

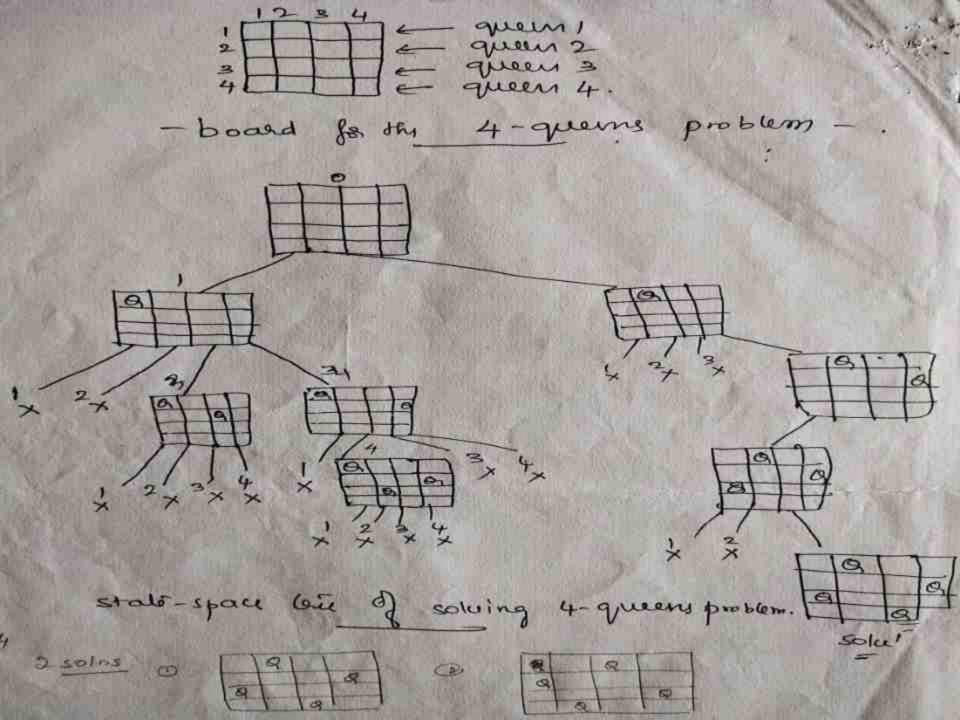
## **Design and Analysis of Algorithms**

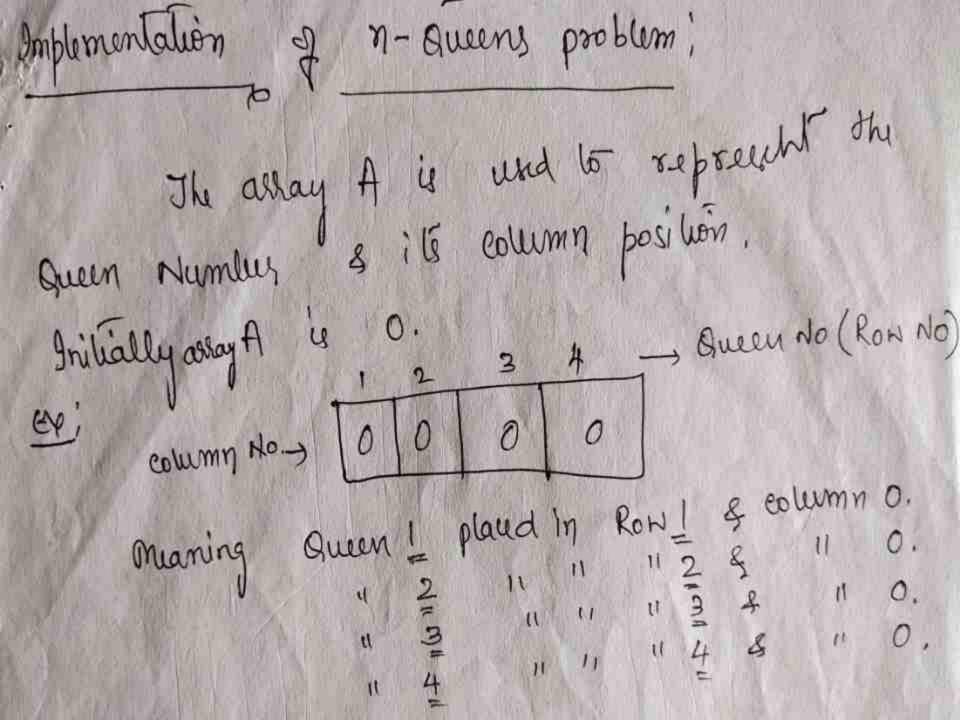
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# BACKTRACKING

