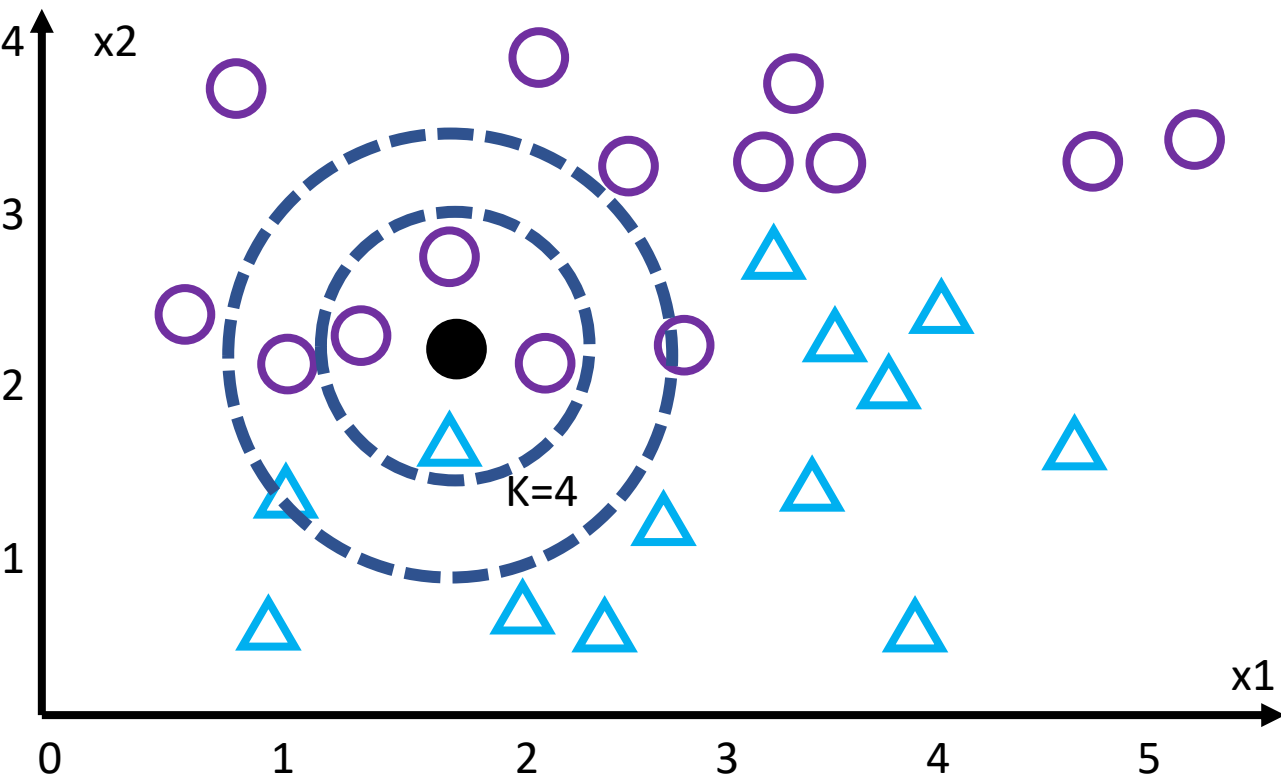
Another tree

# Random Forest

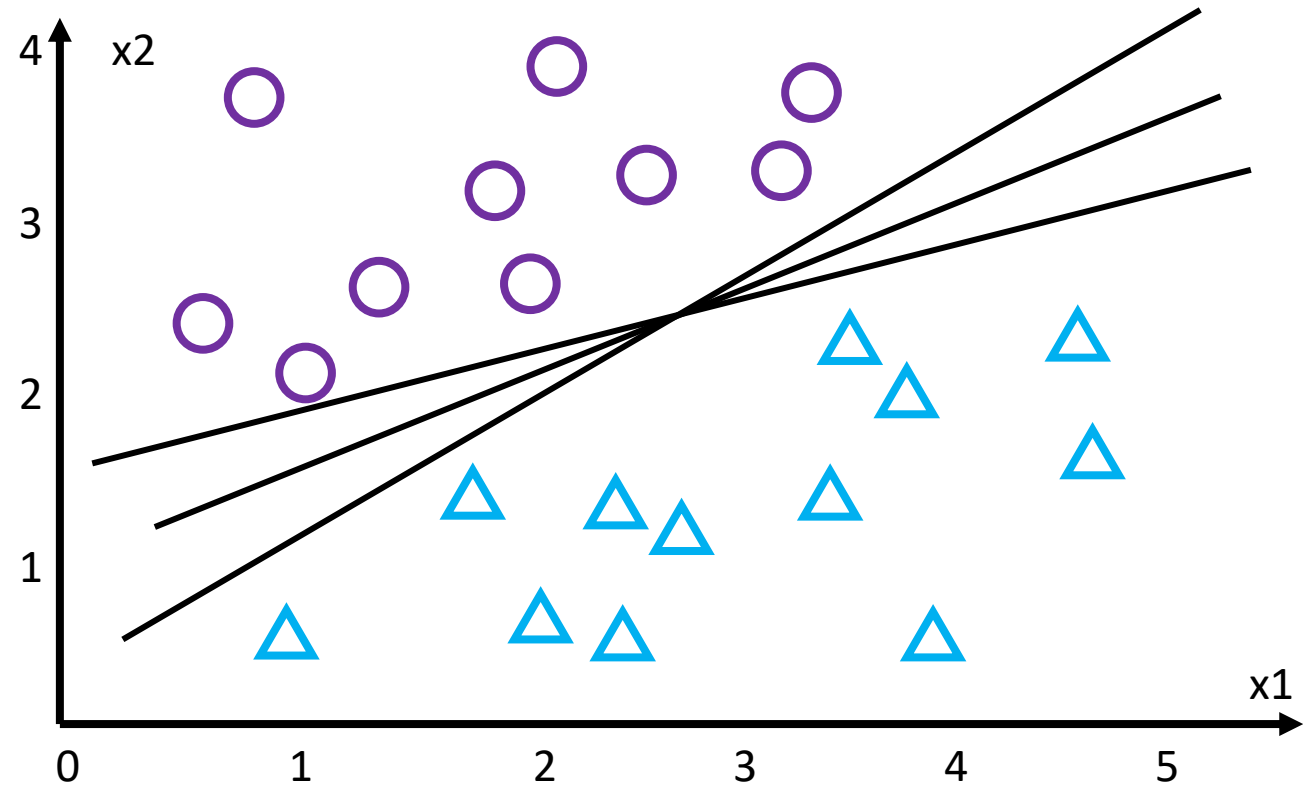




# K-nearest neighbor

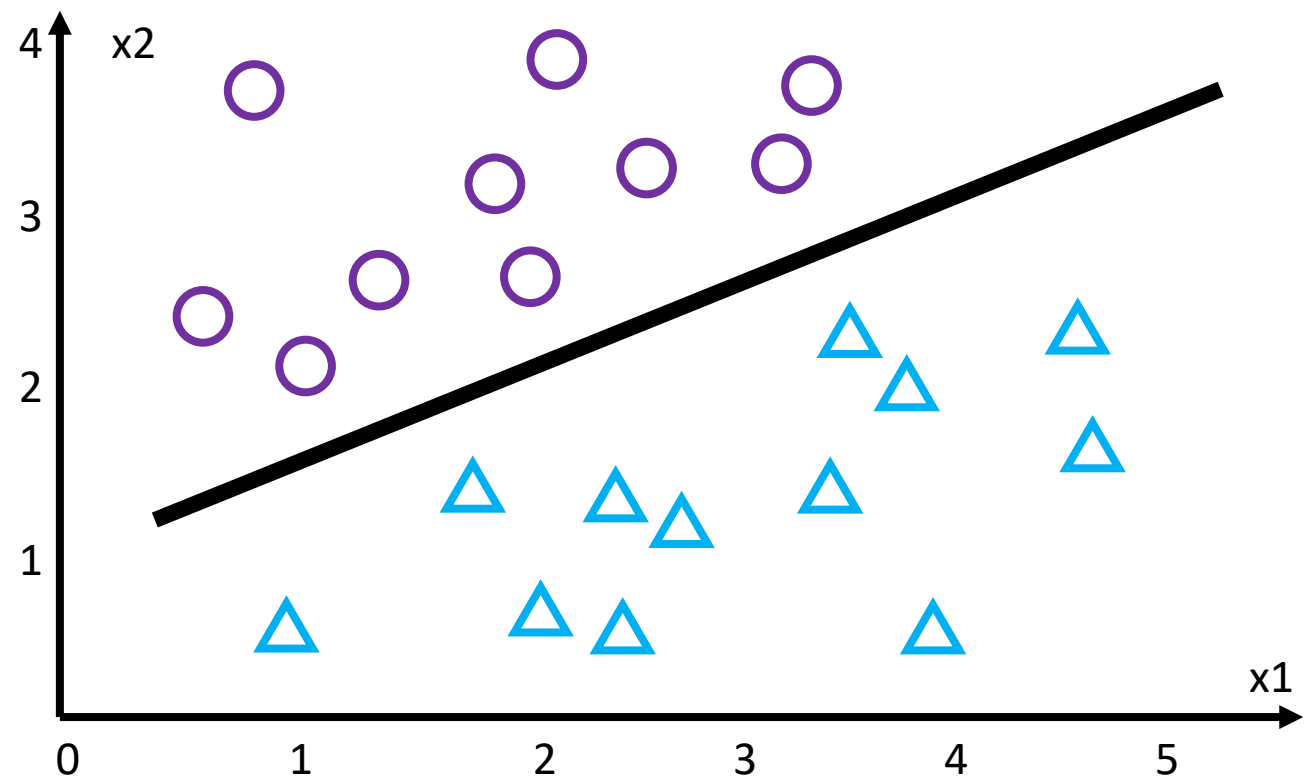


# Support vector machines

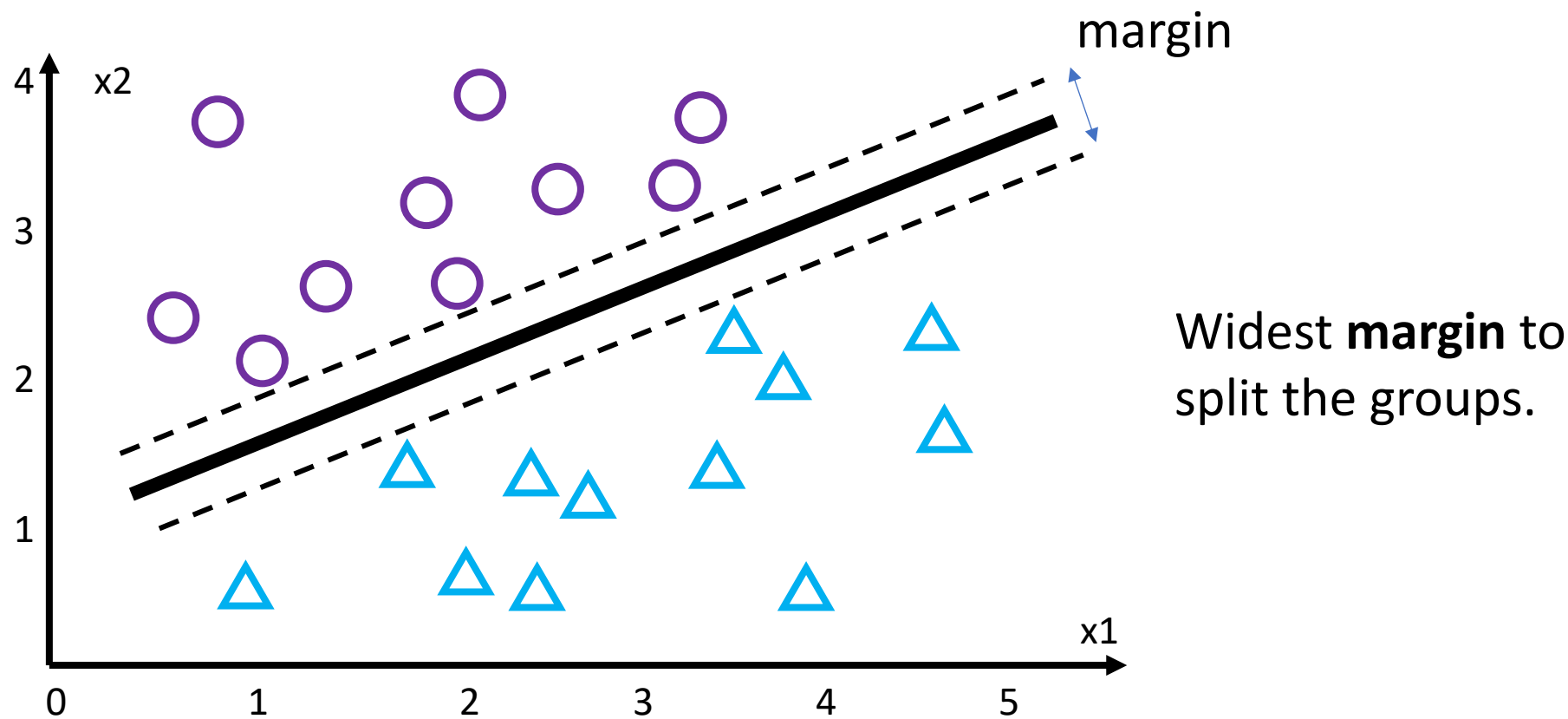


