

Vectors, Matrices, Multidimensional Arrays

[NumPy Website](#)

Importing the Modules

```
In [59]: import numpy as np
```

The NumPy Array Object

```
In [ ]: np.ndarray?
```

Init signature: `np.ndarray(self, /, *args, **kwargs)`

Docstring:

`ndarray(shape, dtype=float, buffer=None, offset=0, strides=None, order=None)`

An array object represents a multidimensional, homogeneous array of fixed-size items. An associated data-type object describes the format of each element in the array (its byte-order, how many bytes it occupies in memory, whether it is an integer, a floating point number, or something else, etc.)

Arrays should be constructed using ``array``, ``zeros`` or ``empty`` (refer to the See Also section below). The parameters given here refer to a low-level method (``ndarray(...)``) for instantiating an array.

For more information, refer to the ``numpy`` module and examine the methods and attributes of an array.

Parameters

(for the `__new__` method; see Notes below)

`shape` : tuple of ints

Shape of created array.

`dtype` : data-type, optional

Any object that can be interpreted as a numpy data type.

`buffer` : object exposing buffer interface, optional

Used to fill the array with data.

`offset` : int, optional

Offset of array data in buffer.

`strides` : tuple of ints, optional

Strides of data in memory.

`order` : {'C', 'F'}, optional

Row-major (C-style) or column-major (Fortran-style) order.

Attributes

`T` : ndarray

Transpose of the array.

`data` : buffer

The array's elements, in memory.

`dtype` : dtype object
 Describes the format of the elements in the array.

`flags` : dict
 Dictionary containing information related to memory use, e.g.,
 'C_CONTIGUOUS', 'OWNDATA', 'WRITEABLE', etc.

`flat` : `numpy.flatiter` object
 Flattened version of the array as an iterator. The iterator
 allows assignments, e.g., ```x.flat = 3``` (See ``ndarray.flat`` for
 assignment examples; TODO).

`imag` : `ndarray`
 Imaginary part of the array.

`real` : `ndarray`
 Real part of the array.

`size` : int
 Number of elements in the array.

`itemsize` : int
 The memory use of each array element in bytes.

`nbytes` : int
 The total number of bytes required to store the array data,
 i.e., ```itemsize * size```.

`ndim` : int
 The array's number of dimensions.

`shape` : tuple of ints
 Shape of the array.

`strides` : tuple of ints
 The step-size required to move from one element to the next in
 memory. For example, a contiguous ```(3, 4)``` array of type
```int16``` in C-order has strides ```(8, 2)```. This implies that  
 to move from element to element in memory requires jumps of 2 bytes.  
 To move from row-to-row, one needs to jump 8 bytes at a time  
 (```2 * 4```).

`ctypes` : `ctypes` object  
 Class containing properties of the array needed for interaction  
 with `ctypes`.

`base` : `ndarray`  
 If the array is a view into another array, that array is its ``base``  
 (unless that array is also a view). The ``base`` array is where the  
 array data is actually stored.

#### See Also

-----

`array` : Construct an array.  
`zeros` : Create an array, each element of which is zero.  
`empty` : Create an array, but leave its allocated memory unchanged (i.e.,  
 it contains "garbage").  
`dtype` : Create a data-type.  
`numpy.typing.NDArray` : A :term:`generic <generic type>` version  
 of `ndarray`.

#### Notes

-----

There are two modes of creating an array using ```__new__```:

1. If ``buffer`` is `None`, then only ``shape``, ``dtype``, and ``order``  
are used.
2. If ``buffer`` is an object exposing the buffer interface, then  
all keywords are interpreted.

No ```__init__``` method is needed because the array is fully initialized  
after the ```__new__``` method.

## Examples

-----

These examples illustrate the low-level `ndarray` constructor. Refer to the `See Also` section above for easier ways of constructing an ndarray.

First mode, `buffer` is None:

```
>>> np.ndarray(shape=(2,2), dtype=float, order='F')
array([[0.0e+000, 0.0e+000], # random
 [nan, 2.5e-323]])
```

Second mode:

```
>>> np.ndarray((2,), buffer=np.array([1,2,3]),
... offset=np.int_().itemsize,
... dtype=int) # offset = 1*itemsize, i.e. skip first element
array([2, 3])
File: c:\miniconda3\lib\site-packages\numpy__init__.py
Type: type
Subclasses: chararray, recarray, memmap, matrix, MaskedArray
```

```
In []: data = np.array([[1, 2], [3, 4], [5, 6]]) # Matrix data
```

```
In []: type(data)
```

```
Out[]: numpy.ndarray
```

```
In []: data
```

```
Out[]: array([[1, 2],
 [3, 4],
 [5, 6]])
```

```
In []: data.ndim # data dimension --> or use np.ndim(data)
```

```
Out[]: 2
```

```
In []: data.shape # shape of data
```

```
Out[]: (3, 2)
```

```
In []: data.size # elements number
```

```
Out[]: 6
```

```
In []: data.dtype # each element's data type
```

```
Out[]: dtype('int32')
```

```
In []: data.nbytes # whole data's size in bytes
```

```
Out[]: 24
```

## Data Type

```
In []: # int -> int 8, 16, 32, 64
 # uint -> 8, 16, 32, 64
 # bool
 # float -> 16, 32, 64, 128
 # complex -> 64, 128, 256
```

```
In []: np.array([1, 2, 3], dtype = int)
```

```
Out[]: array([1, 2, 3])
```

```
In []: np.array([1, 2, 3], dtype = float)
```

```
Out[]: array([1., 2., 3.])
```

```
In []: np.array([1, 2, 3], dtype = complex)
```

```
Out[]: array([1.+0.j, 2.+0.j, 3.+0.j])
```

```
In []: data = np.array([1.0, 2.0, 3.0])
 print(data.dtype)
```

```
float64
```

```
In []: data = np.array([1, 2, 3], dtype = float)
```

```
In []: data
```

```
Out[]: array([1., 2., 3.])
```

```
In []: data.dtype
```

```
Out[]: dtype('float64')
```

```
In []: data = np.array(data, dtype = int) # Type casting
```

```
In []: data
```

```
Out[]: array([1, 2, 3])
```

```
In []: data.dtype
```

```
Out[]: dtype('int32')
```

```
In []: data = np.array([1, 2, 3], dtype = float)
```

```
In []: data
```

```
Out[]: array([1., 2., 3.])
```

```
In []: data.astype(int) # another Type casting
```

```
Out[]: array([1, 2, 3])
```

```
In []: data
```

```
Out[]: array([1., 2., 3.])
```

```
In []: d1 = np.array([1, 2, 3], dtype = float)
 d2 = np.array([1, 2, 3], dtype = complex)
```

```
In []: d1 + d2 # Automatic Type casting
```

```
Out[]: array([2.+0.j, 4.+0.j, 6.+0.j])
```

```
In []: _.dtype # last cell's data type
```

```
Out[]: dtype('complex128')
```

```
In []: np.sqrt(np.array([-1, 0, 1]))
```

```
C:\Users\vision\AppData\Local\Temp\ipykernel_16044\208196152.py:1: RuntimeWarning: invalid value encountered in sqrt
 np.sqrt(np.array([-1, 0, 1]))
Out[]: array([nan, 0., 1.]
```

```
In []: np.sqrt(np.array([-1, 0, 1]), dtype = complex)
```

```
Out[]: array([0.+1.j, 0.+0.j, 1.+0.j])
```

```
In []: data = np.array([1, 2, 3], dtype = complex)
```

```
In []: data
```

```
Out[]: array([1.+0.j, 2.+0.j, 3.+0.j])
```

```
In []: data.real
```

```
Out[]: array([1., 2., 3.])
```

```
In []: data.imag
```

```
Out[]: array([0., 0., 0.])
```

## Order of Array Data in Memory

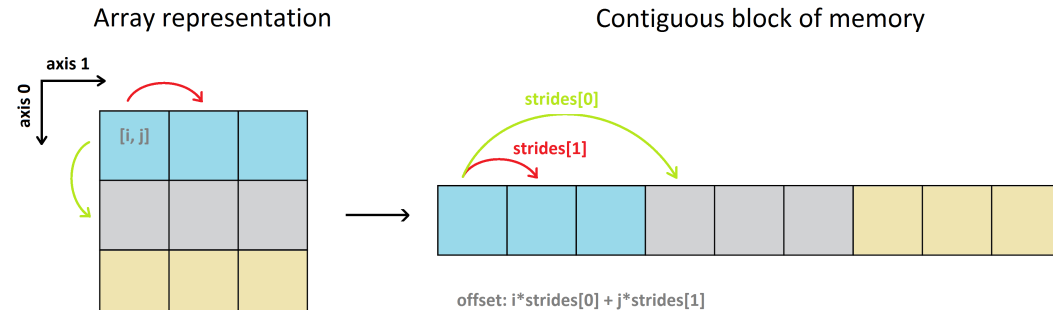
row-major format : keyword argument `order= 'C'` | column-major format : keyword argument `order= 'F'` default format is row-major

NumPy array attribute : `ndarray.strides`

Example: C-order array A with shape  $(2, 3)$  | data type : `int32` | total memory buffer for the array :  $2 \times 3 \times 4 = 24$

strides attribute of this array :  $(4 \times 3, 4 \times 1) = (12, 4)$  | F order , the strides :  $(4, 8)$

Stride



Ref

```
In []: a = np.arange(1, 10).reshape(3, 3)
```

```
In []: a
```

```
Out[]: array([[1, 2, 3],
 [4, 5, 6],
 [7, 8, 9]])
```

```
In []: a.itemsize # each elemnt's byte size
```

```
Out[]: 4
```

```
In []:
```

```
a.size
```

```
Out[]: 9
```

```
In []: a.nbytes
```

```
Out[]: 36
```

```
In []: a.strides
```

```
Out[]: (12, 4)
```

```
In []: b = np.array([[1, 4, 7],
 [2, 5, 8],
 [3, 6, 9]]).T
```

```
In []: b
```

```
Out[]: array([[1, 2, 3],
 [4, 5, 6],
 [7, 8, 9]])
```

```
In []: b.strides
```

```
Out[]: (4, 12)
```

```
In []: a == b
```

```
Out[]: array([[True, True, True],
 [True, True, True],
 [True, True, True]])
```

## Creating Arrays

### Arrays Created from Lists and Other Array-Like Objects

```
In [60]: data = np.array([1, 2, 3, 4])
```

```
In []: data.ndim
```

```
Out[]: 1
```

```
In []: data.shape
```

```
Out[]: (4,)
```

```
In []: data.size
```

```
Out[]: 4
```

```
In []: data = np.array((1, 2, 3, 4))
```

```
In []: data
```

```
Out[]: array([1, 2, 3, 4])
```

```
In []: data.shape
```

```
Out[]: (4,)
```

```
In []: data = np.array({1, 2, 3, 4})
```

```
In []: data
```

```
Out[]: array({1, 2, 3, 4}, dtype=object)
```

```
In []: data = np.array([[1, 2],
 [3, 4]])
```

```
In []: data
```

```
Out[]: array([[1, 2],
 [3, 4]])
```

```
In []: data.shape
```

```
Out[]: (2, 2)
```

## Arrays Filled with Constant Values

```
In [61]: np.zeros(5)
```

```
Out[61]: array([0., 0., 0., 0., 0.])
```

```
In []: np.zeros((3, 4))
```

```
In []: np.ones(10)
```



```
In [66]: np.ones((5, 5))
```

```
Out[66]: array([[1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.]])
```

