

DATA STRUCTURE AND ALGORITHMS

Lecture 03, 04: Arrays, Sparse Matrix, String

ADDRESSING VARIABLES

指標就是用位置去處理資料

- Every variable residing in memory has an address!
- What doesn't have an address?
 - register variables
 - constants/literals/preprocessor defines
 - expressions (unless result is a variable)
- How to find an address of a variable? The & operator

```
int n = 4;
```

```
double pi = 3.14159;
```

```
int *pn = &n; /* address of integer n */
```

```
double *ppi = &pi; /* address of double pi */
```

*pn = &n

有個pointer叫做pn

這個pointer裡面存了n的位置

這個a代表了位置 (地址)

$C = a + b$
memory

a →	10
b →	2
c →	12

a+b

會把a先存到暫存器1

把b加到暫存器1

所以暫存器1現在存著a+b

再把這個內容存到指標c裡面

DEREFERENCING POINTERS

- Accessing/modifying addressed variable: dereferencing/indirection operator *

```
/* prints "pi = 3.14159\n" */  
printf("pi = %g\n" ,*ppi ) ;  
/* pi now equals 7.14159 */  
*ppi = *ppi + *pn ;
```

ppi是個指標變數

透過這個變數可以得到pi的位置

*ppi是個pointer裡面存了&pi，透過&pi可以找到pi這個位置，
所以會印出pi這個位置裡面存的值。

- Dereferenced pointer like any other variable
- null pointer, i.e. 0 (NULL): pointer that does not reference anything

global變數，大家都可以看得到，大家都可以去改，
所以只要有一個地方寫錯了，整個就會算錯。

當程式多的時候，你想要改變某些記憶體裡的資料，我們可以透過
pointer去找到位置，

ACCESSING CALLER'S VARIABLES

利用pointer來做swap（兩個變數互換）

- write function to swap two integers
- Need to modify variables in caller to swap them
- Pointers to variables as arguments

```
void swap( int *x , int *y ){  
    int temp = *x ;    把*x裡的東西複製一份到temp  
    *x = *y ;           再把*y裡的東西放到*x裡面  
    *y = temp ;         最後把temp(原本的*x)存進*y裡  
}
```

- Calling swap() function:

```
int a = 5 , b = 7;  
swap(&a , &b); /* now , a = 7 , b = 5 */
```

要呼叫的時候，用swap(&a, &b)，這個時候a裡面存的是原本的b，b裡面存的是原本的a（兩者已交換）

EXAMPLE

- Consider the Fibonacci Function that is written previously.

```
#include <stdio.h>

int iterFib(int);
int recurFib(int);

int main() {
    int n;

    while (1) {
        printf("n:(>=0): ");
        scanf("%d", &n);
        while (n < 0) {
            /* error loop */
            if (n == -999) return 0;
            printf("invalid number.\nn:(>=0), exit program by entering -999: ")
            scanf("%d", &n);
        }

        printf("iterFib(%d) Fibonacci is %d. ", n, iterFib(n));
        printf("recurFib(%d) Fibonacci is %d. \n\n", n, recurFib(n));
    }
}

int recurFib(int n) { /* recursive version */
    if ((n == 0) || (n == 1)) return n;
    return recurFib(n - 1) + recurFib(n - 2);
}

int iterFib(int n) { /* find the factorial,
return as a double to keep it from overflowing */
    int i;
    int fib, fib1, fib2;

    if ((n == 0) || (n == 1)) {
        return n;
    } else {
        fib1 = 0;
        fib2 = 1;
        for (i = 2; i <= n; i++) {
            fib = fib1 + fib2;
            fib2 = fib1;
            fib1 = fib;
        }
        return fib;
    }
}
```

INTRODUCE STEP COUNT GLOBALLY

```
#include <stdio.h>
global變數宣告step count，在副程式
設成0 初始化 (自訂函式) 裡面就可以直接用來算
int stepCount = 0;
/* a global step-count for iterative Fibonacci */
int iterFib(int);
int recurFib(int);

int main() {
    int n;

    while (1) {
        printf("n:(>=0): ");
        scanf("%d", &n);
        while (n < 0) {
            /* error loop */
            if (n == -999) return 0;
            printf("invalid number.\nn:(>=0), exit program by entering -9\n");
            scanf("%d", &n);
        }
        stepCount = 0; /*initialize step-count */

        printf("iterFib(%d) Fibonacci is %d. ", n, iterFib(n));
        printf("Step count is %d. \n", stepCount);
        printf("recurFib(%d) Fibonacci is %d. \n\n", n, recurFib(n));
    }
}
```

```
int iterFib(int n) { /* find the factorial, return
as a double to keep it from overflowing */
    int i;
    int fib, fib1, fib2;
    stepCount++; /* count for if-condition */
    if ((n == 0) || (n == 1)) {
        stepCount++; /* count for return */
        return n;
    } else {
        fib1 = 0;
        stepCount++; /* count for assignment */
        fib2 = 1;
        stepCount++; /* count for assignment */
        for (i = 2; i <= n; i++) {
            stepCount++; /* count for for-loop */
            fib = fib1 + fib2;
            fib2 = fib1;
            fib1 = fib;
            stepCount += 3; /* count for assignments */
        }
        stepCount++; /* count for last for-loop */

        stepCount++; /* count for return */
        return fib;
    }
}
```

2次
3次

• How about the recursive one?

```
int recurFib(int n) { /* recursive version */
    if ((n == 0) || (n == 1)) return n;
    return recurFib(n - 1) + recurFib(n - 2);
}
```

賦值 後要+1
if判斷 前要+1
for迴圈 內要+1
for迴圈 外 (出來後) 要+1
return 前要+1

EXAMPLE

用pointer來做iterative的Fibonacci

- What if using a pointer?