Which is the best?

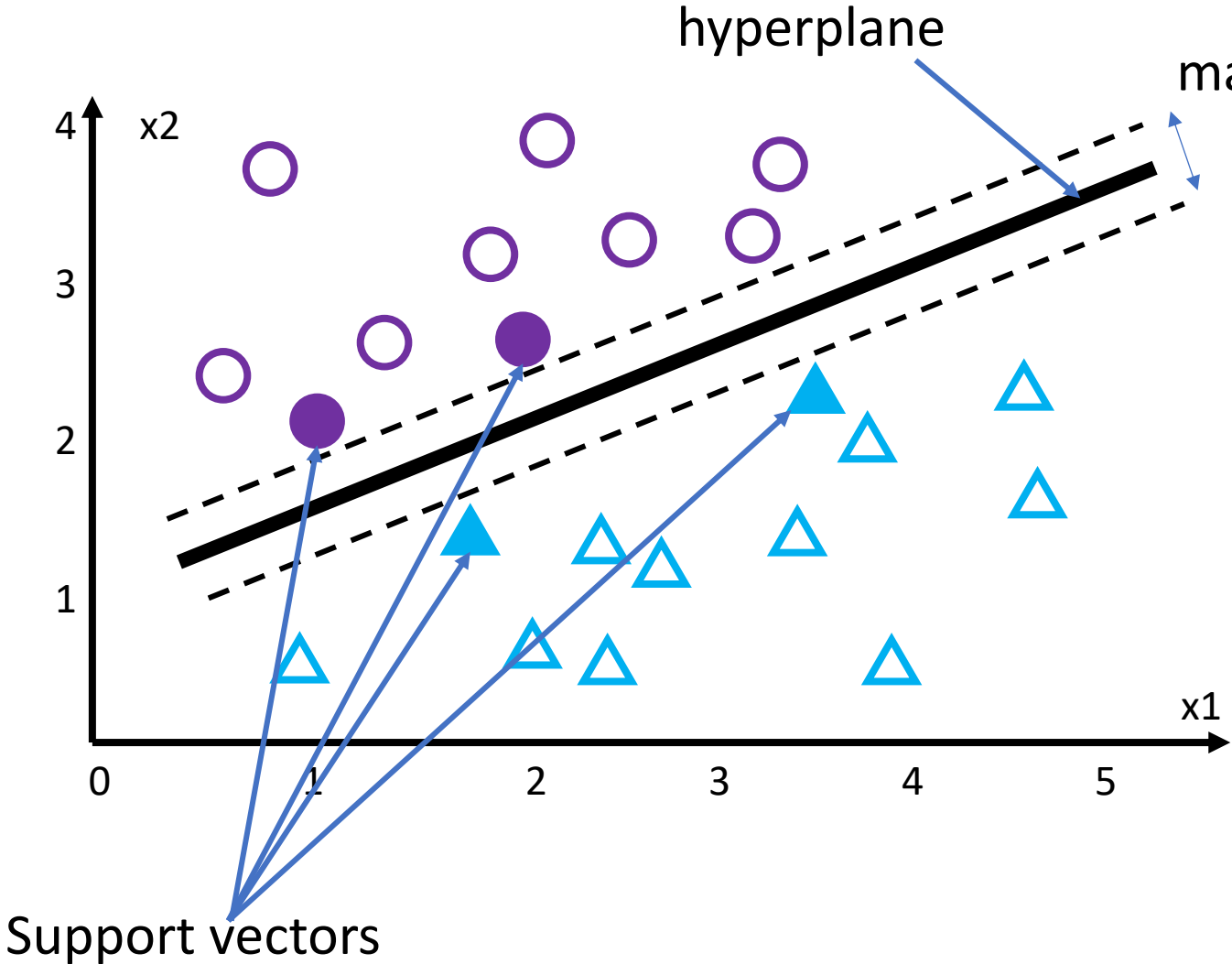
# Support vector machines



# Support vector machines



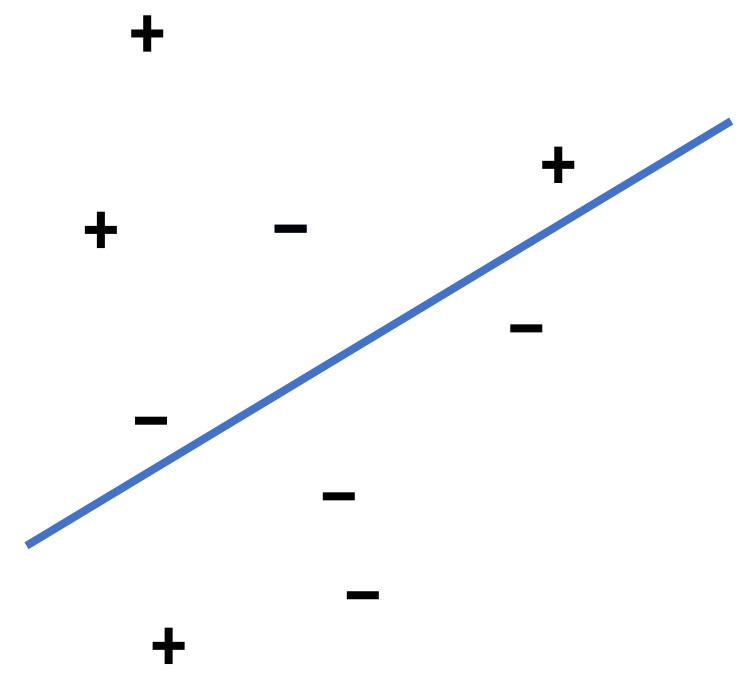
# Support vector machines



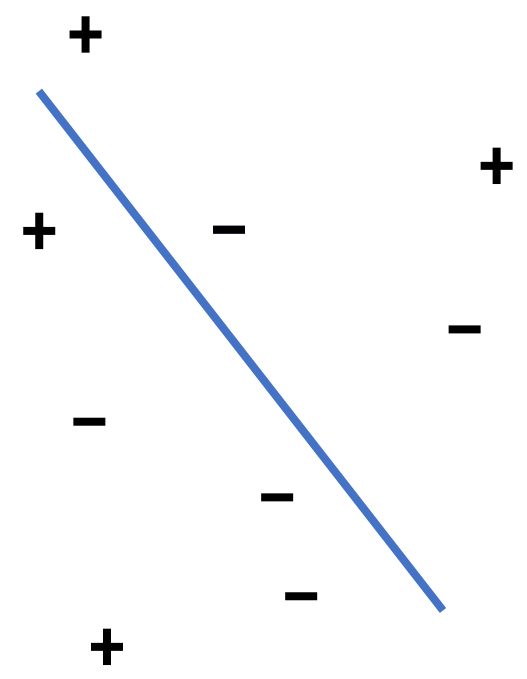
Widest **margin** to split the groups.

