

ESPRESSIF

TRAINING

ESP Bootstrap



ESP Bootstrap: Objective

- Build a complete “product”: Smart Power Outlet
 - Control GPIO output
 - Network Configuration
 - Remote control through cloud
 - OTA Upgrades
 - Reset to Factory



Hello World



Objective

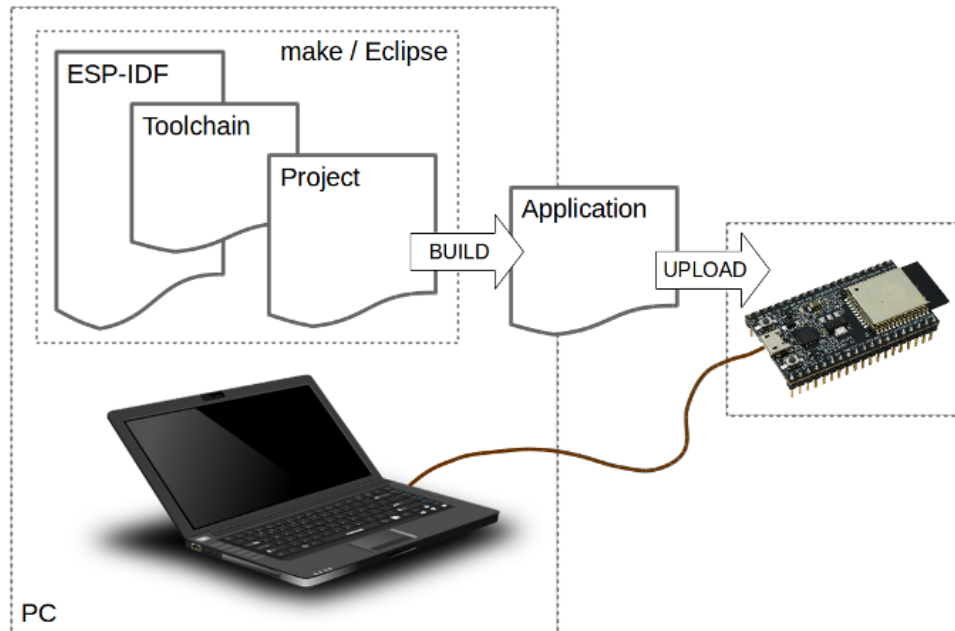
- Getting Ready
- Development Host Setup
- Configure and Build
- Flash
- Console



- Development Host PC
 - Windows, Linux, Mac
- ESP32 DevKit - C
- USB to mini-USB cable
- Wi-Fi Access Point