```
In [65]: data = np.ones(4)
```

```
In [64]: data
```

```
Out[64]: array([1, 1, 1, 1])
```

```
In [63]: data.dtype
```

```
Out[63]: dtype('int32')
```

```
In [67]: data = np.ones(4, dtype = int)
```

```
In [68]: data
```

```
Out[68]: array([1, 1, 1, 1])
```

```
In [69]: data.dtype
```

```
Out[69]: dtype('int32')
```

```
In [70]: x1 = 8.3 * np.ones(15)
```

```
In [71]: x1
```

```
Out[71]: array([8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3,
 8.3, 8.3])
```

```
In [72]: x2 = np.full(15, 8.3)
```

```
In [73]: x2
```

```
Out[73]: array([8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3, 8.3,
 8.3, 8.3])
```

```
In [74]: x3 = np.full((4, 3), 8.3)
```

In [75]: x3

Out[75]: array([[8.3, 8.3, 8.3],  
[8.3, 8.3, 8.3],  
[8.3, 8.3, 8.3],  
[8.3, 8.3, 8.3]])

In [76]: x4 = np.empty(5)

In [77]: x4

Out[77]: array([0., 0., 0., 0., 0.])

In [78]: x4.fill(6.9)

In [79]: x4

Out[79]: array([6.9, 6.9, 6.9, 6.9, 6.9])

In [80]: x5 = np.full(10, 5.8)

In [81]: x5

Out[81]: array([5.8, 5.8, 5.8, 5.8, 5.8, 5.8, 5.8, 5.8, 5.8, 5.8])

## Arrays Filled with Incremental Sequences

In [ ]: *# np.arange(start = 0, end (up to but not including), increment = 1)*

In [82]: np.arange(0, 10, 1)

Out[82]: array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])

In [83]: np.arange(2)

Out[83]: array([0, 1])

In [84]: np.arange(0)

Out[84]: array([], dtype=int32)

In [85]: np.arange(1, 11, 3)

Out[85]: array([ 1, 4, 7, 10])

```
In []: # np.linspace(start, end (up to but including), total number of elements in the array)
```

```
In [87]: np.linspace(0, 10 , 11, dtype = int)
```

```
Out[87]: array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10])
```

```
In [86]: np.linspace?
```

**Signature:**

```
np.linspace(
 start,
 stop,
 num=50,
 endpoint=True,
 retstep=False,
 dtype=None,
 axis=0,
)
```

**Docstring:**

Return evenly spaced numbers over a specified interval.

Returns `num` evenly spaced samples, calculated over the interval [`start`, `stop`].

The endpoint of the interval can optionally be excluded.

```
.. versionchanged:: 1.16.0
 Non-scalar `start` and `stop` are now supported.
```

```
.. versionchanged:: 1.20.0
 Values are rounded towards ``-inf`` instead of ``0`` when an
 integer ``dtype`` is specified. The old behavior can
 still be obtained with ``np.linspace(start, stop, num).astype(int)``
```

**Parameters**

-----

start : array\_like

The starting value of the sequence.

stop : array\_like

The end value of the sequence, unless `endpoint` is set to False.

In that case, the sequence consists of all but the last of ``num + 1`` evenly spaced samples, so that `stop` is excluded. Note that the step size changes when `endpoint` is False.

num : int, optional

Number of samples to generate. Default is 50. Must be non-negative.

endpoint : bool, optional

If True, `stop` is the last sample. Otherwise, it is not included. Default is True.

retstep : bool, optional

If True, return (`samples`, `step`), where `step` is the spacing between samples.

dtype : dtype, optional

The type of the output array. If `dtype` is not given, the data type is inferred from `start` and `stop`. The inferred dtype will never be an integer; `float` is chosen even if the arguments would produce an

array of integers.

.. versionadded:: 1.9.0

axis : int, optional

The axis in the result to store the samples. Relevant only if start or stop are array-like. By default (0), the samples will be along a new axis inserted at the beginning. Use -1 to get an axis at the end.

.. versionadded:: 1.16.0

Returns

-----

samples : ndarray

There are `num` equally spaced samples in the closed interval ``[start, stop]`` or the half-open interval ``[start, stop)`` (depending on whether `endpoint` is True or False).

step : float, optional

Only returned if `retstep` is True

Size of spacing between samples.

See Also

-----

arange : Similar to `linspace`, but uses a step size (instead of the number of samples).

geomspace : Similar to `linspace`, but with numbers spaced evenly on a log scale (a geometric progression).

logspace : Similar to `geomspace`, but with the end points specified as logarithms.

Examples

-----

```
>>> np.linspace(2.0, 3.0, num=5)
array([2. , 2.25, 2.5 , 2.75, 3.])
>>> np.linspace(2.0, 3.0, num=5, endpoint=False)
array([2. , 2.2, 2.4, 2.6, 2.8])
>>> np.linspace(2.0, 3.0, num=5, retstep=True)
(array([2. , 2.25, 2.5 , 2.75, 3.]), 0.25)
```

Graphical illustration:

```
>>> import matplotlib.pyplot as plt
>>> N = 8
>>> y = np.zeros(N)
>>> x1 = np.linspace(0, 10, N, endpoint=True)
>>> x2 = np.linspace(0, 10, N, endpoint=False)
>>> plt.plot(x1, y, 'o')
[<matplotlib.lines.Line2D object at 0x...>]
>>> plt.plot(x2, y + 0.5, 'o')
[<matplotlib.lines.Line2D object at 0x...>]
>>> plt.ylim([-0.5, 1])
(-0.5, 1)
>>> plt.show()
File: c:\miniconda3\lib\site-packages\numpy\core\function_base.py
Type: function
```

In [88]:

```
np.linspace(0, 10)
```

```
Out[88]: array([0. , 0.20408163, 0.40816327, 0.6122449 , 0.81632653,
 1.02040816, 1.2244898 , 1.42857143, 1.63265306, 1.83673469,
 2.04081633, 2.24489796, 2.44897959, 2.65306122, 2.85714286,
 3.06122449, 3.26530612, 3.46938776, 3.67346939, 3.87755102,
 4.08163265, 4.28571429, 4.48979592, 4.69387755, 4.89795918,
 5.10204082, 5.30612245, 5.51020408, 5.71428571, 5.91836735,
 6.12244898, 6.32653061, 6.53061224, 6.73469388, 6.93877551,
 7.14285714, 7.34693878, 7.55102041, 7.75510204, 7.95918367,
 8.16326531, 8.36734694, 8.57142857, 8.7755102 , 8.97959184,
 9.18367347, 9.3877551 , 9.59183673, 9.79591837, 10.])
```

```
In [89]: np.linspace(0, 10 , 11, endpoint = False)
```

```
Out[89]: array([0. , 0.90909091, 1.81818182, 2.72727273, 3.63636364,
 4.54545455, 5.45454545, 6.36363636, 7.27272727, 8.18181818,
 9.09090909])
```

```
In [90]: np.arange?
```

**Docstring:**

```
arange([start,] stop[, step,], dtype=None, *, like=None)
```

Return evenly spaced values within a given interval.

Values are generated within the half-open interval ``[start, stop)`` (in other words, the interval including ``start`` but excluding ``stop``). For integer arguments the function is equivalent to the Python built-in ``range`` function, but returns an ndarray rather than a list.

When using a non-integer step, such as 0.1, the results will often not be consistent. It is better to use ``numpy.linspace`` for these cases.

**Parameters**

-----

**start** : integer or real, optional

Start of interval. The interval includes this value. The default start value is 0.

**stop** : integer or real

End of interval. The interval does not include this value, except in some cases where ``step`` is not an integer and floating point round-off affects the length of ``out``.

**step** : integer or real, optional

Spacing between values. For any output ``out``, this is the distance between two adjacent values, ``out[i+1] - out[i]``. The default step size is 1. If ``step`` is specified as a position argument, ``start`` must also be given.

**dtype** : dtype

The type of the output array. If ``dtype`` is not given, infer the data type from the other input arguments.

**like** : array\_like

Reference object to allow the creation of arrays which are not NumPy arrays. If an array-like passed in as ``like`` supports the ``\_\_array\_function\_\_`` protocol, the result will be defined by it. In this case, it ensures the creation of an array object compatible with that passed in via this argument.

.. versionadded:: 1.20.0

## Returns

-----

arange : ndarray  
 Array of evenly spaced values.

For floating point arguments, the length of the result is `ceil((stop - start)/step)`. Because of floating point overflow, this rule may result in the last element of `out` being greater than `stop`.

## See Also

-----

`numpy.linspace` : Evenly spaced numbers with careful handling of endpoints.  
`numpy.ogrid`: Arrays of evenly spaced numbers in N-dimensions.  
`numpy.mgrid`: Grid-shaped arrays of evenly spaced numbers in N-dimensions.

## Examples

-----

```
>>> np.arange(3)
array([0, 1, 2])
>>> np.arange(3.0)
array([0., 1., 2.])
>>> np.arange(3,7)
array([3, 4, 5, 6])
>>> np.arange(3,7,2)
array([3, 5])
Type: builtin_function_or_method
```

## Arrays Filled with Logarithmic Sequences

```
In [91]: np.logspace(0, 3, 20) # 20 data points between 10**0 =1 to 10**3 = 1000
```

```
Out[91]: array([1. , 1.43844989, 2.06913808, 2.97635144,
 4.2813324 , 6.15848211, 8.8586679 , 12.74274986,
 18.32980711, 26.36650899, 37.92690191, 54.55594781,
 78.47599704, 112.88378917, 162.37767392, 233.57214691,
 335.98182863, 483.29302386, 695.19279618, 1000.])
```