Back Tracking. - The main idea behind backtracking is to construct solutions one component at a time and evaluate such partially constructed candidates. - If a partially constructed solution can be developed further without violating the problem's constraint, it is done by taking the first remaining ligitimate option component, no allinatives for any rumaining component nud to be considered. In this case, the algorithm backbacks to seplace the last component of the partially constructed solution with its next option. n-Queens Problem! The problem is to place or queens on an n-by-n (nxn) chessboard so that no two queens attack each other by being in the same row on the same column of on the same diagonal. n=1 -> trivial solm. n=2,3 -> No solm. n=4 Here is a solution. Note; The state-space but for 4-quely problem given below:





main() of int n head on. if (n <= 3 && n > 1)

print No solution.

else nqueen (n); void nqueen (int n) ENT K = 1; 11 Queen 1, in RON 1.

int e, count = 0;

int A[K] = 0; 11 Queen 1 in RON 1, Column 0. while (Kb=0) 11 back hack hack (11 K==1. A[K] = A[K]+1; 1) Queen K, in next column. While (A(K) (= n & f (place (K) = = 0)) 3 H(x) ++;

ef (A[h] <= n) ef(k==n)printf ("soln No Y,d In", ++ count) fs (i=1: i <= n: i++) print ("rid Queen & placed on") ; ((137A , 5, 3 8 K++;
8[K)=0;

Subset- Sum Problem! - Find a subset of a given set \$=qs1,.... Sn3

of n position integers whom sum is equal to a

given the integer d. Example: \$= \$1,215,6183, and d=9. There are 2 solutions: 4 1,2,63 & & 1,83. - Some instantis of this problem may solution. .... in including odes

Stati-space but for the problem S= & 3,5,6,7}, and d=15 is given below; with 3 (0)---> total sum. WITH 5 (3) HIO 5шім в В 1106 мім в 1106 мім в 1106 от 13 СІГ 4 мім в 1106 мім в 1106 от 13 СІГ 14+7715 ПО В 11+7715 В 1 Subset W -> ser of elements initially all o, indialisely elements are added to the soln is added, essesponding x[1°] is

```
int n, x[20], N[20], count=0, d;
main ()
   Read no. of elementé n.
  る (= 1) i と= かりi++)
   Enles elements in ascending sides.
Jes (i= 1: i<=n; i++)
        X[0]=0;
         -scanf ("y,d", & N(10));
   ENES the sum.
          -scang ("v.d", &d);
    -sum = 0
    傷(i=1; i(=カ·, i++)
             : ( o) ju + mus = mus-
     ef (sum < d) "No solution
     else
           Subset Sum (0, 1, sum);
```

2 Remaining Sum subsetsum (int &, int k, int Void ' milled Sum sofas interdilem No. X[K] = I;it (2+ H[K) == 9) eount++; 88 (i=1; ic=K; i++) if (x[c) = = 1) i (Eila 'n +4/4") Ariad EF (3+ W[K]+ W[K+1] <= d) SUB Set Sum (8+ WEB), K+1, -6- WEED); Et ((8+(8- MEX)))>== d && (-8+MEX+1)) 43 2- M[13]); subsetsum (18, 141,



8) Roshan Feenaudy. Branch - and - Bound. Compared to backleracking, branch- and-bound highing two additional Elems: A way to provide, for every node of a state-space bue, a bound on the beet value of the objective function, on any solution that can du oblained by adding further components to the partial solution represented by the node. value of the best solution seen so far \* This bound should be a lower bound for a minimization problem. and an upper bound for a maximization problem. un leximinale a seasch path at the energy node in a state-space lete of a branch-and bound algorithm for any one of the following 3 reasons: than the value of the nodi's bound is not better, . The node represents no feasible solution because the constraints of the problem is an completely violated. The Rubert of feasible Rollhoire Represented of the node consists of a single point & hence no fuestile ahoises can be made.