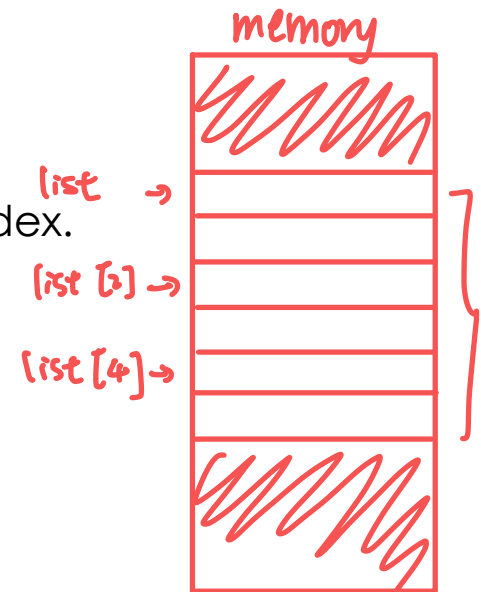
```
#include <stdio.h>
void iterFib(int, int*, int*);
int recurFib(int);

int main(){
    int n;
    int count1;
    int ifib;
    while (1){
        printf("n:(>=0): ");
        scanf("%d", &n);
        while (n < 0)
        { /*error loop */
            if(n==-999) return 0;
            printf("invalid number.\nn:(>=0), exit program by entering -999: ");
            scanf("%d", &n);
        }
        iterFib(n, &ifib, &count1);
        printf("iterFib(%d) Fibonacci is %d. Step count is %d. \n", n, ifib, count1);
        printf("recurFib(%d) Fibonacci is %d. \n\n", n, recurFib(n));
    }
}
```

- The calling function shall be modified. Try!!

ARRAYS AND POINTERS

- Array: a set of **index** and **value**
- Data structure
 - For each index, there is a value associated with that index.
- Representation (**possible**)
 - Implemented by using consecutive memory.
- `int list[5]: list[0], ..., list[4]`, each contains an integer



list[5]

0	1	2	3	4

ADT是一個虛擬的資料型態

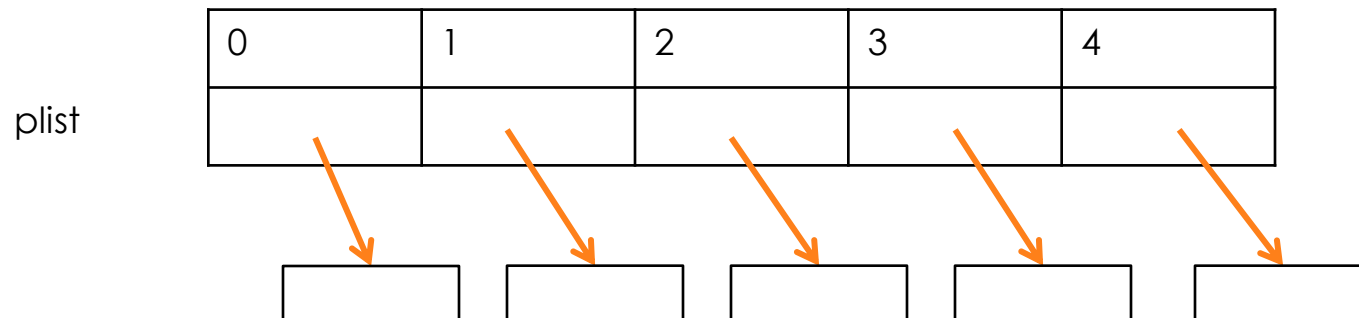
- **Structure** Array is
objects: A set of pairs $\langle index, value \rangle$ where for each value of *index* there is a value from the set *item*. *Index* is a finite ordered set of one or more dimensions, for example, $\{0, \dots, n-1\}$ for one dimension, $\{(0,0), (0,1), (0,2), (1,0), (1,1), (1,2), (2,0), (2,1), (2,2)\}$ for two dimensions, etc.
Functions:
for all $A \in \text{Array}, i \in \text{index}, x \in \text{item}, j, \text{size} \in \text{integer}$
Array Create(*j*, *list*) ::= **return** an array of *j dimensions* where *list* is a *j-tuple* whose *i*th element is the *size* of the *i*th dimension. *Items* are undefined.
Item Retrieve(*A*, *i*) ::= **if** ($i \in \text{index}$) **return** the item associated with index value *i* in array *A*
else return error
Array Store(*A*, *i*, *x*) ::= **if** ($i \in \text{index}$) **return** an array that is identical to array *A* except the new pair $\langle i, x \rangle$ has been inserted **else return** error
end array
***Structure 2.1:** Abstract Data Type Array (p.50)

ARRAY IN C

- `int list[5], *plist[5]`
- `list[5]`: five integers
`list[0], list[1], list[2], list[3], list[4]`
- `*plist[5]`: five pointers to integer

list[5]

0	1	2	3	4



ARRAY IN C (CONT'D)

- Implementation of 1-D array

list[0]	base address = a
list[1]	a + 1*sizeof(int)
list[2]	a + 2*sizeof(int)
list[3]	a + 3*sizeof(int)
list[4]	a + 4*sizeof(int)

→ 要連續的位置

- Compare `int *list1` and `int list2` in C

same: list1 and list2 are pointers

difference: list2 reserve five locations

- Notations:

list2 - a pointer to list2[0]

(list2 + i) - a pointer to list2[i] (&list2[i])

*list2 + i - list2[i]

