

Assignment -4

Assignment Date	24 Oct 2022
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Maximum Marks	2 marks

Question:

Write a Code and Connections in wokwi for **ultrasonic sensor**. Whenever distance is less than 100 cms send “**alert**” to ibm cloud and display in device recent events

Code:

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT
WiFiClient wifiClient;
String data3;
#define ORG "g05aq3"
#define DEVICE_TYPE "selva"
#define DEVICE_ID "selva_assignment_4"
#define TOKEN "qwertyuio"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
```

```
char publishTopic[] = "iot-2/evt/selva/fmt/json";
char topic[] = "iot-2/cmd/status/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
```

```
const int trigpin=19;
const int echopin=18;
String command;
String data="";
```

```
long duration;
float dist;
```

```
void setup()
{
    Serial.begin(115200);
    pinMode(led, OUTPUT);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}
```

```
void loop()
{
```

```

bool isNearby = dist < 100;
digitalWrite(led, isNearby);

publishData();
delay(500);

if (!client.loop())
{
    mqttConnect();
}
}

void wifiConnect()
{
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED)
    {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect()
{
    if (!client.connected())
    {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token))
        {

```

```

        Serial.print(".");
        delay(500);
    }
    initManagedDevice();
    Serial.println();
}

}

void initManagedDevice() {
    if (client.subscribe(topic))
    {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    }
    else
    {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration=pulseIn(echopin, HIGH);
    dist=duration*speed/2;
    if(dist<100)
    {
        String payload = "{\"Alert Distance\":\"";
        payload += dist;
    }
}

```

```

payload += "}";

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))
{
    Serial.println("Publish OK");
}
}
if(dist>100){
String payload = "{\"Distance\":\"";
payload += dist;
payload += "}";

Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
    Serial.println("Publish OK");
}
Else
{
    Serial.println("Publish FAILED");
}

}

}

```