**margin** = distance between the **support vectors** and the **hyperplane**.

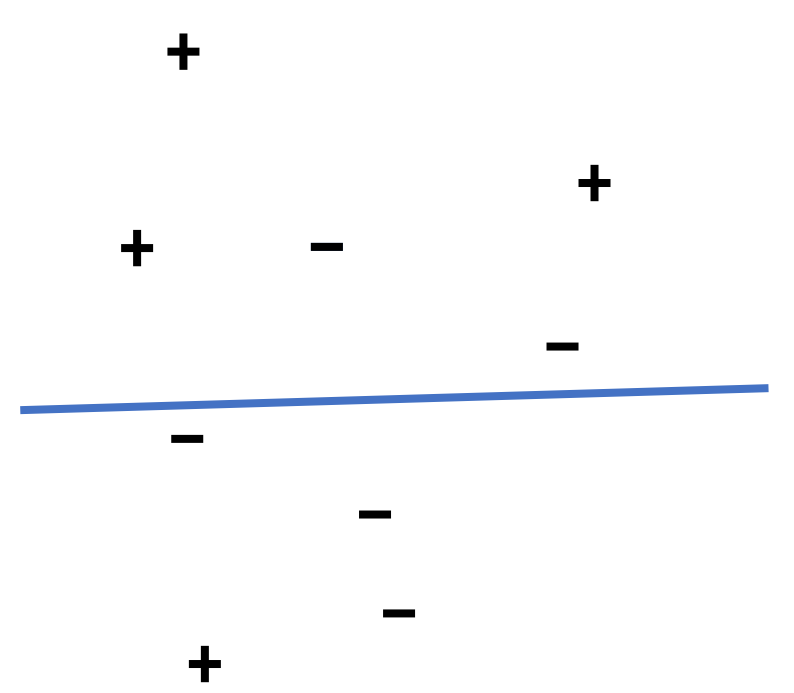
# Support vector machines: Kernel Trick



Not a good separator

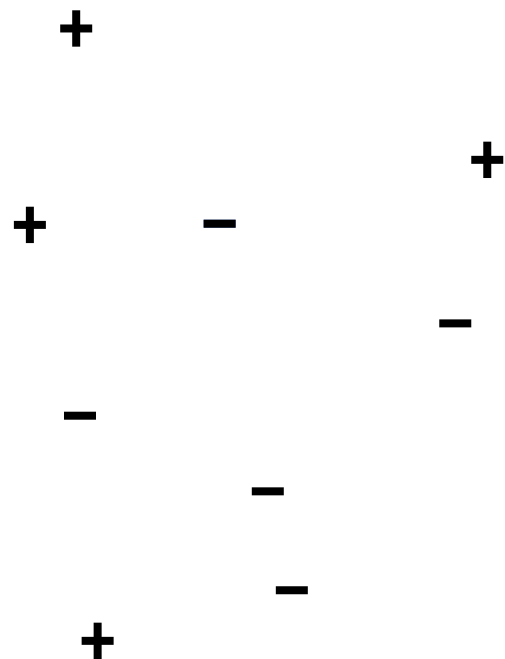


Not a good separator



Not a good separator

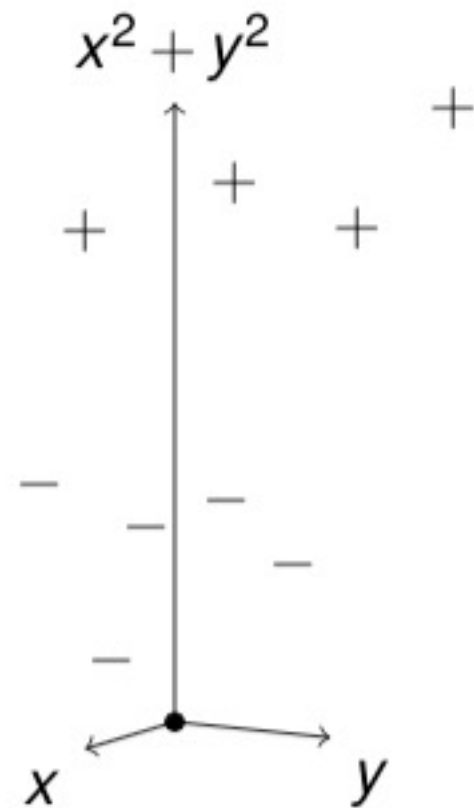
# Support vector machines: Kernel Trick



To map point  $(x,y)$  to point  $(x,y,x^2 + y^2)$

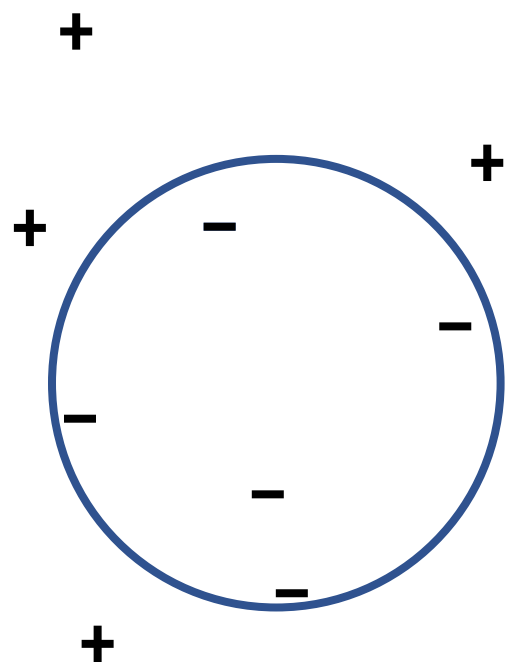
Kernel functions:

- Linear
- Radial Basis Function (RBF)
- Polynomial
- Sigmoid



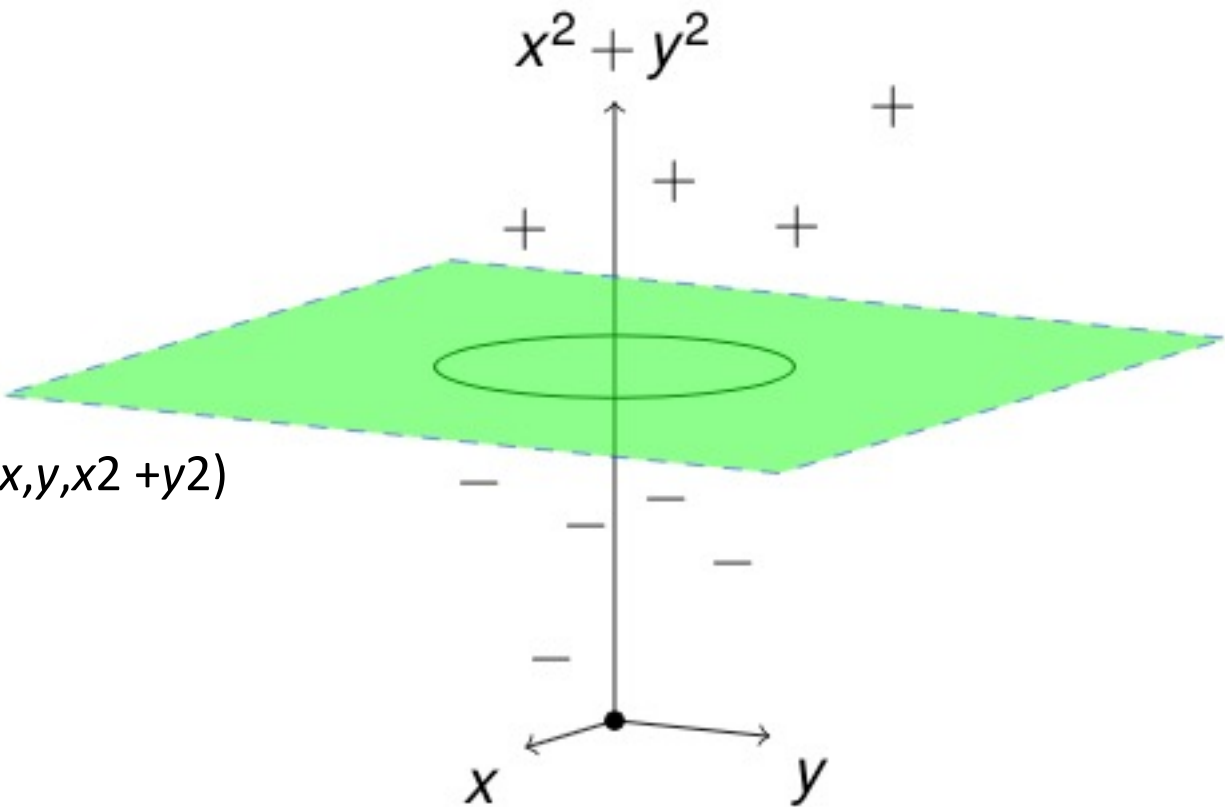
# Support vector machines: Kernel Trick

A visualization: <https://www.youtube.com/watch?v=3liCbRZPrZA>



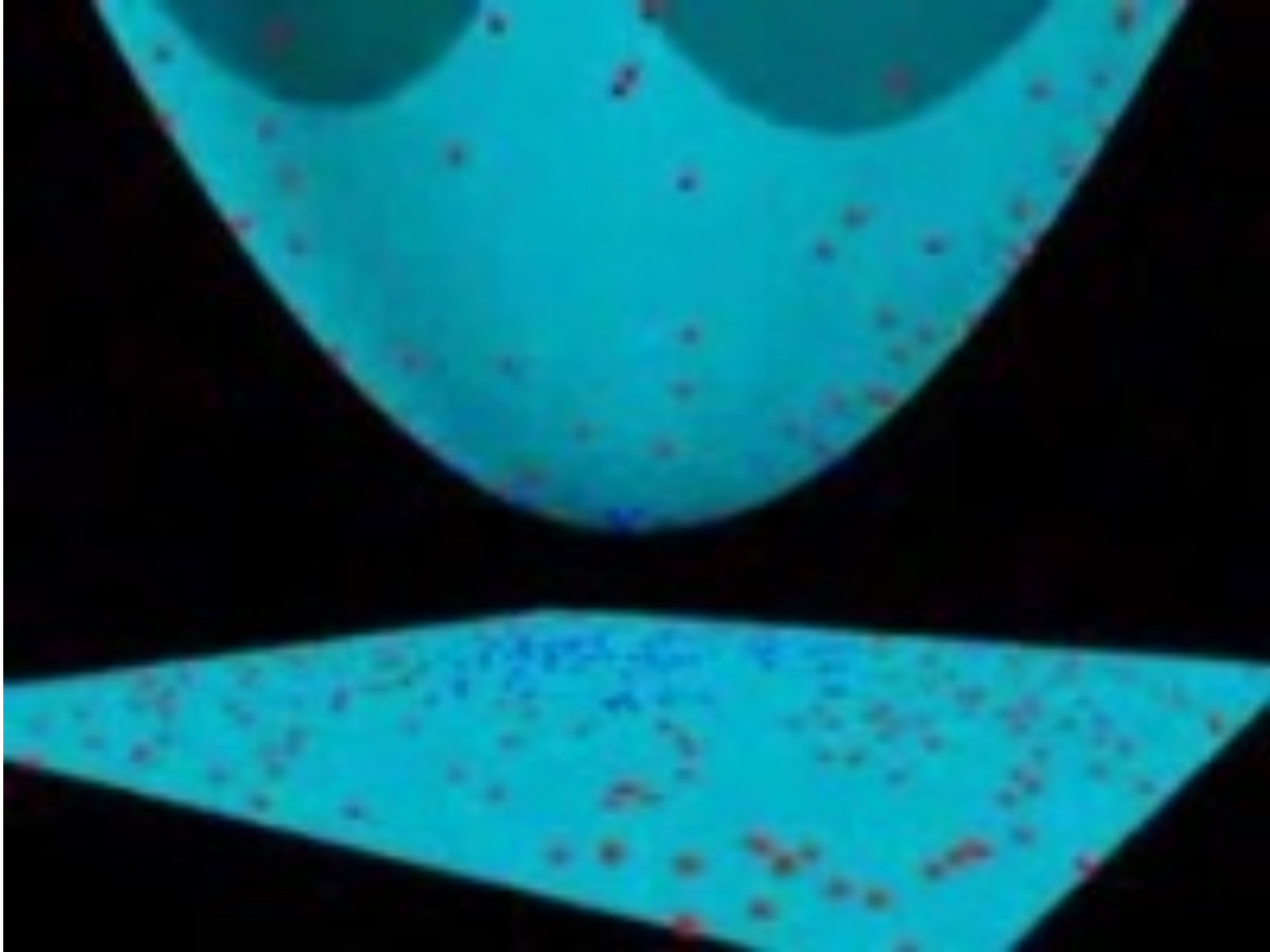
To map point  $(x,y)$  to point  $(x,y,x^2 + y^2)$