取到的是list2+i這個位址的值

EXAMPLE: 1-DIMENSION ARRAY ADDRESSING

```
int one[] = {0, 1, 2, 3, 4};
```

Goal: print out address and value

```
void print1 (int *ptr, int rows)
{
    /* print out a one-dimensional array using a
    pointer*/
    int i;
    printf("Address Contents\n");
    for (i = 0; i<rows; i++)
        printf("%8u%5d\n", ptr+i, *(ptr+i));
    printf("\n")
}
```

索引 (位置)

内容

EXAMPLE: 1-DIMENSION ARRAY ADDRESSING (CONT'D)

- Call `print1(&one[0],5)`

Address	Contents
1228	0
1230	1
1232	2
1234	3
1236	4

***Figure 2.1:** One-dimensional array addressing (p.53)

STRUCTURES (RECORDS)

```
struct {  
    char name[10];  
    int age;  
    float salary;  
} person;  
strcpy(person.name, "James")  
person.age = 10;  
person.salary = 35000;
```

把有關的東西都存放在一個結構裡

用struct設定出一個queue或是stack

CREATE STRUCTURE DATA TYPE

新建一個structure的方式：

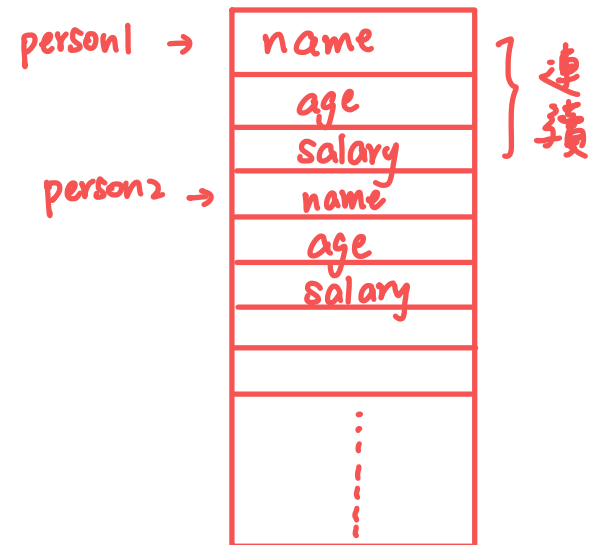
```
typedef struct 名稱{
}
```

```
typedef struct human_being {
    char name[10];
    int age;
    float salary;
};
```

Or

```
typedef struct {
    char name[10];
    int age;
    float salary;
} human_being;
```

```
Human_being person1, person2;
```



ORDERED LIST

- Ordered (linear) list:
 - (item1, item2, item3,..., itemK)
- Examples
 - (MONDAY, TUESDAY, WEDNESDAY, THURSDAY, FRIDAY, SATURDAY, SUNDAY)
 - (2, 3, 4, 5, 6, 7, 8, 9, 10, Jack, Queen, King, Ace)
 - (1941, 1942, 1943, 1944, 1945)
 - ($a_1, a_2, a_3, \dots, a_{n-1}, a_n$)

OPERATIONS ON ORDERED LIST

- (1) Find the length, n , of the list.
- (2) Read the items from left to right (or right to left).
- (3) Retrieve the i^{th} element.
- (4) Store a new value into the i^{th} position.
- (5) Insert a new element at the position i , causing elements numbered $i, i+1, \dots, n$ to become numbered $i+1, i+2, \dots, n+1$
- (6) Delete the element at position i , causing elements numbered $i+1, \dots, n$ to become numbered $i, i+1, \dots, n-1$

其他花 $O(1)$

用array的話做插入&刪除會很慢，會花 $O(n)$ 的時間

IMPLEMENTATION ON ORDERED LIST

- Implementing ordered list by array
 - Sequential mapping
 - (1)~(4) ○
 - (5)~(6) X
- Performing operations 5 and 6 requires data movement
 - Costly
- This overhead motivates us to consider non-sequential mapping of order lists in Chapter 4
 - Linked list

插入跟刪除可以用linked list來做，花費時間 $O(1)$

$$A(x) = A \begin{array}{|c|c|c|c|c|} \hline 4 & 2 & 3 & 0 & 0 \\ \hline \end{array} \quad \text{POLYNOMIAL}$$

0 1 2 3 4 \rightarrow 次方

- Example:

$$A(X) = 3X^2 + 2X + 4$$

$$B(X) = X^4 + 10X^3 + 3X^2 + 1$$

$$B(x) = B \begin{array}{|c|c|c|c|c|} \hline 1 & 0 & 3 & 10 & 1 \\ \hline \end{array}$$

0 1 2 3 4

把多項式存進array裡面只需要記係數就好

- The largest exponent of a polynomial is called **degree**
- A polynomial is called **sparse** when it has many zero terms
- Implement polynomials by arrays

多項式裡最高次項的指數，叫做degree

$$c(x) = x^{20} + 1$$

$$d(x) = x + 1$$

$c(x) \times d(x) \rightarrow$ 會有22項（21次方項和常數項），因此array要給他22個以上的空間

Polynomials $A(X)=3X^{20}+2X^5+4$, $B(X)=X^4+10X^3+3X^2+1$

• **Structure** *Polynomial* is

objects: $p(x) = a_1x^{e_1} + \dots + a_nx^{e_n}$; a set of ordered pairs of $\langle e_i, a_i \rangle$
 where a_i in *Coefficients* and e_i in *Exponents*, e_i are integers ≥ 0

用電腦來表示多項式 (polynomials) 的時候，把係數抓出來存就好

functions:

for all *poly*, *poly1*, *poly2*: *Polynomial*, *coef*: *Coefficients*,
expon: *Exponents*

Polynomial Zero()

::= **return** the polynomial,

$p(x) = 0$

Boolean IsZero(*poly*)

