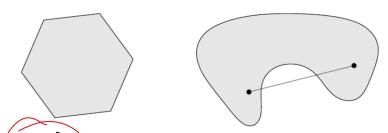
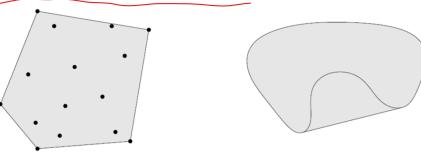
#### 凸包

- - 集合内任意两点的连线属于该集合



- 集合S的凸包 (convex hull) H
  - 包含S的最小凸集合



• 凸缺 (convex deficiency) : H - S



# 构建凸包算法





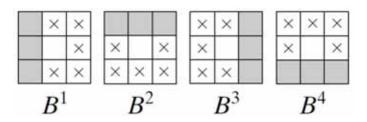
- 四个结构元
  - 黑色表示1前
- 白色表示0 ×表示任意值
- 1. 按照下面的公式更新

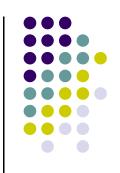


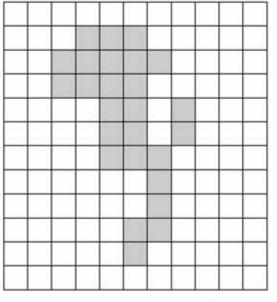
- $X_k^i = (X_{k-1}^i \otimes B^i) \cup A \quad i = 1, 2, 3, 4 \text{ and } k = 1, 2, 3, \dots$ 
  - 其中 $X_0^i = A$
  - 2. 重复上述公式,直到 $X_k^i = X_{k-1}^i$
  - 3. 集合A的凸包
    - 其中 $D^i = X_k^i$

