Paper Publication

| Mentor Name | Domain/Category | Project Title | Project Abstract/PS Description |
|---------------------------|-----------------|---|---|
| Dr. Kishorebabu Dasari | Cyber Security | Al-Powered Intrusion Detection System (IDS) | Description: Develop an intelligent IDS that uses machine learning/deep learning to monitor network traffic and detect malicious activities in real time. Objectives: Detect DoS, DDoS, brute force, port scans, and zero-day attacks. Improve detection accuracy and reduce false positives using ensemble or deep models. |
| | | Al for Malware Analysis and Classification | Description: Classify malware samples based on behavior or static features using deep learning, enabling faster threat detection in antivirus systems. Objectives: Automate malware family classification. Use opcode, bytecode, or behavior logs for feature extraction. |
| | | Phishing and Spam Detection with NLP | Description: Use NLP models to detect phishing and spam messages in emails, SMS, and chats by analyzing content, intent, and structure. Objectives: Build real-time phishing detection system. |
| | | Quantum Machine Learning for Threat Detection | Use transformers (like BERT) for better contextual understanding. Description: Apply quantum machine learning (QML) techniques like variational classifiers to detect cyber threats in network logs or malware behavior. Objectives: Simulate quantum-enhanced models for security classification. |
| | Aggriculture | Al-Powered Crop Disease and Pest Detection | Description: Use image classification to detect plant diseases or pests from leaf images or field drone footage, helping farmers act early. Objectives: Classify diseases (e.g., rust, blight) using CNNs. Integrate with smartphone app for field usability |
| | | Al-Powered Weed Detection System | Description: Identify weeds in agricultural fields using deep learning-based object detection (e.g., YOLO) and image segmentation (e.g., U-Net). Objectives: Detect weed locations for precision pesticide application. Deploy model on drones or field robots. |