- Kernel functions:
- Linear
  - Radial Basis Function (RBF)
  - Polynomial
  - Sigmoid

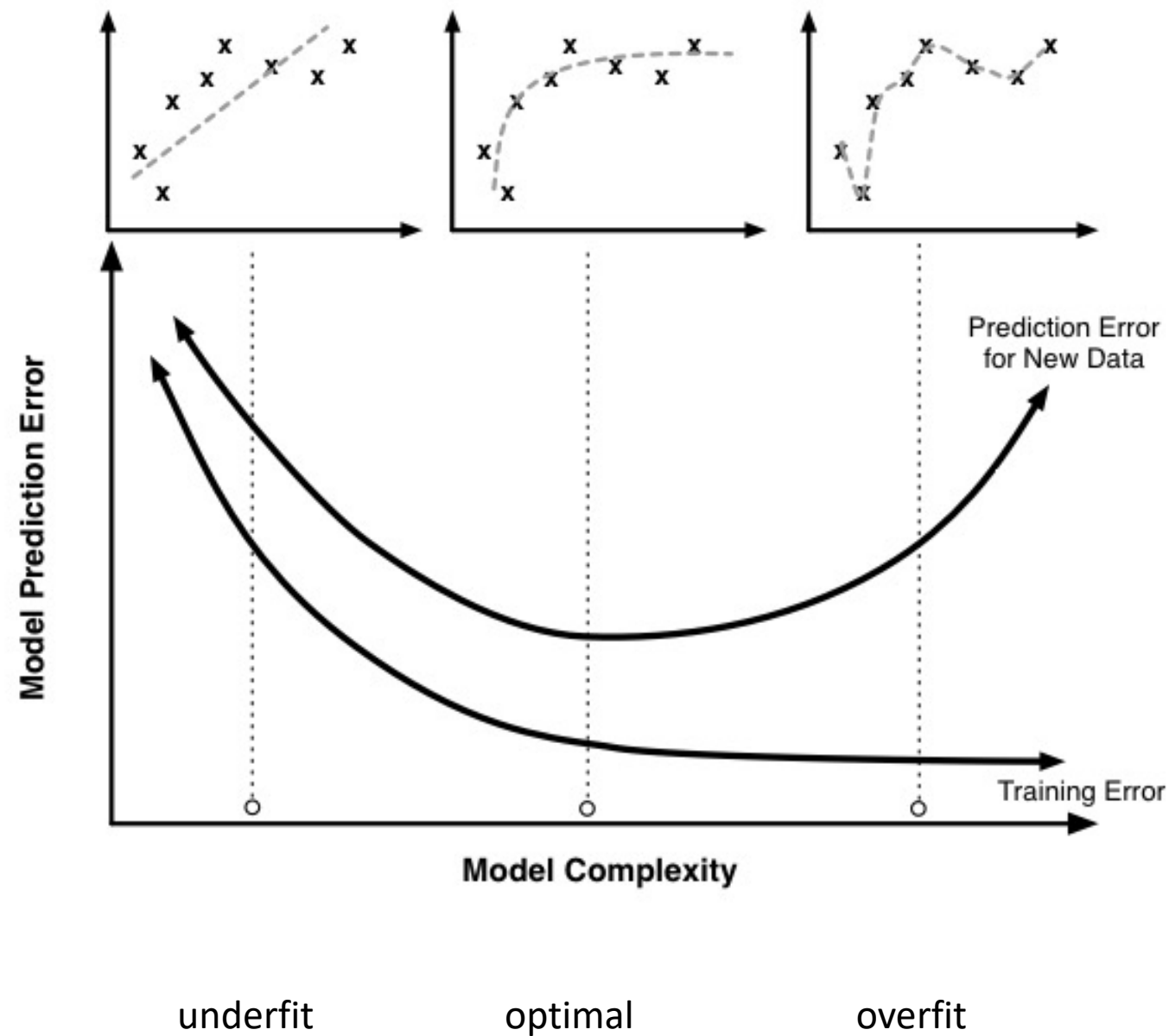




A visualization: <https://www.youtube.com/watch?v=3liCbRZPrZA>



# What is a good model?



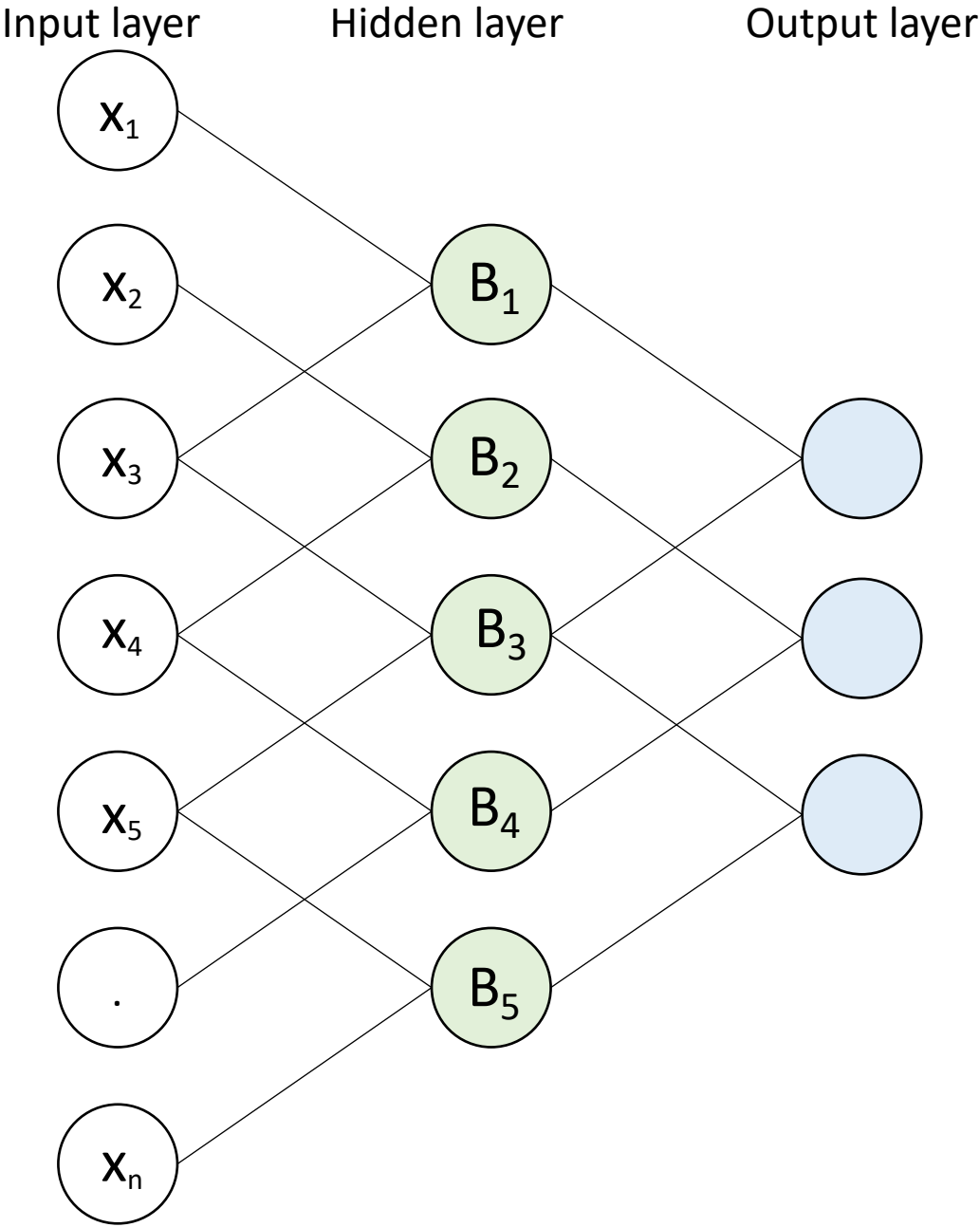
## Demos

Will do demos in Jupyter notebooks

# **Part 2**

# **Deep Learning**

# Multilayer perceptron (Neural network)



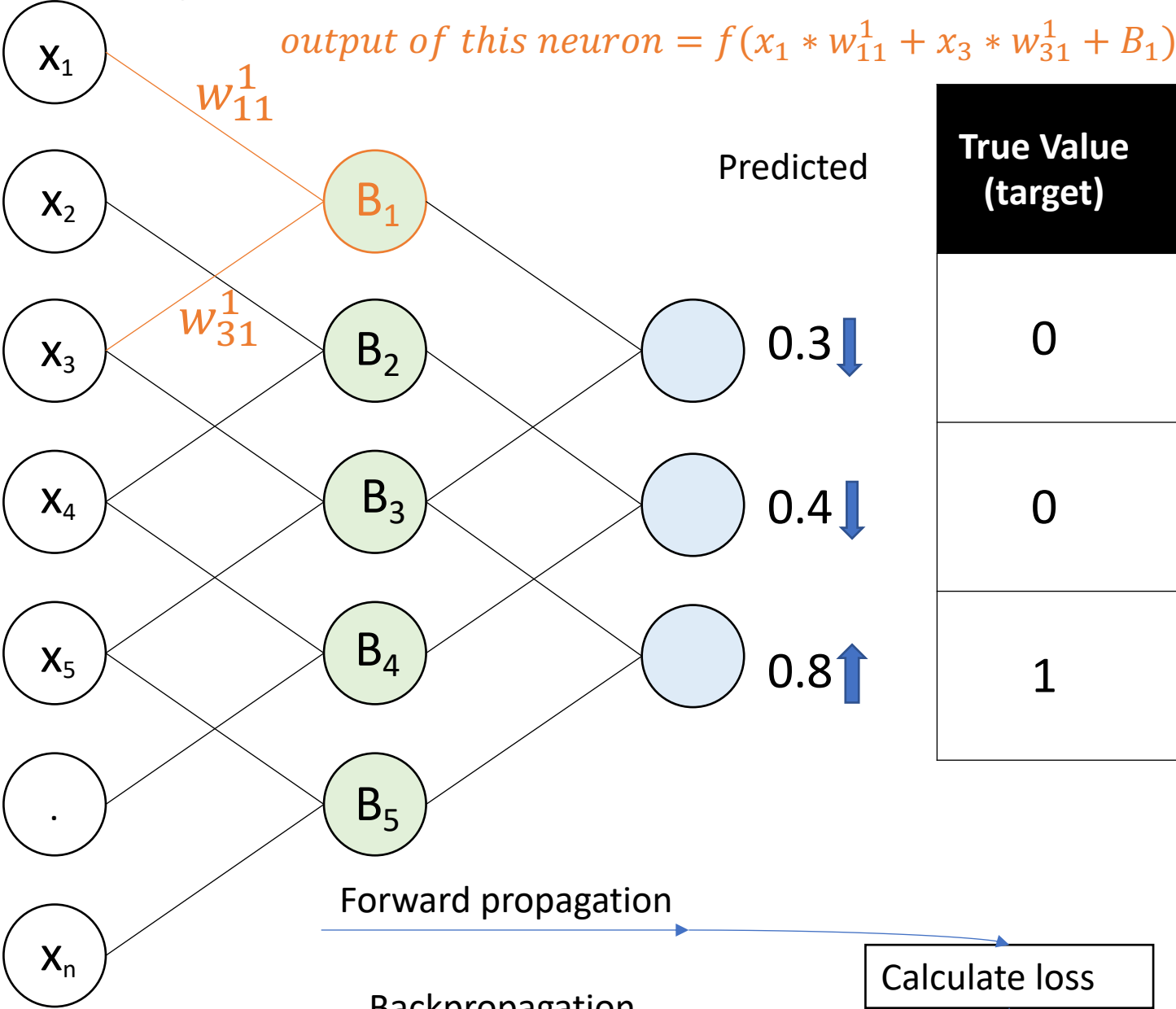
# Multilayer perceptron (Neural network)