```
In [92]: np.logspace?
```

**Signature:**

```
np.logspace(
 start,
 stop,
 num=50,
 endpoint=True,
 base=10.0,
 dtype=None,
 axis=0,
)
```

**Docstring:**

Return numbers spaced evenly on a log scale.

In linear space, the sequence starts at `base ** start` (`base` to the power of `start`) and ends with `base ** stop` (see `endpoint` below).

.. versionchanged:: 1.16.0

Non-scalar ``start`` and ``stop`` are now supported.

#### Parameters

-----

`start` : array\_like  
``base ** start`` is the starting value of the sequence.

`stop` : array\_like  
``base ** stop`` is the final value of the sequence, unless ``endpoint`` is False. In that case, ``num + 1`` values are spaced over the interval in log-space, of which all but the last (a sequence of length ``num``) are returned.

`num` : integer, optional  
 Number of samples to generate. Default is 50.

`endpoint` : boolean, optional  
 If true, ``stop`` is the last sample. Otherwise, it is not included. Default is True.

`base` : array\_like, optional  
 The base of the log space. The step size between the elements in ``ln(samples) / ln(base)`` (or ``log_base(samples)``) is uniform. Default is 10.0.

`dtype` : dtype  
 The type of the output array. If ``dtype`` is not given, the data type is inferred from ``start`` and ``stop``. The inferred type will never be an integer; ``float`` is chosen even if the arguments would produce an array of integers.

`axis` : int, optional  
 The axis in the result to store the samples. Relevant only if start or stop are array-like. By default (0), the samples will be along a new axis inserted at the beginning. Use -1 to get an axis at the end.

.. versionadded:: 1.16.0

#### Returns

-----

`samples` : ndarray  
``num`` samples, equally spaced on a log scale.

#### See Also

-----

`arange` : Similar to `linspace`, with the step size specified instead of the number of samples. Note that, when used with a float endpoint, the endpoint may or may not be included.

`linspace` : Similar to `logspace`, but with the samples uniformly distributed in linear space, instead of log space.

`geomspace` : Similar to `logspace`, but with endpoints specified directly.

#### Notes

-----

`Logspace` is equivalent to the code

```
>>> y = np.linspace(start, stop, num=num, endpoint=endpoint)
... # doctest: +SKIP
>>> power(base, y).astype(dtype)
... # doctest: +SKIP
```

#### Examples

-----

```
>>> np.logspace(2.0, 3.0, num=4)
array([100. , 215.443469 , 464.15888336, 1000.])
```

```
>>> np.logspace(2.0, 3.0, num=4, endpoint=False)
array([100. , 177.827941 , 316.22776602, 562.34132519])
>>> np.logspace(2.0, 3.0, num=4, base=2.0)
array([4. , 5.0396842 , 6.34960421, 8.])
```

Graphical illustration:

```
>>> import matplotlib.pyplot as plt
>>> N = 10
>>> x1 = np.logspace(0.1, 1, N, endpoint=True)
>>> x2 = np.logspace(0.1, 1, N, endpoint=False)
>>> y = np.zeros(N)
>>> plt.plot(x1, y, 'o')
[<matplotlib.lines.Line2D object at 0x...>]
>>> plt.plot(x2, y + 0.5, 'o')
[<matplotlib.lines.Line2D object at 0x...>]
>>> plt.ylim([-0.5, 1])
(-0.5, 1)
>>> plt.show()
File: c:\miniconda3\lib\site-packages\numpy\core\function_base.py
Type: function
```

```
In [93]: np.logspace(0, 3, 20, base = 3)
```

```
Out[93]: array([1. , 1.18941917, 1.41471797, 1.68269268, 2.00142693,
 2.38053557, 2.83145465, 3.36778645, 4.00570977, 4.764468 ,
 5.66694959, 6.7403785 , 8.01713542, 9.53573458, 11.34198554,
 13.49037507, 16.04571076, 19.08507602, 22.70015534, 27.])
```

## Meshgrid Arrays

```
In [94]: x = np.array([-1, 0 , 1])
 y = np.array([-2, 0 , 2])
```

```
In [95]: X, Y = np.meshgrid(x, y)
```

```
In [96]: x
```

```
Out[96]: array([[-1, 0, 1],
 [-1, 0, 1],
 [-1, 0, 1]])
```

```
In [97]: y
```

```
Out[97]: array([[-2, -2, -2],
 [0, 0, 0],
 [2, 2, 2]])
```

```
In [98]: x = np.array([-1.5, -1, -0.5, 0, 0.5, 1, 1.5])
```

```
In [99]: y = np.array([-2, -1, 0, 1, 2])
```



```
In [100... X, Y = np.meshgrid(x, y)
```

```
In [101... x
```

```
Out[101... array([[-1.5, -1. , -0.5, 0. , 0.5, 1. , 1.5],
 [-1.5, -1. , -0.5, 0. , 0.5, 1. , 1.5],
 [-1.5, -1. , -0.5, 0. , 0.5, 1. , 1.5],
 [-1.5, -1. , -0.5, 0. , 0.5, 1. , 1.5],
 [-1.5, -1. , -0.5, 0. , 0.5, 1. , 1.5]])
```

```
In [102... y
```

```
Out[102... array([[-2, -2, -2, -2, -2, -2, -2],
 [-1, -1, -1, -1, -1, -1, -1],
 [0, 0, 0, 0, 0, 0, 0],
 [1, 1, 1, 1, 1, 1, 1],
 [2, 2, 2, 2, 2, 2, 2]])
```

```
In [103... z = (X + Y) ** 2
```

```
In [104... z
```

```
Out[104... array([[12.25, 9. , 6.25, 4. , 2.25, 1. , 0.25],
 [6.25, 4. , 2.25, 1. , 0.25, 0. , 0.25],
 [2.25, 1. , 0.25, 0. , 0.25, 1. , 2.25],
 [0.25, 0. , 0.25, 1. , 2.25, 4. , 6.25],
 [0.25, 1. , 2.25, 4. , 6.25, 9. , 12.25]])
```

```
In []: # np.mgrid, np.ogrid
```

## Creating Uninitialized Arrays

```
In [107... np.empty(10, dtype = float)
```

```
Out[107... array([0.90909091, 1.81818182, 2.72727273, 3.63636364, 4.54545455,
 5.45454545, 6.36363636, 7.27272727, 8.18181818, 9.09090909])
```

## Creating Arrays with Properties of Other Arrays

```
In []: # np.ones_like, np.zeros_like, np.full_like, np.empty_like
```

```
In [108... def f(x):
 y = np.ones_like(x)
 return y
```

```
In [109... x = np.array([1, 5, 8, 9, 12], dtype = complex)
```

```
In [111...
```

x

Out [111...] array([ 1.+0.j, 5.+0.j, 8.+0.j, 9.+0.j, 12.+0.j])

In [110...] f(x)

Out [110...] array([1.+0.j, 1.+0.j, 1.+0.j, 1.+0.j, 1.+0.j])

## Creating Matrix Arrays

In [ ]: # np.array([[ ], [ ]])

In [112...] np.identity(5)

Out [112...] array([[1., 0., 0., 0., 0.],  
[0., 1., 0., 0., 0.],  
[0., 0., 1., 0., 0.],  
[0., 0., 0., 1., 0.],  
[0., 0., 0., 0., 1.]])

In [116...] np.eye(5)

Out [116...] array([[1., 0., 0., 0., 0.],  
[0., 1., 0., 0., 0.],  
[0., 0., 1., 0., 0.],  
[0., 0., 0., 1., 0.],  
[0., 0., 0., 0., 1.]])

In [113...] np.eye(5, k = 0)

Out [113...] array([[1., 0., 0., 0., 0.],  
[0., 1., 0., 0., 0.],  
[0., 0., 1., 0., 0.],  
[0., 0., 0., 1., 0.],  
[0., 0., 0., 0., 1.]])

In [114...] np.eye(5, k = 3)

Out [114...] array([[0., 0., 0., 1., 0.],  
[0., 0., 0., 0., 1.],  
[0., 0., 0., 0., 0.],  
[0., 0., 0., 0., 0.],  
[0., 0., 0., 0., 0.]])

In [115...] np.eye(5, k = -1)

Out [115...] array([[0., 0., 0., 0., 0.],  
[1., 0., 0., 0., 0.],  
[0., 1., 0., 0., 0.],  
[0., 0., 1., 0., 0.],  
[0., 0., 0., 1., 0.]])

In [123... np.diag?

**Signature:** np.diag(v, k=0)**Docstring:**

Extract a diagonal or construct a diagonal array.

See the more detailed documentation for ``numpy.diagonal`` if you use this function to extract a diagonal and wish to write to the resulting array; whether it returns a copy or a view depends on what version of numpy you are using.

**Parameters**

-----

**v** : array\_like

If `v` is a 2-D array, return a copy of its `k`-th diagonal.

If `v` is a 1-D array, return a 2-D array with `v` on the `k`-th diagonal.

**k** : int, optional

Diagonal in question. The default is 0. Use `k&gt;0` for diagonals above the main diagonal, and `k&lt;0` for diagonals below the main diagonal.

**Returns**

-----

**out** : ndarray

The extracted diagonal or constructed diagonal array.

**See Also**

-----

**diagonal** : Return specified diagonals.**diagflat** : Create a 2-D array with the flattened input as a diagonal.**trace** : Sum along diagonals.**triu** : Upper triangle of an array.**tril** : Lower triangle of an array.**Examples**

-----

```
>>> x = np.arange(9).reshape((3,3))
```

```
>>> x
```

```
array([[0, 1, 2],
 [3, 4, 5],
 [6, 7, 8]])
```

```
>>> np.diag(x)
```

```
array([0, 4, 8])
```

```
>>> np.diag(x, k=1)
```

```
array([1, 5])
```

```
>>> np.diag(x, k=-1)
```

```
array([3, 7])
```

```
>>> np.diag(np.diag(x))
```

```
array([[0, 0, 0],
 [0, 4, 0],
 [0, 0, 8]])
```

**File:** c:\miniconda3\lib\site-packages\numpy\lib\twodim\_base.py**Type:** function

In [122... np.diag(np.arange(0, 27, 5))

```
Out[122...] array([[0, 0, 0, 0, 0, 0],
 [0, 5, 0, 0, 0, 0],
 [0, 0, 10, 0, 0, 0],
 [0, 0, 0, 15, 0, 0],
 [0, 0, 0, 0, 20, 0],
 [0, 0, 0, 0, 0, 25]])
```

## Indexing and Slicing

```
In []: # [m = 0: n(up to but not including) = end: p(step) = 1]
```

### One-Dimensional Arrays

```
In [124...] a = np.arange(0, 11)
```

```
In [125...] a
```

```
Out[125...] array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10])
```

```
In [126...] a[0]
```

```
Out[126...] 0
```

```
In [127...] a[-1]
```

```
Out[127...] 10
```

```
In [128...] a[5]
```

```
Out[128...] 5
```

```
In [129...] a[-5]
```

```
Out[129...] 6
```

```
In [130...] a[2:-2]
```

```
Out[130...] array([2, 3, 4, 5, 6, 7, 8])
```

```
In [131...] a[2:-2:2]
```

```
Out[131...] array([2, 4, 6, 8])
```

```
In []: a[:6]
```

```
In [132... a[-6:]
```

```
Out[132... array([5, 6, 7, 8, 9, 10])
```

```
In [133... a[::-2]
```

```
Out[133... array([10, 8, 6, 4, 2, 0])
```

```
In [134... a[:]
```

```
Out[134... array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10])
```

```
In [137... a[0:]
```

```
Out[137... array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10])
```

```
In [138... a[0:-1]
```

```
Out[138... array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```

```
In [135... a[1:8:-1]
```

```
Out[135... array([], dtype=int32)
```

```
In [139... a[8:1:-1]
```

```
Out[139... array([8, 7, 6, 5, 4, 3, 2])
```