Overview

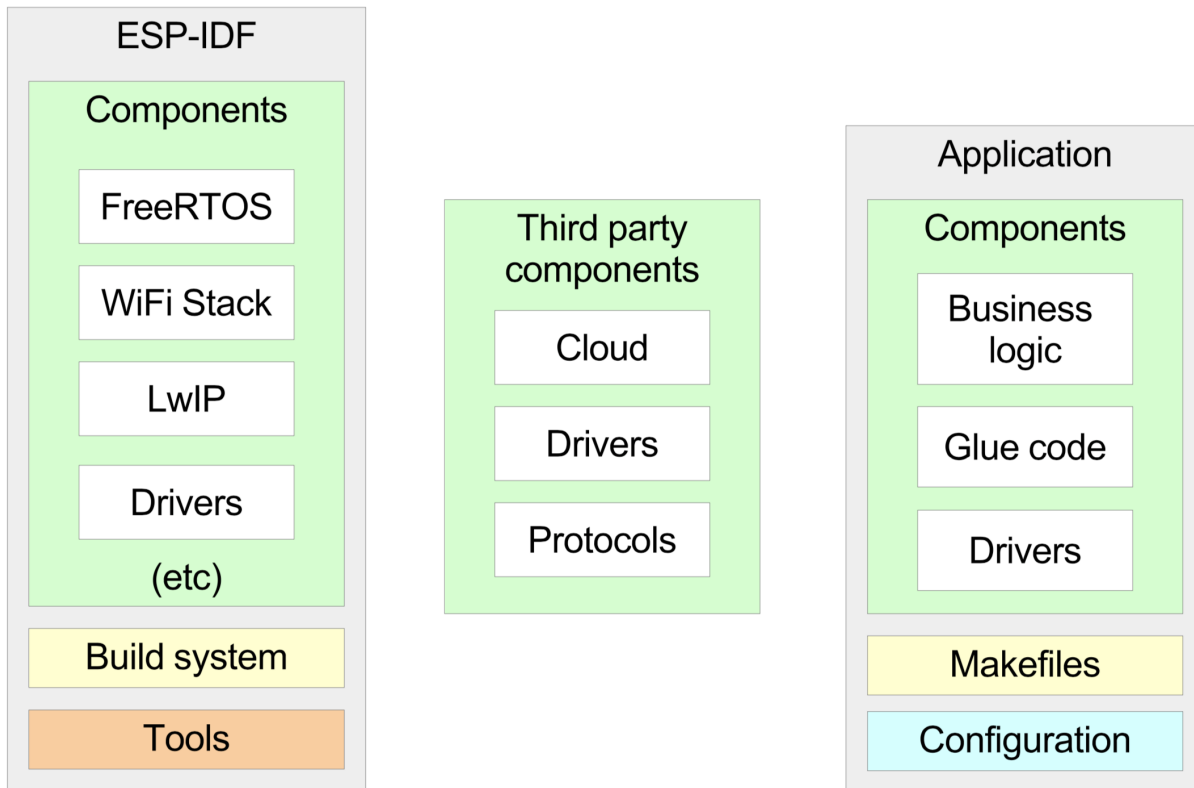




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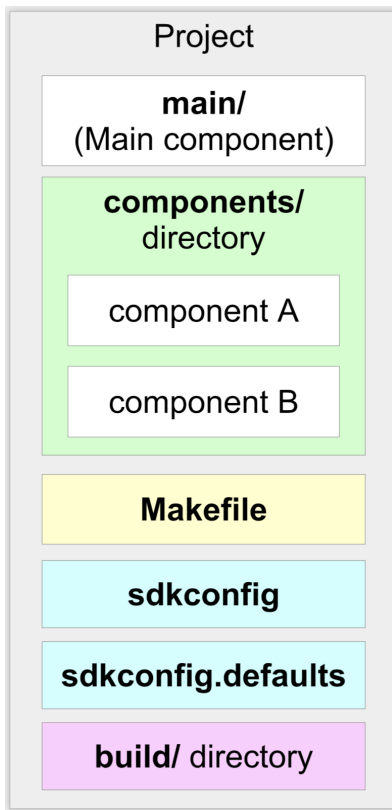


Component Based Design





Structure of an application/project





Configuration

- Configuration system based on Linux kernel's kconfig
- Configure settings for your project (impacts feature, performance, memory)
- Each component can define its own configuration options
- Use **make menuconfig** command to edit the configuration



Code

```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"

void app_main()
{
    int i = 0;
    while (1) {
        printf("[%d] Hello world!\n", i);
        i++;
        vTaskDelay(5000 / portTICK_PERIOD_MS);
    }
}
```




The C standard Library

ESP-IDF uses newlib 2.2.0 as C standard library

- Parts of newlib are placed into ESP32 ROM
- Newlib interacts with RTOS through a syscall table
- Newlib supports per-task reentrant structures
- Most of the C standard library is supported, plus extras



The C standard Library

Not supported

- Wide character functions
- Signals
- Locales
- atexit, system, mallinfo

Supported

- stdlib, stdio, string, math, time
- File/Directory operations
- Reentrant functions
- Timezones, DST



FreeRTOS

Real-Time Operating System <https://www.freertos.org>

- Threads
- Interrupts
- Message Queues, Semaphores and Mutexes
- Timers

API Reference: <https://www.freertos.org/a00106.html>



Objective

- Use GPIOs
- Configure a push-button
- Control an output



Code

```
#include <iot_button.h>
```

```
button_handle_t  
btn_handle=iot_button_create(BUTTON_GPIO,  
                             BUTTON_ACTIVE_LEVEL);
```

```
iot_button_set_evt_cb(btn_handle, BUTTON_CB_RELEASE,  
                      btn_cb, "RELEASE");
```



- Configure mode
- Set output



Code

```
gpio_config_t io_conf;
io_conf.mode = GPIO_MODE_OUTPUT;
io_conf.pull_up_en = 1;
io_conf.pin_bit_mask = ((uint64_t)1 << OUTPUT_GPIO);

/* Configure the GPIO */
gpio_config(&io_conf);

/* Assert GPIO */
gpio_set_level(OUTPUT_GPIO, target);
```



Wi-Fi



Objective

- Configure Wi-Fi station interface
- Connect to pre-configured AP
- Asynchronous event handler:
 - Connected
 - Disconnected
 - IP Address assignment



Code

```
#include <esp_wifi.h>
#include <esp_event_loop.h>

tcpip_adapter_init();
esp_event_loop_init(event_handler, NULL);

wifi_init_config_t cfg = WIFI_INIT_CONFIG_DEFAULT();
esp_wifi_init(&cfg);
esp_wifi_set_mode(WIFI_MODE_STA);
```



Code

```
wifi_config_t wifi_config = {  
    .sta = {  
        .ssid = EXAMPLE_ESP_WIFI_SSID,  
        .password = EXAMPLE_ESP_WIFI_PASS,  
    },  
};  
esp_wifi_set_config(ESP_IF_WIFI_STA, &wifi_config);  
  
esp_wifi_start();
```



