

7.12 激励方程:  $D_1 = \overline{Q_1} + Q_2$ ,  $D_2 = X \cdot \overline{Q_2}$

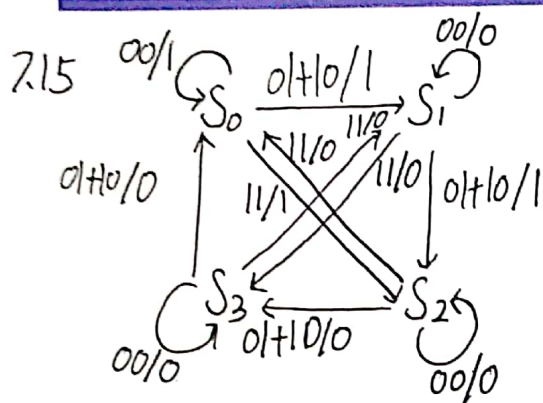
激励转移表:

现态	X	
	0	1
A	C	D
B	C	C
C	A	B
D	C	C
	$Q_1^* Q_2^*$	

状态/输出表:  $Z = Q_1 + \overline{Q_2}$

现态	输出
A	1
B	0
C	1
D	1





7.18 激励方程:  $D_2 = \overline{Q_1 + Q_2} \oplus (Q_1 \oplus Q_0)$

$$D_1 = Q_2$$

$$D_0 = Q_1$$

激励转移表:

现态 ( $Q_2 Q_1 Q_0$ )	次态 ( $Q_2^* Q_1^* Q_0^*$ )
000	1 00
001	0 00
010	1 01
011	0 01
100	0 10
101	1 10
110	1 11
111	0 11

状态输出表:

现态 ( $Q_2 Q_1 Q_0$ )	输出 ( $Q_2 Q_1 Q_0$ )
A	<del>A</del> A
B	<del>A</del> B
C	<del>F</del> C
D	<del>B</del> D
E	<del>C</del> E
F	<del>G</del> F
G	<del>H</del> G
H	<del>D</del> H



7.19. 激励方程:  $D_1 = X$   
 $D_2 = (Q_1 + Y) \cdot \overline{Q_3}$   
 $D_3 = (\overline{Q_2} \cdot Y) + \overline{Q_1}$

激励转移表: 现态( $Q_1 Q_2 Q_3$ )

现态( $Q_1 Q_2 Q_3$ )	<del>次态(<math>Q_1^* Q_2^* Q_3^*</math>)</del>		$X Y$	
	00	01	10	11
000	00	01	10	11
001	00	00	10	10
010	00	01	10	11
011	00	00	10	10
100	01	01	11	11
101	00	00	10	10
110	01	01	11	10
111	00	00	10	10
	次态( $Q_1^* Q_2^* Q_3^*$ )			

状态<sup>输出</sup>表

现态( $Q_1 Q_2 Q_3$ )	输出( $Q_1 Q_2 Q_3$ )
A	A
B	B
C	C
D	D
E	E
F	F
G	G
H	H



7.20 激励方程:  $EN_1 = Y$

$$EN_2 = \bar{X} \cdot Y \cdot Q_1$$

激励转移表:

$$\text{转移方程为 } Q_1^* = EN_1 \cdot \bar{Q}_1 + \overline{EN_1} \cdot Q_1 = Y \cdot \bar{Q}_1 + \bar{Y} \cdot Q_1$$

$$Q_2^* = EN_2 \cdot \bar{Q}_2 + \overline{EN_2} \cdot Q_2$$

$$= \bar{X} \cdot Y \cdot Q_1 \cdot \bar{Q}_2 + (X + \bar{Y} + \bar{Q}_1) \cdot Q_2$$

现态 ( $Q_1 Q_2$ )	X Y			
	00	01	10	11
00	00	10	00	10
01	01	11	01	11
10	10	01	10	00
11	11	00	11	01
次态 ( $Q_1^* Q_2^*$ )				

状态/输出表:

$$\text{输出方程: } z = \bar{X} \cdot \bar{Q}_2$$

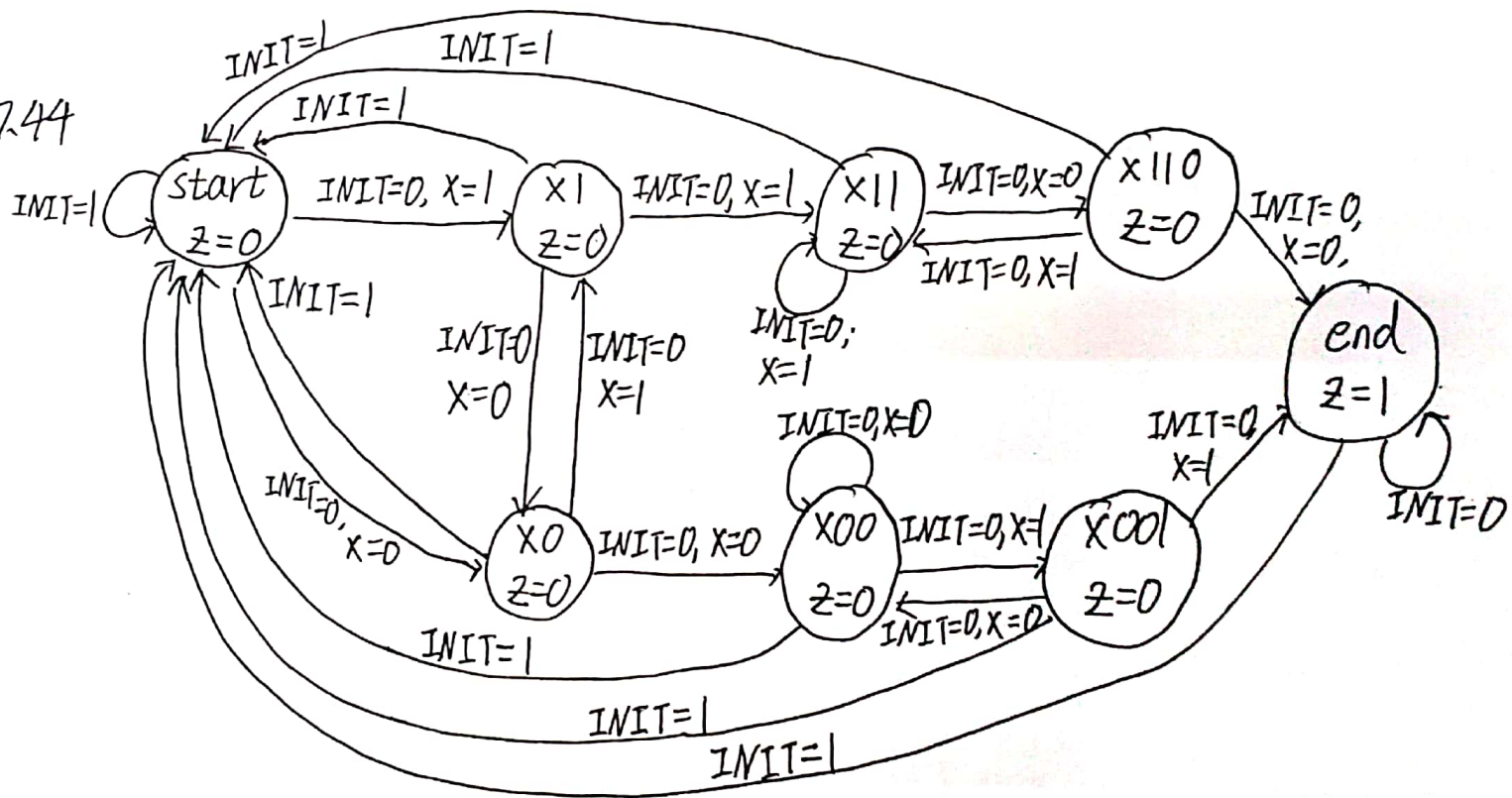
状态 ( $Q_1 Q_2$ )	X	
	0	1
A	1	0
B	0	0
C	1	0
D	0	0
输出 (z)		





7.43  $t_{Fmax} + 2 \cdot \max\{t_{CQmax}, t_{DQmax}\} \leq t_H + t_L$   
 $t_{setup} < \min\{t_L, t_H\}$   
 $t_{hold} < \min\{t_L, t_H\}$

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46. 卡诺图:

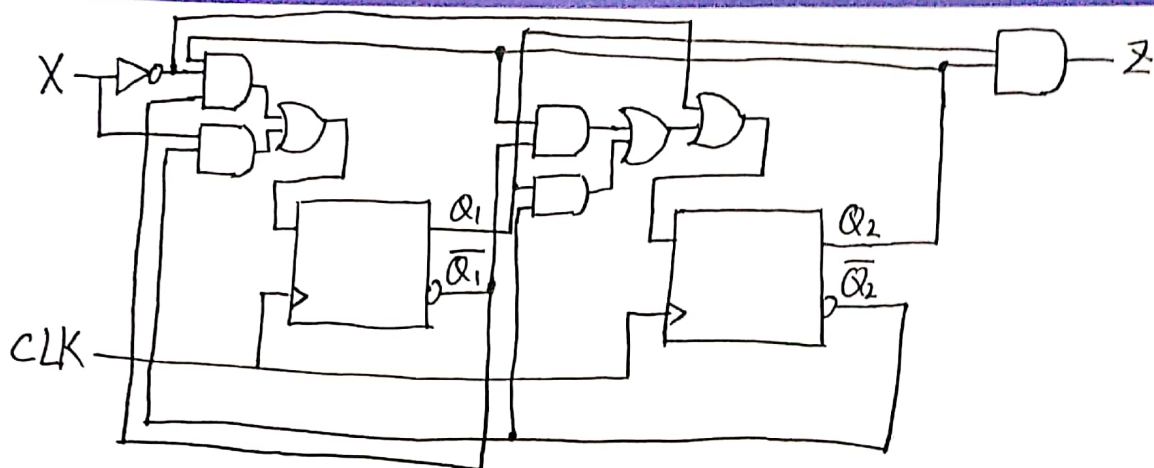
		$Q_1^*$	
$\bar{x}$	$x$	0	1
0	0	0	1
0	1	1	0
1	1	0	0
1	0	0	1