## Multidimensional Arrays

```
In [140... f = lambda m, n: n + 10 * m
```

```
In [141... A = np.fromfunction(f, (7, 7), dtype = int)
```

```
In [142... A
```

```
Out[142... array([[0, 1, 2, 3, 4, 5, 6],
 [10, 11, 12, 13, 14, 15, 16],
 [20, 21, 22, 23, 24, 25, 26],
 [30, 31, 32, 33, 34, 35, 36],
 [40, 41, 42, 43, 44, 45, 46],
 [50, 51, 52, 53, 54, 55, 56],
 [60, 61, 62, 63, 64, 65, 66]])
```

```
In [143... A[2, 3]
```

```
Out[143... 23
```

```
In [144... A[:, 3]
```

```
Out[144... array([3, 13, 23, 33, 43, 53, 63])
```

```
In [145... A[2, :4]
```

```
Out[145... array([[0, 1, 2, 3],
 [10, 11, 12, 13]])
```

```
In [146... A[2:, 4:]
```

```
Out[146... array([[24, 25, 26],
 [34, 35, 36],
 [44, 45, 46],
 [54, 55, 56],
 [64, 65, 66]])
```

```
In [147... A[::3, ::2]
```

```
Out[147... array([[0, 2, 4, 6],
 [30, 32, 34, 36],
 [60, 62, 64, 66]])
```

## Views

```
In [148... f = lambda m, n : n + 10 * m
a = np.fromfunction(f, (7, 7), dtype = int); a
```

```
Out[148... array([[0, 1, 2, 3, 4, 5, 6],
 [10, 11, 12, 13, 14, 15, 16],
 [20, 21, 22, 23, 24, 25, 26],
 [30, 31, 32, 33, 34, 35, 36],
 [40, 41, 42, 43, 44, 45, 46],
 [50, 51, 52, 53, 54, 55, 56],
 [60, 61, 62, 63, 64, 65, 66]])
```

```
In [154... b = a[::3, ::2]; b
```

```
Out[154... array([[100, 100, 100, 100],
 [100, 100, 100, 100],
 [100, 100, 100, 100]])
```

```
In [156... b[:, :] = 100; b
```

```
Out[156... array([[100, 100, 100, 100],
 [100, 100, 100, 100],
 [100, 100, 100, 100]])
```

```
In [157...
```

a

```
Out [157...] array([[100, 1, 100, 3, 100, 5, 100],
 [10, 11, 12, 13, 14, 15, 16],
 [20, 21, 22, 23, 24, 25, 26],
 [100, 31, 100, 33, 100, 35, 100],
 [40, 41, 42, 43, 44, 45, 46],
 [50, 51, 52, 53, 54, 55, 56],
 [100, 61, 100, 63, 100, 65, 100]])
```

```
In [158...] b[:2, 1:]
```

```
Out [158...] array([[100, 100, 100],
 [100, 100, 100]])
```

```
In [159...] c = b[:2, 1:].copy(); c
```

```
Out [159...] array([[100, 100, 100],
 [100, 100, 100]])
```

```
In [160...] c[:, :] = -500
```

```
In [161...] c
```

```
Out [161...] array([[-500, -500, -500],
 [-500, -500, -500]])
```

```
In [162...] b
```

```
Out [162...] array([[100, 100, 100, 100],
 [100, 100, 100, 100],
 [100, 100, 100, 100]])
```

## Fancy Indexing and Boolean-Valued Indexing

```
In [165...] A = np.linspace(0, 1, 11); A
```

```
Out [165...] array([0. , 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.])
```

```
In [167...] A[np.array([0, 4, 6])]
```

```
Out [167...] array([0. , 0.4, 0.6])
```

```
In [173...] A[0, 4, 6]
```

```

IndexError Traceback (most recent call last)
~\AppData\Local\Temp\ipykernel_15992\3363190361.py in <module>
----> 1 A[0, 4, 6]
```

**IndexError**: too many indices for array: array is 1-dimensional, but 3 were indexed

```
In [168... A[[0, 4, 6]]
```

```
Out[168... array([0. , 0.4, 0.6])
```

```
In [169... A > 0.5
```

```
Out[169... array([False, False, False, False, False, False, True, True, True,
 True, True])
```

```
In [170... A[A > 0.5]
```

```
Out[170... array([0.6, 0.7, 0.8, 0.9, 1.])
```

```
In [171... A = np.arange(10)
indexes = [1, 3, 5]
B = A[indexes]
print(f'A: {A}')
print(f'B: {B}')
```

```
A: [0 1 2 3 4 5 6 7 8 9]
B: [1 3 5]
```

```
In [172... B[0] = -200
print(f'A: {A}')
print(f'B: {B}')
```

```
A: [0 1 2 3 4 5 6 7 8 9]
B: [-200 3 5]
```

```
In [175... A[indexes] = -200; A
```

```
Out[175... array([0, -200, 2, -200, 4, -200, 6, 7, 8, 9])
```

```
In [186... A = np.arange(10); A
```

```
Out[186... array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```

```
In [187... B = A[A > 5]; B
```

```
Out[187... array([6, 7, 8, 9])
```

```
In [188... B[0] = -500; B
```

```
Out[188... array([-500, 7, 8, 9])
```

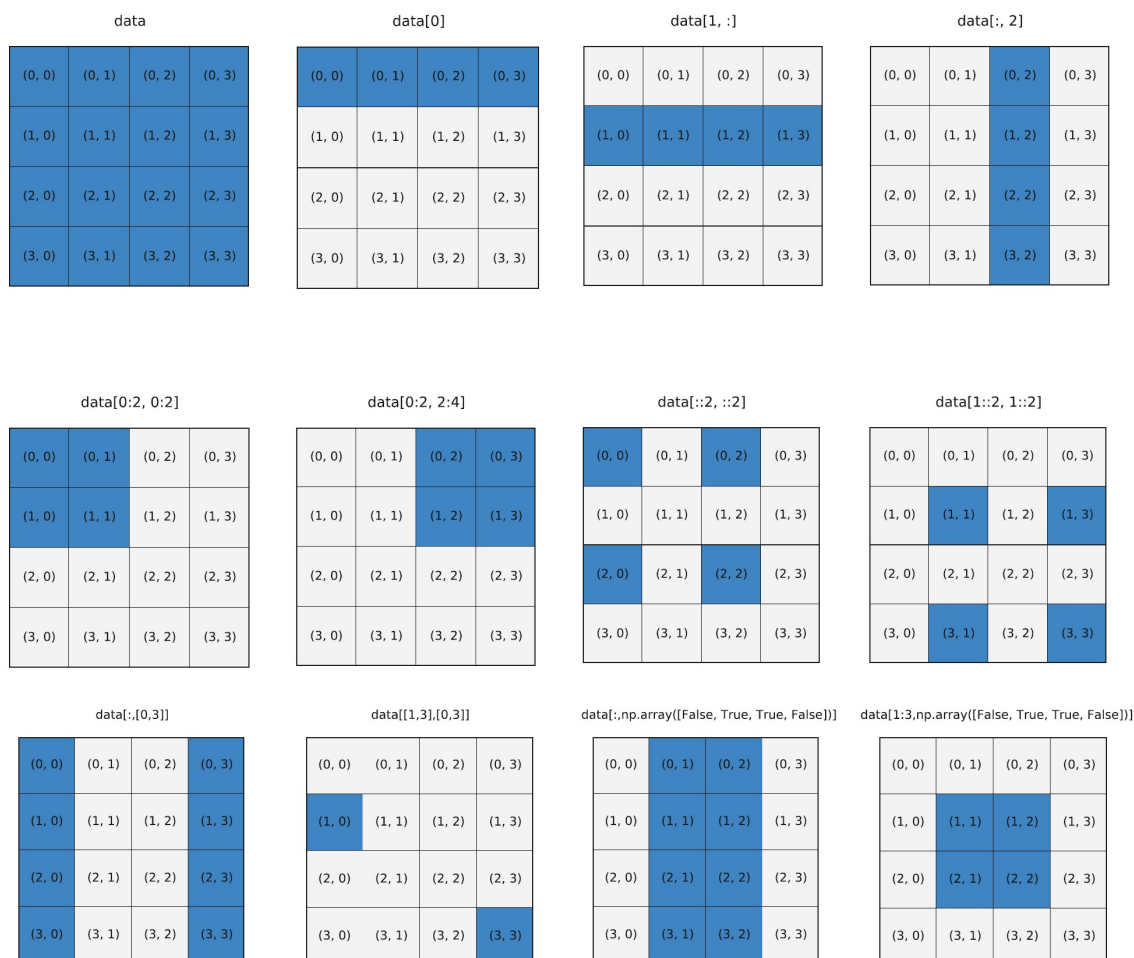
```
In [189... A
```

```
Out[189... array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```



In [190... `A[A > 5] = -500; A`

Out [190... `array([ 0, 1, 2, 3, 4, 5, -500, -500, -500, -500])`



## Reshaping and Resizing

In [191... `data = np.array([[1, 2], [3, 4]])`

In [193... `np.reshape(data, (1, 4))`

Out [193... `array([[1, 2, 3, 4]])`

In [197... `a = data.reshape((1, 4)); a`

Out [197... `array([[1, 2, 3, 4]])`

In [198... `a.shape`

Out [198... `(1, 4)`

```
In [199... b = data.reshape(4); b
```

```
Out[199... array([1, 2, 3, 4])
```

```
In [200... b.shape
```

```
Out[200... (4,)
```

```
In []: # np.ravel() -> change view , np.flatten() -> give a copy
```

```
In [202... data = np.array([[1, 2], [3, 4]]); data
```

```
Out[202... array([[1, 2],
 [3, 4]])
```

```
In [203... data.flatten()
```

```
Out[203... array([1, 2, 3, 4])
```

```
In [204... data.flatten().shape
```

```
Out[204... (4,)
```

```
In [205... np.shape(data.flatten())
```

```
Out[205... (4,)
```

```
In [208... data = np.arange(5); data
```

```
Out[208... array([0, 1, 2, 3, 4])
```

```
In [209... data.shape
```

```
Out[209... (5,)
```

```
In [210... col = data[:, np.newaxis]; col
```

```
Out[210... array([[0],
 [1],
 [2],
 [3],
 [4]])
```

```
In [211... col.shape
```

```
Out[211... (5, 1)
```

```
In [212]: row = data[np.newaxis, :]; row
```

```
Out[212]: array([[0, 1, 2, 3, 4]])
```

```
In [3]: data = np.arange(5); data
```

```
Out[3]: array([0, 1, 2, 3, 4])
```

```
In [4]: np.expand_dims(data, axis = 1) # -> data[:, np.newaxis]
```

```
Out[4]: array([[0],
 [1],
 [2],
 [3],
 [4]])
```

```
In [5]: np.expand_dims(data, axis = 0) # -> data[np.newaxis, :]
```

```
Out[5]: array([[0, 1, 2, 3, 4]])
```

```
In [7]: data = np.arange(5); data
```

```
Out[7]: array([0, 1, 2, 3, 4])
```

```
In [8]: np.vstack((data, data, data, data))
```

```
Out[8]: array([[0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4]])
```

```
In [9]: data
```

```
Out[9]: array([0, 1, 2, 3, 4])
```

```
In [10]: np.hstack((data,data,data,data))
```

```
Out[10]: array([0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4])
```

```
In [11]: data = data[:, np.newaxis]
```

```
In [12]: data
```

```
Out[12]: array([[0],
 [1],
 [2],
 [3],
 [4]])
```

```
In [13]: np.hstack((data, data, data, data))
```

```
Out[13]: array([[0, 0, 0, 0],
 [1, 1, 1, 1],
 [2, 2, 2, 2],
 [3, 3, 3, 3],
 [4, 4, 4, 4]])
```

```
In [14]: np.concatenate((data, data, data, data), axis = 1)
```

```
Out[14]: array([[0, 0, 0, 0],
 [1, 1, 1, 1],
 [2, 2, 2, 2],
 [3, 3, 3, 3],
 [4, 4, 4, 4]])
```

```
In [19]: data = np.arange(5); data
```

```
Out[19]: array([0, 1, 2, 3, 4])
```

```
In [21]: np.concatenate((data, data, data, data), axis = 0)
```

```
Out[21]: array([0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4])
```

```
In [22]: np.concatenate((data, data, data, data), axis = 1)
```

```

AxisError Traceback (most recent call last)
~\AppData\Local\Temp\ipykernel_6048\1188247215.py in <module>
----> 1 np.concatenate((data, data, data, data), axis = 1)

<__array_function__ internals> in concatenate(*args, **kwargs)

AxisError: axis 1 is out of bounds for array of dimension 1
```

```
In [23]: data = data[np.newaxis, :]; data
```

```
Out[23]: array([[0, 1, 2, 3, 4]])
```

```
In [25]: np.concatenate((data, data, data, data), axis = 0)
```

```
Out[25]: array([[0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4],
 [0, 1, 2, 3, 4]])
```