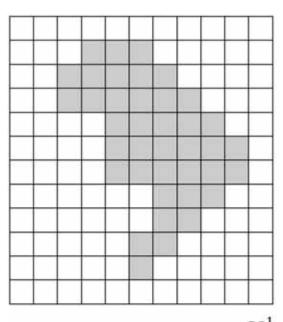
$$C(A) = \bigcup_{i=1}^{4} D$$

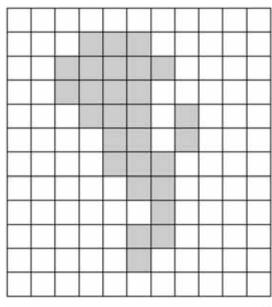










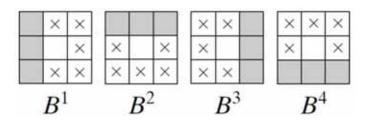


 $X_0^1 = A$ 

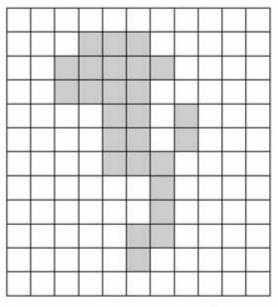
 $X_4^1$ 

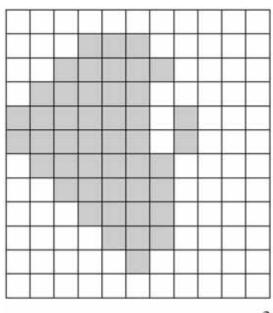
 $X_{2}^{2}$ 

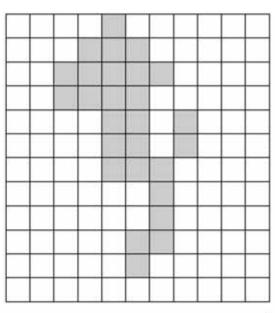










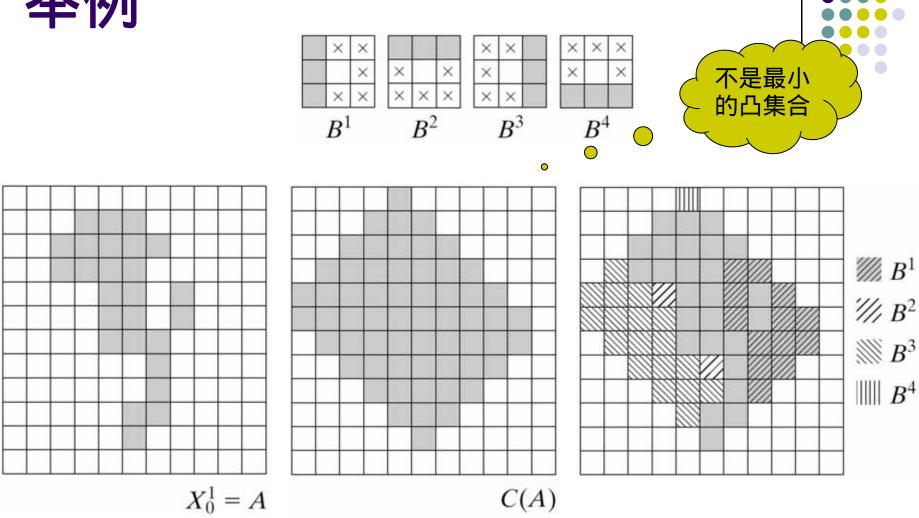


$$X_0^1 = A$$

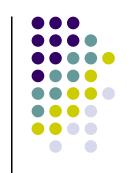
$$X_{8}^{3}$$

 $X_{2}^{4}$ 

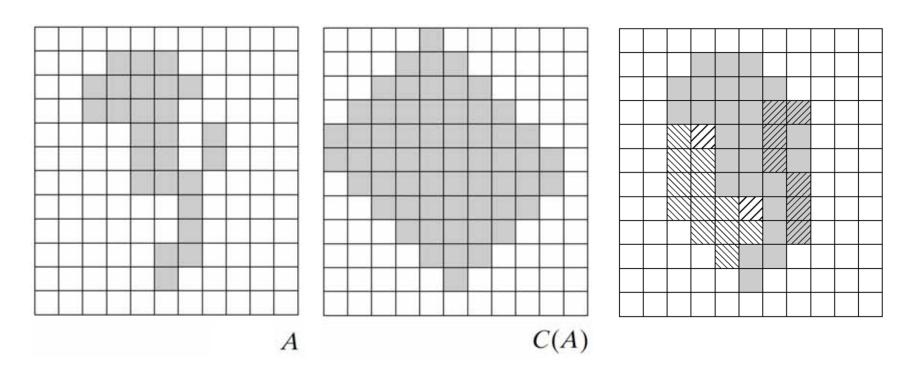








• 不能超过原图像的垂直和水平范围



• 还可以添加更复杂的约束

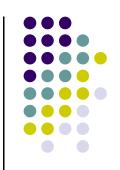


### 提纲

- 预备知识
- 腐蚀和膨胀
- 开操作和闭操作
- 击中或击不中变换
- 基本形态学算法
  - 边界提取、孔洞填充
  - 连通分量提取、凸包
  - 细化、粗化
  - 骨架、裁剪



## 细化



• 结构元B对集合A的细化(thinning)

$$A \otimes B = A - (A \otimes B) = A \cap (A \otimes B)^{c}$$

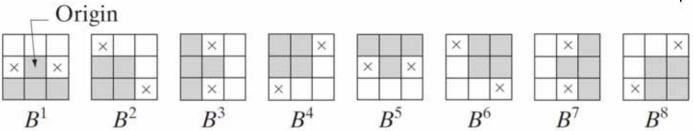
- ◈不用考虑外围背景
- 与边界提取很类似
- 结构元序列 $\{B\} = \{B^1, B^2, ..., B^n\}$ 对集合A的细化

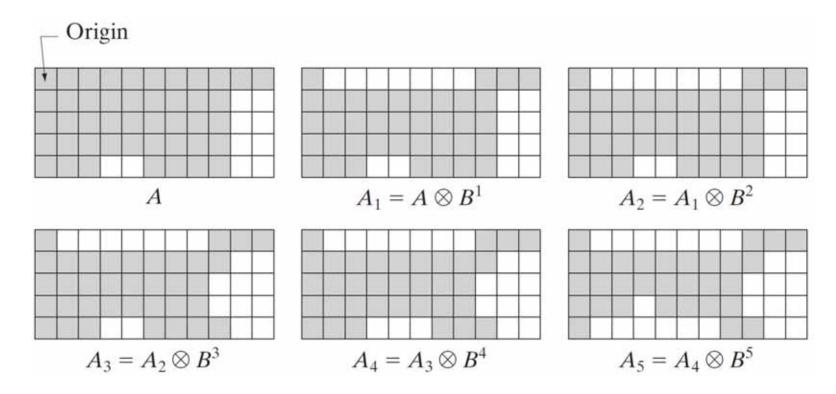
$$A \otimes \{B\} = ((\dots((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$$