Assignment Broblem!	Sobl Sob2 Sob3 Soby. Г9 2 7 8	Person a
PROPERTY OF THE PARTY OF THE PA	5061 5062 5063 5064. 5061 5062 5063 5064. 5061 2 7 8 7 8 7 8 7 8 7 8 9 4	
· Calculate the	lower bound.	so the optimal, soly
· Lower bour	each RON.	10

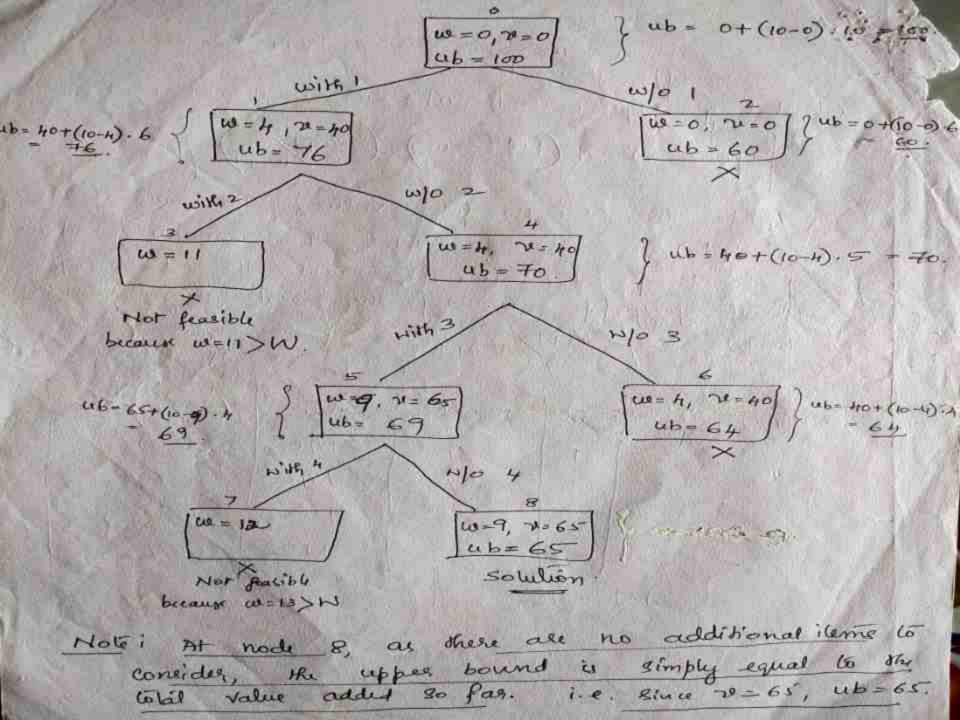
i.e.

example observe that min, value Noti; In the about 3 & 1 are from same column which laken is not permitted for solving the assignment problem Bur 15 calculate bound, it is fine. stast 2b= 2+3+1+4=10 0=4 a=2 16=8+3+1+6=M 26=9+3+1+4=17 Rb = 2+3+1+4=10 b=1 2b=2+6+1+4=13 2 a→2 fixed. c=4 16=2+6+1+4=13 } b = 1 fixed. 186=2+6+8+9=25 pesson a - Job 2 7 an 2 fixed. , b-> 1 fixed. pegson by Job1 16=2+6+1+4=13 person c - Jobs C +3 & xed. - oplimal solution pesson d - Job 4



Knapsack Problem; so calculate the - is a maximization problem upper bound. alculating upper bound (ub) to knapsack problem; ub = 2 + (W - w) · (Ve+1/we+1) Add to re (the total value of the items already selected), the product of the remaining eapacity of the knapsack W-w and the best per unit payoff among the remaining items, is 21+1/wi+1 which

Z. ROWN III MANY ZERO		LV-SHARRA COMM	No. of the second	THE RESERVE OF STREET	
Example;	Clim	weight	Value	Yalus/weight	
	1	11	\$40	10	40/4
	2	5/	\$42	6	42/7
	3	5	\$25	5	28/5
	1	3	\$12	4	12/3
	W = 10.		calculate this		
		This will be the pooble	m.	eolumn	

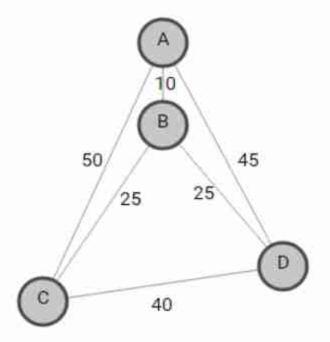


### **Traveling Salesman Problem**



Given a set of cities and the distance between every pair of cities, the problem is to find the shortest possible route that visits every city exactly once and returns to the starting point.

