

# ***Deep Learning Crash Course***

*Notes for derivative of CE loss*



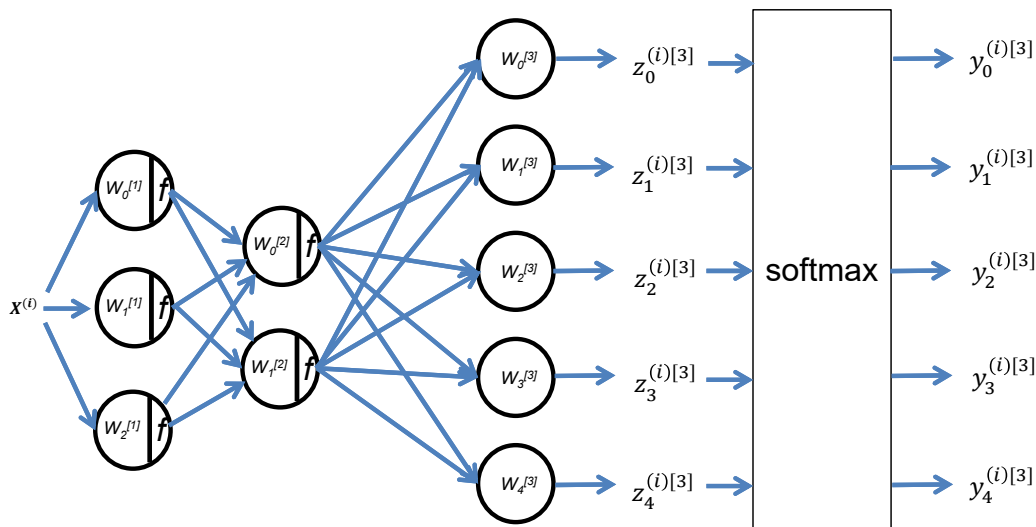
[www.deeplearningcrashcourse.org](http://www.deeplearningcrashcourse.org)

**Hui Xue**

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# CE-Loss

K=5, 5 class classification



$$loss = \frac{1}{B} \sum_{i=0}^{B-1} L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})$$

$$\hat{\mathbf{y}}^{(i)} = \hat{\mathbf{y}}(\mathbf{X}^{(i)}; \boldsymbol{\theta})$$

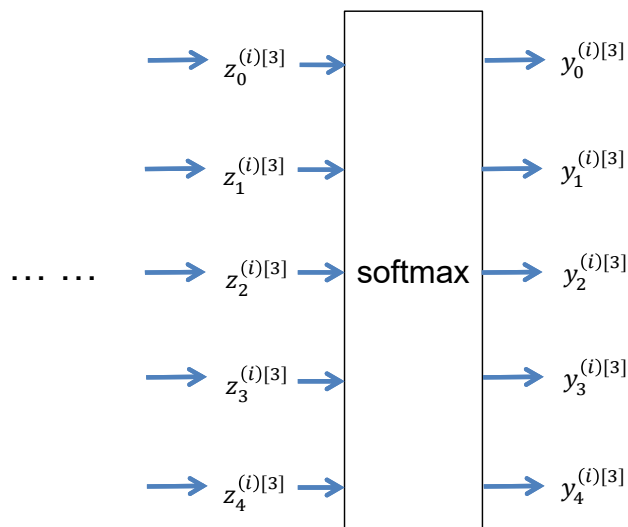
$$L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)}) = - \sum_{j=0}^{K-1} y_j^{(i)} \log(\hat{y}_j^{(i)})$$

$$\hat{y}_j^{(i)} = \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}}$$

The goal is to compute  $\frac{\partial loss}{\partial \boldsymbol{\theta}}$

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The goal is to compute  $\frac{\partial loss}{\partial \boldsymbol{\theta}}$

$$\frac{\partial loss}{\partial \boldsymbol{\theta}} = \frac{1}{B} \sum_{i=0}^{B-1} \frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \boldsymbol{\theta}}$$

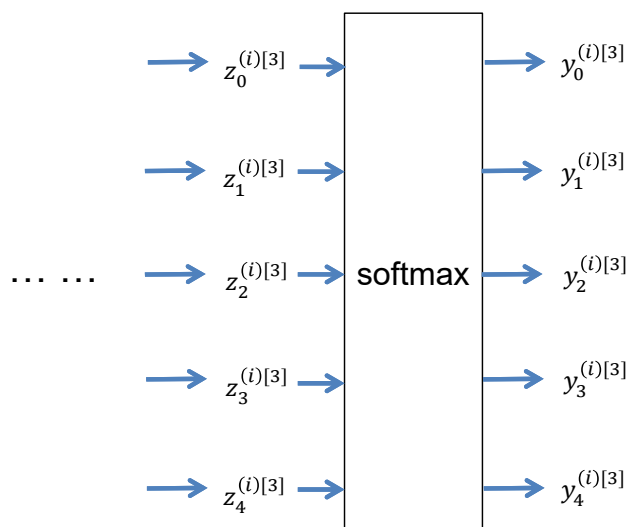
$$\frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \boldsymbol{\theta}} = \left( \frac{\partial \mathbf{z}}{\partial \boldsymbol{\theta}} \right)^T \frac{\partial L}{\partial \mathbf{z}}$$

