










2-1 True-False Exercises


- a. The determinant of the 2×2 matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is $ad + bc$. 
- b. Two square matrices that have the same determinant must have the same size. 
- c. The minor M_{ij} is the same as the cofactor C_{ij} if $i + j$ is even. 
- d. If A is a 3×3 symmetric matrix, then $C_{ij} = C_{ji}$ for all i and j . 
- e. The number obtained by a cofactor expansion of a matrix A is independent of the row or column chosen for the expansion. 

f. If A is a square matrix whose minors are all zero, then $\det(A) = 0$. 

g. The determinant of a lower triangular matrix is the sum of the entries along the main diagonal. 

h. For every square matrix A and every scalar c , it is true that $\det(cA) = c \det(A)$. 

i. For all square matrices A and B , it is true that 
$$\det(A + B) = \det(A) + \det(B)$$

j. For every 2×2 matrix A it is true that 
$$\det(A^2) = (\det(A))^2$$

(a) False. The determinant is $ad - bc$.

(b) False. E.g., $\det(I_2) = \det(I_3) = 1$.

(c) True. If $i + j$ is even then $(-1)^{i+j} = 1$ therefore $C_{ij} = (-1)^{i+j} M_{ij} = M_{ij}$.

(d) True. Let $A = \begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix}$.

Then $C_{12} = (-1)^{1+2} \begin{vmatrix} b & e \\ c & f \end{vmatrix} = -(bf - ec)$ and $C_{21} = (-1)^{2+1} \begin{vmatrix} b & c \\ e & f \end{vmatrix} = -(bf - ce)$ therefore $C_{12} = C_{21}$. In the same way, one can show $C_{13} = C_{31}$ and $C_{23} = C_{32}$.

(e) True. This follows from Theorem 2.1.1.

(f) True. In formulas (7) and (8), each cofactor C_{ij} is zero.

(g) False. The determinant of a lower triangular matrix is the *product* of the entries along the main diagonal.




(h) False. E.g. $\det(2I_2) = 4 \neq 2 = 2\det(I_2)$.

(i) False. E.g., $\det(I_2 + I_2) = 4 \neq 2 = \det(I_2) + \det(I_2)$.

(j) True. $\det\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}^2\right) = \begin{vmatrix} a^2 + bc & ab + bd \\ ac + cd & bc + d^2 \end{vmatrix} = (a^2 + bc)(bc + d^2) - (ab + bd)(ac + cd)$
 $= a^2bc + a^2d^2 + b^2c^2 + bcd^2 - a^2bc - abcd - abcd - bcd^2 = a^2d^2 + b^2c^2 - 2abcd$.


$\begin{vmatrix} a & b \\ c & d \end{vmatrix}^2 = (ad - bc)^2 = a^2d^2 - 2adbc + b^2c^2$ therefore $\det\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}^2\right) = \left(\det\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right)\right)^2$.


2-2 True-False Exercises

- a. If A is a 4×4 matrix and B is obtained from A by interchanging the first two rows and then interchanging the last two rows, then $\det(B) = \det(A)$. 
- b. If A is a 3×3 matrix and B is obtained from A by multiplying the first column by 4 and multiplying the third column by $\frac{3}{4}$, then $\det(B) = 3 \det(A)$. 
- c. If A is a 3×3 matrix and B is obtained from A by adding 5 times the first row to each of the second and third rows, then $\det(B) = 25 \det(A)$. 

- d.** If A is an $n \times n$ matrix and B is obtained from A by multiplying each row of A by its row number, then

$$\det(B) = \frac{n(n+1)}{2} \det(A) \quad \times$$

- e.** If A is a square matrix with two identical columns, then $\det(A) = 0$. 

- f.** If the sum of the second and fourth row vectors of a 6×6 matrix A is equal to the last row vector, then $\det(A) = 0$. 