Code

```
esp_err_t event_handler(void *ctx, system_event_t
*event)
{
    switch(event->event_id) {
        case SYSTEM_EVENT_STA_START:
            esp_wifi_connect();
            break;
        case SYSTEM_EVENT_STA_GOT_IP:
            ESP_LOGI(TAG, "Connected with IP Address:%s",
ip4addr_ntoa(&event->event_info.got_ip.ip_info.ip));
            break;
        case SYSTEM_EVENT_STA_DISCONNECTED:
            esp_wifi_connect();
            break;
    }
    return ESP_OK;
}
```



Network Configuration



- Get your product on the user's home network
 - as opposed to a pre-configured network
- User Settings and Reset to Factory



- Soft AP
 - Manual Wi-Fi change on iOS
- Bluetooth
 - Larger flash footprint
- Smart-Config



- Specification to securely transfer credentials to the device, independent of the transport (SoftAP, Bluetooth)
- Device-side implementation of the specification
- Libraries for Android/iOS that implement the specification
- Reference applications on the device and Android/iOS



- SoftAP or BLE?
- Secure Exchange?
- Proof of possession?
- Service Name?



Code

```
if (conn_mgr_prov_is_provisioned(&provisioned) !=
ESP_OK) {
    return;
}

if (! provisioned) {
    /* Starting provisioning */
    conn_mgr_prov_start_provisioning(prov_type,
                                     security, pop, service_name,
service_key);
} else {
    /* Start the station */
    wifi_init_sta();
}
```



Code

```
esp_err_t event_handler(void *ctx, system_event_t
*event)
{
    conn_mgr_prov_event_handler(ctx, event);

    switch(event->event_id) {
    case SYSTEM_EVENT_STA_START:
...
...
...
```



Flash Partitions

- Store user's configuration: NVS
- Custom Partition Table: partitions.csv
- Update in 'menuconfig'



NVS

- Key-Value store in flash
- Power loss resilient
- Wear-levelling: Log based structure
- Support namespaces
- Used for: Manufacturing settings, User's configuration, Maintaining state across resets



Reset to Factory

- Long-press Push Button
- Erase NVS



Code

```
static void button_press_3sec_cb(void *arg)
{
    nvs_flash_erase();
    esp_restart();
}

iot_button_add_on_press_cb(btn_handle, 3,
                           button_press_3sec_cb, NULL);
```



Phone Application

- Android and iOS
- Structured as library and phone app
- Android: <https://github.com/espressif/esp-idf-provisioning-android>
- iOS: <https://github.com/espressif/esp-idf-provisioning-ios>



Objective

- Cloud communication:
 - Update local state information
 - Fetch commands
- Security:
 - Cloud CA Certificate
 - Device's authentication Certificates
- Example Cloud: AWS



AWS

- Example Cloud
- Uses Device Certificate and Key for authentication
 - Pre-generated for the training



Embedding Files in the Firmware

- Update your component.mk

```
COMPONENT_EMBED_TXTFILES := certs/aws-root-ca.pem \
                             certs/certificate.pem.crt \
                             certs/private.pem.key
```

- Access in your code

```
extern const uint8_t aws_root_ca_pem_start[]

asm("_binary_aws_root_ca_pem_start");
extern const uint8_t aws_root_ca_pem_end[]
asm("_binary_aws_root_ca_pem_end");
```



Change the thing name

- Update the thing-name in your code to match your thing-name



- ```
$ curl --tlsv1.2 --cert /work/certificate.pem.crt --
key /work/private.pem.key https://aln7lww42a72l-
ats.iot.us-east-2.amazonaws.com:8443/things/chicago1/
shadow | python -mjson.tool
```



# RESTful API write

---

- Update state using HTTP API

```
$ curl -d '{"state":{"desired":{"output":false}}}' --
tlsv1.2 --cert /work/certificate.pem.crt --key /work/
private.pem.key https://aln7lww42a72l-ats.iot.us-
east-2.amazonaws.com:8443/things/chicago1/shadow |
python -mjson.tool
```