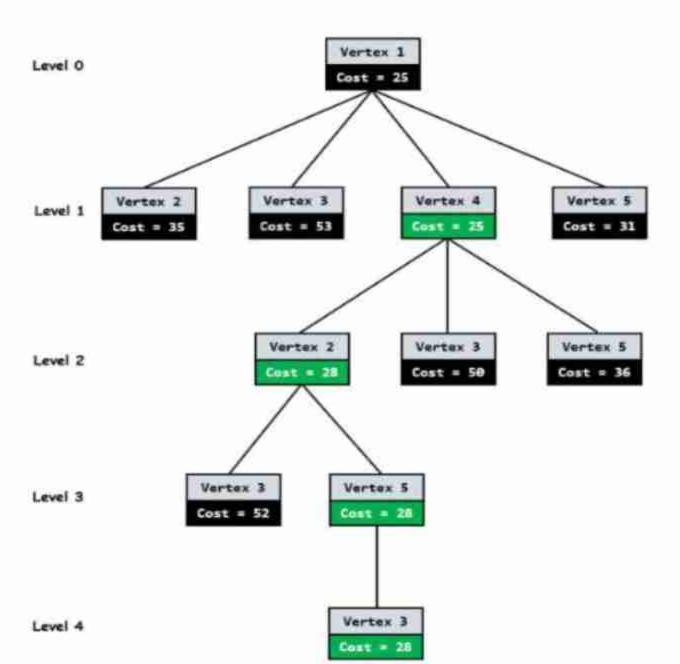
For example, consider the following graph. A TSP tour in the graph is  $A \rightarrow B \rightarrow C \rightarrow D \rightarrow B \rightarrow A$ . The cost of the tour is 10 + 25 + 40 + 25 + 10 = 100.



For example, consider the following cost matrix M,

```
C1 C2 C3 C4
   CO
   INF
        20 30
               10 11
   15
       INF
           16
C1
C2
        5 INF
C3
   19
        6 18 INF
C4 16
              16 INF
         7
```

Following is the state-space tree for the above TSP problem, which shows the optimal solution marked in green:





Now, how do we calculate the lower bound of the path starting at any node?

In general, to get the lower bound of the path starting from the node, we reduce each row and column so that there must be at least one zero in each row and Column. We need to reduce the minimum value from each element in each row and column.

#### Let's start from the root node.

We reduce the minimum value in each row from each element in that row. The minimum in each row of cost matrix M is marked by blue [10 2 2 3 4] below.

```
INF 20 30 10 11
15 INF 16 4 2
3 5 INF 2 4
19 6 18 INF 3
16 4 7 16 INF
```

After reducing the row, we get the below reduced matrix.

```
INF 10 20 0 1
13 INF 14 2 0
1 3 INF 0 2
16 3 15 INF 0
12 0 3 12 INF
```

We then reduce the minimum value in each column from each element in that column. Minimum in each column is marked by blue [1 0 3 0 0]. After reducing the column, we get below the reduced matrix. This matrix will be further processed by child nodes of the root node to calculate their lower bound.

```
INF 10 17 0 1
12 INF 11 2 0
0 3 INF 0 2
15 3 12 INF 0
11 0 0 12 INF
```

The total expected cost at the root node is the sum of all reductions.

Since we have discovered the root node C0, the next node to be expanded can be any node from C1, C2, C3, C4. Whichever node has a minimum cost will be expanded further. So, we have to find out the expanding cost of each node.

The parent node CO has below reduced matrix:

```
INF 10 17 0 1
12 INF 11 2 0
0 3 INF 0 2
15 3 12 INF 0
11 0 0 12 INF
```

#### Let's consider an edge from 0 -> 1.

 As we add an edge (0, 1) to our search space, set outgoing edges for city 0 to INFINITY and all incoming edges to city 1 to INFINITY. We also set (1, 0) to INFINITY.

So in a reduced matrix of the parent node, change all the elements in row 0 and column 1 and at index (1, 0) to INFINITY (marked in red).

```
INF 10 17 0 1
12 INF 11 2 0
0 3 INF 0 2
15 3 12 INF 0
11 0 0 12 INF
```

The resulting cost matrix is:

2. We try to calculate the lower bound of the path starting at node 1 using the above resulting cost matrix. The lower bound is 0 as the matrix is already in reduced form, i.e., all rows and all columns have zero value.