The weight linking the 1<sup>st</sup> hidden layer and its prior layer

$w_{31}^1$

Neuron 3 from previous layer

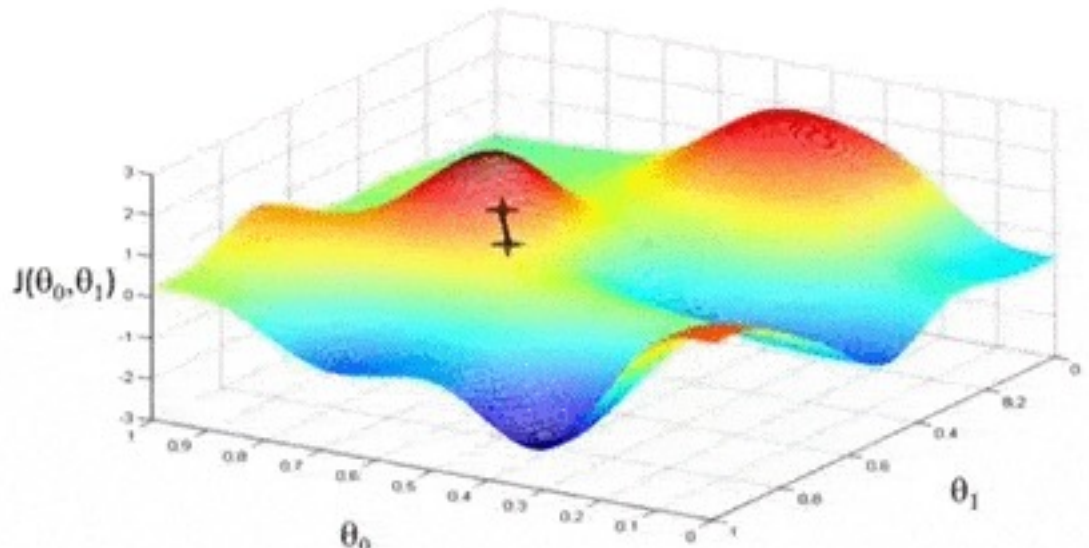
Neuron 1 in the current layer



True Value (target)		Error
0		-0.3
0		-0.4
1		0.2

# Multilayer perceptron (Neural network)

## Gradient Descent

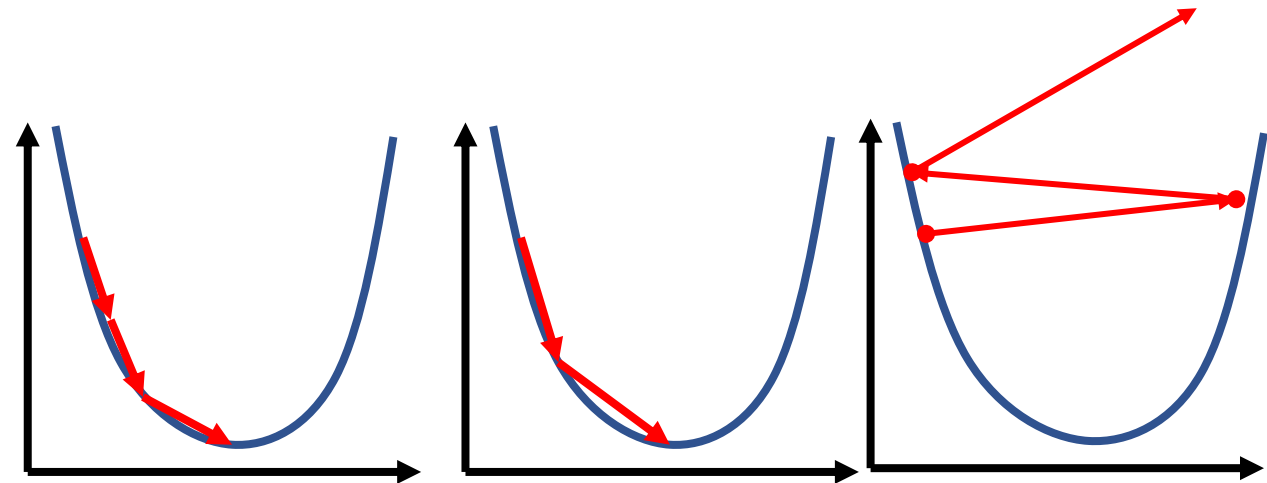


J can be any loss function.  
 $\theta$  is the parameter of the loss function.  
(It is the weights in a neural network.)

(From Andrew Ng)

- 1. Compute the slope (gradient) at the current step
- 2. Make a move in the direction opposite to the slope

## Learning rate

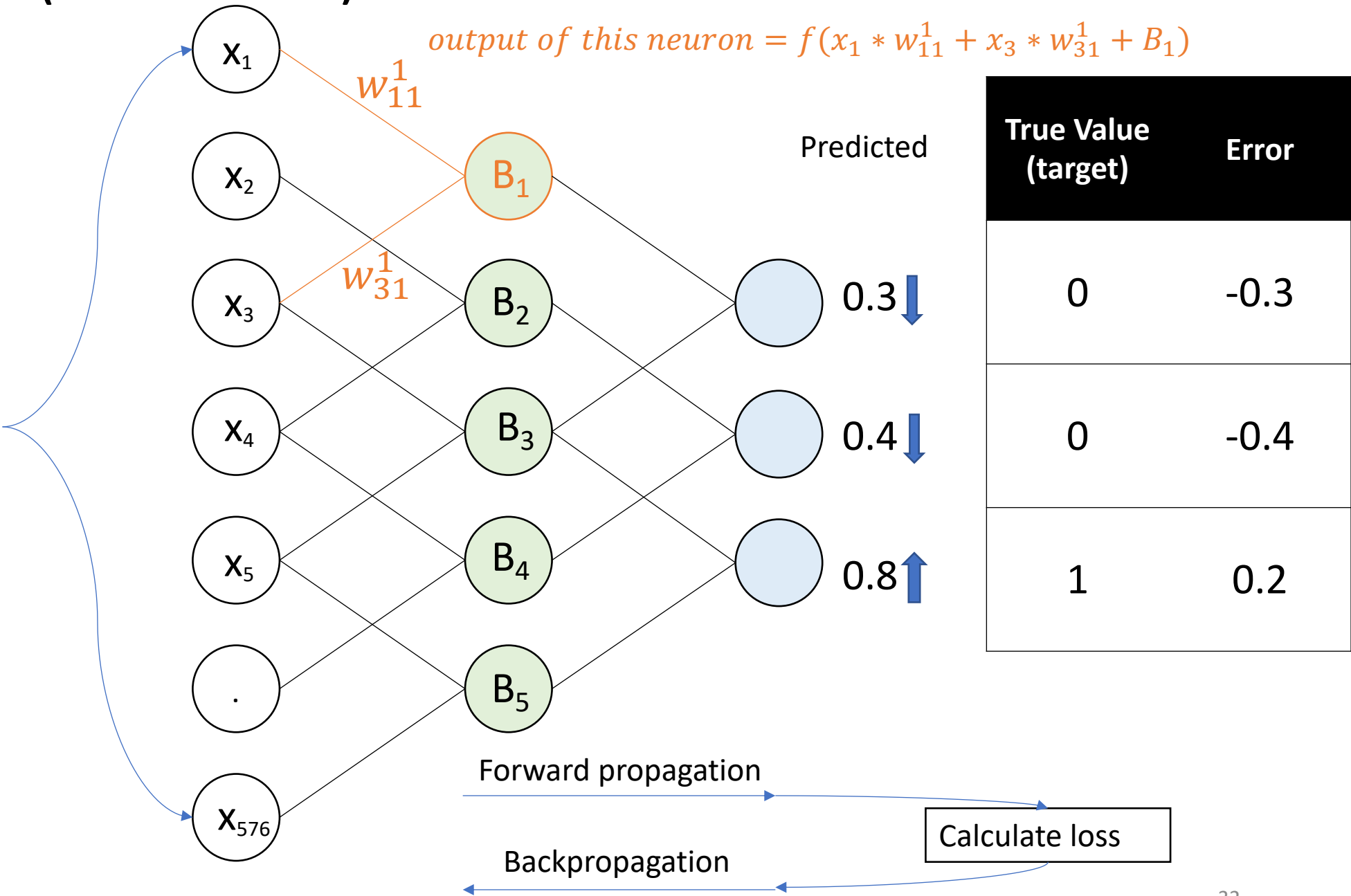


Too small                      Good                      Overshoot

# Multilayer perceptron (Neural network)











A 24x24 image can be expanded as a vector  
[ $x_1, x_2, \dots, x_{576}$ ]



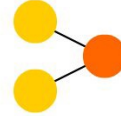


# Neural Networks

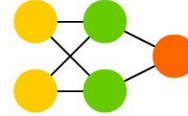
*A mostly complete chart of architectures*

-  Backfed Input Cell
-  Input Cell
-  Noisy Input Cell
-  Hidden Cell
-  Probablistic Hidden Cell
-  Spiking Hidden Cell
-  Output Cell
-  Match Input Output Cell
-  Recurrent Cell
-  Memory Cell
-  Open Memory Cell
-  Scanning Filter
-  Convolution

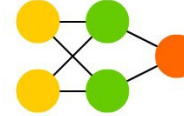
Feed Forward And



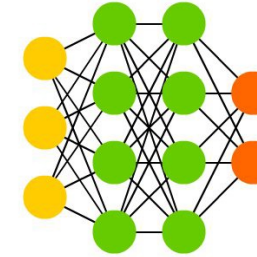
Feed Forward Xor



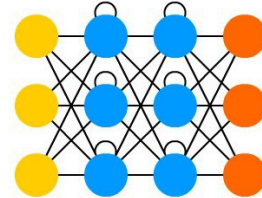
Radial Basis Network



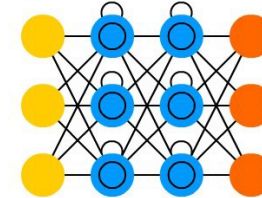
Deep Feed Forward



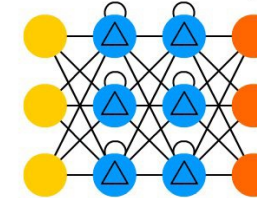
Recurrent Neural Network (bi)