- $B^{i}$ 是 $B^{i-1}$ 的旋转版本
- 重复上述过程,直至结果不发生变化



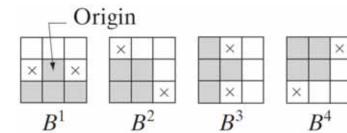


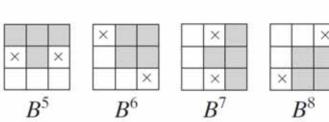


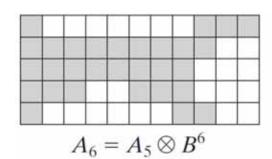




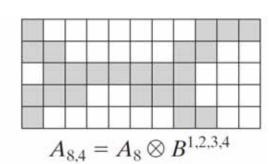


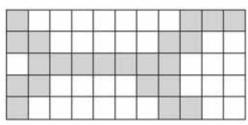


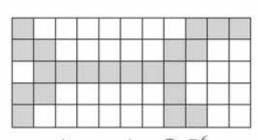


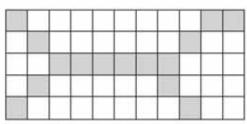


$$A_8 = A_6 \otimes B^{7,8}$$









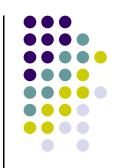
$$A_{8,5} = A_{8,4} \otimes B^5$$

 $A_{8,6} = A_{8,5} \otimes B^6$ No more changes after this.

 $A_{8,6}$  converted to m-connectivity.



## 粗化



● 结构元B对集合A的粗化(thickening)

$$A \odot B = A \cup (A \circledast B)$$

- ③不用考虑外围背景
- 结构元和细化的相反
- 结构元序列 $\{B\} = \{B^1, B^2, ..., B^n\}$ 对集合A的粗化

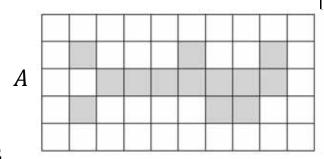
$$A \odot \{B\} = ((\ldots((A \odot B^1) \odot B^2) \ldots) \odot B^n)$$

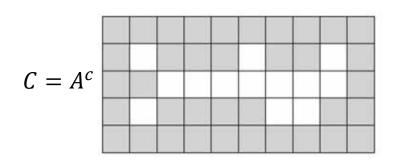
- $B^{i}$ 是 $B^{i-1}$ 的旋转版本
- 重复上述过程,直至结果不发生变化



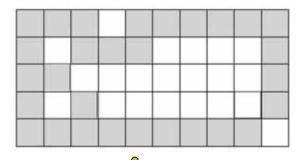
# 粗化算法

- 1. 计算集合A的补集C
- 2. 细化C
- 3. 计算上述结果的补集

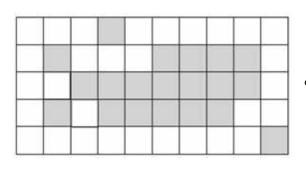




细化



求补



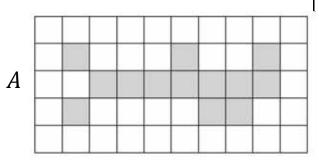
存在立点

形成了一个边界

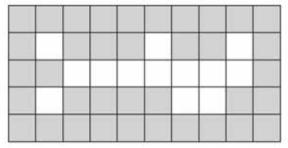
# 粗化算法

- 1. 计算集合A的补集C
- 2. 细化C

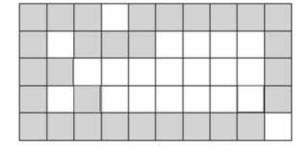
3. 计算上述结果的补集



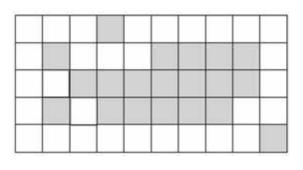
 $C = A^c$ 



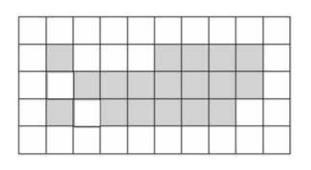
细化



求补



去掉 孤立点

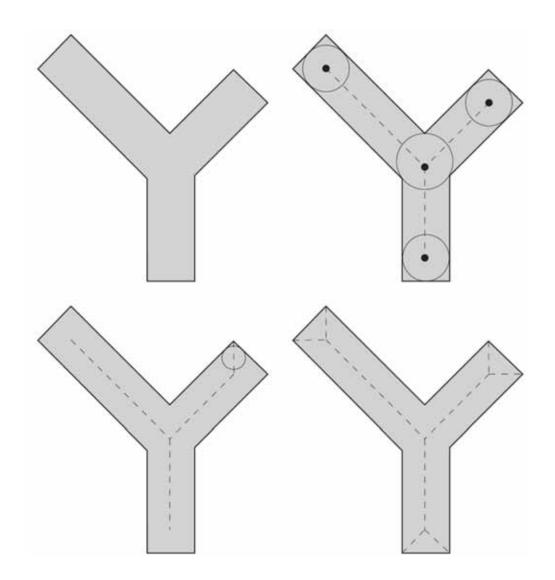


### 提纲

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  - 连通分量提取、凸包
  - 细化、粗化
  - 骨架、裁剪