- (a) True. $\det(B) = (-1)(-1)\det(A) = \det(A)$.
- (b) True. $\det(B) = (4)\left(\frac{3}{4}\right)\det(A) = 3\det(A)$.
- (c) False. $\det(B) = \det(A)$.
- (d) False. $\det(B) = n(n-1)\cdots 3\cdot 2\cdot 1\cdot \det(A) = (n!)\det(A)$.
- (e) True. This follows from Theorem 2.2.5.
- (f) True. Let B be obtained from A by adding the second row to the fourth row, so $\det(A) = \det(B)$. Since the fourth row and the sixth row of B are identical, by Theorem 2.2.5 $\det(B) = 0$.

2-3 True-False Exercises

- a. If A is a 3×3 matrix, then $\det(2A) = 2 \det(A)$. \times
- b. If A and B are square matrices of the same size such that $\det(A) = \det(B)$, then $\det(A + B) = 2 \det(A)$. \times
- c. If A and B are square matrices of the same size and A is invertible, then

$$\det(A^{-1}BA) = \det(B) \quad \bigcirc$$

- d. A square matrix A is invertible if and only if $\det(A) = 0$. \times
- e. The matrix of cofactors of A is precisely $[\text{adj}(A)]^T$. \bigcirc

f. For every $n \times n$ matrix A , we have

$$A \cdot \text{adj}(A) = (\det(A))I_n$$

g. If A is a square matrix and the linear system $A\mathbf{x} = \mathbf{0}$ has multiple solutions for \mathbf{x} , then $\det(A) = 0$.

h. If A is an $n \times n$ matrix and there exists an $n \times 1$ matrix \mathbf{b} such that the linear system $A\mathbf{x} = \mathbf{b}$ has no solutions, then the reduced row echelon form of A cannot be I_n .

i. If E is an elementary matrix, then $E\mathbf{x} = \mathbf{0}$ has only the trivial solution.

j. If A is an invertible matrix, then the linear system $A\mathbf{x} = \mathbf{0}$ has only the trivial solution if and only if the linear system $A^{-1}\mathbf{x} = \mathbf{0}$ has only the trivial solution.

- k. If A is invertible, then $\text{adj}(A)$ must also be invertible. ○
- l. If A has a row of zeros, then so does $\text{adj}(A)$. ✗

- (a) False. By Formula (1), $\det(2A) = 2^3 \det(A) = 8 \det(A)$.
- (b) False. E.g. $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ have $\det(A) = \det(B) = 0$ but $\det(A + B) = 1 \neq 2 \det(A)$.
- (c) True. By Theorems 2.3.4 and 2.3.5,

$$\det(A^{-1}BA) = \det(A^{-1})\det(B)\det(A) = \frac{1}{\det(A)}\det(B)\det(A) = \det(B).$$
- (d) False. A square matrix A is invertible if and only if $\det(A) \neq 0$.
- (e) True. This follows from Definition 1.
- (f) True. This is Formula (8).
- (g) True. If $\det(A) \neq 0$ then by Theorem 2.3.8 $A\mathbf{x} = \mathbf{0}$ must have only the trivial solution, which contradicts our assumption. Consequently, $\det(A) = 0$.

- (h) True. If the reduced row echelon form of A is I_n then by Theorem 2.3.8 $A\mathbf{x} = \mathbf{b}$ is consistent for every \mathbf{b} , which contradicts our assumption. Consequently, the reduced row echelon form of A cannot be I_n .
- (i) True. Since the reduced row echelon form of E is I then by Theorem 2.3.8 $E\mathbf{x} = 0$ must have only the trivial solution.
- (j) True. If A is invertible, so is A^{-1} . By Theorem 2.3.8, each system has only the trivial solution.
- (k) True. From Theorem 2.3.6, $A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$ therefore $\text{adj}(A) = \det(A)A^{-1}$. Consequently,

$$\left(\frac{1}{\det(A)}A\right) \text{adj}(A) = \left(\frac{1}{\det(A)}A\right) (\det(A)A^{-1}) = \frac{\det(A)}{\det(A)}(AA^{-1}) = I_n \text{ so } (\text{adj}(A))^{-1} = \frac{1}{\det(A)}A.$$
- (l) False. If the k th row of A contains only zeros then all cofactors C_{jk} where $j \neq i$ are zero (since each of them involves a determinant of a matrix with a zero row). This means the matrix of cofactors contains at least one zero row, therefore $\text{adj}(A)$ has a *column* of zeros.