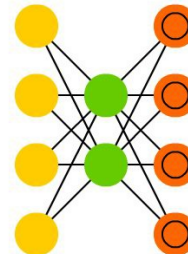
Long / Short Term Memory (bi)



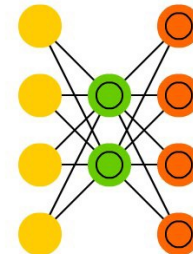
Gated Recurrent Unit (bi)



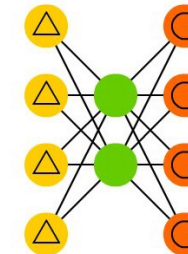
Auto Encoder



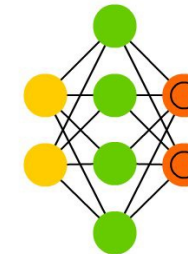
Variational Auto Encoder



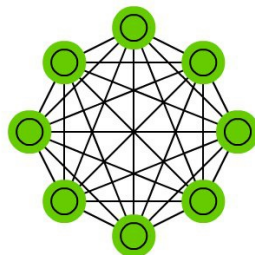
Denoising Auto Encoder



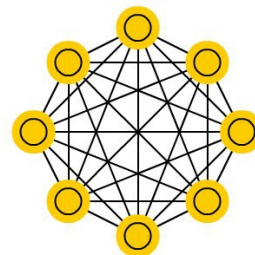
Sparse Auto Encoder



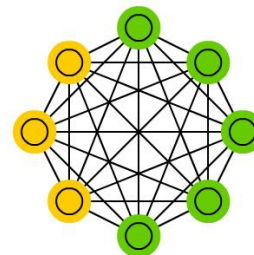
Markov Chain



Hopfield Network



Boltzmann Machine



Restricted Boltz. Ma.



Deep Belief Network

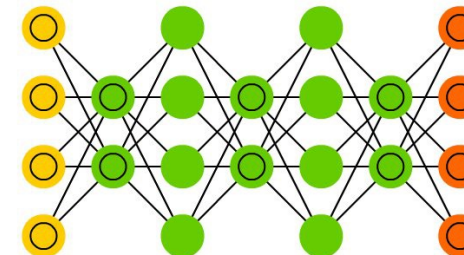
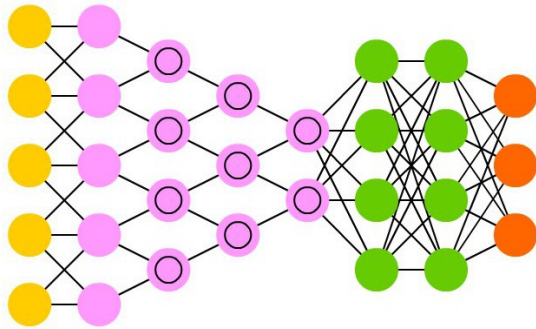
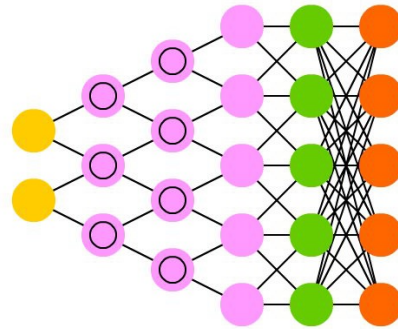


Image from  
The Asimov Institute

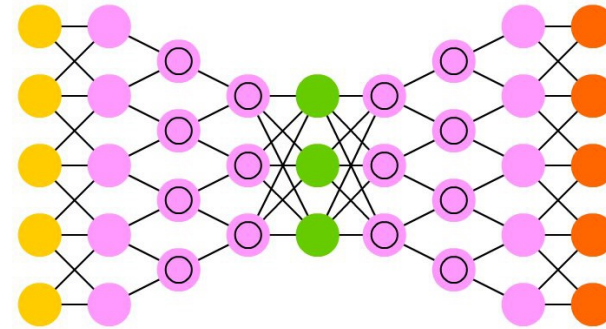
Deep Convolutional Network



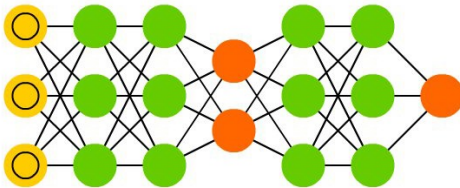
Deconvolutional Network



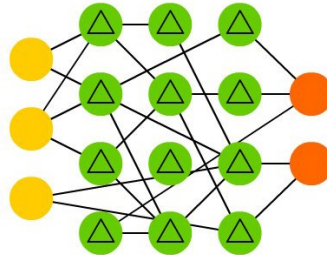
Deep Convolutional Inverse Graphics Network



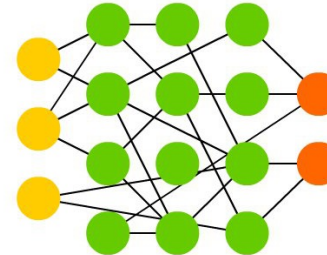
Generative Adversarial Network



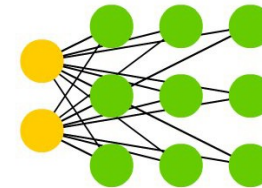
Liquid State Machine



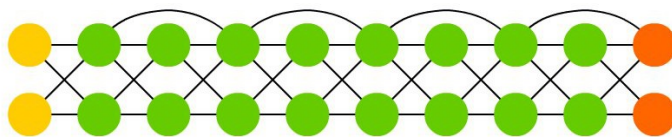
Echo State Network



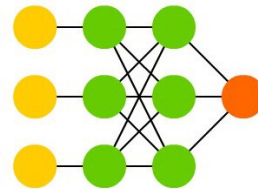
Kohonen Network



Deep Residual Network



Support Vector Machine



Neural Turing Machine

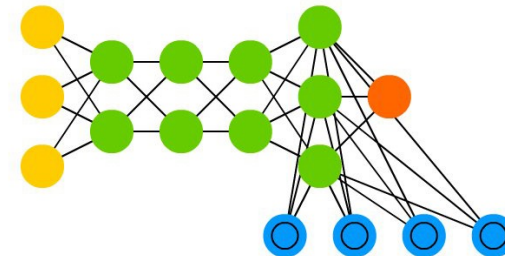
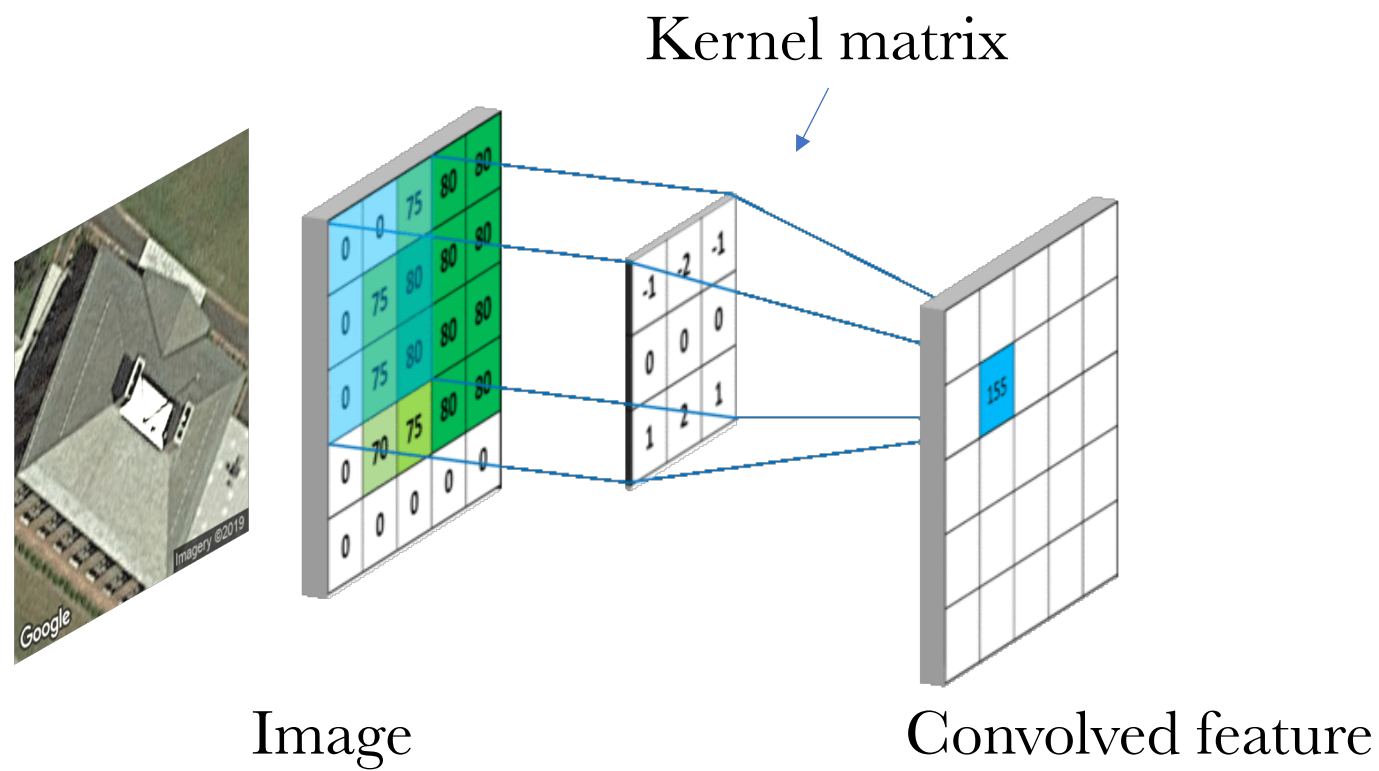