::= **if** (*poly*) **return** FALSE
else return TRUE

Coefficient Coef(*poly*, *expon*)

::= **if** (*expon* \in *poly*) **return** its
 coefficient **else return** Zero

Exponent Lead_Exp(*poly*)

::= **return** the largest exponent

in *poly*

Polynomial Attach(*poly*, *coef*, *expon*) ::= **if** (*expon* \in *poly*) **return** error
else return the polynomial

poly

with the term $\langle \text{coef}, \text{expon} \rangle$
 inserted

ADT：說出這個物件是什麼，以及他對應可以做的事情是什麼

ADT跟語言沒有關係，不是C語言裡面特定的資料結構/型態

Polynomial Remove(poly, expon)

::= **if** ($\text{expon} \in \text{poly}$) **return** the polynomial *poly* with the term whose exponent is *expon* deleted
else return error

Polynomial SingleMult(poly, coef, expon) ::= **return** the polynomial $\text{poly} \cdot \text{coef} \cdot x^{\text{expon}}$

Polynomial Add(poly1, poly2)

::= **return** the polynomial $\text{poly1} + \text{poly2}$

Polynomial Mult(poly1, poly2)

::= **return** the polynomial $\text{poly1} \cdot \text{poly2}$

End *Polynomial*

***Structure 2.2:**Abstract data type *Polynomial* (p.61)

Polynomial Addition

data structure 1:

```
#define MAX_DEGREE 101
typedef struct {
    int degree;
    float coef[MAX_DEGREE];
} polynomial;
```

- /* d = a + b, where a, b, and d are polynomials */
d = Zero()
while (! IsZero(a) && ! IsZero(b)) do { 如果a不是0而且b也不是0，才要執行下面的動作
 switch COMPARE (Lead_Exp(a), Lead_Exp(b)) {
 case -1: d =
 Attach(d, Coef (b, Lead_Exp(b)), Lead_Exp(b));
 b = Remove(b, Lead_Exp(b));
 break;
 case 0: sum = Coef (a, Lead_Exp (a)) + Coef (b, Lead_Exp(b));
 if (sum) {
 Attach (d, sum, Lead_Exp(a));
 a = Remove(a , Lead_Exp(a));
 b = Remove(b , Lead_Exp(b));
 }
 break;


```
case 1: d =  
    Attach(d, Coef (a, Lead_Exp(a)), Lead_Exp(a));  
    a = Remove(a, Lead_Exp(a));  
}  
}  
insert any remaining terms of a or b into d
```

advantage: easy implementation
disadvantage: waste space when sparse

會預留很多空間給實際不存在於多項式中的次方項

***Program 2.4** :Initial version of *padd* function(p.62)

比較有效率的做法是開兩個array，一個用來存係數 (coeff)，一個用來存指數 (expo) 見下頁

DATA STRUCTURE 2: USE ONE GLOBAL ARRAY TO STORE ALL POLYNOMIALS

$$A(X) = 2X^{1000} + 1$$

$$B(X) = X^4 + 10X^3 + 3X^2 + 1$$

***Figure 2.2:** Array representation of two polynomials
(p.63)

	<i>starta</i>	<i>finisha</i>	<i>startb</i>			<i>finishb</i>	<i>avail</i>
	↓	↓	↓			↓	↓
<i>coef</i>	2	1	1	10	3	1	
<i>exp</i>	1000	0	4	3	2	0	
	0	1	2	3	4	5	6

specification

poly

A

B

representation

<start, finish>

<0,1>

<2,5>

- storage requirements: start, finish, $2*(\text{finish}-\text{start}+1)$
- nonparse: twice as much as (1)
- when all the items are nonzero

```
MAX_TERMS 100 /* size of terms array */
typedef struct {
    float coef;
    int expon;
} polynomial;
polynomial terms[MAX_TERMS];
int avail = 0;
```

*(p.62)

Add two polynomials: $D = A + B$

```

void padd (int starta, int finisha, int startb, int finishb, int * startd,
           int * finishd)
{
    /* add A(x) and B(x) to obtain D(x) */
    float coefficient;
    *startd = available;

    while (starta <= finisha && startb <= finishb)
        switch (COMPARE(terms[starta].expon,
                       terms[startb].expon)) {

            case -1: /* a expon < b expon */
                attach(terms[startb].coef, terms[startb].expon);
                startb++;
                break;

```

Diagram illustrating the polynomial addition process:

$A(x)$ is represented by the first four terms (indices 0 to 3), and $B(x)$ is represented by the next four terms (indices 4 to 7). The result $D(x)$ is stored in the remaining terms (indices 8 to 10).

Index	0	1	2	3	4	5	6	7	8	9	10
coef	2	1	1	10	3	1	2	1	10	3	2
exp	1000	0	4	3	2	0	1000	4	3	2	0

The available pointer starts at index 8 and moves to the next available slot as terms are added.

$$A(X) = 2X^{1000} + 1$$

$$B(X) = X^4 + 10X^3 + 3X^2 + 1$$

```
case 0: /* equal exponents */  
    coefficient = terms[starta].coef +  
                terms[startb].coef;  
    if (coefficient) 不是0的時候就會進來做 attach 的動作  
        attach (coefficient, terms[starta].expon);  
    starta++;  
    startb++;  
    break;
```

```
case 1: /* a expon > b expon */  
    attach(terms[starta].coef, terms[starta].expon);  
    starta++;  
}
```

$$A(X) = 2X^{1000} + 1$$

$$B(X) = X^4 + 10X^3 + 3X^2 + 1$$

```
/* add in remaining terms of A(x) */  
for( ; starta <= finisha; starta++)  
    attach(terms[starta].coef, terms[starta].expon);
```

```
/* add in remaining terms of B(x) */  
for( ; startb <= finishb; startb++)  
    attach(terms[startb].coef, terms[startb].expon);  
*finishd = avail - 1;  
}
```



Analysis:

$O(n+m)$

where n, m are the number of nonzeros in A, B , respectively.