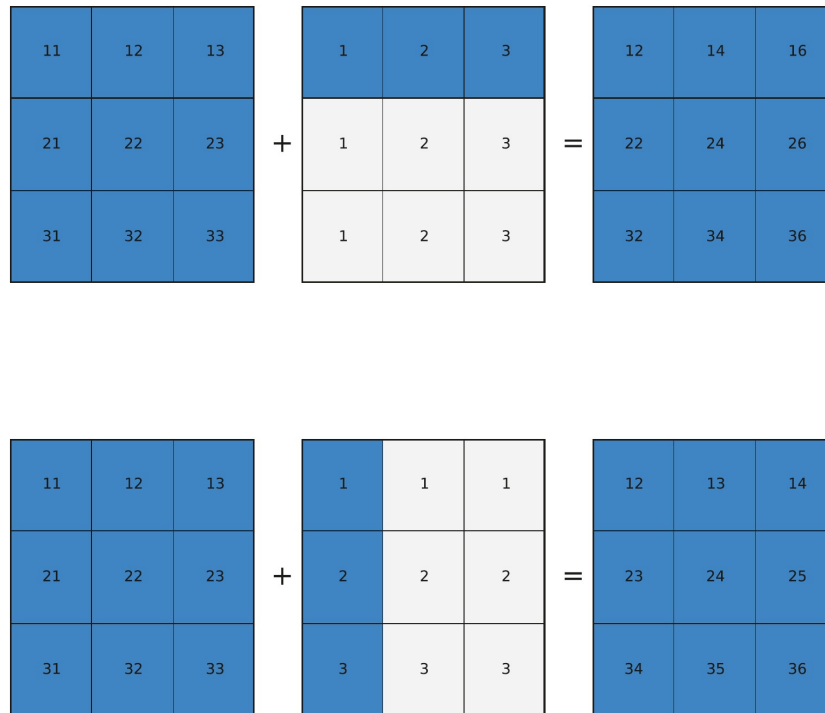
```
In [26]: np.concatenate((data, data, data, data), axis = 1)
```

```
Out[26]: array([[0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4, 0, 1, 2, 3, 4]])
```

## Vectorized Expressions

## Broadcasting Law in NumPy

luzumi be yek size budan araye ha nist, amma size ha sazgar bashand jam ettefagh mioftad. mehvar ha ya bayad bar ruye yek mabnaye moshtarak tul e yeksan dashte bashand va ya tule yek kodum az anha 1 bashad.



## Arithmetic Operations

### Operators for Elementwise Arithmetic Operation on NumPy Arrays

Operator	Operation
+, +=	Addition
-, -=	Subtraction
*, *=	Multiplication
/, /=	Division
//, //=	Integer division
**, **=	Exponentiation

```
In [27]: x = np.array([[1, 2], [3, 4]]); x
```

```
Out[27]: array([[1, 2],
 [3, 4]])
```

```
In [28]: y = np.array([[5, 6], [7, 8]]); y
```

```
Out[28]: array([[5, 6],
 [7, 8]])
```

```
[7, 8]])
```

```
In [29]: x + y
```

```
Out[29]: array([[6, 8],
 [10, 12]])
```

```
In [30]: y - x
```

```
Out[30]: array([[4, 4],
 [4, 4]])
```

```
In [31]: x * y
```

```
Out[31]: array([[5, 12],
 [21, 32]])
```

```
In [32]: x * 2
```

```
Out[32]: array([[2, 4],
 [6, 8]])
```

```
In [33]: 2 ** x
```

```
Out[33]: array([[2, 4],
 [8, 16]], dtype=int32)
```

```
In [34]: y / 2
```

```
Out[34]: array([[2.5, 3.],
 [3.5, 4.]])
```

```
In [36]: (y / 2).dtype
```

```
Out[36]: dtype('float64')
```

```
In [6]: x = np.array([1, 2, 3, 4]).reshape((2,2)); x
```

```
Out[6]: array([[1, 2],
 [3, 4]])
```

```
In [40]: z = np.array([1, 2, 3, 4])
```

```
In [41]: x / z
```

```

ValueError Traceback (most recent call last)
~\AppData\Local\Temp\ipykernel_6048\2868904118.py in <module>
----> 1 x / z
```

```
ValueError: operands could not be broadcast together with shapes (2,2) (4,)
```

```
In [4]: z = np.array([[2, 4]])
```

```
In [43]: z.shape
```

```
Out[43]: (1, 2)
```

```
In [44]: x / z
```

```
Out[44]: array([[0.5, 0.5],
 [1.5, 1.]])
```

```
In [46]: zz = np.concatenate((z ,z), axis = 0); zz
```

```
Out[46]: array([[2, 4],
 [2, 4]])
```

```
In [48]: x / zz
```

```
Out[48]: array([[0.5, 0.5],
 [1.5, 1.]])
```

```
In [8]: z = np.array([[2], [4]]); z
```

```
Out[8]: array([[2],
 [4]])
```

```
In [50]: z.shape
```

```
Out[50]: (2, 1)
```

```
In [51]: x / z
```

```
Out[51]: array([[0.5 , 1.],
 [0.75, 1.]])
```

```
In [52]: z / x
```

```
Out[52]: array([[2. , 1.],
 [1.33333333, 1.]])
```

```
In [9]: zz = np.concatenate((z, z), axis = 1); zz
```

```
Out[9]: array([[2, 2],
 [4, 4]])
```

```
In [10]: x / zz
```

```
Out[10]: array([[0.5 , 1.],
 [0.75, 1.]])
```

```
In [11]:
```

```
x = x + y | x += y (In place operator)
```

# Elementwise Functions

## NumPy Functions for Elementwise Elementary Mathematical Functions

NumPy Function	Description
np.cos, np.sin, np.tan	Trigonometric functions.
np.arccos, np.arcsin, np.arctan	Inverse trigonometric functions.
np.cosh, np.sinh, np.tanh	Hyperbolic trigonometric functions.
np.arccosh, np.arcsinh, np.arctanh	Inverse hyperbolic trigonometric functions.
np.sqrt	Square root.
np.exp	Exponential.
np.log, np.log2, np.log10	Logarithms of base e, 2, and 10, respectively.

```
In [13]: x = np.linspace(-1, 1, 11); x
```

Out[13]: array([-1. , -0.8, -0.6, -0.4, -0.2, 0. , 0.2, 0.4, 0.6, 0.8, 1. ])

```
In [15]: y = np.sin(np.pi * x); y
```

Out[15]: array([-1.22464680e-16, -5.87785252e-01, -9.51056516e-01, -9.51056516e-01, -5.87785252e-01, 0.00000000e+00, 5.87785252e-01, 9.51056516e-01, 9.51056516e-01, 5.87785252e-01, 1.22464680e-16])

```
In [16]: np.round(y, decimals = 5)
```

Out[16]: array([-0. , -0.58779, -0.95106, -0.95106, -0.58779, 0. , 0.58779, 0.95106, 0.95106, 0.58779, 0. ])

## NumPy Functions for Elementwise Mathematical Operations

NumPy Function	Description
np.add, np.subtract, np.multiply, np.divide	Addition, subtraction, multiplication, and division of two NumPy arrays.
np.power	Raises first input argument to the power of the second input argument (applied elementwise).
np.remainder	The remainder of division.
np.reciprocal	The reciprocal (inverse) of each element.
np.real, np.imag, np.conj	The real part, imaginary part, and the complex conjugate of the elements in the input arrays.
np.sign, np.abs	The sign and the absolute value.
np.floor, np.ceil, np rint	Convert to integer values.
np.round	Rounds to a given number of decimals.



```
In [17]: np.add(np.sin(x)**2 , np.cos(x) ** 2)
```

```
Out[17]: array([1., 1., 1., 1., 1., 1., 1., 1., 1., 1., 1.])
```

```
In [18]: np.sin(x)**2 + np.cos(x) ** 2
```

```
Out[18]: array([1., 1., 1., 1., 1., 1., 1., 1., 1., 1., 1.])
```

```
In [19]: def heaviside(x):
 return 1 if x>0 else 0
```

```
In [20]: heaviside(5)
```

```
Out[20]: 1
```

```
In [21]: heaviside(-5)
```

```
Out[21]: 0
```

```
In [22]: x = np.linspace(-5 , 5 , 11); x
```

```
Out[22]: array([-5., -4., -3., -2., -1., 0., 1., 2., 3., 4., 5.])
```

```
In [23]: heaviside(x)
```

-----  
**ValueError**

Traceback (most recent call last)

~\AppData\Local\Temp\ipykernel\_9040\1443328523.py in <module>

----> 1 heaviside(x)

~\AppData\Local\Temp\ipykernel\_9040\2135315997.py in heaviside(x)

```
1 def heaviside(x):
----> 2 return 1 if x>0 else 0
```

**ValueError:** The truth value of an array with more than one element is ambiguous. Use a.any() or a.all()

```
In [24]: heaviside = np.vectorize(heaviside)
```

```
In [25]: heaviside(x)
```

```
Out[25]: array([0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1])
```

```
In [26]: heaviside(-3)
```

```
Out[26]: array(0)
```

```
In [27]: def heaviside(x):
 return 1.0 * (x > 0)
```

