Summary

• Dynamic professional with 3 years of robotics and automation expertise, excelling in forging strategic partnerships to achieve key goals. Thrives in fast-paced environments, leveraging expertise in robotics, interdisciplinary skills and programming prowess to drive team success. Committed to consistent growth and exceeding expectations for continuous improvement.

Skills

- Robotics: kinematics & dynamics, control systems, SLAM, Path-Planning, Navigation
- ROS/ROS2: ROS services, actions, Path-Planners, Movebase, Moveit, Library
- Proficient in programming languages: C/C++, Python, URDF, Shell Scripting
- Strong knowledge of electronics and communication, and control algorithms, Image processing and Deep Learning
- Robotics Hardware: sensors(IMU, camera, lidar), motors, Turtlebot, Open Manipulator, Open-Source hardware, National Instruments
- Git, Robotic systems design, development and integration, AWS, Linux, Enterprise Architecture

Experience

- Robotics Engineer, Bosch Global Software Technologies Private Limited, Bangalore (Feb 2022 to Present)
 - Evaluated and integrated 3D navigation packages for drones.
 - Developed prototypes of indoor drones, achieving 80% stability in flight even at full payload.
 - Crafted a robust software architecture for smooth operation in 4 complex scenarios in Enterprise Architecture.
 - Constructed Gazebo simulation models of bulldozers and outdoor environments.
 - Generated Path Planner to enable remote automation of bulldozers in Japan, achieving 100% success rate in path generation.
 - Maintained precise control, ensuring that bulldozer overshooting during motion stayed under 45% of the bull-dozer's dimensions at boundaries.
 - Constructed a mobile service robot equipped with a robotic arm, with pick and place operation having a success rate of 50-60%.
- System Administrator, Nexuba, Bangalore

(May 2021 to Feb 2022)

- Performed secure data management for servers and automating maintenance tasks of SQL databases in EC2 servers, on AWS.
- Internship, on IoT & Robotics at Serpro Consulting, MRPL and CSD NITK, Mangalore (May 2019 to June 2020)

Projects

- Autonomous Navigation of multiple Mobile robots: Autonomous navigation of 3 robots in Gazebo with SMACH, 100% success rate. Partial mobile robot prototype interfaced with ROS.
- Quadruped robot: Prototype of quadruped robot (4 legged) was designed and developed.

Education

- M.Tech in Mechatronics Engineering, National Institute of Technology Karnataka
- B.Tech in Electronics and Communication Engineering, Palakkad

Certifications & Achievements

- Deep Learning Specialization courses offered by deeplearning.ai from Coursera.
- \bullet Winner of Fitfor Future Robot competitions at Bosch.
- Mentored in terns and guided colleagues in robotics.
- Conducted a Visual Odometry based Hackathon at Bosch.