***Program 2.5:** Function to add two polynomial (p.64)

- void attach(float coefficient, int exponent)
{
/* add a new term to the polynomial */
if (avail >= MAX_TERMS) {
 fprintf(stderr, "Too many terms in the polynomial\n");
 exit(1);
}
terms[avail].coef = coefficient;
terms[avail++].expon = exponent;
}

***Program 2.6:**Function to add anew term (p.65)

Problem: Compaction is required
 when polynomials that are no longer needed.
 (data movement takes time.)

DISADVANTAGES OF REPRESENTING POLYNOMIALS BY ARRAYS

- The value of *free* is continually incremented until it tries to exceed *MaxTerms*
- What should we do when *free* is going to exceed *MaxTerms*?
 - Either quit or reuse the space of unused polynomials by compacting the global array
 - It is costly!
- A more elegant solution is proposed in Chapter 4 by employing linked list

SPARSE MATRIX

$$\begin{bmatrix} -27 & 3 & 4 \\ 6 & 82 & -2 \\ 109 & -64 & 11 \\ 12 & 8 & 9 \\ 48 & 27 & 47 \end{bmatrix}$$

5x3

mat [5] [3]

$$\begin{bmatrix} 15 & 0 & 0 & 22 & 0 & -15 \\ 0 & 11 & 3 & 0 & 0 & 0 \\ 0 & 0 & 0 & -6 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 91 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 28 & 0 & 0 & 0 \end{bmatrix}$$

6x6

sparse

row

0 0 15

0 3 22

0 5 -15

1 1 ... 11

8 2 ... 28

只有8個位置在存值，
所以浪費了28個位置在存0

3/27 start

SPARSE MATRIX (CONT'D)

- A general matrix consists of m rows and n columns of numbers
 - An $m \times n$ matrix
 - It is natural to store a matrix in a two dimensional array, say $A[m][n]$
- A matrix is called **sparse** if it consists of many zero entries
 - Implementing a spare matrix by a two dimensional
- array waste a lot of memory
 - Space complexity is $O(m \times n)$

一個很稀疏（充滿0）的矩陣，如果用dimensional array來存會很佔記憶體

傳統的man 矩陣，時間複雜度會是 $O(m \times n)$

SPARSE MATRIX REPRESENTATION

- Represented by a two-dimensional array.
 - Sparse matrix wastes space.
- Use triple <row, column, value>
 - Store triples row by row
 - For all triples within a row, their column indices are in ascending order.
 - Must know the numbers of rows and columns and the number of nonzero elements

ADT OF SPARSE MATRIX

Structure *Sparse_Matrix* is

objects: a set of triples, $\langle \text{row}, \text{column}, \text{value} \rangle$, where *row* and *column* are integers and form a unique combination, and *value* comes from the set *item*.

functions:

for all $a, b \in \text{Sparse_Matrix}$, $x \in \text{item}$,

$i, j, \text{max_col}, \text{max_row} \in \text{index}$

Sparse_Marix **Create**(*max_row*, *max_col*) ::=

return a *Sparse_matrix* that can hold up to $\text{max_items} = \text{max_row} \times \text{max_col}$ and whose maximum row size is *max_row* and whose maximum column size is *max_col*.

ADT OF SPARSE MATRIX (CONT'D)

Sparse_Matrix **Transpose**(a) ::=

return the matrix produced by interchanging the row and column value of every triple.

Sparse_Matrix **Add**(a, b) ::=

if the dimensions of a and b are the same
return the matrix produced by adding corresponding items, namely those with identical row and column values.

else return error

Sparse_Matrix **Multiply**(a, b) ::=

if number of columns in a equals number of rows in b

return the matrix d produced by multiplying a by b according to the formula: $d[i][j] = \sum (a[i][k] \cdot b[k][j])$ where d (i, j) is the (i,j)th element

else return error.

會先把同一個row存完

	row col value				row col value			
		# of rows	(columns)			# of nonzero terms		
a[0]	6	6	8		b[0]	6	6	8
[1]	0	0	15		[1]	0	0	15
[2]	0	3	22		[2]	0	4	91
[3]	0	5	-15		[3]			
[4]	1	1	11	transpose →	[4]			
[5]	1	2	3		[5]			
[6]	2	3	-6		[6]			
[7]	4	0	91		[7]			
[8]	5	2	28		[8]			
	(a)				(b)			

row, column in ascending order

***Figure 2.4:** Sparse matrix and its transpose stored as triples (p.69)

Sparse_matrix Create(max_row, max_col) ::=

```
#define MAX_TERMS 101 /* maximum number of terms +1*/
typedef struct {
    int col;
    int row;
    int value;
} term;
term a[MAX_TERMS]
```

↑
of rows (columns)
of nonzero terms

TRANSPOSE A MATRIX

要思考他的動作什麼規律？有規律才能用程式實作出來

(1) For each **row** i

- take element $\langle i, j, \text{value} \rangle$ and
- store it in element $\langle j, i, \text{value} \rangle$ of the transpose.

difficulty: where to put $\langle j, i, \text{value} \rangle$

$(0, 0, 15) \rightarrow (0, 0, 15)$

$(0, 3, 22) \rightarrow (3, 0, 22)$

$(0, 5, -15) \rightarrow (5, 0, -15)$

$(1, 1, 11) \rightarrow (1, 1, 11)$

Move elements down very often.