# Aggregate Functions

## NumPy Functions for Calculating Aggregates of NumPy Arrays

NumPy Function	Description
np.mean	The average of all values in the array.
np.std	Standard deviation.
np.var	Variance.
np.sum	Sum of all elements.
np.prod	Product of all elements.
np.cumsum	Cumulative sum of all elements.
np.cumprod	Cumulative product of all elements.
np.min, np.max	The minimum/maximum value in an array.
np.argmin, np.argmax	The index of the minimum/maximum value in an array.
np.all	Returns True if all elements in the argument array are nonzero.
np.any	Returns True if any of the elements in the argument array is nonzero.

```
In [28]: # np.mean(data) | data.mean()
```

```
In [31]: data = np.random.normal(size = (15, 15)); data
```

```
Out[31]: array([[9.65902062e-02, -9.07721677e-01, 1.16723803e+00,
 3.67566263e-01, -5.75895256e-01, -1.56814517e-01,
 -5.41257181e-01, 2.22830952e+00, 1.02806566e+00,
 6.57531730e-01, -1.25418649e+00, -2.64031712e-01,
 -8.90088450e-01, -1.51032774e-02, -3.40704562e-01],
 [-6.20874908e-01, -6.59477208e-01, -3.71718250e-01,
 -2.31770143e-01, -8.84834179e-01, -7.56117024e-01,
 1.15035541e+00, 1.82426459e+00, -6.79074145e-01,
 -4.24984183e-01, 6.20873701e-02, -2.46049071e+00,
 -4.74779083e-01, -3.73983079e-01, 1.09242337e+00],
 [8.33546128e-01, 1.78947322e+00, 8.11402812e-01,
 1.69684672e-02, 3.74188521e-02, -5.42847927e-01,
 1.13197657e+00, -8.18438158e-01, -6.01928615e-01,
 -1.25159753e+00, -5.93448032e-01, 1.16860355e+00,
 -1.02980399e+00, 6.36123215e-01, 8.30023034e-01],
 [1.71240265e-01, -5.74340350e-01, 4.75304824e-01,
 7.13236787e-01, 1.17382373e+00, -9.18379811e-01,
 -1.12849000e-01, -1.21924139e+00, -8.63430237e-01,
 6.11082639e-01, -2.17986776e+00, -1.88198907e+00,
 -2.46002337e-01, 2.58312900e+00, -5.21903467e-01],
 [4.44057850e-01, -5.91581273e-01, -7.28954318e-02,
 -1.67553208e+00, -5.92632519e-01, -3.09638207e-01,
 2.32435422e-02, 8.17934054e-01, 6.80482873e-01,
 2.69029230e+00, -8.62156856e-01, 1.09390940e-01,
 4.50016068e-01, -6.32972533e-01, 2.47814456e-02],
 [1.53391392e+00, 2.88796068e-01, -1.83171205e-01,
 4.78465930e-01, -1.62516774e+00, -6.51653452e-01,
```

```

-4.51785167e-01, 9.61677474e-01, -1.55062010e-03,
 5.44447815e-01, -9.21585557e-01, 8.43838703e-01,
 1.48459821e+00, -6.99801384e-01, -9.20405604e-01],
[5.76121927e-01, -3.53390875e-01, 8.30625254e-01,
 2.89804058e-01, 1.96014994e+00, -2.91897348e-01,
-1.56103120e-01, -6.20505724e-01, 7.88314121e-01,
 1.10673050e+00, 2.37003986e-02, -6.50565807e-01,
 1.04233577e+00, -1.30039671e-01, -1.05516961e+00],
[-7.72371807e-01, 9.87239142e-01, 1.25884169e+00,
 2.27751632e-01, 1.64752238e+00, 2.41279909e+00,
-1.52295552e+00, 1.28114015e-01, -3.15248483e-01,
 8.62723551e-01, 5.02291285e-01, 1.24406693e-01,
 1.23745557e+00, -2.26893207e-01, -1.21927956e+00],
[1.27846642e+00, 9.23821924e-01, 1.33263242e+00,
 3.49152568e-01, -1.32613389e+00, -2.07179876e-01,
-4.58400879e-01, 8.29701588e-02, 7.81653770e-01,
-1.85244361e-01, 6.31011182e-01, -4.75063017e-01,
 1.16881259e+00, 1.81775373e-01, -2.73820130e+00],
[-9.98469145e-01, 1.25492489e-01, -3.89747751e-02,
-2.90608616e-01, 9.76366270e-01, 2.57680111e-01,
-7.97439177e-01, 1.41321642e+00, -2.40754458e-01,
-1.44511031e+00, 1.54415991e+00, 3.24465057e-01,
 4.36140649e-01, 2.55483651e-01, 1.62508093e+00],
[2.53824798e+00, -7.35248735e-01, 2.32185466e+00,
 1.29568722e+00, 5.12326415e-01, 9.63211069e-01,
-5.28567897e-01, -2.66216285e-01, -4.86743918e-01,
 8.99952872e-01, 1.65877754e+00, 1.04025399e+00,
-7.28895323e-01, -9.73239387e-01, 1.33936789e+00],
[-5.74743970e-02, 3.45086088e-01, -1.71756225e+00,
 1.92792109e+00, 4.49398617e-02, -7.48841304e-01,
 5.44385345e-01, 9.43639154e-01, 1.70134584e+00,
-7.72962594e-01, -2.04242475e+00, 2.55831337e-01,
-2.97280397e-01, 2.25083612e-01, 1.88345191e+00],
[-4.82322998e-02, -4.89783742e-01, -1.50605196e+00,
-3.32715844e-01, 7.53883477e-02, 8.96628165e-01,
 1.11997524e-02, -7.08127448e-01, 2.27980415e-01,
-2.37269479e-01, 5.05060351e-01, 8.59336705e-01,
-1.11873260e+00, 1.89788903e+00, -2.70875176e-01],
[6.65079648e-01, -2.92062944e-01, 4.28167726e-02,
-1.14517109e+00, -1.17562335e+00, -1.57985621e-01,
 9.70839554e-01, 9.71456058e-01, 1.41239805e+00,
-8.42636955e-01, -1.47816193e+00, 1.28203347e-01,
-4.46151366e-01, -1.09236386e+00, 1.81221889e+00],
[-1.01105743e+00, -1.60538202e+00, 2.30666959e-01,
 1.23156846e+00, 1.59446405e+00, 3.17872228e-01,
-2.55353261e+00, -1.08274855e-02, 1.36427260e-01,
 8.96182406e-01, -1.43112300e+00, 9.71547737e-01,
 3.54745106e-01, 7.69945816e-01, 1.22146037e-01]]])

```

In [32]: `np.mean(data)`

Out[32]: 0.09339834249582513

In [33]: `data.mean()`

Out[33]: 0.09339834249582513

```
In [34]: data = np.random.normal(size = (5, 10, 15))
```

```
In [35]: data.sum(axis = 0).shape
```

```
Out[35]: (10, 15)
```

```
In [36]: data.sum(axis = (0, 2)).shape
```

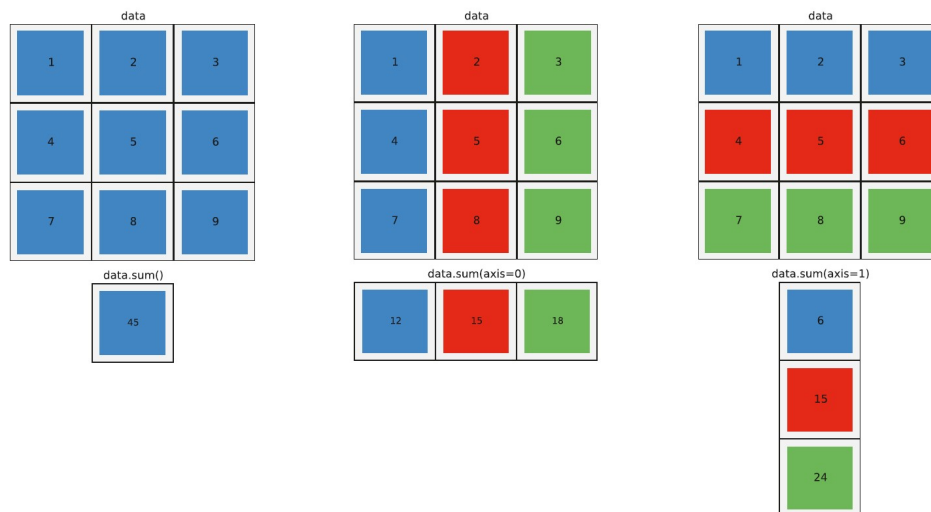
```
Out[36]: (10,)
```

```
In [37]: data.sum()
```

```
Out[37]: -16.285187474805525
```

```
In [40]: data = np.arange(1, 10).reshape((3, 3)); data
```

```
Out[40]: array([[1, 2, 3],
 [4, 5, 6],
 [7, 8, 9]])
```



```
In [41]: data.sum()
```

```
Out[41]: 45
```

```
In [42]: data.sum(axis = 0)
```

```
Out[42]: array([12, 15, 18])
```

```
In [44]: data.sum(axis = 1)
```

```
Out[44]: array([6, 15, 24])
```

```
In [43]: np.sum(data, axis = 0)
```

Out[43]: array([12, 15, 18])

# Boolean Arrays and Conditional Expressions

## NumPy Functions for Conditional and Logical Expressions

Function	Description
np.where	Chooses values from two arrays depending on the value of a condition array.
np.choose	Chooses values from a list of arrays depending on the values of a given index array.
np.select	Chooses values from a list of arrays depending on a list of conditions.
np.nonzero	Returns an array with indices of nonzero elements.
np.logical_and	Performs an elementwise AND operation.
np.logical_or, np.logical_xor	Elementwise OR/XOR operations.
np.logical_not	Elementwise NOT operation (inverting).

```
In []: # <, >, <=, >=, ==, !=
```

```
In [45]: a = np.array([1, 2, 3, 4])
```

```
In [46]: b = np.array([4, 3, 2, 1])
```

```
In [47]: a < b
```

Out[47]: array([ True, True, False, False])

```
In [49]: (a < b).dtype
```

Out[49]: dtype('bool')

```
In [50]: np.all(a < b)
```

Out[50]: False

```
In [52]: np.any(a < b)
```

Out[52]: True

```
In [53]: if np.all(a < b):
 print('All elements in a is lower than all elements in b.')
```

```

elif np.any(a < b):
 print('some elements in a is lower than some elements in b.')
else:
 print('all elements in a is bigger than all elements in b.')

