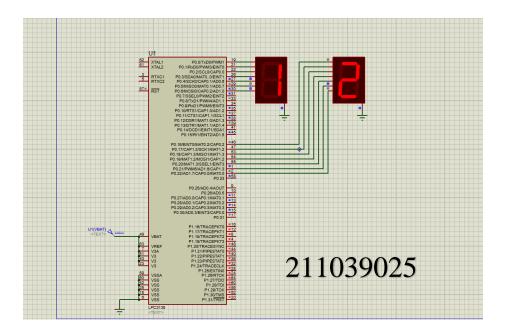
```
//2. Implement using Proteus and Keil, for the following: (15 marks) Implement a 00-99 counter(up
counter) using two 7 segment display.
#include < lpc214x.h>
#define SIZE 10
int d1[SIZE]={0x3F, 0x06, 0x5B, 0x4F, 0x66, 0x6D, 0x7D, 0x07, 0x7F, 0x6F};
int d2[SIZE]={0x003F0000, 0x00060000, 0x005B0000, 0x004F0000, 0x00660000, 0x006D0000,
0x007D0000, 0x00070000, 0x007F0000, 0x006F0000};
void pll();
void msecdelay(int x);
int main(void)
{
        int i = 0, j = 0;
                                       // Cong POL as GPIO
        PINSEL0 = 0x000000000;
        PINSEL1 = 0x000000000;
                                       // Cong POH as GPIO
        IOODIR = 0x00FF00FF;
                                               // P0.0 to P0.6 D2 and P0.16 to P0.22 D1
       while(1)
       {
                       for(i=0;i<SIZE;i++)
                       {
                               IOOSET = d1[i];
                               for(j=0; j<SIZE; j++)
                                {
                                               IOOPIN = (d1[i] | d2[j]);
                                               msecdelay(20);
                                               IOOPIN = (d1[i] \& 0x00FF0000);
                               }
                       }
```

```
}
       return 0;
}
void pll()
{
       PLLOCON = 0x01;
                                           //PLL Enable
       PLLOCFG = 0x24;
                                                  //F-osc=12Mhz,CCLK=60Mhz,PCLK=60MHz
==> Calculated M = 5 (Value to be loaded 4) and P = 2.5 (Value to be loaded 2)
       PLLOFEED = 0xAA;
       PLLOFEED = 0x55;
       while(!(PLLOSTAT&(1<<10))); // Wait till PLL gets lock
       PLLOCON = 0x03;
                                                  // PLL EN and Connect
       PLLOFEED = 0xAA;
       PLLOFEED = 0x55;
       VPBDIV = 0x01; // PCLK = CCLK
}
void msecdelay(int x)
{
  TOCTCR=0x0;
                              //Select Timer Mode
                     //Timer off
  TOTCR=0x00;
  TOPR=59999;
                      //Prescaler value for 1ms
                      //Timer reset
  TOTCR=0x02;
                      //Timer ON
  TOTCR=0x01;
  while(T0TC < x);
                     //Timer OFF
  T0TCR=0x00;
```

TOTC=0; //Clear the TC value. This is Optional.

}



//1. Connect two switches (SW1 and SW2) and two LED. On press of first switch SW1, the led 1 should on and off with a delay of 1 sec and other switch SW2, LED2 should be on and off at 500 ms. #include<lpc214x.h> void delay(unsigned int z); void pll(); int main(void) { IOODIR=0xfffffff; IO1DIR = 0x0;pll(); while(1) { if((IO1PIN & (1<<16)) ==0) { IO0SET=0x000000ff; delay(1000); IOOCLR=0x000000ff; delay(1000); } if((IO1PIN & (1<<17)) ==0) { IO0SET=0x0000ff00; delay(500); //500msec delay IOOCLR=0x0000ff00; delay(500); } void pll() { PLLOCON=0x01; PLLOCFG=0x24;

```
PLLOFEED=0xaa;
  PLLOFEED=0x55;
  while(!(PLLOSTAT&(1<<10)));
  PLL0CON=0x03;
  PLLOFEED=0xaa;
  PLLOFEED=0x55;
  VPBDIV=0x01;
}
void delay(unsigned int z)
{
  TOCTCR=0x0;
                              //Select Timer Mode
  T0TCR=0x00;
                      //Timer off
  TOPR=59999;
                      //Prescaler value for 1ms
  T0TCR=0x02;
                      //Timer reset
  T0TCR=0x01;
                      //Timer ON
  while(T0TC<z);
  TOTCR=0x00;
                      //Timer OFF
  TOTC=0;
                    //Clear the TC value. This is Optional.
}
```