Therefore, for node 1, the cost will be:

Cost = cost of node 
$$0 + \cos \theta$$
 cost of the edge $(0, 1) + \cos \theta$  lower bound of the path starting at node  $1 = 25 + 10 + 0 = 35$ 

#### Let's consider an edge from 0 -> 2

1. Change all the elements in row 0 and column 2 and at index (2, 0) to INFINITY (marked in red).

```
INF 10 17 0 1
12 INF 11 2 0
0 3 INF 0 2
15 3 12 INF 0
11 0 0 12 INF
```

The resulting cost matrix is:

```
INF INF INF INF INF
12 INF INF 2 0
INF 3 INF 0 2
15 3 INF INF 0
11 0 INF 12 INF
```

Now calculate the lower bound of the path starting at node 2 using the approach discussed earlier. The resultant matrix will be:

```
INF INF INF INF INF
1 INF INF 2 0
INF 3 INF 0 2
4 3 INF INF 0
0 0 INF 12 INF
```

Therefore, for node 2, the cost will be

```
Cost = cost of node 0 +

cost of the edge(0, 2) +

lower bound of the path starting at node 2

= 25 + 17 + 11 = 53
```

#### Let's consider an edge from 0 -> 3.

1. Change all the elements in row 0 and column 3 and at index (3, 0) to INFINITY (marked in red).

```
INF 10 17 0 1
12 INF 11 2 0
0 3 INF 0 2
15 3 12 INF 0
11 0 0 12 INF
```

The resulting cost matrix is:

```
INF INF INF INF INF
12 INF 11 INF 0
0 3 INF INF 2
INF 3 12 INF 0
11 0 0 INF INF
```

2. Now calculate the lower bound of the path starting at node 3 using the approach discussed earlier. The lower bound of the path starting at node 3 is 0 as it is already in reduced form, i.e., all rows and all columns have zero value.

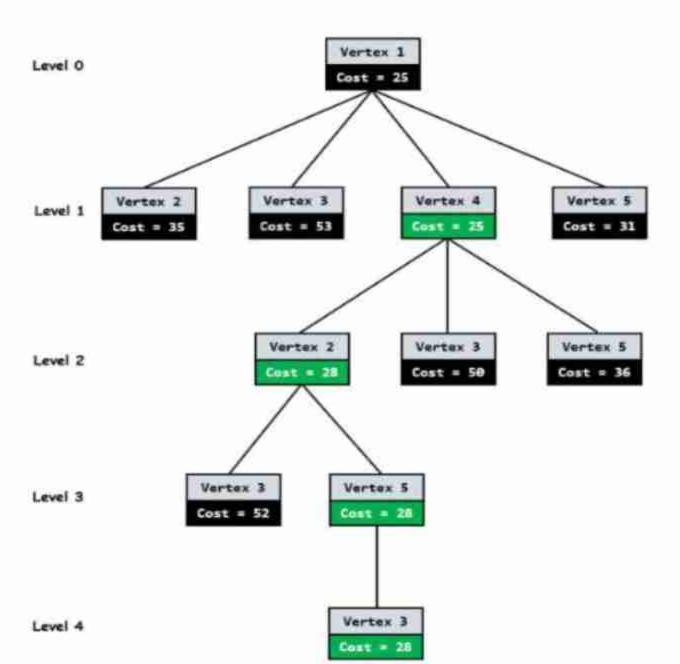
Therefore, for node 3, the cost will be

Cost = cost of node 
$$0 + \cos \theta$$
 cost of the edge( $0$ ,  $3$ ) +

lower bound of the path starting at node  $3 = 25 + 0 + 0 = 25$ 

Similarly, we calculate the cost of  $0 \rightarrow 4$ . Its cost will be 31.