Image from  
The Asimov Institute

# Convolutional neural network

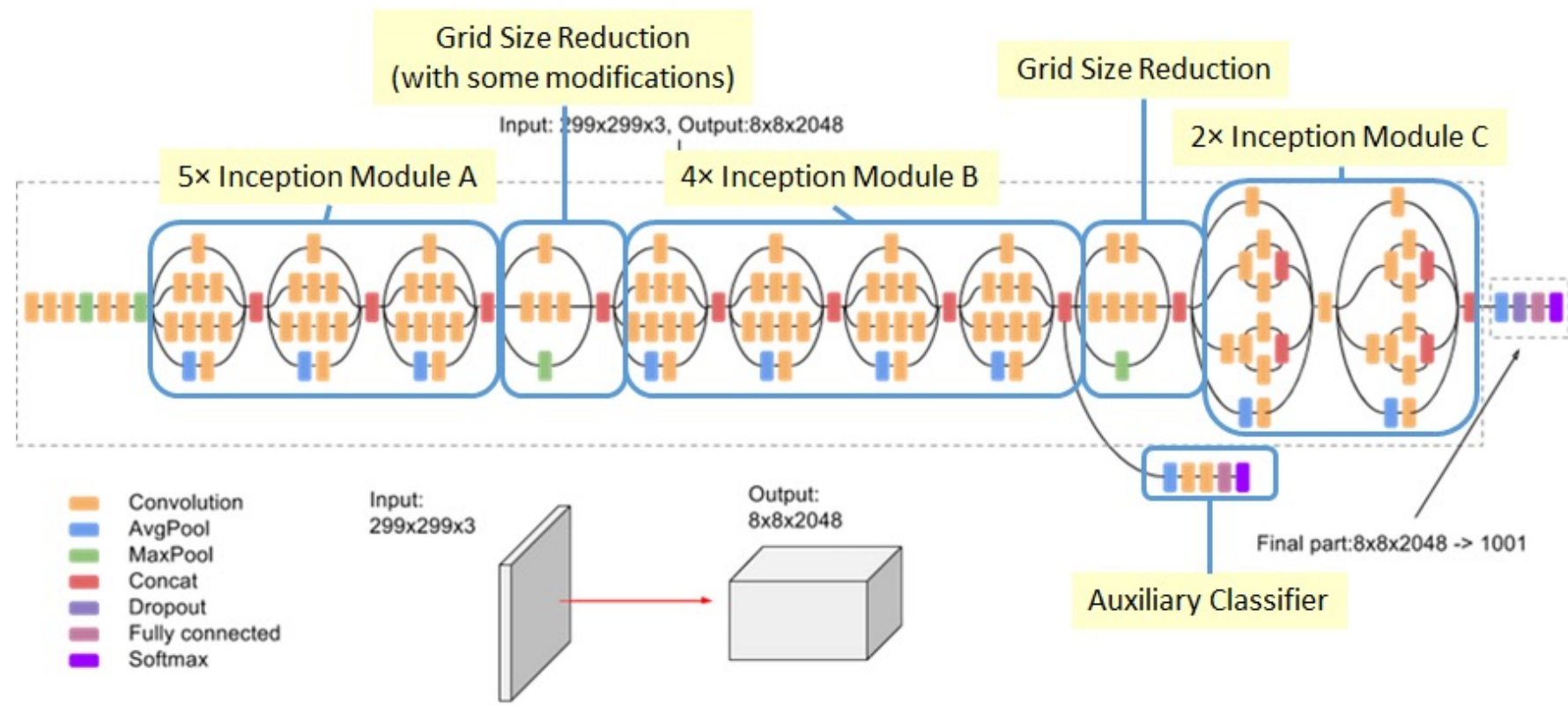


A 2D convolution operation



# Popular deep CNN architectures

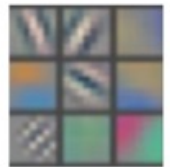
- AlexNet
- VGGNet
- GoogLeNet
- Microsoft ResNet
- Google Inception
- ...



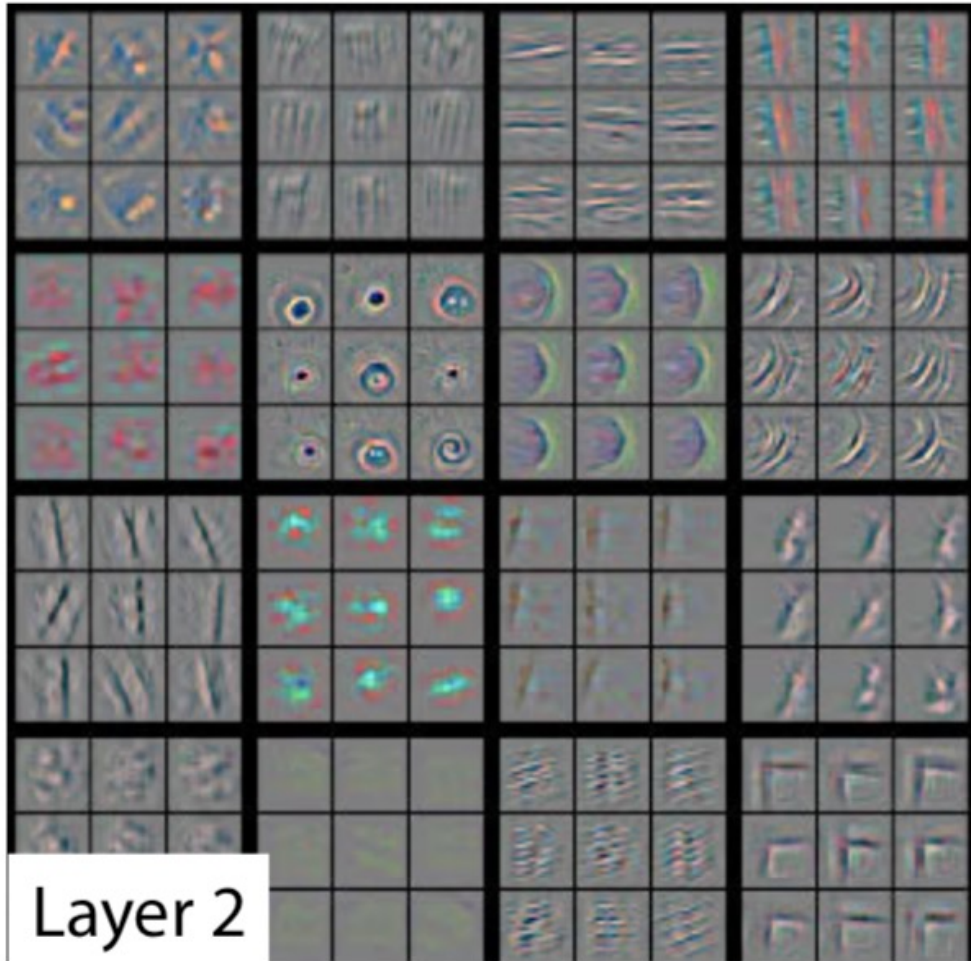
Example: Inception v3

# Transfer Learning

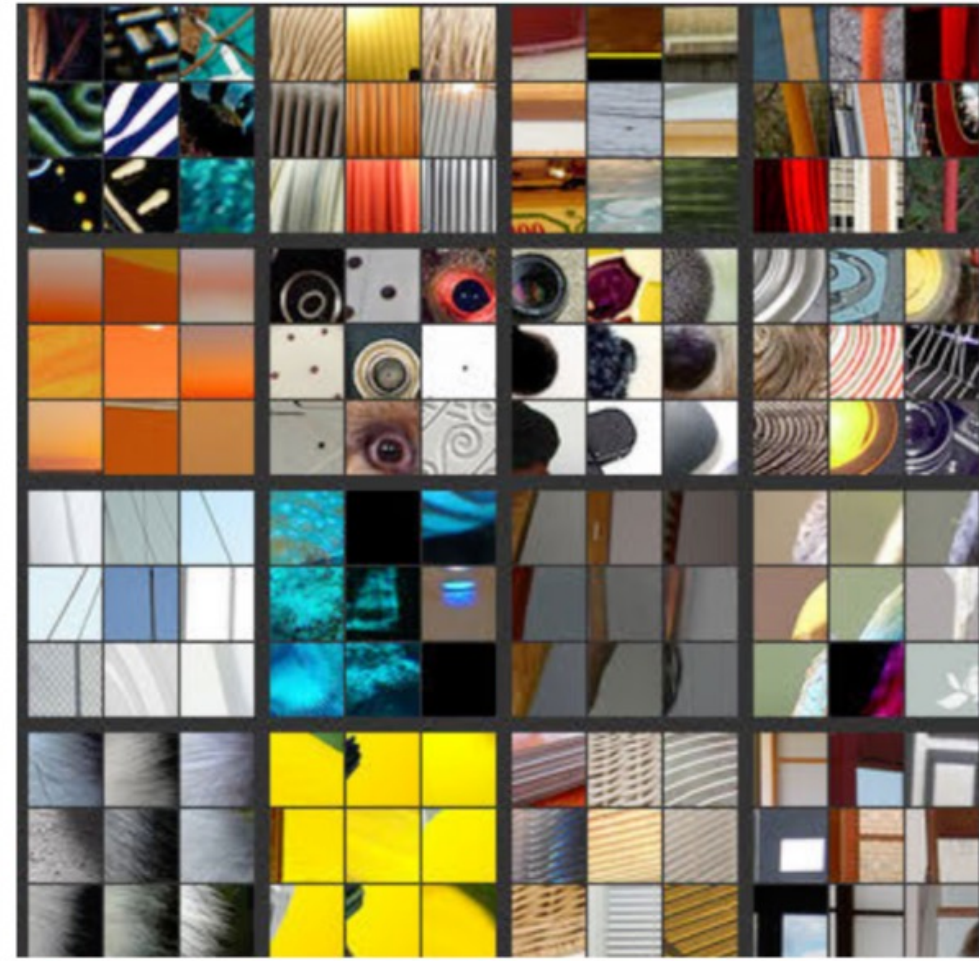
The first few layers of CNN detect general features: Edges, Corners, Circles, Blobs colors, ...



Layer 1



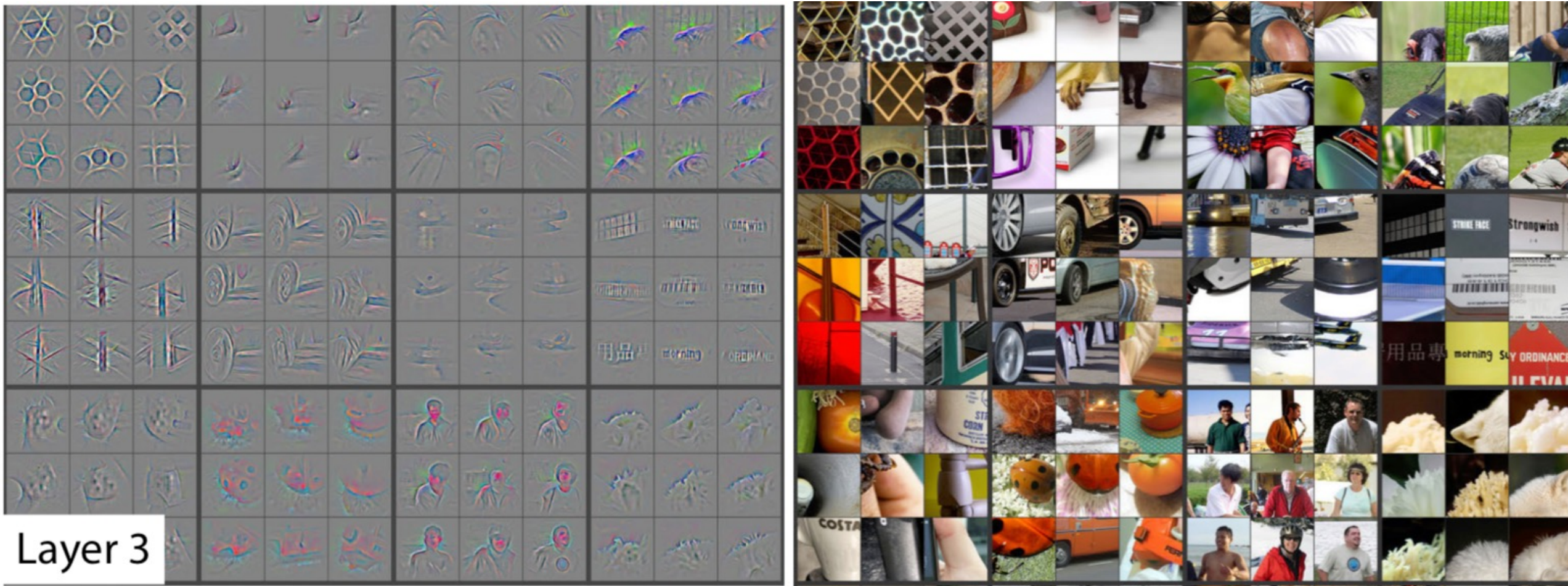
Layer 2





# Transfer Learning

As it goes deeper into the CNN, it starts to detect more concrete things such as eyes, faces, and full objects.