		$Q_2^*$	
$\bar{x}$	$x$	0	1
0	0	0	1
0	1	1	1
1	1	1	0
1	0	1	1

		$z$	
$Q_1$	$Q_2$	0	1
0	0	0	0
0	1	0	0
1	0	0	1
1	1	0	0

$D_1 = x \cdot \bar{Q}_2 + \bar{x} \cdot \bar{Q}_1 \cdot Q_2$   $D_2 = \bar{x} + \bar{Q}_1 \cdot Q_2 + Q_1 \cdot \bar{Q}_2$   $z = Q_1 \cdot Q_2$





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S Q <sub>1</sub> Q <sub>2</sub> Q <sub>3</sub>	AB				Z
	00	01	11	10	
000	001	001	010	010	0
001	011	011	010	010	0
010	001	001	100	100	0
011	011	011	100	010	1
100	001	011	100	100	1
$S^*(Q_1^*Q_2^*Q_3^*)$					

D<sub>1</sub>:

Q <sub>1</sub> Q <sub>2</sub> Q <sub>3</sub> \ AB	000	001	011	010	110	111	101	100
00	0	0	0	0	d	d	d	0
01	0	0	0	0	d	d	d	0
11	0	0	1	1	d	d	d	1
10	0	0	1	0	d	d	d	1

$D_1 = A \cdot \bar{Q}_1 \cdot Q_2 \cdot Q_3$   
 $+ A \cdot B \cdot \bar{Q}_2$   
 $+ A \cdot Q_1 \cdot \bar{Q}_2 \cdot \bar{Q}_3$

D<sub>2</sub>:

Q <sub>1</sub> Q <sub>2</sub> Q <sub>3</sub> \ AB	000	001	011	010	110	111	101	100
00	0	1	0	1	d	d	d	0
01	0	1	0	1	d	d	d	1
11	1	1	0	0	d	d	d	0
10	1	1	0	1	d	d	d	0

$D_2 = \bar{Q}_2 \cdot Q_3$   
 $+ A \cdot \bar{Q}_1 \cdot \bar{Q}_2$   
 $+ \bar{A} \cdot Q_2 \cdot \bar{Q}_3$   
 $+ \bar{B} \cdot Q_2 \cdot \bar{Q}_3$   
 $+ \bar{A} \cdot B \cdot Q_1$



$Q_1 Q_2 Q_3$		AB							
		000	001	011	010	110	111	101	100
$P_3$	00	1	1	1	1	d	d	d	1
	01	1	1	1	1	d	d	d	1
	10	0	0	0	0	d	d	d	0
	11	0	0	0	0	d	d	d	0

$$D_3 = A$$

$Q_2 Q_3$		$Q_1$		$z$
		0	1	
00	0	0	1	$z = Q_1 + Q_2' Q_3$
01	0	0	d	
11	1	1	d	
10	0	0	d	

除  $P_3$  的激励方程外, 成本都要比 2.4.4 节给出的成本要高  
整体上成本也要高于 2.4.4 节给出的方程

2.4.8	$Q_1 Q_2 Q_3 Q_4$	AB				$z$
		00	01	11	10	
	0000	0001	0001	0010	0010	0
	0001	0100	0100	0010	0010	0
	0010	0001	0001	1000	1000	0
	0100	0100	0100	1000	0010	1
	1000	0001	0100	1000	1000	1
		$Q_1^* Q_2^* Q_3^* Q_4^*$				





$D_1$ :