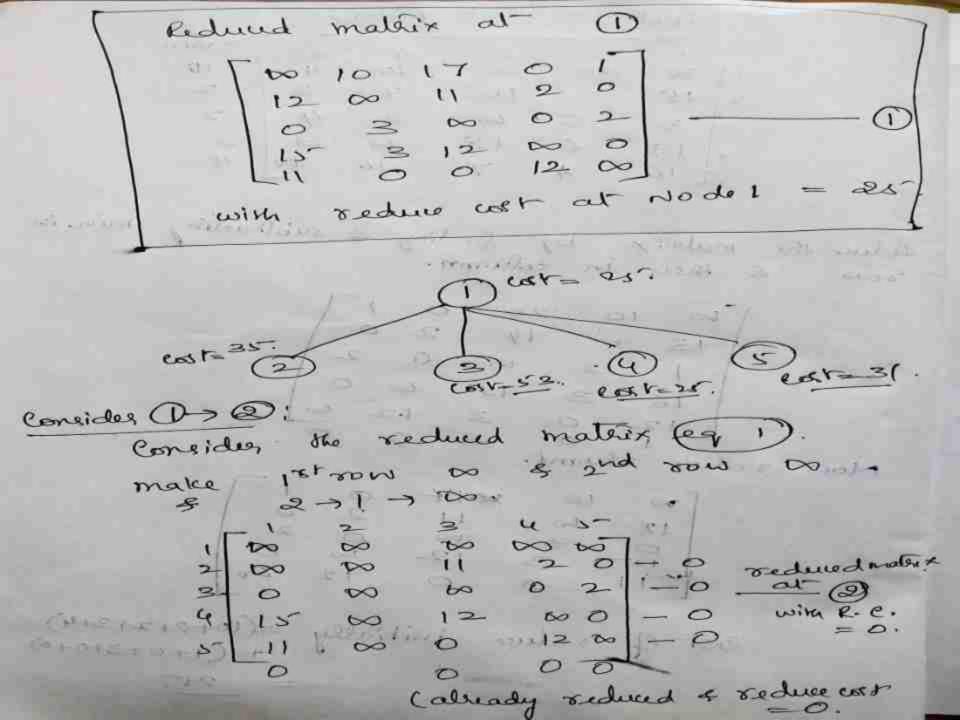
Following is the state-space tree for the above TSP problem, which shows the optimal solution marked in green:



Now find a live node with the least estimated cost. Live nodes 1, 2, 3, and 4 have costs 35, 53, 25, and 31, respectively. The minimum among them is node 3, having cost 25. So, node 3 will be expanded further, as shown in the state-space tree diagram. After adding its children to the list of live nodes, find a live node with the least cost and expand it. Continue the search till a leaf is encountered in the space search tree. If a leaf is encountered, then the tour is completed, and we will return to the root node.

CEST Malou x min. 11 0 20 30 . 10 11 7 15 00 16 4 4 19 6 18 6 Reduce the materix by finding & subtracting min in & they in column. 13 to 20 0 1 13 to 14 2 0 1 3 to 0 2 16 3 15 60 0 12 10 13100 Now reduce esums. w 10 molt 0 cost of reduce initially = (10+2+2+2+4)

mitial



extat 2 Tedus cost at at at (1,2) + reduce cost of @ we plu a la 25+10+0=35 Consider 1 > 3. make row 1 to 5 cd 3 00 (1) rielam 20 · 000 -3-31 3 00 3 00 12 60 - 0 CONTE OHI = 11. 100 11 0 4 (3) yestern Reduce it Reduced malaux 3 60 0 2 1 with R.C. = 11. 30 00 CBY at 1-> 3. = 25+17+11=53.

Consider 1 -> 4. F& materix 1 make sow1 & est4 > 00 8 4 ×1 08 00. maleix at wird r.c. = 0. eat at 4 = 25+0+0 = 25= Consider 1-5-\$ ed 500 For make row 1 = 00 11 -8 5-1/ as on 3 6 3 60 0 60 + 0 0 1200 + 000

with re- = 5 reduction cost = 5. 2471+5=3 2,3, 4,5 min 4 So consides the reduction materix of 4. 12 00

make Gothrow as Consides 4 >> 2. 2 to 1 as 00. and col. % & reduced (6)

with reces COST 1-14-2 = cost at 4 + c(4,2) + sed costate 25+3+0=28

Pod malce 8010 2 -> 60 Cd 3 -> 00 & 3 -1 -> 00 - 88 malaix 6). 2 00 00 00 ∞ reduction coll= 13. Cost = car al moderatex 2 + c(2,3) + rest 28+11+13 = 52.

TON 2 4 CB 5 00 8 5 05 1 20 6 gos maleix Grad



# Thank You!!!