• 举例







- 集合A的骨架 (skeleton) 记为S(A)
  - 1. 如果 $z \in S(A)$ ,并且 $(D)_z$ 是A内以z为中心的最大圆盘,则不存在包含 $(D)_z$ 且位于A内的更大圆盘。
    - $(D)_z$ 被称为最大圆盘
  - $(D)_z$ 在两个或多个不同的位置与A的边界接触。





• 数学公式

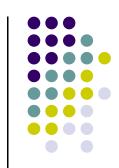
$$S(A) = \bigcup_{k=0}^{K} S_k(A)$$

$$S_k(A) = (A \ominus kB) - (A \ominus kB) \circ B$$

- $S_k(A)$ 是骨架子集
- B是结构元
- $A \ominus kB$ 表示对A进行k次连续腐蚀  $(A \ominus kB) = ((...((A \ominus B) \ominus B) \ominus ...) \ominus B)$
- K是A被腐蚀成空集的最后一次迭代

$$K = \max\{k | (A \ominus kB) \neq \emptyset\}$$





$$S(A) = \bigcup_{k=0}^{K} S_k(A)$$

$$S_k(A) = (A \ominus kB) - (A \ominus kB) \circ B$$

$$(A \ominus kB) = ((\dots((A \ominus B) \ominus B) \ominus \dots) \ominus B)$$

$$K = \max\{k | (A \ominus kB) \neq \emptyset\}$$

#### 重构集合A

$$A = \bigcup_{k=0}^{K} (S_k(A) \oplus kB)$$

$$(S_k(A) \oplus kB) = ((\ldots((S_k(A) \oplus B) \oplus B) \oplus \ldots) \oplus B)$$





k	$A\ominus kB$	$(A\ominus kB)\circ B$	$S_k(A)$	$\bigcup_{k=0}^{K} S_k(A)$	$S_k(A) \oplus kB$	$\bigcup_{k=0}^{K} S_k(A) \oplus kB$	
0							
1							
2				S(A)		A	



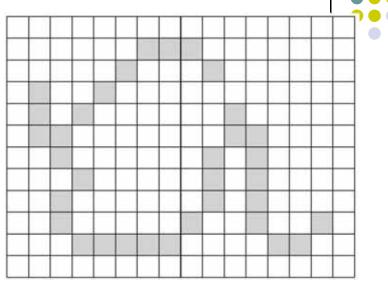


- 裁剪 (pruning)的作用
  - 对细化、骨架的补充
  - 上述操作易产生寄生分量,需要后处理去除

- 自动手写体识别
  - 通过需要分析字母的骨架形状
  - 但骨架往往带有许多"毛刺"(寄生分量)
  - "毛刺"是由笔画的不均匀造成
  - 假设寄生分量的长度较短



- 字符a的骨架
  - 最左边存在毛刺
  - 通过删除端点去除
  - 删除长度≤3的分支



1. 使用检测端点的结构元对集合A细化

$$X_1 = A \otimes \{B\} = ((\dots((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$$



 $B^1$ ,  $B^2$ ,  $B^3$ ,  $B^4$  (rotated 90°)



 $B^5$ ,  $B^6$ ,  $B^7$ ,  $B^8$  (rotated 90°)



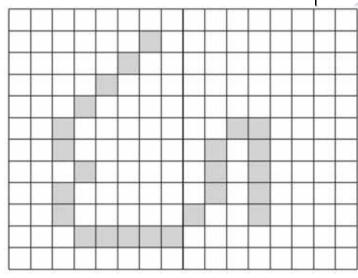


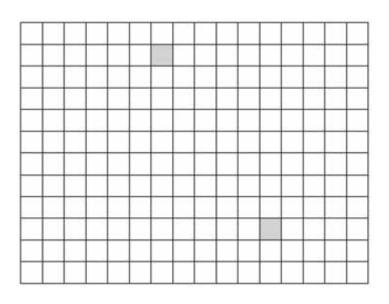
1. 使用检测端点的结 构元对集合A细化

$$X_1 = A \otimes \{B\}$$

- 细化3次
- 复原形状
- 2. 计算 $X_1$ 的端点

$$X_2 = \bigcup_{k=1}^8 (X_1 \circledast B^k)$$









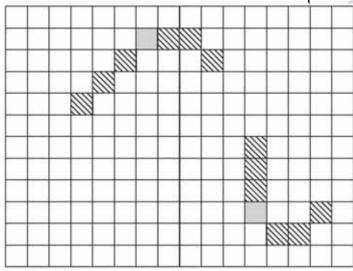
#### 3. 对端点进行膨胀

$$X_3 = (X_2 \oplus H) \cap A$$

• 条件膨胀3次



Н



#### 4. 合并结果

$$X_4 = X_1 \cup X_3$$