$Q_4 Q_3 Q_2 Q_1$ \ AB	00	01	11	10
0000	0	0	0	0
0001	0	0	0	0
0011	d	d	d	d
0010	0	0	d	d
0110	d	d	d	d
0111	d	d	d	d
0101	d	d	d	d
0100	0	0	d	0
1100	d	d	d	d
1101	d	d	d	d
1111	d	d	d	d
1110	d	d	d	d
1010	d	d	d	d
1011	d	d	d	d
1001	d	d	d	d
1000	0	0	1	1

$$D_1 = A \cdot \bar{Q}_1 \cdot Q_3 + A \cdot B \cdot Q_2 + A \cdot Q_1$$

$Q_4 Q_3 Q_2 Q_1$ \ AB	00	01	11	10
0000	0	0	1	1
0001	0	0	1	1
0011	d	d	d	d
0010	0	0	0	0
0110	d	d	d	d
0111	d	d	d	d
0101	d	d	d	d
0100	0	0	0	1
1100	d	d	d	d
1101	d	d	d	d
1111	d	d	d	d
1110	d	d	d	d
1010	d	d	d	d
1011	d	d	d	d
1001	d	d	d	d
1000	0	0	0	0

$$D_3 = A \cdot \bar{Q}_1 \cdot \bar{Q}_2 \cdot \bar{Q}_3 + A \cdot \bar{B} \cdot Q_2$$

$Q_4 Q_3 Q_2 Q_1$ \ AB	00	01	11	10
0000	0	0	0	0
0001	1	1	0	0
0011	d	d	d	d
0010	0	0	0	0
0110	d	d	d	d
0111	d	d	d	d
0101	d	d	d	d
0100	1	1	0	0
1100	d	d	d	d
1101	d	d	d	d
1111	d	d	d	d
1110	d	d	d	d
1010	d	d	d	d
1011	d	d	d	d
1001	d	d	d	d
1000	0	1	0	0

$$D_2 = \bar{A} \cdot \bar{Q}_2 \cdot Q_4 + \bar{A} \cdot Q_2 + A \cdot B \cdot Q_1$$





	00	01	11	10		00	01	11	10
0000	1	1	0	0	0000	0	0	0	0
0001	0	0	0	0	0001	0	0	0	0
$D_4$ : 0010	d	d	d	d	0011	d	d	d	d
0011	1	1	0	0	0010	0	0	0	0
0110	d	d	d	d	0110	d	d	d	d
0111	d	d	d	d	0111	d	d	d	d
0101	d	d	d	d	0101	d	d	d	d
0100	0	0	0	0	0100	1	1	1	1
1100	d	d	d	d	1100	d	d	d	d
1101	d	d	d	d	1101	d	d	d	d
1110	d	d	d	d	1111	d	d	d	d
1111	d	d	d	d	1110	d	d	d	d
1010	d	d	d	d	1010	d	d	d	d
1011	d	d	d	d	1011	d	d	d	d
1001	d	d	d	d	1001	d	d	d	d
1000	1	0	0	0	1000	1	1	1	1

$$D_4 = \bar{A} \cdot \bar{Q}_1 \bar{Q}_2 \bar{Q}_3 \bar{Q}_4 + \bar{A} \cdot \bar{Q}_1 \cdot Q_3 + \bar{A} \cdot \bar{B} \cdot Q_1$$

$$Z = Q_1 + Q_2$$

与2.4.4节相比, 输出逻辑成本不变  
激励逻辑成本较高



7.54

	$Q_1 Q_2 Q_3$	X	
		0	1
A	000	001, 01	000, 00
B	001	001, 00	011, 01
C	011	001, 00	010, 01
D	010	110, 01	000, 00
E	110	001, 00	111, 01
F	111	001, 00	101, 01
G	101	110, 00	100, 01
H	100	001, 00	000, 00

$Q_1^* Q_2^* Q_3^*$ , UNLK, HINT

$Q_1 Q_2 \backslash Q_3 X$	00	01	11	10
00	1	0	1	1
01	0	0	0	1
11	1	1	1	1
10	1	0	0	0

$$D_3 = Q_1 Q_2 + \bar{X} \cdot Q_2 \cdot \bar{Q}_3 + \bar{Q}_1 \bar{Q}_2 Q_3 + \bar{X} \cdot \bar{Q}_1 \cdot Q_3$$

与课本相比:

$D_1$  成本相同

$D_2$  成本升高

$D_3$  成本较低

整体成本与课本方案要高

$D_1$

$Q_1 Q_2 \backslash Q_3 X$	00	01	11	10
00	0	0	0	0
01	1	0	0	0
11	0	1	1	0
10	0	0	1	1

$$D_1 = \bar{X} \cdot \bar{Q}_1 \cdot Q_2 \cdot \bar{Q}_3 + X \cdot Q_1 Q_2 + Q_1 \bar{Q}_2 \cdot Q_3$$

$D_2$

$Q_1 Q_2 \backslash Q_3 X$	00	01	11	10
00	0	0	1	0
01	1	0	1	0
11	0	1	0	0
10	0	0	0	1

$$D_2 = \bar{X} \cdot \bar{Q}_1 Q_2 \cdot \bar{Q}_3 + X \cdot Q_1 Q_2 \bar{Q}_3 + \bar{X} \cdot Q_1 \bar{Q}_2 \cdot Q_3 + X \cdot \bar{Q}_1 Q_3$$