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# OTA Upgrade





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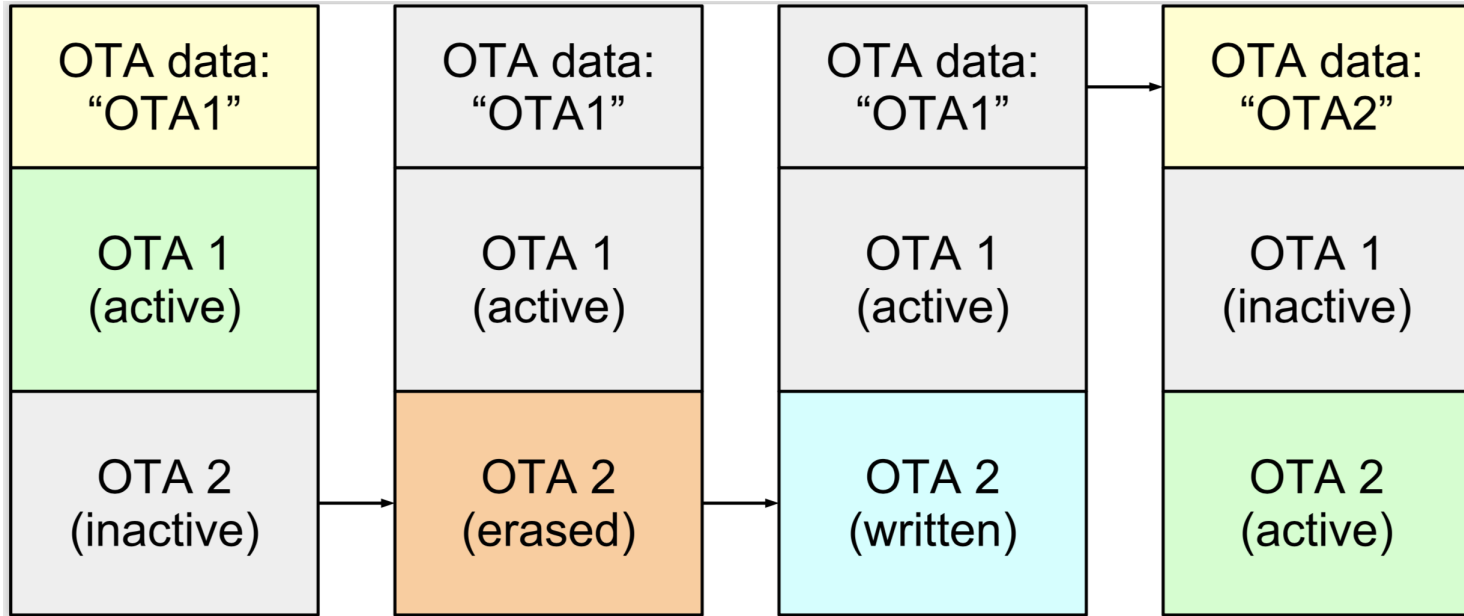
# Flash Partitions once more

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- Active-Passive Firmware Partitions
- OTA Data partition stores currently active partition state



# Flash Partitions once more







# Code

---

```
esp_http_client_config_t config = {
 .url = url,
 .cert_pem =
(char*)upgrade_server_cert_pem_start,
};
esp_err_t ret = esp_https_ota(&config);
if (ret == ESP_OK) {
 esp_restart();
} else {
 ESP_LOGE(TAG, "Firmware Upgrades Failed");
}
```



- <https://raw.githubusercontent.com/kedars/drawer/master/hello-world.bin>



---

# Factory Partition



# Objective

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- Allow configuring per-device unique configurations
- To be applied at the factory during manufacturing





- Separate NVS partition for storing factory settings
- So 2 NVS partitions:
  - For storing user configuration. Is erased on reset-to-factory action
  - For storing device-unique configuration at the time of manufacturing. Is never erased
- Update the partitions.csv with this new partition



# Pre-generate NVS Partition

---

- Decide partition content:

`key, type, encoding, value`

`mfg_ns, namespace, ,`

`serial_no, data, string, btest1`

`cert, file, string, /training/esp-bootstrap/7mfg/main/`

`certs/certificate.pem.crt`

`priv_key, file, string, /training/esp-bootstrap/7mfg/main/`

`certs/private.pem.key`

- Three keys: `serial_no`, `cert` and `priv_key`, are part of the NVS within the 'mfg\_ns' namespace of this NVS partition



# Pre-generate NVS Partition

---

- Convert the file to an NVS on-flash image:

```
$ python /training/esp-bootstrap/esp-idf/components/
nvs_flash/nvs_partition_generator/nvs_partition_gen.py
--version v1 mfg_config.csv mfg.bin
```

- Flash this partition at its right location:

```
$ /training/esp-bootstrap/esp-idf/components/esptool_py/
esptool/esptool.py --port /dev/tty.SLAB_USBtoUART
write_flash 0x340000 mfg.bin
```



# Read the manufacturing data

---

- Read the manufacturing data from the firmware using NVS API

```
nvs_handle fctry_handle;
nvs_flash_init_partition(MFG_PARTITION_NAME);

nvs_open_from_partition(MFG_PARTITION_NAME, "mfg_ns",
 NVS_READONLY, &fctry_handle);
nvs_get_str(fctry_handle, "serial_no", serial_no);
nvs_close(fctry_handle);
```



# Product Ready!

---

- Now we have a complete end-product:
  - Control GPIO output
  - Network Configuration
  - Remote control through cloud
  - OTA Upgrades
  - Reset to Factory



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**Thank You!**