(2) For all elements in **column** j ,

- place element $\langle i, j, \text{value} \rangle$ in element $\langle j, i, \text{value} \rangle$

term a是原本的矩陣，team b 是轉換過後矩陣

```
void transpose (term a[], term b[])
/* b is set to the transpose of a */
{
    int n, i, j, currentb;
    n = a[0].value; /* total number of elements */
    b[0].row = a[0].col; /* rows in b = columns in a */
    b[0].col = a[0].row; /* columns in b = rows in a */
    b[0].value = n;
    if (n > 0) { /*non zero matrix */
        currentb = 1;
        for (i = 0; i < a[0].col; i++) 針對 columns 去做操作
            /* transpose by columns in a */
            for (j = 1; j <= n; j++)
                /* find elements from the current column */
                if (a[j].col == i) {
                    /* element is in current column, add it to b */
```

columns

elements

```
b[currentb].row = a[j].col;
b[currentb].col = a[j].row;
b[currentb].value = a[j].value;
currentb++
```

}

}

}

*** Program 2.7:** Transpose of a sparse matrix (p.71)

兩層迴圈，所以 $O(\text{columns} * \text{element的數量})$

Scan the array “#columns” times.
The array has “#elements” elements. $\Rightarrow O(\text{columns} * \text{elements})$

COMPARE WITH 2-DIMENSIONAL ARRAY REPRESENTATION

- Discussion: compared with 2-D array representation

- $O(\text{columns} \times \text{elements})$ versus $O(\text{columns} \times \text{rows})$
- elements \rightarrow columns \times rows when non-sparse
- $\rightarrow O(\text{columns}^2 \times \text{rows})$ when non-sparse

如果今天的矩陣不是這麼稀疏 (sparse matrix) ，就不能用這個方法，不然時間複雜度會變成 $O(\text{columns}^2 * \text{rows})$

- Problem: Scan the array “#columns” times.

- Solution:

- Determine the number of elements in each column of the original matrix.
- Determine the starting positions of each row in the transpose matrix.

a[0]	6	6	8
a[1]	0	0	15
a[2]	0	3	22
a[3]	0	5	-15
a[4]	1	1	11
a[5]	1	2	3
a[6]	2	3	-6
a[7]	4	0	91
a[8]	5	2	28

INDEX	[0]	[1]	[2]	[3]	[4]	[5]
ROW_TERMS =	2	1	2	2	0	1
STARTING_POS =	1					

FAST MATRIX TRANSPOSING

- Store some information to avoid scanning all terms back and forth
- **FastTranspose** requires more space than **Transpose**
 - RowSize
 - RowStart

FAST MATRIX TRANSPOSING (CONT'D)

```

void fast_transpose(term a[ ], term b[ ])
{
    /* the transpose of a is placed in b */
    int row_terms[MAX_COL], starting_pos[MAX_COL];
    int i, j, num_cols = a[0].col, num_terms = a[0].value;
    b[0].row = num_cols; b[0].col = a[0].row;
    b[0].value = num_terms;
    if (num_terms > 0){ /*nonzero matrix*/
        columns [ for (i = 0; i < num_cols; i++)
                  row_terms[i] = 0;
        elements [ for (i = 1; i <= num_terms; i++)
                  row_term [a[i].col]++
                  starting_pos[0] = 1;
        columns [ for (i = 1; i < num_cols; i++)
                  starting_pos[i]=starting_pos[i-1] +row_terms [i-1];

```



```

elements {
    for (i=1; i <= num_terms, i++) {
        j = starting_pos[a[i].col]++;
        b[j].row = a[i].col;
        b[j].col = a[i].row;
        b[j].value = a[i].value;
    }
}

```

***Program 2.8:** Fast transpose of a sparse matrix

Compared with 2-D array representation

$O(\text{columns} + \text{elements})$ vs. $O(\text{columns} * \text{rows})$

elements \rightarrow columns * rows

$O(\text{columns} + \text{elements}) \rightarrow O(\text{columns} * \text{rows})$

Cost: Additional row_terms and starting_pos arrays are required.

Let the two arrays row_terms and starting_pos be shared.

MATRIX MULTIPLICATION

- Definition: Given A and B, where A is $m \times n$ and B is $n \times p$, the product matrix Result has dimension $m \times p$. Its $[i][j]$ element is

$$result_{ij} = \sum_{k=0}^{n-1} a_{ik} b_{kj}$$

for $0 \leq i < m$ and $0 \leq j < p$

REPRESENTATION OF ARRAYS

- Multidimensional arrays are usually implemented by one dimensional array via either **row major order** or **column major order**.
- Example: One dimensional array

a	a+1	a+2	a+3	a+4
A[0]	A[1]	A[2]	A[3]	A[4]