We will compute

$$\frac{\partial L}{\partial \mathbf{z}} = \left[ \frac{\partial L}{\partial z_0}, \frac{\partial L}{\partial z_1}, \dots, \frac{\partial L}{\partial z_{K-1}} \right]^T$$

# CE-Loss

K=5, 5 class classification



$$loss = \frac{1}{B} \sum_{i=0}^{B-1} L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})$$

$$\hat{\mathbf{y}}^{(i)} = \hat{\mathbf{y}}(\mathbf{X}^{(i)}; \boldsymbol{\theta})$$

$$L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)}) = - \sum_{j=0}^{K-1} y_j^{(i)} \log(\hat{y}_j^{(i)})$$

$$\hat{y}_j^{(i)} = \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}}$$

The goal is to compute  $\frac{\partial loss}{\partial \boldsymbol{\theta}}$

$$\frac{\partial L}{\partial z_k} = \frac{\partial [-\sum_{j=0}^{K-1} y_j \log(\hat{y}_j)]}{\partial z_k}$$

$$= - \sum_{j=0}^{K-1} y_j \frac{\partial \log(\hat{y}_j)}{\partial z_k}$$

$$= - \sum_{j=0}^{K-1} \frac{y_j}{\hat{y}_j} \frac{\partial \hat{y}_j}{\partial z_k}$$

$$\frac{\partial \hat{y}_j}{\partial z_k} = \frac{\partial [\frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}}]}{\partial z_k}$$

# CE-Loss

$$\frac{\partial \hat{y}_j}{\partial z_k} = \frac{\partial \left[ \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}} \right]}{\partial z_k}$$

If  $k = j$

$$\begin{aligned} \frac{\partial \hat{y}_j}{\partial z_j} &= \frac{\partial \left[ \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}} \right]}{\partial z_j} \\ &= \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}} \cdot - \frac{e^{z_j}}{[\sum_{t=0}^{K-1} e^{z_t}]^2} e^{z_j} \\ &= \hat{y}_j - \hat{y}_j^2 \end{aligned}$$

If  $k \neq j$

$$\begin{aligned} \frac{\partial \hat{y}_j}{\partial z_k} &= \frac{\partial \left[ \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}} \right]}{\partial z_k} \\ &= - \frac{e^{z_j}}{[\sum_{t=0}^{K-1} e^{z_t}]^2} e^{z_k} \\ &= -\hat{y}_j \hat{y}_k \end{aligned}$$

# Jacobian

$$\frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{z}} = \begin{bmatrix} \frac{\partial \hat{y}_0}{\partial z_0} & \cdots & \frac{\partial \hat{y}_0}{\partial z_{K-1}} \\ \vdots & \ddots & \vdots \\ \frac{\partial \hat{y}_{K-1}}{\partial z_0} & \cdots & \frac{\partial \hat{y}_{K-1}}{\partial z_{K-1}} \end{bmatrix} = \begin{bmatrix} \hat{y}_0 - \hat{y}_0^2 & \cdots & -\hat{y}_0 \hat{y}_{K-1} \\ \vdots & \ddots & \vdots \\ -\hat{y}_{K-1} \hat{y}_0 & \cdots & \hat{y}_{K-1} - \hat{y}_{K-1}^2 \end{bmatrix}$$

A symmetric jacobian

$$\hat{y}_j = \frac{e^{z_j}}{\sum_{t=0}^{K-1} e^{z_t}}$$

# CE-Loss

$$\begin{aligned}\frac{\partial L}{\partial z_k} &= - \sum_{j=0}^{K-1} \frac{y_j}{\hat{y}_j} \frac{\partial \hat{y}_j}{\partial z_k} \\&= - \frac{y_k}{\hat{y}_k} (\hat{y}_k - \hat{y}_k^2) - \sum_{j=0, j \neq k}^{K-1} \frac{y_j}{\hat{y}_j} (-\hat{y}_j \hat{y}_k) \\&= -y_k(1 - \hat{y}_k) + \sum_{j=0, j \neq k}^{K-1} y_j \hat{y}_k \\&= -y_k + y_k \hat{y}_k + \sum_{j=0, j \neq k}^{K-1} y_j \hat{y}_k \\&= -y_k + \sum_{j=0}^{K-1} y_j \hat{y}_k \\&= -y_k + \hat{y}_k \sum_{j=0}^{K-1} y_j = \hat{y}_k - y_k\end{aligned}$$

So we get:

$$\frac{\partial L}{\partial \mathbf{z}} = [\hat{y}_0 - y_0, \hat{y}_1 - y_1, \dots, \hat{y}_{K-1} - y_{K-1}]^T$$

$$\frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \boldsymbol{\theta}} = \left( \frac{\partial \mathbf{z}}{\partial \boldsymbol{\theta}} \right)^T \frac{\partial L}{\partial \mathbf{z}}$$

We will not need to explicitly compute  $\frac{\partial \mathbf{z}}{\partial \boldsymbol{\theta}}$

But compute  $\frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \mathbf{W}^{[3]}}$ ,  $\frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \mathbf{W}^{[2]}}$ ,  $\frac{\partial L_{CE}(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)})}{\partial \mathbf{W}^{[1]}}$  layer by layer using backprop