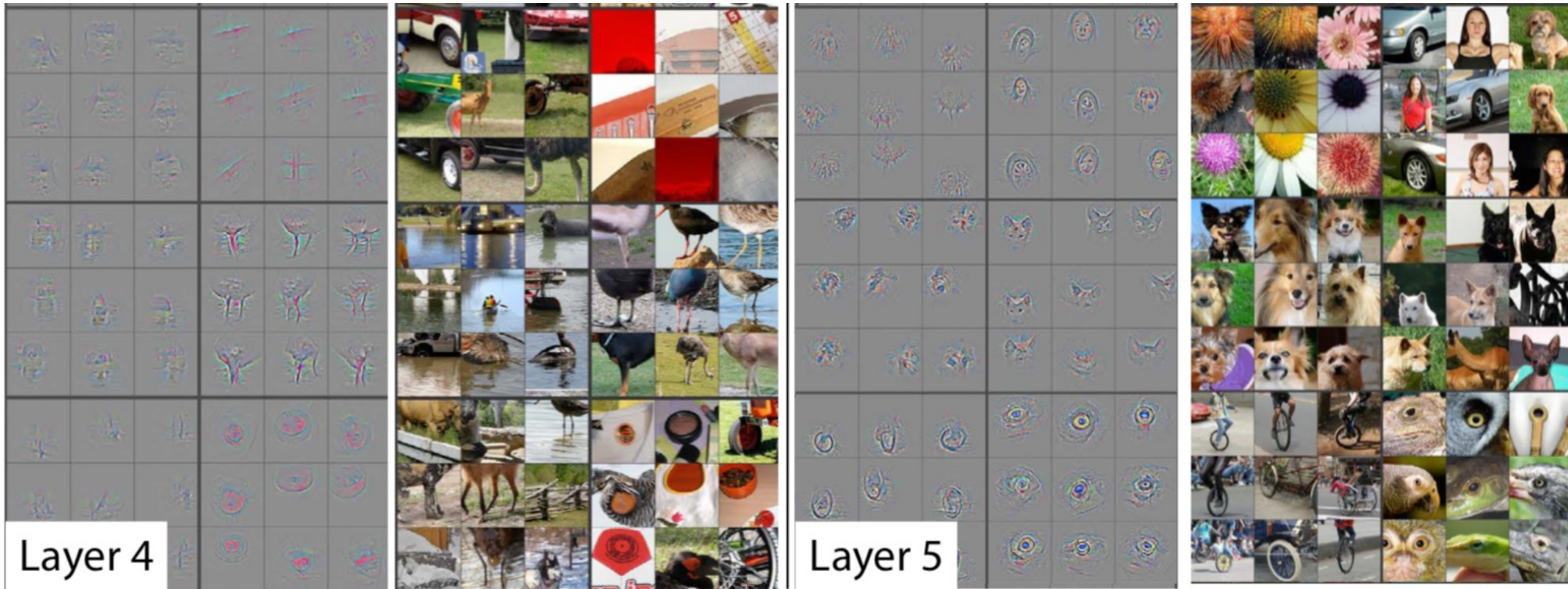


Zeiler, Matthew D., and Rob Fergus. "Visualizing and understanding convolutional networks." European conference on computer vision. Springer, Cham, 2014.



# Transfer Learning

More concrete things ...



Zeiler, Matthew D., and Rob Fergus. "Visualizing and understanding convolutional networks." European conference on computer vision. Springer, Cham, 2014.

# Transfer Learning

The weights in a pretrained neural network is the learned knowledge.

So a deep CNN trained on a large dataset contains knowledge (weights) that can be used to understand basic features in any given new image. This is the concept of transfer learning.

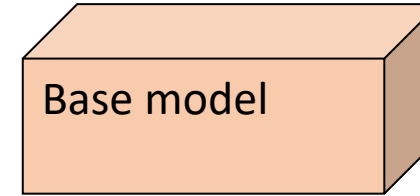
To do transfer learning, we

- Freeze the first layers of the pretrained neural network. These are the layers that detect general features that are common across all domains.
- Then we finetune the deeper layers with our own training data and add new layers to classify new categories included in our training dataset.

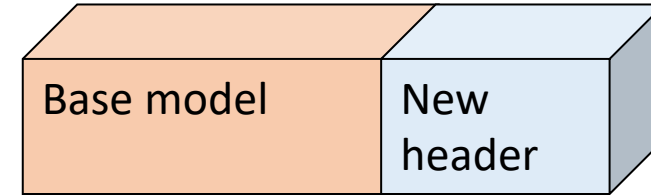


# Transfer Learning: Fine tuning

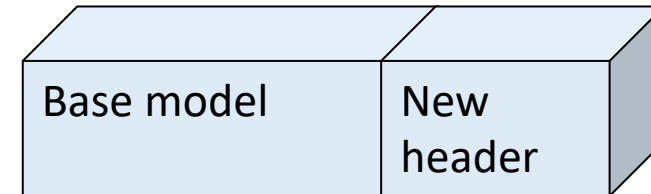
**Take a pre-trained model (with learned weights) as base model**



**Add a header and train with the base model's weights frozen**

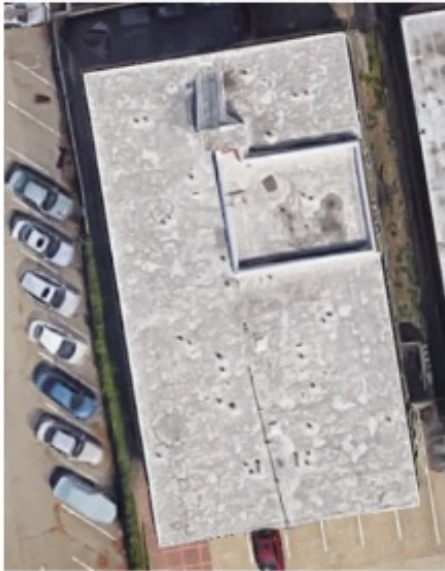


**Unfreeze the base model and train**



# Demo: Roof shape classification

Will do this demo in a Jupyter notebook.



Flat



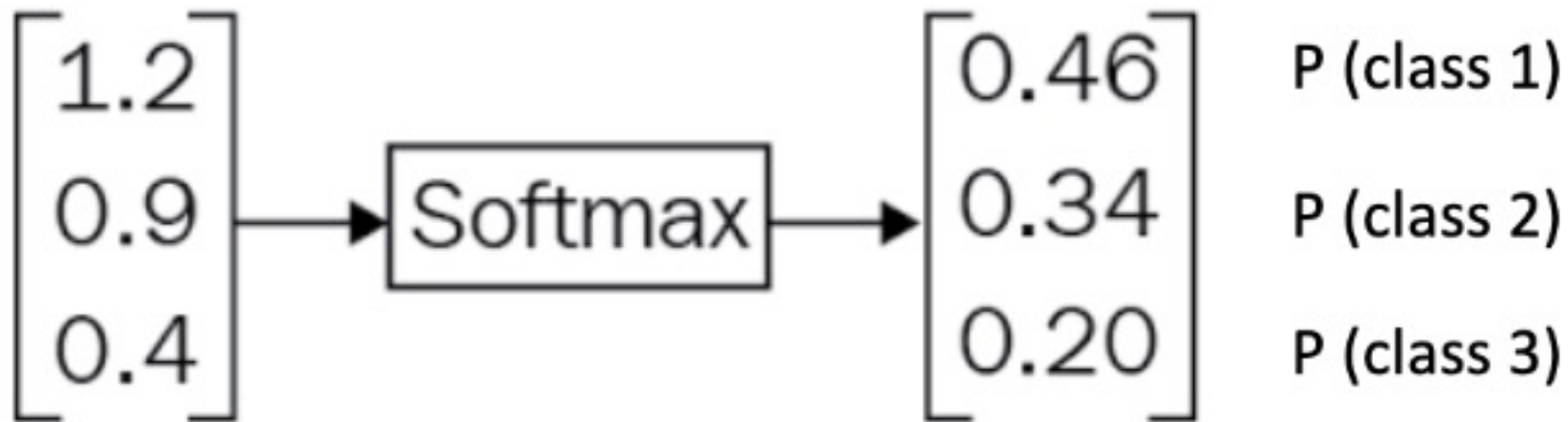
Gabled



Hipped

## Softmax

$$S(y_i) = \frac{e^{y_i}}{\sum_j e^{y_j}}$$



Probabilities, sum is 1.0

## Software and Platforms

scikit-learn (conventional ML)

Tensorflow (deep neural networks)

PyTorch (deep neural networks)

...

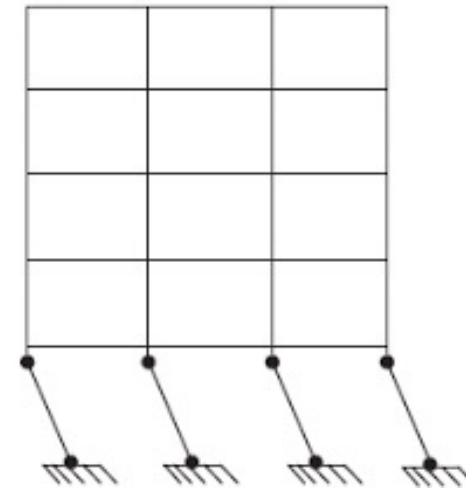
## Exercise

# Train a soft-story building classifier.

Data: <http://doi.org/10.5281/zenodo.4092974>



Soft-story collapse



Failure mechanism