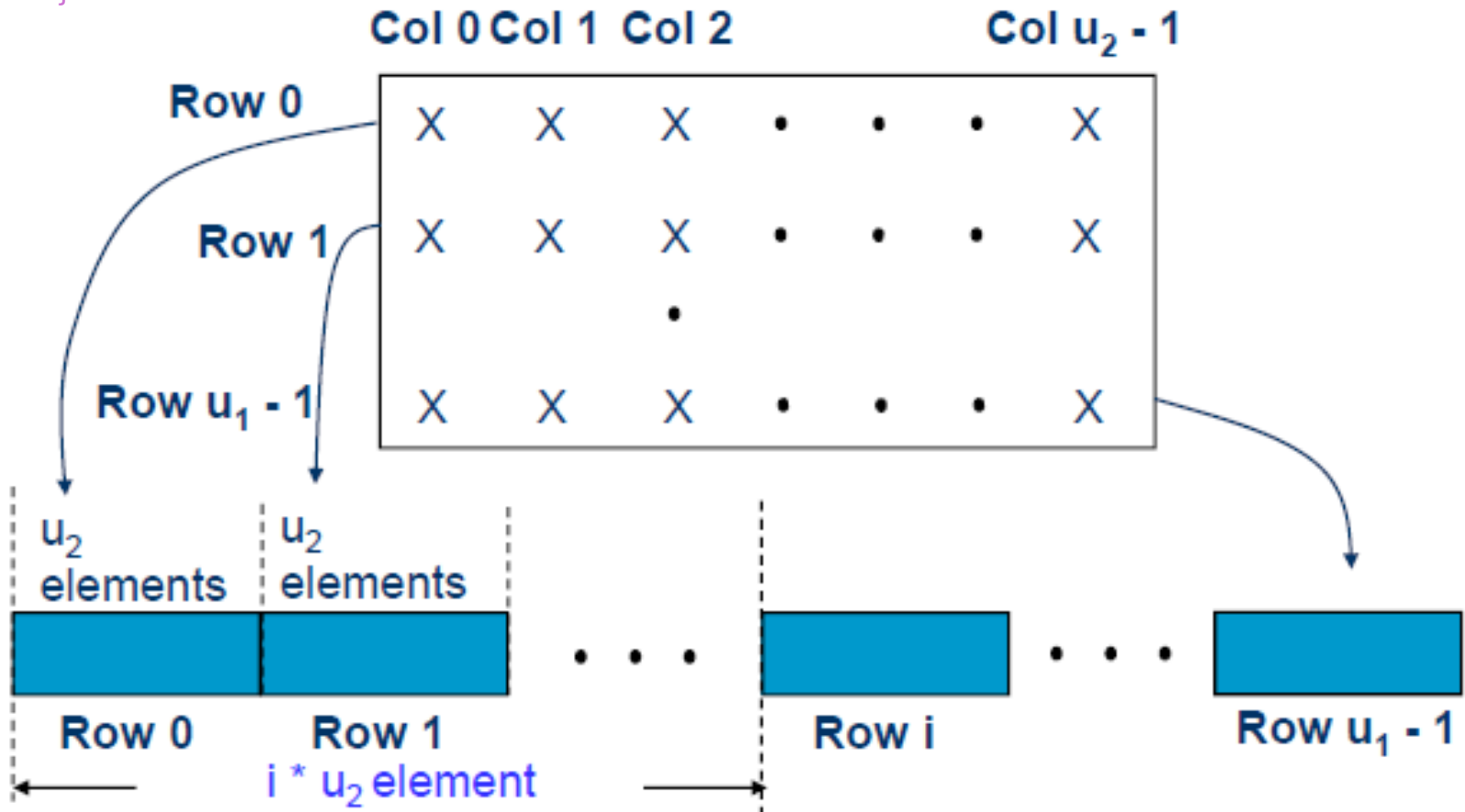
— row —

column

TWO DIMENSIONAL ARRAY - ROW MAJOR ORDER

two dimensional array存放方式有兩種：

1. row major order
- 2.



之後的內容不考

GENERALIZING ARRAY REPRESENTATION

- The address indexing of Array $A[i_1], [i_2], \dots, [i_n]$ is

$$\begin{aligned}
 & \alpha + i_1 u_2 u_3 \dots u_n \\
 & \quad + i_2 u_3 u_4 \dots u_n \\
 & \quad + i_3 u_4 u_5 \dots u_n \\
 & \quad \cdot \\
 & \quad \cdot \\
 & \quad \cdot \\
 & \quad + i_{n-1} u_n \\
 & \quad + i_n
 \end{aligned}$$

$$= \alpha + \sum_{j=1}^n i_j a_j, \text{ where } \begin{cases} a_j = \prod_{k=j+1}^n u_k, 1 \leq j \leq n \\ a_n = 1 \end{cases}$$

STRING

- Usually string is represented as a character array.
- General string operations include comparison, string concatenation, copy, insertion, string matching, printing, etc.

Note: '\0' is a null character, which is used to represent the end of a string.

H	e	l	l	o		W	o	r	l	d	\0
---	---	---	---	---	--	---	---	---	---	---	----

- [illegible]

KMP ALGORITHM

- KMP Algorithm
 - Proposed by Knuth, Morris and Pratt
- Concept
 - Use the characteristic of the pattern string
- Phase 1:
 - Generate an array to indicate the moving direction
- Phase 2:
 - Use the array to move and match string

THE FIRST CASE FOR THE KMP ALGORITHM

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	T	C	A	C	A	T	T	A	G	T	A	A	A	A

P:	A	G	C	G	C
	0	1	2	3	4

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	T	C	A	C	A	T	T	A	G	T	A	A	A	A

P:	A	G	C	G	C
	0	1	2	3	4

THE SECOND CASE FOR THE KMP ALGORITHM

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	G	C	T	C	A	T	T	A	G	T	A	A	A	A

P:	A	G	C	C	T	A	C
	0	1	2	3	4		

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	G	C	T	C	A	T	T	A	G	T	A	A	A	A

P:	A	G	C	C	T	A	C
	0	1	2	3	4		

THE THIRD CASE FOR THE KMP ALGORITHM

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	G	G	T	C	A	T	T	A	G	T	A	A	A	A