```

some elements in a is lower than some elements in b.

```
In [54]: x = np.array([-2, -1, 0, 1, 2])
```

```
In [55]: x > 0
```

```
Out[55]: array([False, False, False, True, True])
```

```
In [56]: 1.0 * (x > 0)
```

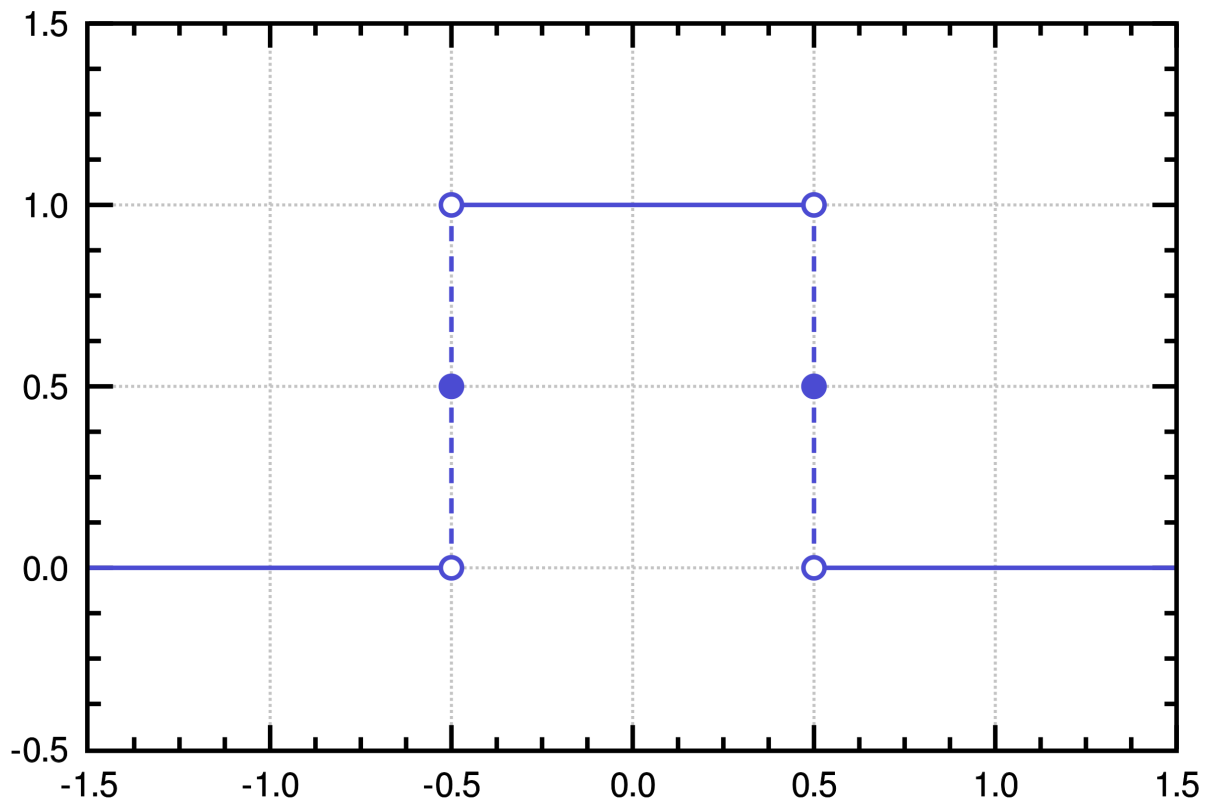
```
Out[56]: array([0., 0., 0., 1., 1.])
```

```
In [57]: x * (x > 0)
```

```
Out[57]: array([0, 0, 0, 1, 2])
```

```
In [62]: from IPython.display import Image
 Image(data = 'PulseFunc.png')
```

Out[62]:



```
In [67]: # Desing piece wise functions like pulse function
```

```
def pulse(x, position, height, width):
 return height * (x >= position) * (x <= (position + width))
```

```
In [66]: x = np.linspace(-5, 5, 11); x
```

```
Out[66]: array([-5., -4., -3., -2., -1., 0., 1., 2., 3., 4., 5.])
```

```
In [68]: pulse(x, position = -3, height = 5, width = 6)
```

```
Out[68]: array([0, 0, 5, 5, 5, 5, 5, 5, 5, 0, 0])
```

```
In [73]: def pulse(x, position, height, width):
 return height * np.logical_and(x >= position, x <= (position + width))
```

```
In [74]: pulse(x, position = -3, height = 5, width = 6)
```

```
Out[74]: array([0, 0, 5, 5, 5, 5, 5, 5, 5, 0, 0])
```

```
In [78]: x = np.linspace(-4, 4, 9);x
```

```
Out[78]: array([-4., -3., -2., -1., 0., 1., 2., 3., 4.])
```

```
In [77]: np.where(x < 0 , x**2, x**3)
```

```
Out[77]: array([16., 9., 4., 1., 0., 1., 8., 27., 64.])
```

```
In [79]: np.select([x < -1, x < 2, x >= 2], [x**2, x**3, x**4])
```

```
Out[79]: array([16., 9., 4., -1., 0., 1., 16., 81., 256.])
```

```
In [80]: np.choose([0, 0 ,0, 1, 1, 1, 2, 2, 2], [x**2, x**3, x**4])
```

```
Out[80]: array([16., 9., 4., -1., 0., 1., 16., 81., 256.])
```

```
In [81]: x
```

```
Out[81]: array([-4., -3., -2., -1., 0., 1., 2., 3., 4.])
```

```
In [82]: np.nonzero(abs(x) > 2)
```

```
Out[82]: (array([0, 1, 7, 8], dtype=int64),)
```

```
In [83]: x[np.nonzero(abs(x) > 2)]
```

```
Out[83]: array([-4., -3., 3., 4.])
```

```
In [84]: x[abs(x) > 2]
```

```
Out[84]: array([-4., -3., 3., 4.])
```

## Set Operations

### NumPy Functions for Operating on Sets

Function	Description
<code>np.unique</code>	Creates a new array with unique elements, where each value only appears once.
<code>np.in1d</code>	Tests for the existence of an array of elements in another array.
<code>np.intersect1d</code>	Returns an array with elements that are contained in two given arrays.
<code>np.setdiff1d</code>	Returns an array with elements that are contained in one, but not the other, of two given arrays.
<code>np.union1d</code>	Returns an array with elements that are contained in either, or both, of two given arrays.

```
In [3]: a = np.unique([1, 2, 2, 3, 3, 3]); a
```

```
Out[3]: array([1, 2, 3])
```

```
In [5]: b = np.unique([2, 3, 3, 4, 4, 4, 5, 6, 3, 2, 4]); b
```

```
Out[5]: array([2, 3, 4, 5, 6])
```

```
In [6]: np.in1d(a, b)
```

```
Out[6]: array([False, True, True])
```

```
In [7]: a[np.in1d(a, b)]
```

```
Out[7]: array([2, 3])
```

```
In [8]: np.in1d(b, a)
```

```
Out[8]: array([True, True, False, False, False])
```

```
In [9]: 1 in a
```

```
Out[9]: True
```

```
In [10]: 1 in b
```



Out[10]: False

In [11]: `np.all(np.in1d(a , b)) # subset checking`

Out[11]: False

In [12]: `np.union1d(a, b)`

Out[12]: array([1, 2, 3, 4, 5, 6])

In [13]: `np.union1d(b, a)`

Out[13]: array([1, 2, 3, 4, 5, 6])

In [14]: `np.intersect1d(a, b)`

Out[14]: array([2, 3])

In [15]: `np.intersect1d(b, a)`

Out[15]: array([2, 3])

In [18]: `np.setdiff1d(a, b)`

Out[18]: array([1])

In [19]: `np.setdiff1d(b, a)`

Out[19]: array([4, 5, 6])

## Operations on Arrays

### NumPy Functions for Array Operations

Function	Description
<code>np.transpose,</code> <code>np.ndarray.transpose,</code> <code>np.ndarray.T</code>	The transpose (reverse axes) of an array.
<code>np.fliplr/np.flipud</code>	Reverse the elements in each row/column.
<code>np.rot90</code>	Rotates the elements along the first two axes by 90 degrees.
<code>np.sort,</code> <code>np.ndarray.sort</code>	Sort the elements of an array along a given specified axis (which default to the last axis of the array). The <code>np.ndarray</code> method sort performs the sorting in place, modifying the input array.

In [4]: `data = np.arange(9).reshape((3, 3)); data`

```
Out[4]: array([[0, 1, 2],
 [3, 4, 5],
 [6, 7, 8]])
```

```
In [5]: np.transpose(data)
```

```
Out[5]: array([[0, 3, 6],
 [1, 4, 7],
 [2, 5, 8]])
```

```
In [10]: data.transpose()
```

```
Out[10]: array([[0, 3, 6],
 [1, 4, 7],
 [2, 5, 8]])
```

```
In [8]: data.T
```

```
Out[8]: array([[0, 3, 6],
 [1, 4, 7],
 [2, 5, 8]])
```

```
In [13]: data
```

```
Out[13]: array([[0, 1, 2],
 [3, 4, 5],
 [6, 7, 8]])
```

```
In [11]: np.fliplr(data)
```

```
Out[11]: array([[2, 1, 0],
 [5, 4, 3],
 [8, 7, 6]])
```

```
In [14]: np.flipud(data)
```

```
Out[14]: array([[6, 7, 8],
 [3, 4, 5],
 [0, 1, 2]])
```

```
In [15]: np.rot90(data)
```

```
Out[15]: array([[2, 5, 8],
 [1, 4, 7],
 [0, 3, 6]])
```

# Matrix and Vector Operations

## NumPy Functions for Matrix Operations

NumPy Function	Description
np.dot	Matrix multiplication (dot product) between two given arrays representing vectors, arrays, or tensors.
np.inner	Scalar multiplication (inner product) between two arrays representing vectors.
np.cross	The cross product between two arrays that represent vectors.
np.tensordot	Dot product along specified axes of multidimensional arrays.
np.outer	Outer product (tensor product of vectors) between two arrays representing vectors.
np.kron	Kronecker product (tensor product of matrices) between arrays representing matrices and higher-dimensional arrays.
np.einsum	Evaluates Einstein's summation convention for multidimensional arrays.

```
In [5]: A = np.arange(1, 7).reshape((2, 3)); A
```

```
Out[5]: array([[1, 2, 3],
 [4, 5, 6]])
```

```
In [6]: B = np.arange(1, 7).reshape((3, 2)); B
```

```
Out[6]: array([[1, 2],
 [3, 4],
 [5, 6]])
```

```
In [7]: # N * M and M * P -> N * P
```

```
In [8]: np.dot(A, B)
```

```
Out[8]: array([[22, 28],
 [49, 64]])
```

```
In [9]: np.dot(B , A)
```

```
Out[9]: array([[9, 12, 15],
 [19, 26, 33],
 [29, 40, 51]])
```

```
In [10]: A @ B
```

```
Out[10]: array([[22, 28],
 [49, 64]])
```

```
In [12]: B @ A
```

```
Out[12]: array([[9, 12, 15],
 [19, 26, 33],
 [29, 40, 51]])
```

```
In [14]: A = np.arange(9).reshape((3 , 3)); A
```

```
Out[14]: array([[0, 1, 2],
 [3, 4, 5],
```

```
[6, 7, 8]])
```

```
In [15]: x = np.arange(3); x
```

```
Out[15]: array([0, 1, 2])
```

```
In [17]: A.shape
```

```
Out[17]: (3, 3)
```

```
In [18]: x.shape
```

```
Out[18]: (3,)
```

```
In [16]: np.dot(A, x)
```

```
Out[16]: array([5, 14, 23])
```

```
In [19]: y = np.arange(3).reshape((1, 3)); y
```

```
Out[19]: array([[0, 1, 2]])
```

```
In [20]: y.shape
```

```
Out[20]: (1, 3)
```

```
In [21]: np.dot(A, y)
```

```

ValueError Traceback (most recent call last)
~\AppData\Local\Temp\ipykernel_14404\3453443763.py in <module>
----> 1 np.dot(A, y)

<__array_function__ internals> in dot(*args, **kwargs)

ValueError: shapes (3,3) and (1,3) not aligned: 3 (dim 1) != 1 (dim 0)
```

```
In [26]: print(y)
 print('\n',A)
```

```
[[0 1 2]]
```

```
[[0 1 2]
 [3 4 5]
 [6 7 8]]
```

```
In [22]: np.dot(y, A)
```

```
Out[22]: array([[15, 18, 21]])
```