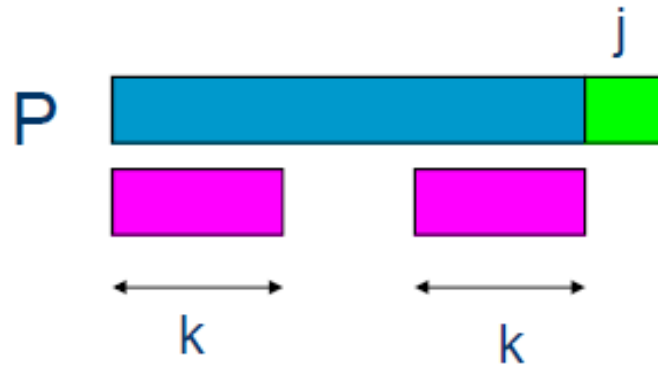
P:	A	G	C	C	T	A	G	C	A	G	G	C
	0	1	2	3	4							

	0	1	2	3	4	5	6	7	8	9	...									
T:	A	G	C	C	T	A	G	G	T	C	A	T	T	A	G	T	A	A	A	A

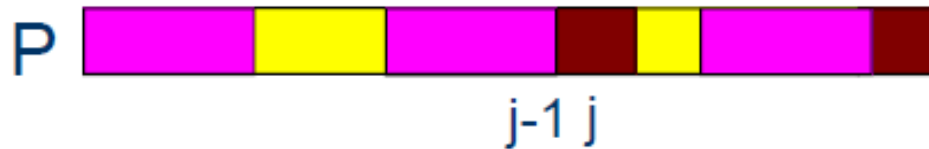
P:	A	G	C	C	T	A	G	C	A	G	G	C
	0	1	2	3	4							

KMP ALGORITHM (CONT'D)

Failure Function



Action



KMP ALGORITHM (CONT'D)

- Definition:

- If $p = p_0p_1 \dots p_{n-1}$ is a pattern, then its failure function, f , is defined as

$$f(j) = \begin{cases} \text{largest } k < j \text{ such that } p_0p_1 \dots p_k = p_{j-k}p_{j-k+1} \dots p_j, \text{ if such a } k \geq 0 \text{ exists} \\ -1, & \text{otherwise} \end{cases}$$

- If a partial match is found such that $s_{i-j} \dots s_{i-1} = p_0p_1 \dots p_{j-1}$ and $s_i \neq p_j$ then matching may be resumed by comparing s_i and $p_{f(j-1)+1}$ if $j \neq 0$. if $j = 0$, then we may continue by comparing s_{i+1} and p_0 .

FAST MATCHING EXAMPLE: FAILURE FUNCTION CALCULATION

- *The largest k such that*
 1. $k < j$
 2. $K \geq 0$
 3. $p_0 p_1 \dots p_k = p_{j-k} p_{j-k+1} \dots p_j$
- $j = 0$
 - Since $k < 0$ and $k \geq 0 \rightarrow$ no such k exists.
 - $f(0) = -1$
- $j = 1$
 - Since $k < 1$ and $k \geq 0$, k may be 0.
 - When $k = 0$, $p_0 = a$, and $p_1 = b \rightarrow \text{X}$
 - $f(1) = -1$

j	0	1	2	3	4	5	6	7	8	9
p	a	b	c	a	b	c	a	c	a	B
f	-1	-1								

FAST MATCHING EXAMPLE: FAILURE FUNCTION CALCULATION (CONT'D)

- $j = 2$
 - Since $k < 2$ and $k \geq 0$, k may be 0, 1.
 - When $k = 1$, $p_0p_1 = ab$, and $p_1p_2 = bc \rightarrow \times$
 - When $k = 0$, $p_0 = a$, and $p_2 = c \rightarrow \times$
 - $f(2) = -1$
- $j = 3$
 -
 -
 -
 -
 - $f(3) = 0$

j	0	1	2	3	4	5	6	7	8	9
p	a	b	c	a	b	c	a	c	a	B
f	-1	-1	-1	0						

FAST MATCHING EXAMPLE: FAILURE FUNCTION CALCULATION (CONT'D)

- $j = 4$
 - Since $k < 4$ and $k \geq 0$, k may be 0, 1, 2, 3.
 - When $k = 3$, $p_0p_1p_2p_3 = abca$, and $p_1p_2p_3p_4 = bcab \rightarrow \text{x}$
 - When $k = 2$, $p_0p_1p_2 = abc$, and $p_2p_3p_4 = cab \rightarrow \text{x}$
 - When $k = 1$, $p_0p_1 = ab$, and $p_3p_4 = ab \rightarrow \text{ok!}$
 - When $k = 0$, $p_0 = a$, and $p_4 = b \rightarrow \text{x}$
 - $f(4) = 1$

j	0	1	2	3	4	5	6	7	8	9
p	a	b	c	a	b	c	a	c	a	b
f	-1	-1	-1	0	1	2	3	-1	0	1

FAST MATCHING EXAMPLE: FAILURE FUNCTION CALCULATION (CONT'D)

- A restatement of failure function

$$f(j) = \begin{cases} -1, & \text{if } j = 0 \\ f^m(j-1) + 1, & \text{where } m \text{ is the least integer } k \text{ for which } P_{f^k(j-1)+1} = P_j \\ -1, & \text{if there is no } k \text{ satisfying the above} \end{cases}$$

- $f^1(j) = f(j)$ and $f^m(j) = f^m(f^{m-1}(j))$

FAST MATCHING EXAMPLE: STRING MATCHING

j	0	1	2	3	4	5	6	7	8	9
p	a	b	c	a	b	c	a	c	a	B
f	-1	-1	-1	0	1	2	3	-1	0	1

$S =$ a b c a ? ? ? ? ? ?
 $P =$ a b c a b c a c a b

2: check failure function f (posP-1)

1: fail at posP = 4

3: move pattern accordingly

a b c a b c a c a b

$\text{posP} = \text{pat.f}[\text{posP}-1] + 1$

THE ANALYSIS OF THE KMP ALGORITHM

- $O(m+n)$
 - $O(m)$ for computing function f
 - $O(n)$ for searching P