In [27]: `A.dot(x)`

Out[27]: `array([ 5, 14, 23])`

In [28]: `# A_prime = BAB^-1`

In [32]: `A = np.random.rand(3, 3); A`

Out[32]: `array([[0.42444768, 0.08570787, 0.23705496],  
[0.50194924, 0.8918437 , 0.85327381],  
[0.78860255, 0.74432695, 0.87303542]])`

In [33]: `B = np.random.rand(3, 3); B`

Out[33]: `array([[0.46871292, 0.42345985, 0.5602959 ],  
[0.16776235, 0.06976333, 0.65776935],  
[0.62478447, 0.51727267, 0.26160816]])`

In [35]: `A_prime = np.dot(B ,np.dot(A, np.linalg.inv(B))); A_prime`

Out[35]: `array([[ 2.54959175, -0.55123481, -0.39885741],  
[ 1.24304873, -0.06916957, 0.08629156],  
[ 2.10241501, -0.43167853, -0.29109538]])`

In [37]: `A_prime = B.dot(A.dot(np.linalg.inv(B))); A_prime`

Out[37]: `array([[ 2.54959175, -0.55123481, -0.39885741],  
[ 1.24304873, -0.06916957, 0.08629156],  
[ 2.10241501, -0.43167853, -0.29109538]])`

In [40]: `A = np.matrix(A); A`

Out[40]: `matrix([[0.42444768, 0.08570787, 0.23705496],  
[0.50194924, 0.8918437 , 0.85327381],  
[0.78860255, 0.74432695, 0.87303542]])`

In [41]: `B = np.matrix(B); B`

Out[41]: `matrix([[0.46871292, 0.42345985, 0.5602959 ],  
[0.16776235, 0.06976333, 0.65776935],  
[0.62478447, 0.51727267, 0.26160816]])`

In [43]: `A_prime = B * A * B.I; A_prime`

Out[43]: `matrix([[ 2.54959175, -0.55123481, -0.39885741],  
[ 1.24304873, -0.06916957, 0.08629156],  
[ 2.10241501, -0.43167853, -0.29109538]])`

In [44]: `A = np.random.rand(3, 3); A`

`array([[0.39468434, 0.4131507 , 0.11883634],`

```
Out[44]: [0.1883368 , 0.00684695, 0.94127215],
 [0.01192458, 0.18653736, 0.29896111]])
```

```
In [45]: B = np.random.rand(3, 3); B
```

```
Out[45]: array([[0.91005693, 0.7889583 , 0.23023307],
 [0.11238977, 0.9456988 , 0.42102974],
 [0.45365817, 0.39384245, 0.38422564]])
```

```
In [46]: type(A)
```

```
Out[46]: numpy.ndarray
```

```
In [47]: A = np.asmatrix(A)
```

```
In [48]: B = np.asmatrix(B)
```

```
In [49]: type(A)
```

```
Out[49]: numpy.matrix
```

```
In [51]: A_prime = B * A * B.I; A_prime
```

```
Out[51]: matrix([[-0.91548479, -0.02343996, 2.96764898],
 [-1.59612519, -0.07995528, 3.72315548],
 [-0.56756356, 0.04404366, 1.69593247]])
```

```
In [53]: A_prime = np.asarray(A_prime); A_prime
```

```
Out[53]: array([[-0.91548479, -0.02343996, 2.96764898],
 [-1.59612519, -0.07995528, 3.72315548],
 [-0.56756356, 0.04404366, 1.69593247]])
```

```
In [54]: x
```

```
Out[54]: array([0, 1, 2])
```

```
In [55]: np.inner(x, x) # np.inner just accepts vectors
```

```
Out[55]: 5
```

```
In [56]: np.sum(x * x)
```

```
Out[56]: 5
```

```
In [57]: np.dot(x, x) # np.dot could accept vbeectors with dimensions like 1*N or N*1
```

Out[57]: 5

In [58]: `y = x[:, np.newaxis]; y`Out[58]: `array([[0],  
 [1],  
 [2]])`In [59]: `np.dot(y.T, y)`Out[59]: `array([[5]])`

## Outer product

Given two vectors

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

their outer product  $\mathbf{u} \otimes \mathbf{v}$  is defined as the  $m \times n$  matrix  $\mathbf{A}$  obtained by multiplying each element of  $\mathbf{u}$  by each element of  $\mathbf{v}$ :

$$\mathbf{u} \otimes \mathbf{v} = \mathbf{A} = \begin{bmatrix} u_1 v_1 & u_1 v_2 & \dots & u_1 v_n \\ u_2 v_1 & u_2 v_2 & \dots & u_2 v_n \\ \vdots & \vdots & \ddots & \vdots \\ u_m v_1 & u_m v_2 & \dots & u_m v_n \end{bmatrix}$$

index notation :

$$(\mathbf{u} \otimes \mathbf{v})_{ij} = u_i v_j$$

The outer product  $\mathbf{u} \otimes \mathbf{v}$  is equivalent to a matrix multiplication  $uv^T$ , provided that  $\mathbf{u}$  is represented as a  $m \times 1$  column vector and  $\mathbf{v}$  as a  $n \times 1$  column vector (which makes  $v^T$  a row vector). For instance, if  $m = 4$  and  $n = 3$ , then

$$\mathbf{u} \otimes \mathbf{v} = \mathbf{u} \mathbf{v}^T = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} = \begin{bmatrix} u_1 v_1 & u_1 v_2 & u_1 v_3 \\ u_2 v_1 & u_2 v_2 & u_2 v_3 \\ u_3 v_1 & u_3 v_2 & u_3 v_3 \\ u_4 v_1 & u_4 v_2 & u_4 v_3 \end{bmatrix}.$$

[Wikipedia](#)

```
In [60]: x = np.array([1, 2, 3])
```

```
In [61]: np.outer(x, x)
```

```
Out[61]: array([[1, 2, 3],
 [2, 4, 6],
 [3, 6, 9]])
```

## Kronecker product

If  $A$  is an  $m \times n$  matrix and  $B$  is a  $p \times q$  matrix, then the Kronecker product  $A \otimes B$  is the  $pm \times qn$  block matrix:

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11} \mathbf{B} & \cdots & a_{1n} \mathbf{B} \\ \vdots & \ddots & \vdots \\ a_{m1} \mathbf{B} & \cdots & a_{mn} \mathbf{B} \end{bmatrix},$$

more explicitly:

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} & \cdots & a_{11}b_{1q} & \cdots & \cdots & a_{1n}b_{11} & a_{1n}b_{12} & \cdots & a_{1n}b_{1q} \\ a_{11}b_{21} & a_{11}b_{22} & \cdots & a_{11}b_{2q} & \cdots & \cdots & a_{1n}b_{21} & a_{1n}b_{22} & \cdots & a_{1n}b_{2q} \\ \vdots & \vdots & \ddots & \vdots & \cdots & \cdots & \vdots & \vdots & \ddots & \vdots \\ a_{11}b_{p1} & a_{11}b_{p2} & \cdots & a_{11}b_{pq} & \cdots & \cdots & a_{1n}b_{p1} & a_{1n}b_{p2} & \cdots & a_{1n}b_{pq} \\ \vdots & \vdots & & \vdots & \ddots & & \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots & & \ddots & \vdots & \vdots & & \vdots \\ a_{m1}b_{11} & a_{m1}b_{12} & \cdots & a_{m1}b_{1q} & \cdots & \cdots & a_{mn}b_{11} & a_{mn}b_{12} & \cdots & a_{mn}b_{1q} \\ a_{m1}b_{21} & a_{m1}b_{22} & \cdots & a_{m1}b_{2q} & \cdots & \cdots & a_{mn}b_{21} & a_{mn}b_{22} & \cdots & a_{mn}b_{2q} \\ \vdots & \vdots & \ddots & \vdots & \cdots & \cdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1}b_{p1} & a_{m1}b_{p2} & \cdots & a_{m1}b_{pq} & \cdots & \cdots & a_{mn}b_{p1} & a_{mn}b_{p2} & \cdots & a_{mn}b_{pq} \end{bmatrix}.$$

[Wikipedia](#)

```
In [62]: np.kron(x, x)
```

```
Out[62]: array([1, 2, 3, 2, 4, 6, 3, 6, 9])
```

```
In [66]: np.kron(x[:, np.newaxis], x[np.newaxis, :]) # to act like outer product our inputs shpu
```



```
Out[66]: array([[1, 2, 3],
 [2, 4, 6],
 [3, 6, 9]])
```

```
In [65]: np.outer(x, x)
```

```
Out[65]: array([[1, 2, 3],
 [2, 4, 6],
 [3, 6, 9]])
```

```
In [67]: np.kron(np.ones((2, 2)), np.identity(2))
```

```
Out[67]: array([[1., 0., 1., 0.],
 [0., 1., 0., 1.],
 [1., 0., 1., 0.],
 [0., 1., 0., 1.]])
```

```
In [70]: np.kron(np.identity(2), np.ones((2, 2)))
```

```
Out[70]: array([[1., 1., 0., 0.],
 [1., 1., 0., 0.],
 [0., 0., 1., 1.],
 [0., 0., 1., 1.]])
```

## Einstein notation

scalar product between two vectors  $x$  and  $y$ :

$$x_n y_n$$

matrix multiplication of  $A$  and  $B$  :  $A_{mk} B_{kn}$

```
In [71]: x = np.arange(1,5)
```

```
In [72]: y = np.array([5, 6, 7, 8])
```

```
In [73]: np.einsum('n, n', x, y)
```

```
Out[73]: 70
```

```
In [74]: np.inner(x, y)
```

```
Out[74]: 70
```

```
In [75]: A = np.arange(9).reshape((3, 3))
```

```
In [76]: B = A.T
```

```
In [77]: np.einsum('mk, kn', A, B)
```

```
Out[77]: array([[5, 14, 23],
 [14, 50, 86],
 [23, 86, 149]])
```

```
In [78]: np.alltrue(np.einsum('mk, kn', A, B) == np.dot(A, B))
```

```
Out[78]: True
```

```
In [1]: !jupyter nbconvert --to html Numpy.ipynb
```

```
In []:
```